

Linear regression via QR decomposition

$$\hat{C} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \vec{y}$$

- Normal Equations are general and in theory will always work. But in practice ...
 - Matrix inverse computationally intensive to solve (large datasets)
 - Matrix inverse easily corrupted by numerical errors.

Example:

$$\begin{bmatrix} 51 + \Delta & 50 \\ 50 & 50 \end{bmatrix} \xrightarrow[\Delta=0]{\text{inverse}} \begin{bmatrix} 1 & -1 \\ -1 & 1.02 \end{bmatrix}$$

$\xrightarrow[\Delta=0.5]{\text{inverse}}$

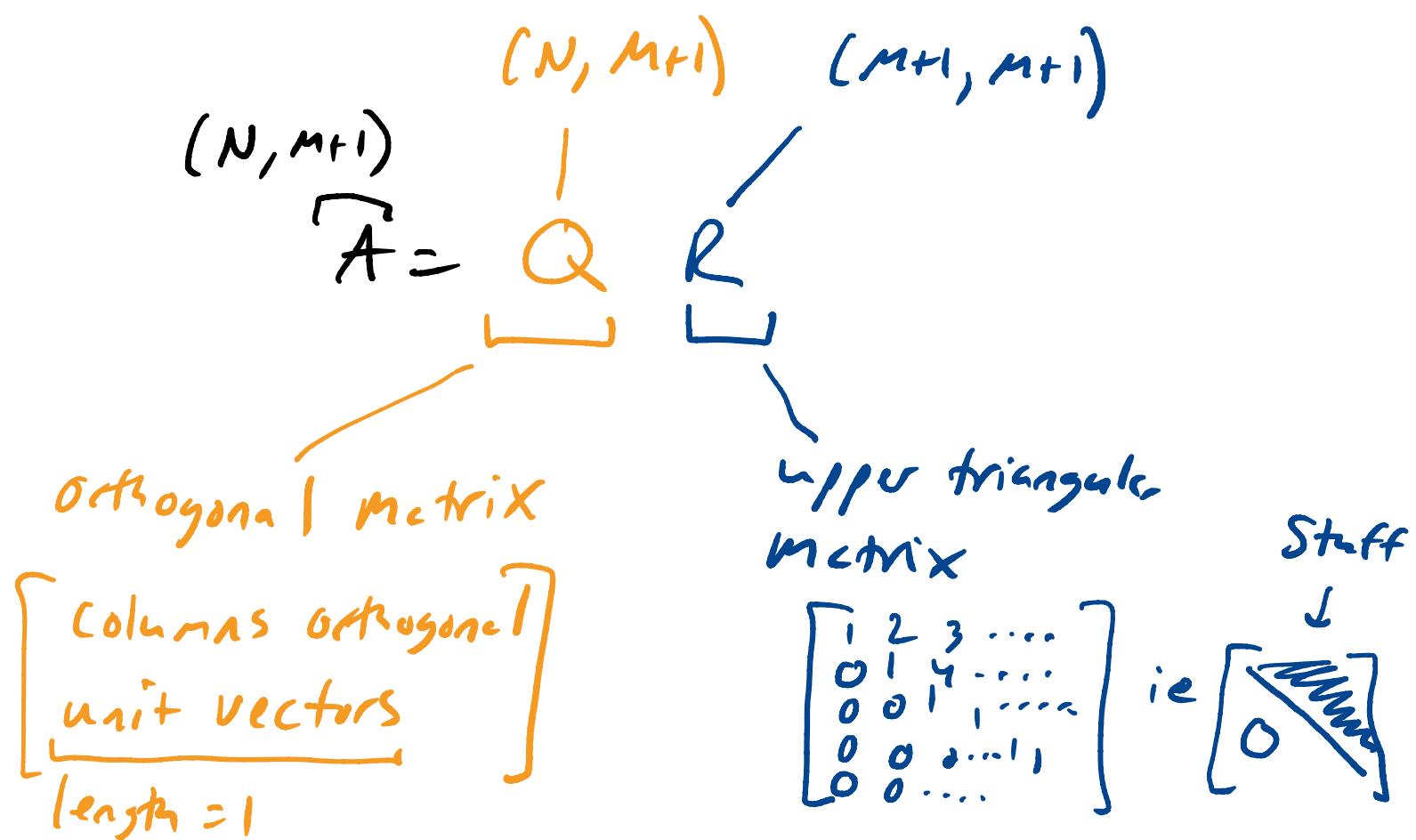
$$\begin{bmatrix} 2/3 & -2/3 \\ -2/3 & 0.687 \end{bmatrix}$$

Numbers changed 50% with small error!

- Factoring independent Variable Matrix A into $A = Q R$ can allow us to solve for \vec{c} without any matrix inversion !!

* Super numerically stable

[Not easily affected by numerical error]



Orthogonal Matrices have the property :

$$Q^T Q = I$$

$$Q^T = Q^{-1}$$

• How to get $Q + R$?

Q : Hard part. Get via Gram-Schmidt algorithm.

