# A CRYOGENIC TESTING ENVIRONMENT FOR SPT-3G, THE NEXT GENERATION SOUTH POLE TELESCOPE CAMERA

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#### ABSTRACT

The next generation camera for the South Pole Telescope, SPT-3G, is set to be deployed in early 2016. This report outlines the fundamental science goals and operation behind SPT-3G, and covers the development of a cryogenic testing environment at the University of Toronto for characterizing the next generation of detectors. The use of a helium pulse tube driven cryostat housing an adiabatic demagnetization refrigerator has enabled sub-Kelvin temperatures on the SPT-3G array wafer stage, essential for operating the superconducting detectors. This has lead to the successful operation of detectors and verification of the entire integrated readout chain.

#### 1. INTRODUCTION

The South Pole Telescope (SPT) is a 10 metre microwave telescope, located at the geographic South Pole in Antarctica. Designed to observe temperature and polarization anisotropies in the Cosmic Microwave Background (CMB) (Ruhl et al. 2004), the telescope has been optimized to operate at millimetre (mm) wavelengths ranging from 75 GHz to 240 GHz. The next generation camera to be installed at the beginning of 2016, SPT-3G, will contain over 16,000 polarization sensitive detectors in the focal plane array. This order of magnitude increase in the number of detectors over the current SPTpol camera will allow for high signal-to-noise mapping of both the E-mode and B-mode CMB polarization anisotropies (Austermann et al. 2012; Benson et al. 2014). With the increased sensitivity achieved by SPT-3G, significant advances can be made in the fields of large scale structure formation, particle physics, and cosmic inflation.

SPT-3G detector arrays are currently being fabricated by Argonne National Laboratory, using a range of designs to tune device parameters. Each array wafer is tested within the SPT collaboration, providing characteristic feedback to the nanofabrication process. The detectors operate in the superconducting transition region for titanium, requiring sub-kelvin cryogenic environments for detector testing. This report outlines the development of such a system at the University of Toronto (UofT), to assist in the testing and characterization of SPT-3G arrays. This system also features the SPT-3G Digital Frequency Multiplexing (DfMUX) readout system, enabling testing of the entire SPT-3G detector readout chain at UofT. In Section 2, the science goals of SPT-3G are outlined, with the instrumentation required to achieve these goals covered in Section 3. Section 4 details the development of the cryogenic testing facility at UofT, with testing results in Section 5. Finally, Section 6 takes a brief look at the processing of SPTpol detector timestreams into useful scientific data.

#### 2. SPT-3G SCIENCE GOALS

The location of the SPT at Amundsen-Scott South Pole Station provides one of best sites on Earth for observing mm-wavelength anisotropies. This is in part due to the South Pole's elevation of 2.8 kilometres above sea level, resulting in desirably low levels of atmospheric fluctuation power. The near zero air humidity also minimises the strong absorption and emission features of atmospheric water vapour at mm-wavelengths. The current optical design produces a beamwidth of ~1 arcmin at 150 GHz, allowing for high resolution mapping of small-scale CMB features. Coupled with the high raw sensitivity achievable through the new multi-chroic polarization-sensitive pixel design, SPT-3G will be able to extract a wealth of previously unobtainable cosmological information from the CMB.

Lensing measurements of the CMB are capable of probing matter fluctuations out to the last scattering surface, providing a detailed lensing power spectrum. SPT-3G's precise measurement of the growth of structure on small angular scales places tight constraints on the number of relativistic species at recombination. Combined with measurements from the *Planck* experiment, it is expected that the sum of neutrino masses will be constrained to within  $\sigma(\Sigma m_{\nu}) \sim 0.06$  eV (Benson et al. 2014).

