

Sakurai 3.1

Sakurai 3.1

$$\exp\left(-\frac{i S_z \phi}{\hbar}\right) S_x \exp\left(\frac{i S_z \phi}{\hbar}\right)$$

$$S_x = \frac{\hbar}{2} (|+\rangle\langle -| + |-\rangle\langle +|)$$

$$\exp\left(-\frac{i\phi}{2}\right) S_x = \frac{\hbar}{2} e^{-i\phi/2} |+\rangle\langle +| (|+\rangle\langle -| + |-\rangle\langle +|)$$

$$+ \frac{\hbar}{2} e^{+i\phi/2} |-\rangle\langle -| (|+\rangle\langle -| + |-\rangle\langle +|)$$

$$= \frac{\hbar}{2} \left(e^{-i\phi/2} (|+\rangle\langle -|) + e^{+i\phi/2} |-\rangle\langle +| \right)$$

$$\sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{-i\phi}{2}\right)^n \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}^n = \sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{-i\phi}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}\right)^n = \begin{pmatrix} e^{-i\phi/2} & 0 \\ 0 & e^{+i\phi/2} \end{pmatrix}$$

$$\exp\left(\frac{-i\phi}{2}\right) S_x \exp\left(\frac{i\phi}{2}\right) = \frac{\hbar}{2} \left(e^{-i\phi/2} |+\rangle\langle -| + e^{+i\phi/2} |-\rangle\langle +| \right)$$

$$\left(e^{+i\phi/2} |+\rangle\langle +| + e^{-i\phi/2} |-\rangle\langle -| \right) = \frac{\hbar}{2} \left(e^{-i\phi} |+\rangle\langle -| + e^{+i\phi} |-\rangle\langle +| \right)$$

Sakurai 3.4

$$A = -a_0 \hat{I} + (a_1 \sigma_1 + a_2 \sigma_2 + a_3 \sigma_3)$$

$$A = \begin{pmatrix} a_0 + ia_3 & ia_1 + a_2 \\ ia_1 - a_2 & a_0 - ia_3 \end{pmatrix} \quad A^\dagger = \begin{pmatrix} a_0 - ia_3 & -ia_1 - a_2 \\ -ia_1 + a_2 & a_0 + ia_3 \end{pmatrix}$$

$$U = A(A^\dagger)^{-1} \quad \text{using Mathematica,} \quad \det(A) = a_0^2 + a_1^2 + a_2^2 + a_3^2 = \alpha^2$$

$$\det(A^\dagger) = a_0^2 + a_1^2 + a_2^2 + a_3^2 = \alpha^2$$

$$\det U = \det(A(A^\dagger)^{-1}) = \det(A) \det((A^\dagger)^{-1}) = \frac{\det(A)}{\det(A^\dagger)} = 1$$

$$\cos\left(\frac{\phi}{2}\right) = \text{Re}(a) = \frac{a_0 - |\vec{a}|^2}{\alpha^2} \quad \sin\left(\frac{\phi}{2}\right) = \sqrt{1 - \cos^2(\phi/2)} = \frac{2a|\vec{a}|}{\alpha^2}$$

$$U = \frac{1}{\alpha^2} \begin{pmatrix} a_0 - |\vec{a}|^2 + 2ia_0a_3 & 2a_0a_2 + 2ia_0a_1 \\ -2a_0a_2 + 2ia_0a_1 & a_0 - \alpha^2 - 2ia_0a_3 \end{pmatrix}$$

