

Matthew Lisondra, Physics HBSc, Eng. MSc (Eng. PhD–Present)

UofT Robotics Institute, Toronto, Canada

University of Toronto

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[Email](#) / [Google Scholar](#) / [LinkedIn](#)

Research Interests	Robotics, Robot Perception, Robot Learning, Computer Vision, SLAM, Autonomous/Intelligent Systems Algorithms, High Framerate Processing Low-Power Unconventional Sensing, 3D Scene Representations and Embodied AI
Education	<p>PhD, Doctor of Philosophy UofT Robotics Institute University of Toronto</p> <ul style="list-style-type: none">- Toronto, ON Sep 2024 – Present- Focus: Robot Perception, Robot Learning, Computer Vision- Leveraging LLM and VLM agents w/ Computer Vision for Robot Learning- Thesis on Foundation Models for Robotics, Embodied AI- Research at the University of Toronto Robotics Institute- Supervised by: Dr. G. Nejat of the ASB Lab- Referred: Dr. S. Saeedi, Dr. K. Zareinia, Dr. G. Wang, Dr. M. Chevik, Dr. F. Xi <p>MSc, Master's of Applied Science Robotics and Computer Vision Laboratory (RCVL) Mechatronics and Robotics Engineering</p> <ul style="list-style-type: none">- Toronto, ON Sep 2022 – Aug 2024- Focus: Computer Vision and Visual-Inertial SLAM- Designed the first 6-DOF Visual Inertial Odometry on FPSPs (BIT-VIO)- Thesis Published, Presentation in Yokohama, Japan for IEEE 2024 ICRA- Collaboration with Imperial College London and University of Manchester- Supervised by: Dr. S. Saeedi of RCVL, Dr. K. Zareinia of HapTel Lab- Referred: Dr. D. Jones <p>HBSc, Honours Bachelor of Science Physics (Advanced) and Computer Science University of Toronto</p> <ul style="list-style-type: none">- Toronto, ON Sep 2017 – June 2021- Focus: Robotic Mechanics, Probability, TS-Analysis, Computational Physics- Research: Time Series Analysis on Global Temperature, Sea Level Pressure- Research: Helium-Neon Laser Analysis (Reviewed by Dr. A. Vutha)- Research: Percolation via Random Processes Monte Carlo, Porous Rock- Collaborated with: Dr. D. Jones of the APCM Group

Peer Reviewed Contributions:

[1] Language-Guided Service Robotics: A Survey on Foundation Models using Embodied AI for Human-Robot Task Completion

M. Lisondra¹, B. Benhabib¹, G. Nejat¹

(¹University of Toronto)

[IEEE Robotics and Automation Magazine \(RA-M\)](#) (In Review)

[2] PovNet+: A Deep Learning Architecture for Socially Assistive Robots to Learn and Assist with Multiple Activities of Daily Living

M. Lisondra^{1,*}, S. Pashangpour^{1,*}, F. Robinson¹, G. Nejat¹

(¹University of Toronto)

[IEEE Robotics and Automation Letters \(RA-L\)](#) (In Review)

[3] TCB-VIO: Tightly-Coupled Focal-Plane

Binary-Feature Visual Inertial Odometry (In Progress)

M. Lisondra^{1,*}, J. Kim^{2,*}, G. Shimoda³, K. Zareinia³, S. Saeedi³

(¹University of Toronto, ²TU Delft, ³TMU)

[IEEE Robotics and Automation Letters \(RA-L\)](#) (In Review)

[4] Microplastics Classification and Size Estimation using High-frequency Focused Ultrasound

N. Zarrabi², E. Strohm², H. Rezvani²,

M. Lisondra¹, N. Yousefi², S. Saeedi², M. Kolios²

(¹University of Toronto, ²TMU)

(In Review)

[5] Design of a Robotic Haptic Device with Variable Stiffness for Finger Rehabilitation

M. Lisondra^{1,*}, A. Basirat Tabrizi^{2,*}, J. Catania², K. Zareinia²

(¹University of Toronto, ²TMU)

[IEEE Transactions on Haptics \(ToH\)](#) (In Review)

[6] Inverse k-visibility for RSSI-based Indoor Geometric Mapping (In Review)

M. Lisondra^{1,*}, J. Kim^{2,*}, Y. Bahoo³, S. Saeedi³

(¹University of Toronto, ²TU Delft, ³TMU)

[IEEE Sensors Journal \(ISJ\) 2025](#) (In Review)

[7] Visual Inertial Odometry using Focal Plane Binary Features (BIT-VIO)

M. Lisondra^{1,*}, J. Kim^{2,*}, R. Murai⁴, K. Zareinia³, S. Saeedi³

(¹University of Toronto, ²TU Delft, ³TMU, ⁴Imperial College London)

Presented in Yokohama, Japan for IEEE 2024 ICRA

[IEEE International Conference on Robotics and Automation \(ICRA\) 2024](#)

[Project Webpage](#) / [PDF](#) / [Video](#) / [Presentation](#)

Forthcoming Contributions:

