#### The CPS Transform

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## **Objectives**

You should be able to ...

You've seen how to write CPS functions by hand, but we want you to know the mathematical definition.

After today's lecture, you will

- Convert a direct-style function into CPS:
  - Both simple and complex, involving nested continuations.

#### The CPS Transform, Simple Expressions

Top Level Declaraion To convert a declaration, add a continuation argument to it and then convert the body.

$$C[[f \operatorname{arg} = e)]] \Rightarrow f \operatorname{arg} k = C[[e]]_k$$

Simple Expressions A simple expression in tail position should be passed to a continuation instead of returned.

$$C[a]_k \Rightarrow ka$$

- "Simple" = "No available function calls."
- f a is available in 3 + f a, but not in  $\lambda x.x + f$  a.

Try converting these functions ...

```
1f x = x
2pi1 a b = a
3const x = 10
```



# Simple Expression Examples

#### Before:

```
1 f x = x
2 pi1 a b = a
3 const x = 10
```

#### After:

```
1 f x k = k x
2 pi1 a b k = k a
3 const x k = k 10
```

#### The CPS Transform, Function Calls

Function Call on Simple Argument To a function call in tail position (where arg is simple), pass the current continuation.

$$C[[f arg]]_k \Rightarrow f arg k$$

Function Call on Non-simple Argument If arg is not simple, we need to convert it first.

$$C[[f arg]]_k \Rightarrow C[[arg]]_{(\lambda v, f \vee k)}$$
, where v is fresh.

Try converting these functions.

#### The CPS Transform, Operators

Operator with Two Simple Arguments If both arguments are simple, then the whole thing is simple.

$$C[e_1 + e_2]_k \Rightarrow k(e_1 + e_2)$$

Operator with One Simple Argument If  $e_2$  is simple, we transform  $e_1$ .

$$C[e_1 + e_2]_k \Rightarrow C[e_1]_{(\lambda v - > k(v + e_2))}$$
 where v is fresh.

Operator with No Simple Arguments If both need to be transformed ...

$$C[\![e_1+e_2]\!]_k \Rightarrow C[\![e_1]\!]_{(\lambda v_1->C[\![e_2]\!]_{\lambda v_2->k(v_1+v_2)})}$$
 where  $v_1$  and  $v_2$  are fresh.

Notice that we need to nest the continuations!

```
1 foo a b = a + b
2 bar a b = inc a + b
3 baz a b = a + inc b
4 quux a b = inc a + inc b
```

```
1 foo a b = a + b
2 bar a b = inc a + b
3 baz a b = a + inc b
4 quux a b = inc a + inc b
1 foo a b k = k (a + b)
```

```
1 foo a b = a + b
2 bar a b = inc a + b
3 baz a b = a + inc b
4 quux a b = inc a + inc b
1 foo a b k = k (a + b)
2 bar a b k = inc a (\v -> k (v + b))
```

```
1 foo a b = a + b
2 bar a b = inc a + b
3 baz a b = a + inc b
4 quux a b = inc a + inc b
1 foo a b k = k (a + b)
2 bar a b k = inc a (\v -> k (v + b))
3 baz a b k = inc b (\v -> k (a + v))
```

```
1 foo a b = a + b
2 bar a b = inc a + b
3 baz a b = a + inc b
4 quux a b = inc a + inc b

1 foo a b k = k (a + b)
2 bar a b k = inc a (\v -> k (v + b))
3 baz a b k = inc b (\v -> k (a + v))
4 quux a b k = inc a (\v1 -> inc b (\v2 -> k (v1 + v2)))
```

#### References

- [DF90] Olivier Danvy and Andrzej Filinski. "Abstracting control". In: Proceedings of the 1990 ACM conference on LISP... (1990), pp. 151–160. ISSN: 1098-6596. DOI: http://doi.acm.org.ezp-prod1.hul.harvard.edu/10.1145/91556.91622.
- [DF92] Oliver Danvy and Andrzex Filinski. "Representing Control: a Study of the CPS Transformation". In: Mathematical Structures in Computer Science 2.04 (1992), p. 361. ISSN: 0960-1295. DOI: 10.1017/S0960129500001535.
- [Rey93] John C. Reynolds. "The discoveries of continuations". In: LISP and Symbolic Computation 6.3 (Nov. 1993), pp. 233–247. ISSN: 1573-0557. DOI: 10.1007/BF01019459. URL: https://doi.org/10.1007/BF01019459.