From general rotation matrix

$$\exp\left(\frac{-i\vec{\sigma} \cdot \hat{n} \phi}{2}\right) = \begin{pmatrix} \cos(\frac{\phi}{2}) - in_z \sin(\frac{\phi}{2}) & (-in_x - in_y) \sin(\frac{\phi}{2}) \\ (-in_x + in_y) \sin(\frac{\phi}{2}) & \cos(\frac{\phi}{2}) + in_z \sin(\frac{\phi}{2}) \end{pmatrix}$$

$$\frac{a_0 - |\vec{a}|^2}{\alpha^2} = \cos\left(\frac{\phi}{2}\right)$$

$$-n_x \sin\left(\frac{\phi}{2}\right) = 2a_0a_1$$

$$-2a_0a_2 = n_y \sin\left(\frac{\phi}{2}\right)$$

$$2a_0a_3 = n_z \sin\left(\frac{\phi}{2}\right)$$

Sakurai 3.10

$$\exp\left(\frac{-i\hat{\sigma} \cdot \hat{n}\phi}{2}\right) = \begin{pmatrix} \cos\left(\frac{\phi}{2}\right) - i n_z \sin\left(\frac{\phi}{2}\right) & (-i n_x - n_y) \sin\left(\frac{\phi}{2}\right) \\ (-i n_x + n_y) \sin\left(\frac{\phi}{2}\right) & \cos\left(\frac{\phi}{2}\right) + i n_z \sin\left(\frac{\phi}{2}\right) \end{pmatrix}$$

$$= \begin{pmatrix} e^{-i(\alpha+\gamma)/2} \cos\left(\frac{\beta}{2}\right) & -e^{-i(\alpha-\gamma)/2} \sin\left(\frac{\beta}{2}\right) \\ e^{i(\alpha-\gamma)/2} \sin\left(\frac{\beta}{2}\right) & e^{i(\alpha+\gamma)/2} \cos\left(\frac{\beta}{2}\right) \end{pmatrix}$$

$$\cos\left(\frac{\phi}{2}\right) - i n_z \sin\left(\frac{\phi}{2}\right) = e^{-i(\alpha+\gamma)/2} \cos\left(\frac{\beta}{2}\right)$$

$$2\cos\left(\frac{\phi}{2}\right) = 2\sin\left(\frac{\alpha+\gamma}{2}\right) \cos\left(\frac{\beta}{2}\right)$$

$$\frac{\phi}{2} = \arccos\left(\sin\left(\frac{\alpha+\gamma}{2}\right) \cos\left(\frac{\beta}{2}\right)\right)$$

$$\phi = 2\arccos\left(\sin\left(\frac{\alpha+\gamma}{2}\right) \cos\left(\frac{\beta}{2}\right)\right)$$

Sakurai 3.20

$$J_- = \hbar\sqrt{2} \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$J_+ = \hbar\sqrt{2} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$J_x = \frac{J_+ + J_-}{2} = \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \rightarrow \lambda = -\hbar, 0, \hbar$$

$$J_y = \frac{J_+ - J_-}{2i} = \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix}$$

$$J_z = \hbar \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$$J_x = \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\lambda_1 = -\hbar : |\lambda_1\rangle = \frac{1}{4} \begin{pmatrix} 1 \\ -\sqrt{2} \\ 1 \end{pmatrix} = \frac{1}{4} (|1+\rangle - \sqrt{2}|0\rangle + |1-\rangle)$$

$$\lambda_2 = 0 : |\lambda_2\rangle = \frac{1}{\sqrt{2}} (|1+\rangle - |1-\rangle)$$

$$\lambda_3 = +\hbar : |\lambda_3\rangle = \frac{1}{4} \begin{pmatrix} 1 \\ \sqrt{2} \\ 1 \end{pmatrix} = \frac{1}{4} (|1+\rangle + \sqrt{2}|0\rangle + |1-\rangle)$$

$$J_y = \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix}$$

$$\lambda_1 = -\hbar \quad |\lambda_1\rangle = \frac{1}{4} (-|1+\rangle + i\sqrt{2}|0\rangle + |1-\rangle)$$

$$\lambda_2 = 0 \quad |\lambda_2\rangle = \frac{1}{\sqrt{2}} (|1+\rangle + |1-\rangle)$$

$$\lambda_3 = +\hbar \quad |\lambda_3\rangle = \frac{1}{4} (-|1-\rangle - i\sqrt{2}|0\rangle + |1+\rangle)$$

