

## Matt Kinsinger, MAT 372 Final

[1] For any set  $E \subseteq \mathbb{R}^2$  define the projection operator  $P : E \rightarrow \mathbb{R}$  by  $P(x, y) = x$ .

(a) Suppose that  $E$  is bounded. Then for all  $u \in E$ , there exists  $M \geq 0$  such that  $\|u\| \leq M$ . Let  $u = (u_1, u_2) \in E$ . Then,

$$|P(u)| = |P(u_1, u_2)| = |u_1| \leq \|u\| \leq M.$$

Thus,  $P(E)$  is bounded. □

(b) Let  $E = \{(x, \frac{1}{x}) : x > 0\} \subseteq \mathbb{R}^2$ , which is closed because any  $u \in \mathbb{R}^2 \cap E^c$  can be enclosed in an open ball  $B(u) \subseteq E^c$ , i.e.  $E^c$  is open. But,  $P(E) = \{x : x > 0\}$  is open. □

(c) Suppose the  $E$  is compact. Let  $\bigcup_{\alpha=1}^{\infty} G_{\alpha}$  be a union of open sets such that  $P(E) \subseteq \bigcup_{\alpha=1}^{\infty} G_{\alpha}$ . It follows that

$$E \subseteq P(E) \times \left( \bigcup_{k \in \mathbb{N}} (-k, k) \right) \subseteq \left( \bigcup_{\alpha=1}^{\infty} G_{\alpha} \right) \times \left( \bigcup_{k \in \mathbb{N}} (-k, k) \right)$$

Since  $E$  is compact, there exists numbers  $N, M$  such that

$$E \subseteq \left( \bigcup_{\alpha=1}^N G_{\alpha} \right) \times \left( \bigcup_{k=1}^M (-k, k) \right)$$

Thus,  $P(E) \subseteq \bigcup_{\alpha=1}^N G_{\alpha}$ . So  $P(E)$  is compact. □

More succinctly (but less fun) you could use continuity of  $P$  and preservation of compact sets by continuous functions. □

[2] Let  $B : \mathbb{R}^p \times \mathbb{R}^p \rightarrow \mathbb{R}^q$  be a bounded bilinear function. Set  $g(x) = B(x, x)$ . For  $x, u \in \mathbb{R}^p$ , prove:

- (i)  $Dg(x)(u) = B(x, u) + B(u, x) = Dg(u)(x)$
- (ii)  $g(x + u) = g(x) + g(u) + Dg(x)(u)$ .

Since  $B$  is a bounded bilinear function, there exists  $M > 0$  such that  $\|B(x, y)\| \leq M\|x\|\|y\|$  for all  $x, y \in \mathbb{R}^p$ .

Let  $x, u \in \mathbb{R}^p$ .

(i) To check that  $F_x(u) = B(x, u) + B(u, x)$  is linear in  $u$ , let  $u = cv + z$  for scalar  $c$  and  $v, z \in \mathbb{R}^p$ .

$$\begin{aligned}
F_x(cv + z) &= B(x, cv + z) + B(cv + z, x) \\
&= cB(x, v) + B(x, z) + cB(v, x) + B(z, x) \\
&= c[B(x, v) + B(v, x)] + B(x, z) + B(z, x) \\
&= cF_x(v) + F_x(z).
\end{aligned}$$

Thus  $F_x$  is linear in  $u$ .

Let  $\epsilon > 0$ . Choose  $t \in \mathbb{R}$  such that  $\|tu\| < \frac{\epsilon}{M}$ . Note that

$$\begin{aligned}
g(x + tu) &= B(x + tu, x + tu) \\
&= B(x, x + tu) + tB(u, x + tu) \\
&= B(x, x) + tB(x, u) + tB(u, x) + t^2B(u, u)
\end{aligned} \tag{1}$$

It follows that

$$\begin{aligned}
\|g(x + tu) - g(x) - F_x(tu)\| &= \|g(x + tu) - g(x) - [B(x, tu) + B(tu, x)]\| \\
&= \|g(x + tu) - g(x) - [tB(x, u) + tB(u, x)]\| \\
&= \|B(x, x) + t^2B(u, u) - g(x)\| \\
&= \|t^2B(u, u)\| \\
&\leq t^2M\|u\|^2 \\
&= M\|tu\|\|tu\| \\
&< \epsilon\|tu\|.
\end{aligned}$$