A measurement of r, the tensor-to-scalar ratio of primordial perturbations (influenced by the energy scale of inflation), is currently being pursued by a number of other experiments (Samtleben et al. 2007). While instruments such as BICEP2/KECK are optimized for measuring low angular modes, they have little or no sensitivity to small-scale temperature and polarization anisotropies. In order to fully characterize the inflationary and lensing B-mode signals, it is vital to take a high-resolution, multifrequency approach. SPT-3G will be capable of producing a high signal-to-noise map of the lensed B-modes, achieving a noise level of  $\sim 3.5 \mu \rm K$ -arcmin. When used in conjunction with its E-mode measurements, the lensing

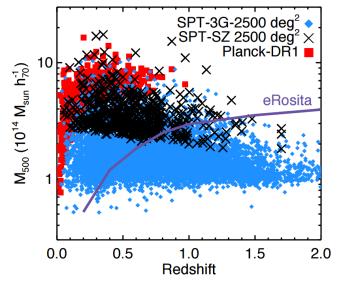


Figure 1. Mass versus redshift for the Sunyaev-Zel'dovich (SZ) galaxy clusters discovered by spt-sz, the *Planck* survey, and the projected spt-3g cluster sample. The increased sensitivity of spt-3g lowers the mass threshold, predicting for 5000 newly identified galaxy clusters including those at higher redshifts. Overplotted is the expected selection threshold for the eRosita X-ray cluster survey (Benson et al. 2014).

potential can be reconstructed, allowing for the separation of the lensing B-mode signal from the inflationary signal. This process is known as "delensing", improving the shape of the tensor power spectrum and constraining r to within  $\sigma(r) \ll 0.01$  (Benson et al. 2014).

The high angular resolution of the telescope also provides a unique way of probing the largest gravitationally bound objects in the universe, clusters of galaxies. CMB photons collide with high energy electrons contained within galaxy clusters, where they inverse Compton scatter to higher energies. This produces a distortion in the CMB signal, known as the Sunyaev-Zel'dovich (SZ) effect. This effect is largely redshift independent, allowing for the identification of almost every massive cluster above a given mass threshold, depending on instrument sensitivity. SPT-3G will be surveying a nearly identical 2500 deg<sup>2</sup> area to SPT-SZ, albeit with noise levels  $\sim$ 12, 7, and 20 times lower at 95, 150, and 220 GHz, respectively. The lowering of the cluster mass threshold will allow SPT-3G to find  $\sim 5000$  clusters at a signal-tonoise > 4.5, an order of magnitude more clusters than SPT-SZ (Bender et al. 2014). The projected SPT-3G cluster sample is shown in Figure 1. The SZ data will also compliment the Dark Energy Survey (DES) cluster survey, providing a calibration of the scatter in the DES optical richness-mass distribution (Wu et al. 2009).

#### 3. SPT-3G INSTRUMENTATION

An upgrade to the SPT optical system, including a new optical cryostat, will take place at the same time as the installation of the SPT-3G camera. However, this report will focus on the detectors contained in the focal plane array and its novel readout system.

#### 3.1. Focal Plane Array

A significant contribution to SPT-3G's leap forward in sensitivity can be attributed to the newly designed focal plane array, featuring 2710 independent pixels com-

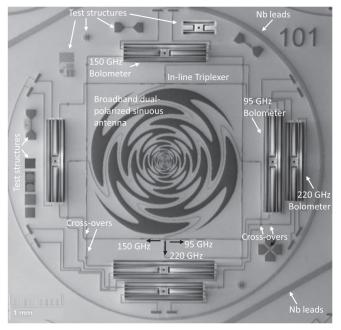


Figure 2. SPT-3G tri-chroic pixel design, featuring a sinuous log-periodic antenna with dual-polarization. The polarized signal is split into three bands at 95, 150, and 220 GHz, with each band sent to an independent TES bolometer (Posada et al. 2015).

pared to sptpol's 768. Each pixel is polarization sensitive across three observing bands at 95, 150, and 220 GHz. Using a sinuous log-periodic antenna, each pixel can absorb a wide band of mm-wave photons at orthogonal polarizations. Once absorbed, microstrip transition line filters route the power from each band to one of six independent transition edge sensor (TES) bolometers (one for each band and polarization). This design results in over 16,000 detectors across the entire focal plane array. The focal plane array itself consist of 10 nanofabricated 6" wafers, each containing 217 of these polarization sensitive tri-chroic pixels in both left and right-handed configurations (to account for polarization wobble induced by the antenna shape).