Sakurai 3.23

$$\psi(\vec{x}) = (x + y + 3z) f(r)$$

$$\hat{L}^2 = -\hbar^2 \left(\frac{1}{\sin\theta} \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial}{\partial\theta} \right) + \frac{1}{\sin^2\theta} \frac{\partial^2}{\partial\phi^2} \right)$$

$$\textcircled{a} \quad \hat{L}^2 \psi = -\hbar^2 f(r) r \left((-6\sin\theta \cos\theta + (\cos\phi + \sin\phi)(\cos^2\theta - \sin^2\theta) - \frac{\cos\phi + \sin\phi}{\sin\theta} \right)$$

$$= 2\hbar^2 f(r) r (\sin\theta \cos\phi + \sin\theta \sin\phi + 3\cos\theta)$$

$$= 2\hbar^2 \psi(\vec{x}) = l(l+1) \hbar^2 \psi(\vec{x}) \rightarrow l=1$$

$$\textcircled{b} \quad \langle x | \hat{L}_z | \psi \rangle = \hat{L}_z \psi(\vec{x})$$

$$\gamma_{\pm 1}^{\pm} = \sqrt{\frac{3}{8\pi}} \frac{(x \pm iy)}{r} \quad \gamma_1^{+1} + \gamma_1^{-1} = \sqrt{\frac{3}{8\pi}} \frac{1}{r} (x + iy + x - iy)$$

$$\gamma_1^0 = \sqrt{\frac{3}{4\pi}} \cos\theta = \sqrt{\frac{3}{4\pi}} x$$

$$x = \sqrt{\frac{2\pi}{3}} r (\gamma_1^{-1} - \gamma_1^{+1})$$

$$\gamma_1^0 = \sqrt{\frac{3}{4\pi}} \frac{z}{r} \quad -i(\gamma_1^{-1} - \gamma_1^{+1}) = \sqrt{\frac{3}{8\pi}} \frac{1}{r} (2y)$$

$$z = \sqrt{\frac{4\pi}{3}} r \gamma_1^0 \quad y = i \sqrt{\frac{2\pi}{3}} r (\gamma_1^{-1} + \gamma_1^{+1})$$

$$\psi(\vec{x}) = \sqrt{\frac{2\pi}{3}} r f(r) (3\sqrt{2} \gamma_1^0 + (1+i) \gamma_1^{-1} + (1-i) \gamma_1^{+1})$$

$$|A|^2 (18 + 2 + 2) = 1 \rightarrow N = \frac{1}{\sqrt{22}}$$

$$\psi(\vec{x}) = \sqrt{\frac{\pi}{33}} r f(r) (3\sqrt{2} \gamma_1^0 + (1+i) \gamma_1^{-1} + (1-i) \gamma_1^{+1})$$

$$P(m=0) = \frac{9}{11}$$

$$P(m=1) = \frac{1}{11}$$

$$P(m=-1) = \frac{1}{11}$$

Sakurai 3.23

$$\begin{aligned} \textcircled{c} \quad & -\frac{\hbar^2}{2m} \left(\frac{\partial^2}{\partial r^2} (r f(r)) + \frac{2}{r} \frac{\partial}{\partial r} (r f(r)) - \frac{2}{r^2} (r f(r)) \right) + V(r) r f(r) Y_\ell^m \\ & = E r f(r) Y_\ell^m \end{aligned}$$

$$V(r) = \frac{\hbar^2}{2m} \left(\frac{r f''(r) + 4 f'(r)}{r f(r)} \right)$$

Sakurai 3.24

$$\hat{J}_x |j, m\rangle = \frac{1}{2} (J_+ + J_-) |j, m\rangle = \frac{\hbar}{2} \sqrt{(j-m)(j+m+1)} |j, m+1\rangle + \frac{\hbar}{2} \sqrt{(j+m)(j-m+1)} |j, m-1\rangle$$

$$J_y |j, m\rangle = \frac{1}{2i} (J_+ - J_-) |j, m\rangle = \frac{\hbar}{2i} [\dots |j, m+1\rangle - \dots |j, m-1\rangle]$$

