

Lecture 6 : Transformation Matrices

project 2 : 3 manipulations via matrix multiplication:

- move : translate data
- Stretch : Scale data
- Rotate data

Matrix transformation : Matrix Multiplication

involving a transformation matrix M

and data matrix A .

$$A' = M @ A$$

manipulated data

numpy matrix multiply operator

data matrix A

R always go on the right

transformation matrix always go on left

$$\cancel{\text{Shape}(\text{Output}) = \text{Shape}(\text{Input})}$$

A' A

Example: Temperature data

$$A = \begin{matrix} \text{ME} & \text{FL} & \text{DC} \\ \text{day 1} & 32 & 105 & 50 \\ \text{day 2} & 6 & 85 & 40 \end{matrix} \quad \begin{matrix} \text{append col of 1s.} \\ | \\ | \end{matrix}$$

shape: (N, M)

$$N = \# \text{ data samples} = 2 \quad : (2, 3)$$

$$M = \# \text{ Vars} = 3 \quad \Rightarrow \text{shape w/ col of 1s} \\ \Rightarrow (2, 4)$$

$$M = \begin{bmatrix} 1 & 0 & 0 & -32 \\ 0 & 1 & 0 & -80 \\ 0 & 0 & 1 & 10 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

want: $A' = \underbrace{M @ A}_{(4,4) \times (2,4)}$ // *mismatch!
Can't do!*

1) Check shapes :

work around : Try transposing, A :

$$A' = M @ A.T$$

$(4, 4) \times (4, 2)$

we're good!

$$A.T = \begin{bmatrix} 32 & 6 \\ 105 & 85 \\ 50 & 40 \\ 1 & 1 \end{bmatrix}$$

2) Figure Out output shape :

$$\text{Shape}(A') = (4, 4) \times (4, 2) = (4, 2)$$

3) Do the maths

$$\begin{array}{c}
 A' \\
 \left[\begin{array}{cc|cc}
 *1 & *2 & & \\
 *3 & *4 & & \\
 *5 & *6 & & \\
 *7 & *8 & & \\
 \end{array} \right] \\
 \underbrace{\quad\quad\quad}_{(4,2)}
 \end{array}
 =
 \begin{array}{c}
 M \\
 \left[\begin{array}{cccc}
 1 & 0 & 0 & -32 \\
 0 & 1 & 0 & -80 \\
 0 & 0 & 1 & 10 \\
 0 & 0 & 0 & 1 \\
 \end{array} \right] \\
 \underbrace{\quad\quad\quad}_{(4,4)}
 \end{array}
 =
 \begin{array}{c}
 A.T \\
 \left[\begin{array}{cc}
 32 & 6 \\
 105 & 85 \\
 50 & 40 \\
 1 & 1 \\
 \end{array} \right] \\
 \underbrace{\quad\quad\quad}_{(4,2)}
 \end{array}$$

$$x_1 = 1 \cdot 32 + 0 \cdot 105 + 0 \cdot 50 + -32 \cdot 1 \\ = 32 - 32 = 0$$

$$*2 = 1.6 + \cancel{0.85} + \cancel{0.40} + -32 - 1 \\ = 6 - 32 = \boxed{-26}$$

$$x_3 = \cancel{0.32} + 1 \cdot 105 + \cancel{0.50} + -80 \cdot 1 \\ = 105 - 80 = \textcircled{25}$$

$$\begin{aligned} *y &= 0.6 + 1 \cdot 85 + 0.40 + -80 \cdot 1 \\ &= 85 - 80 = 5 \end{aligned}$$

$$*S = 1 \cdot 50 + 10 \cdot 1 = 60$$

$$*G = 1 \cdot 40 + 10 \cdot 1 = 50$$

$$*T = 1$$

$$*F = 1 \xrightarrow{\text{need to transpose}} (2, 4)$$

Shape: $(4, 2) \Rightarrow (2, 4)$

wanted: Shape: $(2, 4)$

$$A' = \begin{bmatrix} 0 & -26 \\ 2S & 5 \\ 60 & 50 \\ 1 & 1 \end{bmatrix}$$

$$A'^T = \begin{bmatrix} 0 & 25 & \boxed{60} & 1 \\ -26 & 5 & \boxed{50} & 1 \end{bmatrix}$$

Answer

Compare w/ original A:

$$A = \begin{array}{l} \text{day 1} \\ \text{day 2} \end{array} \begin{bmatrix} ME & FL & DC & I \\ 32 & 105 & 50 & 1 \\ 6 & 85 & 40 & 1 \end{bmatrix}$$

ME col: How does output values (A'^T) compare to those in A? Values are 32 less than original

FL col: Values are 80 less than before

DC col: Values are 10 more than before

$$\overbrace{\begin{bmatrix} 1 & 0 & 0 & -32 \\ 0 & 1 & 0 & -80 \\ 0 & 0 & 1 & 10 \\ 0 & 0 & 0 & 1 \end{bmatrix}}^M \quad \begin{array}{l} \text{shift in 1st Variable (ME)} \\ \text{shift in 2nd Var (FL)} \\ \text{shift in 3rd Var (DL)} \end{array}$$

Translation matrix \overline{T}

$$T = T_3(t_x, t_y, t_z) = \begin{bmatrix} 1 & 0 & 0 & f_x \\ 0 & 1 & 0 & f_y \\ 0 & 0 & 1 & f_z \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \begin{array}{l} \text{shifts in each Var} \\ \text{For 3 vars} \end{array}$$

$$f_x = -32$$

$$f_y = -80$$

$$f_z = 10$$

What if we wanted to translate X variable by +6
and leave the rest alone?

$$t_x = 6 \quad t_y = 0 \quad t_z = 0$$

Translation Summary

To translate 3 variables $\vec{f} = (t_x, t_y, t_z)$:

$$A' = (T @ A \cdot T) \cdot T$$

Implementation tip: $T = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$ identity ↗

$$= np.eye(4)$$

$T = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

$T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ ↗ $\vec{f} = \begin{bmatrix} f_x \\ f_y \\ f_z \\ 1 \end{bmatrix}$] translation amounts ↗ 1 appended

col of ones = homogeneous coordinate