Each detector is a microstrip termination resistor located on a thermally isolated TES bolometer island. The TES bolometer itself is held in its superconducting phase transition, where a small increase in temperature produces a dramatic increase in resistance. By passing current through the TES, a change in resistance can be measured after an absorbed photon transmits its energy to the island through the microstrip. This configuration results in a negative feedback loop, where the increase in resistance restricts the bias current. This lowers the power passing through the TES, dropping the detector back into its superconducting phase transition. The bolometer time constant for this process is  $\sim\!\!3$  ms.

### 3.2. Readout System

If each bolometer within the focal plane array were read out using independent wire pairs, the resulting thermal load would make it near impossible to maintain the array below the TES superconducting transition temperature. As such, a Digital Frequency Multiplexing (Df-MUX) readout system is utilised, allowing 64 bolometers to be read out using a single pair of wires. Developed by McGill University, the DfMUX system relies on each re-

sistive bolometer being placed in series with a unique inductance L and capacitance C. This configuration forms an  $LCR_{bolo}$  resonator, allowing the bolometer to be interrogated using a unique resonant frequency. Recent improvements in the DfMUX bandwidth now permits 64 of these  $LCR_{bolo}$  resonators to be placed in parallel, up from 16, with resonances spaced from 1.6 to 4.6 GHz. A sinusoidal voltage bias can then be fed in on a single pair of wires, consisting of every bolometer's resonant frequency summed together into a single waveform (referred to as a comb of carriers) (Bender et al. 2014). Changes in bolometer resistance from absorbed photons modulates each carrier, appearing as sidebands in the current. This resulting signal is then amplified using Superconducting Quantum Interference Device (SQUID) amplifiers.

SQUIDs are used as the first amplification stage due to their high gain, low input-impedance, and low noise performance. The amplifiers consist of a superconducting loop containing two Josephson junctions for allowing the current to be measured. Any applied magnetic flux to the SQUID will produce a screening current, requiring that the flux within the loop remains at an integer number of magnetic flux quanta. This results in a periodic voltage output as a function of the magnetic flux in the input coil. The DfMUX operation requires SQUIDs to first be tuned to the region of maximum gain and linearity, by applying known current flux biases to the input coil (Bender et al. 2014). As the dynamic range of the SQUIDs can potentially limit the multiplexing factor, an inverted copy of the carrier comb in injected prior to the SQUID input coil (referred to as the nuller). The improved Df-MUX multiplexing factor of 64 is realised through the use of Digital Active Nulling (DAN), an active feedback loop that nulls both the carriers and sidebands for each bolometer. Following the DAN stage, the signal is demodulated back to baseband allowing the current from each bolometer to be measured.

#### 4. TESTING ENVIRONMENT

The operation of SPT-3G arrays and readout demands sub-Kelvin temperatures, requiring a cryogenic testbed. The Long Wavelength Lab (LWlab) at UofT currently houses an Olympus 104 cryostat, designed and fabricated by High Precision Devices (HPD) in Colorado. The cryostat consists of several shells, with successively colder and smaller shells located within one another. The largest of these, a  $50~\mathrm{K}$  stage and  $3~\mathrm{K}$  stage, are driven by a PT415 helium pulse tube refrigerator developed by Cryomech. This refrigerator relies on the acoustic resonance of sharply pulsed highly-pressurised helium gas. Pulses travelling through the tube, tuned to a particular resonance, produce heating on one end and cooling temperatures as low as 2 K at the other. The sub-Kelvin temperatures required for testing SPT-3G arrays are then realised using an Adiabatic Demagnetization Refrigerator (ADR) located on the 3 K stage.