[8] Large-scale Distributed Heterogeneous Multiple-robot Localization and Mapping Dataset with Communication Constraints

M. Lisondra^{1,*}, G. Shimoda^{2,*}, S. Saeedi²

(¹University of Toronto, ²TMU)

[Project Page](#)

[9] AnalogPedestrianNet: High Framerate Focal-Plane Sensor-Processor Pedestrian Tracking (In Progress)

M. Lisondra¹, A. Babaei², A. Ahsan², K. Zareinia², S. Saeedi²

(¹University of Toronto, ²TMU)

[IEEE Conference on Computer and Robot Vision \(CRV\)](#) (In Progress)

Acknowledged Contributions:

[10] M³RS: Multi-robot, Multi-objective, Multi-mode Routing and Scheduling
Ishaan Mehta², J. Kim², S. Taghipour², S. Saeedi²

M. Lisondra¹ in Experiments, Feedback

(¹University of Toronto, ²TMU)

[IEEE Robotics and Automation Letters \(RA-L\)](#) (In Progress)

[11] Structure from WiFi (SfW):

RSSI-based Geometric Mapping of Indoor Environments

J. Kim², J. A. Zalat³, Y. Bahoo³, S. Saeedi³

M. Lisondra¹ in Experiments, Feedback, Paper Publishing/Review

(¹University of Toronto, ²TU Delft, ³TMU)

[IEEE 2024 American Control Conference \(ACC\)](#)

Research Affiliations

**Autonomous Systems
and Biomechatronics Lab (ASB Lab)
UofT Robotics Institute
University of Toronto
([Lab Webpage](#))**

- Toronto, ON

Sep 2024 – Present

- Focus: Robot Perception, Robot Learning, Computer Vision

- Research at the University of Toronto Robotics Institute

- Affiliated with UofT Temerty Faculty of Medicine (TFM)

- Affiliated with Universal Health Network (UHN)

- Supervised by: Dr. G. Nejat

Robotics and Computer Vision Laboratory (RCVL)

([Lab Webpage](#))

- Toronto, ON Sep 2022 – Present
- Focus: Computer Vision and Visual-Inertial SLAM
- Affiliated Research with Imperial College London (i.e. Dyson Robotics Lab)
- Affiliated Research with University of Manchester (i.e. MD Lab)
- Affiliated Research with University of Bath (i.e. Pering Lab)
- Supervised by: Dr. S. Saeedi

Haptics Telerobotics Laboratory (HapTel Lab)
([Lab Webpage](#))

- Toronto, ON Sep 2022 – Present
- Focus: Haptics, Robotic Manipulator Operation, Surgical/Medical Robotics
- Currently: Image-Based Force Estimation in Medical Applications Research
- Supervised by: Dr. K. Zareinia

Organizations	Reviewer (Journal) for ISJ 2025	Fall 2024 – Present
	IEEE Sensors Journal (ISJ) 2025	
	Reviewer (Journal) for RA-L 2024	Fall 2023 – Present
	IEEE Robotics and Automation Letters (RA-L) 2024	
	Reviewer (Conference) for IROS 2024	Winter 2024
	IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)	
	Reviewer (Conference) for ICRA 2024	Fall 2023
	International Conference on Robotics and Automation (ICRA) 2024	
	Reviewer (Conference) for IEEE CCECE 2023	Winter 2023
	2023 Canadian Conference On Electrical and Computer Engineering	
	Reviewer (Conference) for IROS 2023	Winter 2023
	IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)	

Also Affiliated with UHN: Research
 Funding Presentations with S. Pashangpour, G. Nejat

Honors and Awards	NSERC CREATE Next-Generation Mobile Robotics for Human Spaces (ADVENTOR) Award	
	(Award Webpage)	
	- Funding for 4 Years ADVENTOR	Sept 2024 – Sept 2028
	- Collaboration and Affiliated with: Ingenuity Labs Research Institute	
	- Research Papers with Dr. Wu	
	- Responsible for Developing Robotics in Human-Centric Spaces	

Teaching Affiliations	Emerald Valley Academy (EVA)	
	- Toronto, ON	Sept 2024 – Present
	- Leading Department of Mathematics and Science	
	- Teaching Higher-Level Physics, Calculus and Computer Science I, II	
	- Part of EVA Faculty overseeing Ontario Ministry of Education Inspection	

Virtute Innovation Academy (VIA)

- Toronto, ON

Sep 2023 – Aug 2024

- Leading Department of Mathematics and Science

- Teaching Higher-Level Physics, Calculus and Computer Science I, II

- Part of VIA Faculty overseeing Ontario Ministry of Education Inspection

- Collaborated with: Dr. A. Jiang

Select List of Students Currently Teaching†, Alumni Taught and **Refereed***:

