

Dimensionality Reduction: SVD and its applications

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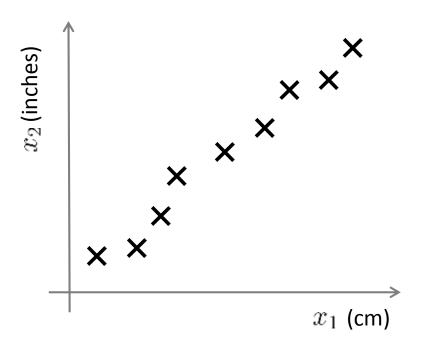
Credits

- Mining of Massive Datasets
 - Jure Leskovec, Anand Rajaraman, Jeff Ullman Stanford University
 - http://www.mmds.org
- Data mining coursera



Motivation

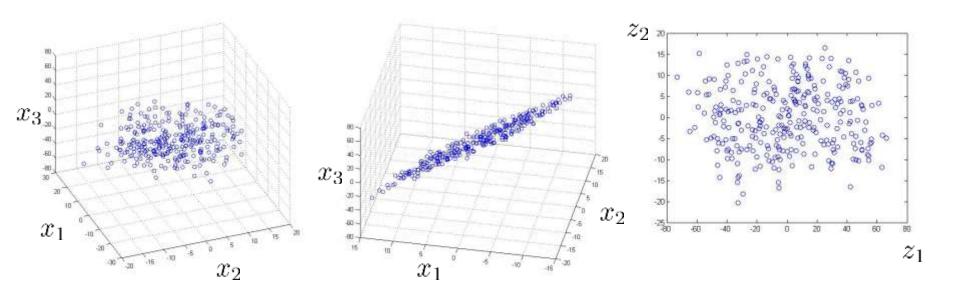
- Data compression
 - Redundancy features
 - Combine features



Reduce features from 2D to 1D



Reduce data from 3D to 2D



Speed up learning algorithms



Better data visualization

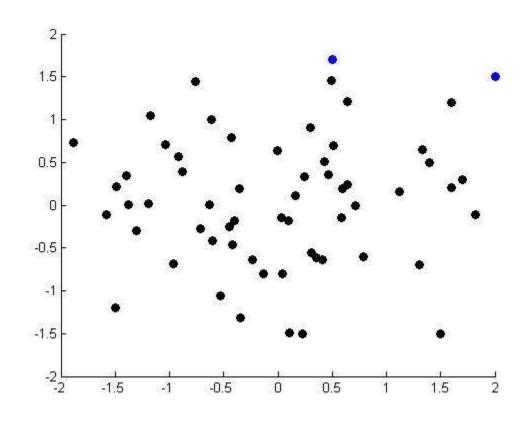
						Mean	
		Per capita			Poverty	household	
	GDP	GDP	Human		Index	income	
	(trillions of	(thousands	Develop-	Life	(Gini as	(thousands	
Country	US\$)	of intl. \$)	ment Index	expectancy	percentage)	of US\$)	
Canada	1.577	39.17	0.908	80.7	32.6	67.293	
China	5.878	7.54	0.687	73	46.9	10.22	•••
India	1.632	3.41	0.547	64.7	36.8	0.735	
Russia	1.48	19.84	0.755	65.5	39.9	0.72	
Singapore	0.223	56.69	0.866	80	42.5	67.1	
USA	14.527	46.86	0.91	78.3	40.8	84.3	
•••	•••	•••	•••	•••	•••	•••	

[resources from en.wikipedia.org]



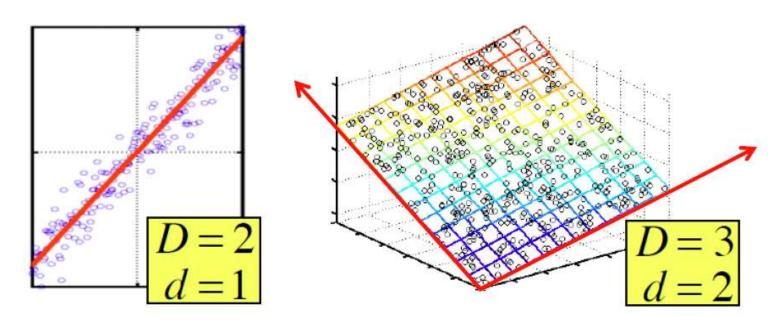
Reduce to 2D

Country		
Canada	1.6	1.2
China	1.7	0.3
India	1.6	0.2
Russia	1.4	0.5
Singapore	0.5	1.7
USA	2	1.5
•••		•••





Dimensionality Reduction



- Assumption: Data lies on or near a low d-dimensional subspace
- Axes of this subspace are effective representation of the data



Rank of a Matrix

- Q: What is rank of a matrix A?
- A: Number of linearly independent columns of A

• For example:

- Matrix
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 1 \\ -2 & -3 & 1 \\ 3 & 5 & 0 \end{bmatrix}$$
 has rank $\mathbf{r} = \mathbf{2}$

• Why? The first two rows are linearly independent.