$$\begin{aligned} \rightarrow \langle l, m | \hat{L}_x | l, m \rangle &= \frac{1}{2} \langle l, m | (\hat{L}_+ + \hat{L}_-) | l, m \rangle \\ &= \frac{1}{2} \left[\langle l, m | \frac{\hbar}{2} \dots | l, m+1 \rangle + \langle l, m | \frac{\hbar}{2} \dots | l, m-1 \rangle \right] \\ &= 0 \end{aligned}$$

$$\begin{aligned} \rightarrow \langle l, m | \hat{L}_y | l, m \rangle &= \frac{1}{2i} \langle l, m | (\hat{L}_+ - \hat{L}_-) | l, m \rangle \\ &= \frac{1}{2i} \left[\langle l, m | \frac{\hbar}{2} \dots | l, m+1 \rangle - \langle l, m | \frac{\hbar}{2} \dots | l, m-1 \rangle \right] \\ &= 0 \end{aligned}$$

$$\begin{aligned} \langle L_x^2 \rangle &= \left\langle \frac{1}{4} (\hat{L}_+ + \hat{L}_-) (\hat{L}_+ + \hat{L}_-) \right\rangle = \frac{1}{4} (\langle \hat{L}_+^2 \rangle + \langle \hat{L}_+ \hat{L}_- \rangle + \langle \hat{L}_- \hat{L}_+ \rangle + \langle \hat{L}_-^2 \rangle) \\ &= \frac{1}{4} (\langle \hat{L}_+ \hat{L}_- \rangle + \langle \hat{L}_- \hat{L}_+ \rangle) \end{aligned}$$

$$\begin{aligned} \langle L_y^2 \rangle &= \left\langle -\frac{1}{4} (\hat{L}_+ - \hat{L}_-) (\hat{L}_+ - \hat{L}_-) \right\rangle \\ &= -\frac{1}{4} (\langle \hat{L}_+^2 \rangle - \langle \hat{L}_+ \hat{L}_- \rangle - \langle \hat{L}_- \hat{L}_+ \rangle + \langle \hat{L}_-^2 \rangle) \\ &= \frac{1}{4} (\langle \hat{L}_+ \hat{L}_- \rangle + \langle \hat{L}_- \hat{L}_+ \rangle) = \langle L_x^2 \rangle = \end{aligned}$$

$$J_{\pm} J_{\mp} = J^2 - J_z^2 \pm \hbar J_z$$

$$\begin{aligned} \rightarrow \frac{1}{4} (\hat{L}_+ \hat{L}_- + \hat{L}_- \hat{L}_+) &= \frac{1}{4} (J^2 - J_z^2 + \hbar J_z + J^2 - J_z^2 - \hbar J_z) \\ &= (J^2 - J_z^2) / 2 = [l(l+1) - m^2] \hbar^2 / 2 \end{aligned}$$

Sakurai 3.24

$$\langle L_x^2 \rangle = \langle L_y^2 \rangle = \frac{1}{2} [l(l+1) - m^2] \hbar^2$$

Sakurai 3.33

$$(3.335) \quad m = m_1 + m_2$$

$$(3.339) \quad S^2 = S_1^2 + S_2^2 + 2S_{1z}S_{2z} + S_{1+}S_{2-} + S_{1-}S_{2+}$$

$$|++\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad |+-\rangle = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \quad |-+\rangle = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$|--\rangle = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$$S^2|++\rangle = (S_1^2 + S_2^2 + 2S_{1z}S_{2z})|++\rangle$$

$$\left(\frac{1}{2}(\frac{1}{2}+1)\hbar^2 + \frac{1}{2}(\frac{1}{2}+1)\hbar^2 + 2\frac{1}{2}\hbar \cdot \frac{1}{2}\hbar\right)|++\rangle$$

$$= \left(\frac{3}{4} + \frac{3}{4} + \frac{1}{2}\right)\hbar^2|++\rangle = 2\hbar^2|++\rangle$$