H. Li

L. Liang

N. Feng

R. Sun* (Multiple Scholarship Offers in Australia, England)

W. Zheng

A. Zhang

A. Huang* (Now at Berkeley Music School)

B. Zheng

B. Luo* (Full Scholarship Physics, University College London)

B. Yang* (Now at King's College London)

C. Yang* (Now at Durham University)

F. Chen

G. Ye* (Now at University of Hong Kong)

J. Wu

K. Sheng (Multiple University Offers)

L. Lin

N. Zhao* (Multiple University Offers in Business)

N. Tian

A. Pu

D. Qiu

M. Wang

R. Zhang

C. Zou

Y. Tang

S. Fan

A. Ma

A. Xu

K. Chen

F. Li

A. Li

C. Tang†

F. Chen†

L. Li†

M. Wu†

R. Zhang†

S. Fan†

Thesis Mentoring/Guidance:

Thesis Mentored Junseo Kim, Project:

[12] Autonomous Truck Navigation

with Trailer Integration via Natural Language Processing (NLP)

J. Kim², R. Raja³, A. Jawaid³, R. Ha³

M. Lisondra¹ in Mentoring/Guidance of Thesis

(University of Toronto¹, ²TU Delft, ³TMU)

[Conference PDF](#) / [Full Thesis](#)

Paper Guidance, PHD Application Guidance of Takashi Glenn Shimoda:

[8] Large-scale Distributed Heterogeneous Multiple-robot Localization

and Mapping Dataset with Communication Constraints

M. Lisondra^{1,*}, G. Shimoda^{2,*}, S. Saeedi²

(¹University of Toronto, ²TMU)

[Project Page](#) / [Full Thesis](#)

Smaller Projects: Industry and PHD Guidance for

Jack Nyugen ([Personal WebPage](#))

and Paper Guidance for Sourabh Prasad, Kevin Hsu

PHD Graduate/Teaching for MIE443

Winter 2025 – Aug 2025

Mechatronics Systems: Design and Integration at University of Toronto (UofT)

MS Graduate/Teaching for MEC411

Winter 2023 – Aug 2024

Mechanics of Machines at Toronto Metropolitan University (TMU)

MS Graduate/Teaching for BME/MEC323

Fall 2022 – Aug 2024

Statics and Mechanics of Materials at Toronto Metropolitan University (TMU)

Academic Horizons★

- Surrey, BC

Oct 2021 – Sep 2023

- Senior Physics and Computer Science Instructor

- Taught 500+ 1-on-1 Teaching Sessions Physics, Math, Computer Science

- Taught 500+ Class Size Teaching Sessions with Director of Education

- Total Taught 100+ Students (Many now in Science, Engineering)

Lumist of Lumi Education★★

- Toronto, ON

April 2021 – Oct 2021

- Leading Physics Education Sector of Lumist, Lumi Education

- Teaching 1st-4th yr. students from UCLA, UC Berkeley, UCSD, among others

- Textbook Draft/Course Material Written of University Physics I, 500+ Pages

- Total Taught 100+ Students (Many now in Science, Engineering)

- Collaborated with: Dr. N. Murray (Now Algoma University Professor)

- Collaborated with: Dr. F.G. Parra (Now Leading Ace Acumen Academy)

Select List of Students Taught from ★, ★★:

J. Zheng
J. Cheema
A. Gill
C. Liu
J. Christofferson
W. Burns
A. Khan
A. Berar
J. Bhatthal
M. Gosal
G. Dhanoa
R. Kashif
B. Hart
G. Kahlon
C. Latham
K. Dokaj
K. Dokaj
Z. Johal
E. Lubinich
M. Fisher
J. Tatla
I. Sandhu
O. Botelho
K. Lalani
S. Johal
C. Holland
A. Young
K. Sidi
K. Chahal
P. Bennett
M. Kashif
A. Psefteas
K. Hilts
A. Purewal
J. Rai
B. McGowan
J. Tatla
Y. Marei
G. D’Haese
N. Ashrafi
R. Chahal
J. Denman

A. Marei
M. Grewal
M. Negrin
R. Naeem
D. Garland
I. Singh
J. Bresciani
S. Dandina
J. Trentini
M. Sanger
A. Sandhu
G. Warrya
A. Anwar
S. Catroppa
G. Warrya
A. Gill
H. Khan
I. Sidi
D. Fam
N. Scoten
K. Abbas
W. Hussain
A. Hayre
A. Ashton
C. Latham
K. Burrell
K. McDermid
M. Ali Shah
D. Jones
D. Barrett
C. Dewaal
C. Mann
S. Minhas
J. Hayer
G. Boychuk
Y. Johal
C. Marshall
D. Gill
K. Borgersen

Industry Affiliations

Rosor Exploration
([Company Webpage](#))

- Toronto, ON

Jan 2024 – May 2024

- Researcher - Robotics, Geoscientific UAVs and Drones

- Working on Development of Rosor's Active Terrain Following (ATR) System
- Currently: Now Led by H. A. Jaafar
- Collaborated with: R. Efrem

Skills

Coding: Python, PyTorch, keras, R, C/C++, Java, R, C#, Javascript, HTML, CSS

Technologies: Windows, Linux, NXP MCUs based on Arm Cortex-M cores

References available on request.