Thus,  $Dg(x)(u) = F_x(u) = B(x, u) + B(u, x)$ . Using symmetry, this same argument shows that  $Dg(u)(x) = B(x, u) + B(u, x)$  as well.  $\square$

[4] Suppose that  $w \in C^2(\Omega) \cap C(\overline{\Omega})$  is a solution to the given partial differential equation. Since  $\Omega \subseteq \mathbb{R}^3$  is bounded,  $\overline{\Omega}$  is both closed and bounded in  $\mathbb{R}^3$ , hence  $\overline{\Omega}$  is compact.  $w$  is continuous on a compact set, thus  $w$  attains a maximum and a minimum on  $\overline{\Omega}$ .

- Case 1: Suppose that both the max and min of  $w$  on  $\overline{\Omega}$  occur on  $\partial\Omega$ . Then

$$\max w = \min w = 0.$$

So  $w = 0$  on  $\overline{\Omega}$ .

- Case 2: Suppose that  $\max w$  occurs at  $x_M \in \Omega$ , and  $\min w$  occurs anywhere in  $\overline{\Omega}$ . Since  $\Omega$  is open,  $x_M$  is an interior point of  $\Omega$ . Since  $w \in C^2(\Omega)$ , both  $Dw(x_M)$  and  $D^2w(x_M)$  exist. Moreover,  $Dw(x_M)y = 0$  and  $D^2w(x_M)y^2 \leq 0$  for all  $y \in \mathbb{R}^3$ . This implies that

$$c \cdot (\nabla w)_{x_M} = c \cdot \left( \frac{\partial w}{\partial x}, \frac{\partial w}{\partial y}, \frac{\partial w}{\partial z} \right)_{x_M} = c \cdot (0, 0, 0) = 0.$$

hence

$$\begin{aligned} -\nabla^2 w + c \cdot \nabla w + w &= 0 \\ w &= \nabla^2 w \end{aligned}$$

But,

$$\begin{aligned} 0 &\geq D^2 w(x_M) e_1^2 = D_{11} w(x_M) \\ 0 &\geq D^2 w(x_M) e_2^2 = D_{22} w(x_M) \\ 0 &\geq D^2 w(x_M) e_3^2 = D_{33} w(x_M) \end{aligned}$$

It follows that

$$\max_{\Omega} w = w(x_M) = \nabla^2 w(x_M) = D_{11} w(x_M) + D_{22} w(x_M) + D_{33} w(x_M) \leq 0$$

Moreover, because  $\Omega \subseteq \overline{\Omega}$ ,

$$\min_{\overline{\Omega}} w \leq \min_{\Omega} w \leq \max_{\Omega} w \leq \max_{\overline{\Omega}} w \leq 0. \quad (1)$$

- Case 3: Suppose that  $\min w$  occurs at  $x_m \in \Omega$ , and  $\max w$  occurs anywhere in  $\overline{\Omega}$ . We can follow that same argument in Case 1, but with

$$\begin{aligned} 0 &\leq D^2 w(x_m) e_1^2 = D_{11} w(x_m) \\ 0 &\leq D^2 w(x_m) e_2^2 = D_{22} w(x_m) \\ 0 &\leq D^2 w(x_m) e_3^2 = D_{33} w(x_m) \end{aligned}$$

Thus,

$$\min_{\Omega} w = w(x_m) = \nabla^2 w(x_m) = D_{11} w(x_m) + D_{22} w(x_m) + D_{33} w(x_m) \geq 0$$

Therefore, because  $\Omega \subseteq \overline{\Omega}$ ,

$$\max_{\overline{\Omega}} w \geq \max_{\Omega} w \geq \min_{\Omega} w \geq \min_{\overline{\Omega}} w \geq 0. \quad (2)$$

(1) and (2) together imply that  $\max w = 0$  and  $\min w = 0$  on  $\overline{\Omega}$ . Thus,  $w = 0$  on  $\overline{\Omega}$ . Since  $w$  was an arbitrary solution,  $w = 0$  is the only solution.  $\square$