R : Easy. Once we have Q , get R via

$$A = QR$$

$$Q^{-1}A = Q^{-1}QR$$

$$Q^{-1}A = R$$

flip \swarrow but $Q^{-1} = Q^T$!

$$R = Q^{-1}A$$

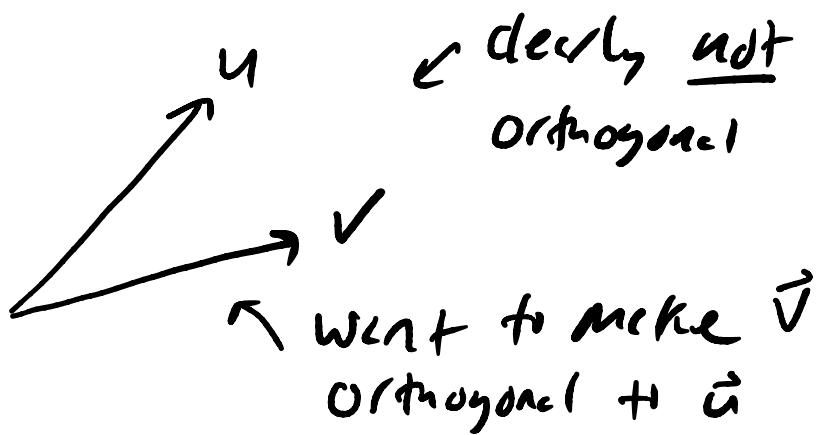
$$R = Q^T A$$

$(M+1, M+1)$ $(M+1, N)$ $(N, M+1)$

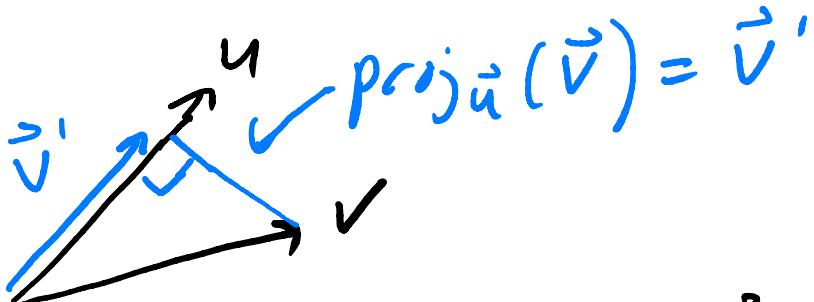
Gram - Schmidt algorithm (intuition) :

Idea: make column vectors orthogonal from one another by subtracting out "overlapping" components via projection:

2D example:

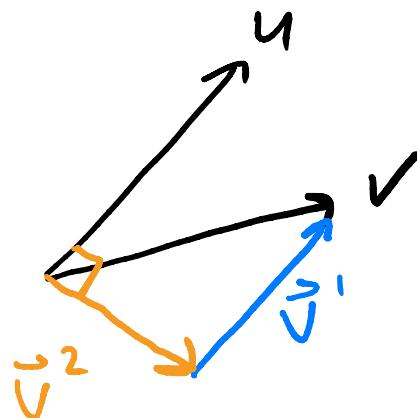


$\Rightarrow \text{proj}_{\vec{u}}(\vec{v}) = \text{project } \vec{v} \text{ onto } \vec{u}$



Then to make \vec{u}, \vec{v}' orthogonal:

$$\vec{v}^2 = \vec{v} - \underbrace{\text{proj}_{\vec{u}}(\vec{v})}_{\vec{v}'}$$



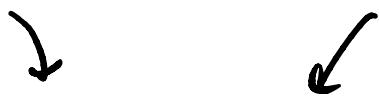
General Case: To make column vectors

$$[\vec{v}_1, \vec{v}_2, \vec{v}_3, \dots, \vec{v}_n]$$

$$\text{Orthogonal} - [\vec{u}_1, \vec{u}_2, \vec{u}_3, \dots, \vec{u}_n]$$

progressively subtract out projections
onto previous column vectors:

Orthogonal original vectors



$$u_1 = v_1$$

$$u_2 = v_2 - \text{proj}_{\vec{u}_1}(\vec{v}_2)$$

$$u_3 = v_3 - \text{proj}_{\vec{u}_1}(\vec{v}_3) - \text{proj}_{\vec{u}_2}(\vec{v}_3)$$

⋮

Gram-Schmidt algorithm (details):

- 1) Initialize Q to an $(N, M+1)$ matrix.
 - 2) Visit columns in A from left-to-right.
Call the index of current column i .

$$\begin{bmatrix} \vdots \\ \downarrow \\ \vdots & \vdots & \vdots & \cdots \end{bmatrix}$$

- 3) with a separate "pointer" j , revisit all columns to the left of i in Q. $j < i$

$$(Q: \begin{bmatrix} \vdots & \vdots & \vdots & \ddots \end{bmatrix})$$

$j=1 \quad j=2$
 $\downarrow \rightarrow \downarrow$

$$A := \begin{bmatrix} & & & \\ & \vdots & \vdots & \vdots \\ & \vdots & \vdots & \vdots \\ & & & \dots \end{bmatrix}$$

purpose of j : visit vectors already
Mutually orthogonal.

4) For all valid j , add to a copy of column i of A
the following:

- $\underbrace{\langle \vec{\text{col}}(i), \vec{\text{col}}(j) \rangle}_{\text{dot product}} \cdot \vec{\text{col}}(j)$

$\xrightarrow{\text{element-wise multiplication}}$

Vector

Dot product \rightarrow Scalar

result = $(N, 1)$ "subtract off Scaled version of vector j "

i.e. $\underbrace{\vec{\text{col}}(i)}_{\text{temp variable}} = \vec{\text{col}}(i) - \sum_{j=1}^{i-1} \langle \vec{\text{col}}(i), \vec{\text{col}}(j) \rangle \cdot \vec{\text{col}}(j)$

- Don't modify A

5) After subtracting off all columns j from the current i column, normalize $\vec{\text{col}}(i)$ by its length / norm :

$$\vec{\text{col}}(i) = \frac{\vec{\text{col}}(i)}{\|\vec{\text{col}}(i)\|_2} = \frac{\vec{\text{col}}(i)}{\sqrt{x_{i,1}^2 + x_{i,2}^2 + \dots}}$$

Components
of column
 i .