The ADR itself consists of two paramagnetic salt pills, situated within a powerful superconducting electromagnet ( $L \sim 10$  H). When a large current is applied to the electromagnet, the produced magnetic field aligns the magnetic domains within the paramagnetic salt pills. This freezes out a thermal degree of freedom within the salt pills. Once soaked, removing the current from the coil allows the magnetic domains to realign, reintered to the salt pills.

troducing the thermal degree of freedom. In accordance with the conservation of energy, this adiabatic realignment process lowers the temperature of the paramagnetic salt pills. The ADR system installed in the Olympus 104 cryostat features two salt pills, one of Ammonium Iron(III) Sulfate (FAA) and one of Gadolonium Gallium Garnet (GGG), with base temperatures 35 mK and 500 mK respectively. The FAA pill drives what is referred to as the ultra-cold stage, while the GGG pill drives the itermediate stage. The inclusion of an intermediate stage allows the ultra-cold stage to be buffered by the GGG pill's greater cooling power. This configuration ensures most of the thermal loading from the cold wiring is absorbed at the GGG pill, rather than the FAA.

The ADR's superconducting electromagnet contains  $\sim 5$  km of Niobium-Titanium (NbTi) wire looped around the magnet bore. This NbTi wire is superconducting below  $T_c = 9.2$  K, possessing a series resistance of  $\sim 0.1~\Omega$  below the critical temperature. While superconducting, the NbTi wire has a critical current density of  $J_c = 10^3$  A·mm<sup>-2</sup> beyond which the superconducting state will break down. This sets a magnet current upper limit of 19.0 A for this given implementation. By exceeding this current or the critical temperature  $T_c$ , the superconductivity of the wire will cease, resulting in the dumping of the magnet's field energy to the 3 K stage. This scenario is called a magnet "quench", and can cause significant damage to the system. As such, multiple safeguards have been implemented in both hardware and software to avoid such a scenario.

Following demagnetization, the ADR's ultra-cold stage temperature is regulated at a chosen setpoint using a Proportional-Integral-Derivative (PID) feedback loop control system. Thermometry feeds in the stage temperature to the PID controller, which if below the chosen setpoint, will apply current to the coil heating up the stage. If above the chosen setpoint, the current is decreased, cooling the stage through the aforementioned adiabatic process. While regulating at 250 mK, this control loop can maintain the FAA temperature to within 0.05 mK. Once the regulation current supplying the cooling power has been depleted, a full magnetization cycle must be repeated.

## 4.1. Control System Development

The LWlab cryostat system is operated using the cryo-server, a python-based control program featuring a tornado web-interface (written in coffeescript). The cryo-server is responsible for a multitude of tasks, from monitoring and logging system parameters (temperature, pressure, etc.), running commands from the web-interface, to performing ADR magnetization cycles with a suite of error checking. In preparation for integrating the SPT-3G testbed, some major improvements were made to the functionality of the cryo-server. These include, but are not limited to;

- The monitoring of electromagnet back-EMF, preventing ADR magnetization cycles from quenching due to excessive current ramping.
- Editing of cycle parameters through the webinterface, controlling ramp-up time, hold current, hold time, and ramp-down time.
- A scheduling interface for automatically starting magnetization cycles, allowing array testing to pro-

- ceed at a specified time.
- An email alert system in the result of a Uninterruptible Power Suply (UPS) failure.
- Stability fixes to prevent the cryo-server from crashing due to multiple connection requests.

The cryo-server now serves as a stable and reliable piece of control system software, allowing the cryostat system to be run remotely for the majority of a cooldown cycle. Given the six-hour duration of a "full" magnetization cycle, the addition of the scheduling interface enables detector testing to take place during work hours without lost time for cycling the ADR, maximising testing throughput.

### 4.2. Hardware Development

To accommodate the integration of an SPT-3G array setup and LC towers (containing the inductors and capacitors for the DfMUX readout), a new 'cold-stage' was purchased and installed. The cold-stage consists of three Oxygen-free High thermal Conductivity (OFHC) Copper rings, each separated by six insulating carbon fibre struts. The upper-most ring attaches to the bottom of the 3 K stage, with the middle and lower rings connected to the intermediate and ultra-cold stages respectively via OHFC copper braids. The SPT-3G array holder is then mounted to the ultra-cold stage, allowing its temperature to be finely controlled and monitored through the control system.