$$= \lambda(\lambda+1)\hbar^2|1,1\rangle$$

$$S_{1+}|--\rangle = S_{1+} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} = |+-\rangle = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

$$S_{1+}|-+\rangle = S_{1+} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$S_{1+} = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$S_{2+}|+-\rangle = \sqrt{\left(\frac{1}{2} + \frac{1}{2}\right)}|++\rangle$$

$$S_{2+} \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \quad S_{2+} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$S_{2+}|--\rangle = |-+\rangle$$

$$S_{1z} |+- \rangle = |-- \rangle \rightarrow \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$S_{1z} |++ \rangle = |-+ \rangle \rightarrow \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$$

$$S_{2z} |++ \rangle = |+- \rangle \rightarrow \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$S_{2z} |-+ \rangle = |-- \rangle \rightarrow \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \rightarrow \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$S_{2z} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

$$S_{1z} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = +\frac{1}{2} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$S_{1z} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = -\frac{1}{2} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$S_{1z} = \begin{pmatrix} \frac{1}{2} & & \\ & +\frac{1}{2} & \\ & & -\frac{1}{2} & \\ & & & -\frac{1}{2} \end{pmatrix}$$

$$S_{1z} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = +\frac{1}{2} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$S_{2z} = \begin{pmatrix} \frac{1}{2} & & \\ & -\frac{1}{2} & \\ & & \frac{1}{2} & \\ & & & -\frac{1}{2} \end{pmatrix}$$

$$S_{1z} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = -\frac{1}{2} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$S^2 = \frac{1}{2}(S_+ S_- + S_- S_+) + S_z^2$$

$$\rightarrow S_1^2 = S_2^2 = \frac{3}{4} \hbar^2 \hat{I} \quad (\text{take } \hbar=1)$$

$$S_1^2 + S_2^2 + 2S_{z1} S_{z2} + S_{1+} S_{2-} + S_{1-} S_{2+}$$

$$= \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix}$$

$$\lambda = 1, 2$$

$$\lambda = 2 \rightarrow \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \quad \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\lambda = 1 \rightarrow \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Sakurai 3.34

$$J_{\pm} |j, m\rangle = \sqrt{(j \mp m)(j \pm m + 1)} |j, m \pm 1\rangle$$

find 9 states from $j=0, 1, 2$ in $|j, m\rangle$ formed by adding $j_1=1, j_2=1$

$$|0, 0\rangle = |+-\rangle \quad |0, 0\rangle \quad |-+\rangle$$

$$|1, 0\rangle = |+-\rangle \quad |-+\rangle$$

$$|1, -1\rangle = |0-\rangle \quad |-0\rangle$$

$$|1, +1\rangle = |0+\rangle \quad |+0\rangle$$

$$|2, -2\rangle = |--\rangle$$

$$|2, -1\rangle =$$

$$|2, 0\rangle =$$

$$|2, +1\rangle$$

$$|2, +2\rangle$$

$$\langle j_1, j_2, m_1, m_2 | J_{\pm} | j, m \rangle$$

$$= \hbar \sqrt{(j_1 \pm m_1)(j_1 \mp m_1 + 1)} \langle j_1, j_2, m_1 \pm 1, m_2 | j, m \rangle$$

$$+ \hbar \sqrt{(j_2 \pm m_2)(j_2 \mp m_2 + 1)} \langle j_1, j_2, m_1, m_2 \pm 1 | j, m \rangle$$

$$J_+ |2, -2\rangle = \hbar \sqrt{(2 - (-2))(2 - 2 + 1)} |2, -1\rangle = 2\hbar |2, -1\rangle$$

$$(J_{1+} + J_{2+}) |2, -2\rangle = (J_{1+} + J_{2+}) |--\rangle = J_{1+} |--\rangle + J_{2+} |--\rangle$$

$$= \hbar \sqrt{(1 - (-1))(1 - 1 + 1)} (|+-\rangle + |-+\rangle)$$

$$= \hbar \sqrt{2} (|0-\rangle + |-0\rangle) \rightarrow |2, -1\rangle = \frac{1}{\sqrt{2}} (|0-\rangle + |-0\rangle)$$