A suite of additional *Lakeshore* thermometry (five *Cernox* and two diodes) were calibrated and distributed across the SPT-3G array installation. Using a 'Cryoboard' (developed at McGill University) for readout, this setup allows for quick identification of high thermal loading points within the array setup by monitoring several points of interest in real time. The Cryoboard installation also accommodates the use of heater blocks (essentially resistors in an OFHC copper seat), allowing varying amounts of thermal power to be dumped onto the ultra-cold stage.

# 4.3. DfMUX Integration

The DfMUX readout system is run from an ICE motherboard Field Programmable Gate Array (FPGA) platform (referred to as an *Iceboard*) developed by McGill. Along with Cryoboard, a custom-built enclosure is needed to house the two motherboards for both protection and compactness. A  $17 \times 12 \times 5$  inch steel box provided sufficient volume for containing the boards, their power supplies, and a dual fan-driven ventilation system. The front and back panels were modelled using Solidworks and exported to SprutCAM, where tool paths were generated for cutting out front panel slots, fan ports, and holes for power and Ethernet jacks. These tool paths can then be loaded onto a Computer Numeric Control (CNC) machine as G-code. The Dunlap Institute's Tormach PCNC 770 was used to mill the front and back panels, which along with suitable mounting points and stand-offs, provided a suitable enclosure for the Iceboard and Cryoboard.

The second major design challenge with integrating the DfMUX system lies with passing hundreds of wires through each stage of the cryostat to the inside the 3 K can. Conveniently, the HPD 104 cryostat comes with

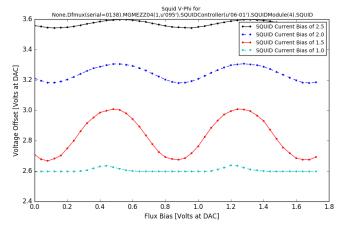


Figure 3. A voltage-flux curve produced by sweeping through flux biases for a range of SQUID bias currents, measuring the voltage required to zero the demodulated output. The tuning algorithm correctly identifies the region of maximum gain and linearity in this case for a SQUID current bias of  $\sim 1.6$  A and flux bias of  $\sim 0.7$  V

additional ports, for which the SPT collaboration has supplied a custom fitting wire harness. The wire harness provides seven slots to the interior of the cryostat, for which one 'cryo-card' and two 'SQUID-cards' have been installed. The cryo-card collects all the thermometry and heater cables for connection to the Cryoboard, while the SQUID-cards each contain four SQUID amplifiers (with each card connected to an LC tower via a stripline). The wire harness exterior features two DB-37 connectors per card slot. The DfMUX readout chain design requires a SQUID controller board to be plugged in directly to the wire harness exterior, for which two are used in our configuration. Unfortunately these devices are extremely sensitive to radio-frequency (RF) interference. As such, an RF-tight box was ordered and installed externally to the cryostat to house the SQUID controller boards. Finally, 37-pin custom cables needed to be fabricated for linking the SQUID controller boards to the Iceboard. To meet noise requirements, the cables must be of a Category 7 standard, meaning each wire pair is individually shielded including the cable bundle as a whole. Two Df-MUX cables bundles were fabricated, each consisting of five individual Category 7 Ethernet cables (often used for 10 Gigabit Ethernet connections) with breakouts to DB-37 connectors at each end.

## 5. TESTING RESULTS

The end goal of characterising detectors conveniently allows multiple facets of the SPT-3G readout chain to be tested in parallel. Prior to operating the bolometers in their superconducting transition, the SQUIDs are tuned to the optimal bias point, testing SQUID performance. Following this is a network analysis to locate each  $LCR_{bolo}$  resonance, verifying array connectivity whilst also testing LC tower performance. Finally the bolometers can be biased, providing a wealth of information on the array characteristics. To date, approximately 30 array wafers have been fabricated by the SPT collaboration. The previously tested 'Wafer 44' is used to validate the functionality of the cryogenic SPT-3G testing environment developed at UofT.