Sakurai 3.34

$$J_+ |2, -1\rangle = \hbar \sqrt{(2-(-1))(2+(-1)+1)} |2, 0\rangle = \hbar \sqrt{6} |2, 0\rangle$$

$$= \frac{\hbar}{\sqrt{2}} [J_{1+} |0-\rangle + J_{1+} |1-0\rangle + J_{2+} |0-\rangle + J_{2+} |1-0\rangle]$$

$$= \frac{\hbar}{\sqrt{2}} (\sqrt{(1-0)(1+0+1)} |1-\rangle + \sqrt{(2)(1)} |00\rangle + \sqrt{2} |00\rangle + \sqrt{2} |1-\rangle)$$

$$= |1-\rangle + 2 |00\rangle + |1-\rangle$$

$$\rightarrow |2, 0\rangle = \frac{1}{\sqrt{6}} |1-\rangle + \sqrt{\frac{2}{3}} |00\rangle + \frac{1}{\sqrt{6}} |1-\rangle$$

$$\hbar \sqrt{(2-0)(2+0+1)} |2, 1\rangle = \hbar \sqrt{6} |2, 1\rangle$$

$$J_+ |2, 1\rangle = \frac{1}{\sqrt{6}} J_{2+} |1-\rangle + \sqrt{\frac{2}{3}} (J_{1+} + J_{2+}) |00\rangle + \frac{1}{\sqrt{6}} J_{1+} |1-\rangle$$

$$\frac{1}{\sqrt{6}} \sqrt{(1-(-1))(1+(-1)+1)} |10\rangle + \sqrt{\frac{2}{3}} (\sqrt{2} |10\rangle + \sqrt{2} |01\rangle) + \frac{1}{\sqrt{3}} |01\rangle$$

$$= \frac{1}{\sqrt{3}} |10\rangle + \sqrt{\frac{4}{3}} |10\rangle + \sqrt{\frac{4}{3}} |01\rangle + \frac{1}{\sqrt{3}} |01\rangle$$

$$= \hbar \frac{3}{\sqrt{3}} (|10\rangle + |01\rangle) \quad |2, 1\rangle = \frac{3}{\sqrt{2}} (|10\rangle + |01\rangle) = \frac{1}{\sqrt{2}} (|10\rangle + |01\rangle)$$

$$\hbar \sqrt{(2-1)(2+1+1)} |2, 2\rangle = 2\hbar |2, 2\rangle = \frac{\hbar}{\sqrt{2}} (\sqrt{(1-0)(2)} (|1+\rangle + |1+\rangle))$$

$$2\hbar |2, 2\rangle = 2\hbar |1+\rangle$$

$$|2, 2\rangle = |1+\rangle$$

In summary, for the $J=2$ states:

$$|2, 2\rangle = |1+\rangle$$

$$|2, 1\rangle = \frac{1}{\sqrt{2}} (|10\rangle + |01\rangle)$$

$$|2, 0\rangle = \frac{1}{\sqrt{6}} |1-\rangle + \sqrt{\frac{2}{3}} |00\rangle + \frac{1}{\sqrt{6}} |1-\rangle$$

$$|2, -1\rangle = \frac{1}{\sqrt{2}} (|10-\rangle + |1-0\rangle)$$

$$|2, -2\rangle = |1--\rangle$$

Sakurai 3.34

$|2, 1\rangle$ to derive $|1, 1\rangle = a|10\rangle + b|01\rangle$

$$\langle 2, 1 | 1, 1 \rangle = \frac{a+b}{\sqrt{2}} = 0 \quad aa^* + bb^* = 1$$

$$a = -b \rightarrow a = \frac{1}{\sqrt{2}} \quad b = -\frac{1}{\sqrt{2}}$$

$$\therefore |1, 1\rangle = \frac{1}{\sqrt{2}}(|10\rangle - |01\rangle)$$

$$\begin{aligned} J_- |1, 1\rangle &= \sqrt{(1+1)(1-1+1)} |1, 0\rangle \\ &= \frac{1}{\sqrt{2}} (J_{1-} |10\rangle + J_{2-} |10\rangle - J_{1-} |01\rangle - J_{2-} |01\rangle) \end{aligned}$$