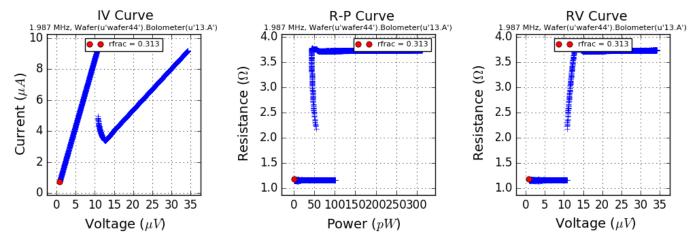


Figure 4. Produced current-voltage (IV), resistance-power (RP), and resistance-voltage (RV) curves during the bolometer biasing process. Bolometer '13.A' achieved a superconducting resistance 0.313 times that of its normal value. The final state of the bolometer is shown in red. The left figure demonstrates a linear decrease in current as the bias voltage is stepped down, with a turnaround into the superconducting region once the bias is sufficiently low. The middle figure shows the saturation power on the bolometer island necessary for the bolometer to go superconducting, with a slight bend due to parasitic resistance located off the island. Figure 3 demonstrates the sharp decrease in bolometer resistance as it transitions from its normal to superconducting state.

### 5.1. SQUID Tuning

The algorithm for tuning the SQUIDs to the region of maximum gain and linearity first starts by producing voltage-flux (V-Phi) curves for assorted SQUID current biases. The flux bias Digital-to-Analog Converter (DAC) is sweeped through a range of values, mimicking the effect of a changing external magnetic field (Bender et al. 2014). The voltage required to zero the demodulated output is measured, forming a periodic function with peaks corresponding to 1/2 of the SQUID flux quanta. The produced V-Phi curves for one of the SQUIDs is shown in Figure 3, demonstrating the periodic voltage output as a function of flux quanta. Following the V-Phi measurement, the tuning algorithm correctly identifies the SQUID current and flux bias for maximum gain, verifying SQUID performance.

#### 5.2. Network Analysis

Once the SQUIDs have been successfully tuned, a network analysis algorithm works to identify each of the  $64\ LCR_{bolo}$  resonant frequencies along with four additional resonances from calibration resistors. The carrier and nuller DACs scan through a range of frequencies in the area of 200 kHz to 7 MHz, operating all 64 readout channels simultaneously until the full bandwidth of the system is probed. The output demodulated amplitude is measured and averaged, producing the readout module response as a function of frequency. A curve-fitting algorithm identifies each peak in the response, ideally producing 68 frequencies corresponding to each  $LCR_{bolo}$  resonance.

To account for systematics in the setup and allow for calibration, the installed configuration features two LC towers. One services the array, while the other connects to a resistor board of known values and hence known resonances. Early network analyses of the system produced poor results, with large noise levels causing the curve-fitting algorithm to fail. Revisions to the cryostat grounding scheme (where ground loops can produce stray currents through electromagnetic induction) and RF environment were successful in reducing the noise level in

the readout module response. All 68 resonances were correctly identified, verifying this stage of the DfMUX readout system. Each bolometer can now be targeted and biased through its unique resonant frequency.

#### 5.3. Bolometer Biasing

The bolometer biasing operation begins by applying an AC bias voltage to each bolometer while above the superconducting transition temperature. In this state, the bolometers behave like resistors and are referred to as being overbiased. The array temperature is then lowered below the transition temperature, but with the bias voltages holding each bolometer in its 'normal' state. Each bias voltage is then gradually stepped down, lowering the bolometers into their superconducting transition. This process is demonstrated in Figure 4, clearly showing a linear decrease in measured current until a sufficiently low bias voltage is reached, at which point the bolometer transitions into its superconducting phase. This is reflected in the sharp drop in resistance between the normal and superconducting phases.

Following the successful bolometer biasing, information can be extracted on the critical TES temperatures, saturation power of the bolometers, and their normal/superconducting resistances. This information is essential for feeding back into the array fabrication process, and even more so for the arrays that will be used in the deployment of SPT-3G. This also concludes the end-toend verification of the developed SPT-3G testing facility at UofT.

## 6. SPTPOL DATA PROCESSING

The SPTpol survey was the first polarization-sensitive survey by the telescope, looking at a 500 deg<sup>2</sup> patch of sky in the 90 and 150 GHz bands (Austermann et al. 2012). Many of the measurement, readout, and processing principals remain the same between this survey and SPT-3G. This section takes a brief look at the SPTpol processing used in converting bolometer timestreams into usable CMB maps and power spectra for extracting scientific data.

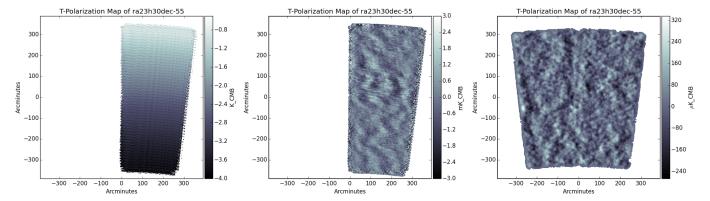


Figure 5. Temperature maps produced using 150 GHz data from the sptpol survey, looking at a 100 deg<sup>2</sup> squared patch of sky centred at RA 23<sup>h</sup>30 and declination 55°. The left panel maps an unfiltered bolometer timestream, demonstrating the first order contamination effect of differing microwave temperature as a function of atmosphere thickness. The middle panel shows the same timestream filtered with a fourth order polynomial and Gaussian smoothing profile, leaving small-scale atmospheric fluctuations. The right panel contains a full season's coaddition of filtered maps for the entire field, averaging out small-scale atmospheric fluctuations. All that remains are the CMB temperature anisotropies.

The raw telescope data is stored across multiple Hierarchical Data Format (HDF) databases, with each corresponding to a block of observation time. Specific scans can be extracted from these databases, and stored as a minimally processed intermediate data file (IDF). The developed SPTDataReader allows the IDF files to be read in as python structures, allowing for easy access and manipulation of vast arrays of telescope data. Including vital bolometer timestreams and scanning strategies, they also contain auxiliary data such as wind speed and direction.

Figure 5 contains maps created using data from a 100 deg<sup>2</sup> survey centred at a Right Ascension (RA) of  $23^{h}30$  and Declination of  $55^{\circ}$ . The scanning strategy splits the field into two halves, using two identical raster scans in succession as the celestial sky rotates through the scanned region (scanning the whole field every hour). The first panel in Figure 5 shows the mapped 150 GHz bolometer timestream from a single raster scan pattern, with minimal filtering to remove 'bad' bolometers. To first order, all that can be seen is the difference in microwave temperature as a function of atmosphere thickness (air mass). The middle panel in Figure 5 features the same mapped timestream, but using a fourth order polynomial fit to each scan segment along with a Gaussian smoothing profile. The visible signal here is due to smaller-scale atmospheric fluctuations, which can be averaged out over multiple scans of the field. The last panel in Figure 5 shows a coadded map of the entire field, averaged over scans taken throughout the course of an entire year (Feb. 2012 - Apr. 2013, excluding Austral summer). Similar filtering is used to that of the middle panel, including point source removal and an apodization mask to smooth out the borders.

Once T, E, and B mode polarization maps have been computed, the SPTpol software library contains a number of functions for producing their power spectra. Map pairs can be used to create their cross-spectra, with options to mask specific features or vary the Fast Fourier Transform (FFT) shape. As with the maps themselves,

the cross-spectra of multiple map bundle pairs can be averaged, also producing the covariance between bins of the cross-spectrum.

### 7. CONCLUSION

I have presented here the development of a cryogenic testing environment for SPT-3G at the University of Toronto. Featuring a stable control system and webinterface, the LWLab cryostat will assist in testing and characterizing SPT-3G arrays and the DfMUX readout system. Array characterization feedback is vital for the nanofabrication process currently underway at Argonne National Laboratory. Each stage of the readout system from array to Iceboard has been installed and tested, allowing the TES bolometers on Wafer 44 to be successfully biased. I have also presented maps produced using SPTpol data, detailing the processing of bolometer current timestreams into usable scientific data from the CMB. Once deployed, SPT-3G will appreciably advance the fields of large scale structure formation, particle physics, and cosmic inflation.

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