$$\sqrt{2} |1, 0\rangle = \frac{1}{\sqrt{2}} (\sqrt{2} |10\rangle + \sqrt{2} |1-0\rangle - \sqrt{2} |1-0\rangle - \sqrt{2} |00\rangle)$$

$$|1, 0\rangle = \frac{1}{\sqrt{2}} (|1-0\rangle - |00\rangle)$$

$$J_- |1, 0\rangle = \sqrt{2} |1, -1\rangle = \frac{1}{\sqrt{2}} (J_{1-} |1-0\rangle + J_{2-} |1-0\rangle - J_{1-} |00\rangle - J_{2-} |00\rangle)$$

$$\sqrt{2} |1, -1\rangle = \frac{1}{\sqrt{2}} (\sqrt{2} |10\rangle - \sqrt{2} |1-0\rangle)$$

$$|1, -1\rangle = \frac{1}{\sqrt{2}} (|10\rangle - |1-0\rangle)$$

$$\langle 2, 0 | 0, 0 \rangle = \langle 1, 0 | 0, 0 \rangle = 0$$

$$|2, 0\rangle = \frac{1}{\sqrt{6}} |+-\rangle + \sqrt{\frac{2}{3}} |00\rangle + \frac{1}{\sqrt{6}} |-+\rangle$$

$$|1, 0\rangle = \frac{1}{\sqrt{2}} (|+-\rangle - |-+\rangle)$$

$$|0, 0\rangle = a |+-\rangle + b |00\rangle + c |--\rangle$$

$$\langle 2, 0 | 0, 0 \rangle = \frac{a}{\sqrt{6}} + \sqrt{\frac{2}{3}} b + \frac{c}{\sqrt{6}} = 0$$

$$\langle 1, 0 | 0, 0 \rangle = \frac{1}{\sqrt{2}} (a - c) = 0 \rightarrow a = c$$

$$\frac{2}{\sqrt{6}} a + \sqrt{\frac{2}{3}} b = 0 \rightarrow a = \frac{\sqrt{6}}{2} \cdot -\sqrt{\frac{2}{3}} b = -b$$

$$a^2 + b^2 + c^2 = 1 \rightarrow 2a^2 + b^2 = 1 \rightarrow 2a^2 + a^2 = 1 \quad a = \sqrt{\frac{1}{3}}$$

$$b = -\sqrt{\frac{1}{3}}$$

$$c = +\sqrt{\frac{1}{3}}$$

$$\rightarrow |0, 0\rangle = \frac{1}{\sqrt{3}} (|+-\rangle - |00\rangle + |-+\rangle)$$

$$|2, 2\rangle = |++\rangle$$

$$|2, 1\rangle = \frac{1}{\sqrt{2}} (|+0\rangle + |0+\rangle)$$

$$|2, 0\rangle = \frac{1}{\sqrt{6}} |+-\rangle + \sqrt{\frac{2}{3}} |00\rangle + \frac{1}{\sqrt{6}} |-+\rangle$$

$$|2, -1\rangle = \frac{1}{\sqrt{2}} (|0-\rangle + |-0\rangle)$$

$$|2, -2\rangle = |--\rangle$$

$$|0, 0\rangle = \frac{1}{\sqrt{3}} (|+-\rangle - |00\rangle + |-+\rangle)$$

$$|1, 1\rangle = \frac{1}{\sqrt{2}} (|+0\rangle - |0+\rangle)$$

$$|1, 0\rangle = \frac{1}{\sqrt{2}} (|+-\rangle - |-+\rangle)$$

$$|1, -1\rangle = \frac{1}{\sqrt{2}} (|0-\rangle - |-0\rangle)$$