- Why? The first two rows are linearly independent, so the rank is at least 2, but all three rows are linearly dependent (the first is equal to the sum of the second and third) so the rank must be less than 3.
- Why do we care about low rank?
 - We can write A as two "basis" vectors: [1 2 1] [-2 -3 1]
 - And new coordinates of : [1 0] [0 1] [1 1]

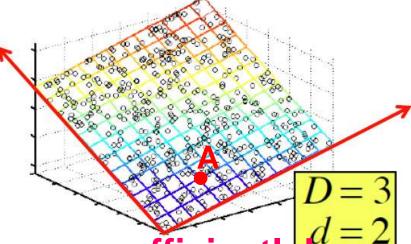


Rank is "Dimensionality"

Cloud of points 3D space:

Think of point positions
 as a matrix:

1 row per point: $\begin{bmatrix} 1 & 2 & 1 \\ -2 & -3 & 1 \\ 3 & 5 & 0 \end{bmatrix}$ A B

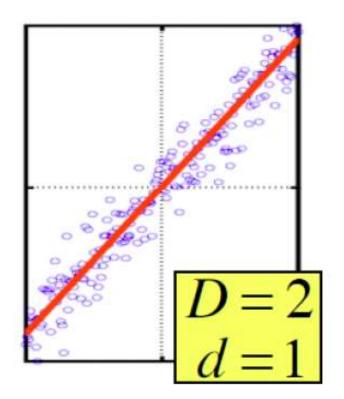


- We can rewrite coordinates more efficiently!
 - Old basis vectors: [1 0 0] [0 1 0] [0 0 1]
 - New basis vectors: [1 2 1] [-2 -3 1]
 - Then A has new coordinates: [1 0]. B: [0 1], C: [1 1]
 - Notice: We reduced the number of coordinates!



Dimensionality Reduction

 Goal of dimensionality reduction is to discover the axis of data!



Rather than representing every point with 2 coordinates we represent each point with 1 coordinate (corresponding to the position of the point on the red line).

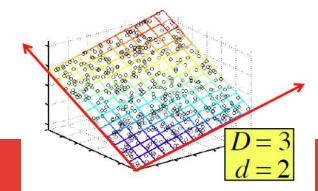
By doing this we incur a bit of **error** as the points do not exactly lie on the line



Sum up

Why reduce dimensions?

- Discover hidden correlations/topics
 - Words that occur commonly together
- Remove redundant and noisy features
 - Not all words are useful
- Interpretation and visualization
- Easier storage and processing of the data





SVD - Definition

$$\mathbf{A}_{[m \times n]} = \mathbf{U}_{[m \times r]} \, \mathbf{\Sigma}_{[r \times r]} \, (\mathbf{V}_{[n \times r]})^{\mathsf{T}}$$

- A: Input data matrix
 - m x n matrix (e.g., m documents, n terms)
- U: Left singular vectors
 - m x r matrix (m documents, r concepts)
- Σ: Singular values
 - r x r diagonal matrix (strength of each 'concept')(r: rank of the matrix A)
- V: Right singular vectors
 - n x r matrix (n terms, r concepts)



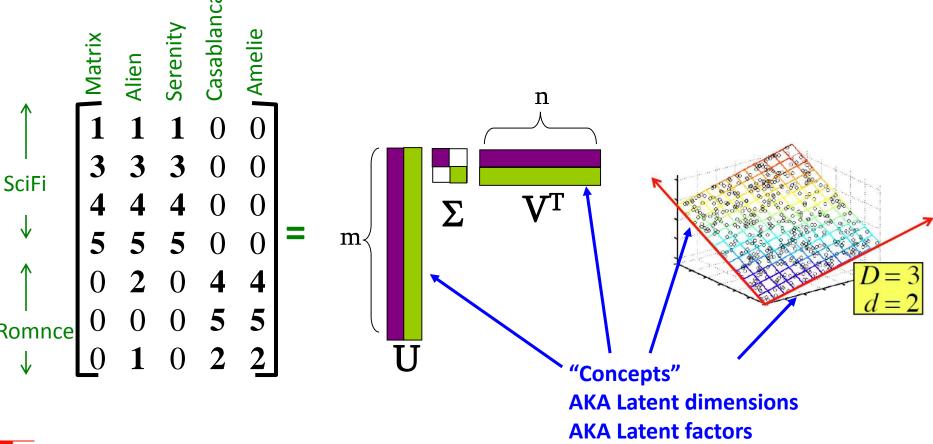
SVD - Properties

It is **always** possible to decompose a real matrix \boldsymbol{A} into $\boldsymbol{A} = \boldsymbol{U} \boldsymbol{\Sigma} \boldsymbol{V}^{\mathsf{T}}$, where

- *U*, Σ, *V*: unique
- U, V: column orthonormal
 - $-U^TU=I$; $V^TV=I$ (I: identity matrix)
 - (Columns are orthogonal unit vectors)
- Σ: diagonal
 - Entries (**singular values**) are positive, and sorted in decreasing order $(\sigma_1 \ge \sigma_2 \ge ... \ge 0)$

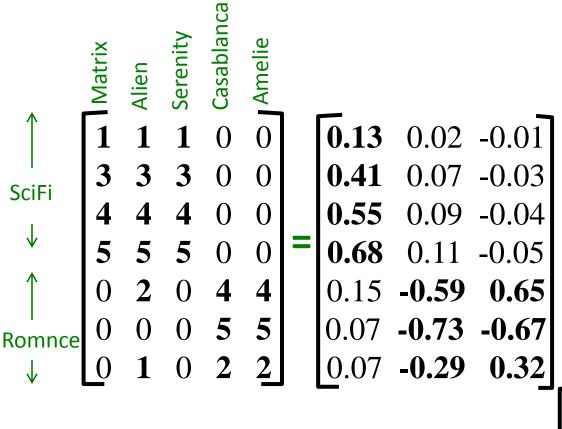


• $A = U \Sigma V^T$ - example: Users to Movies





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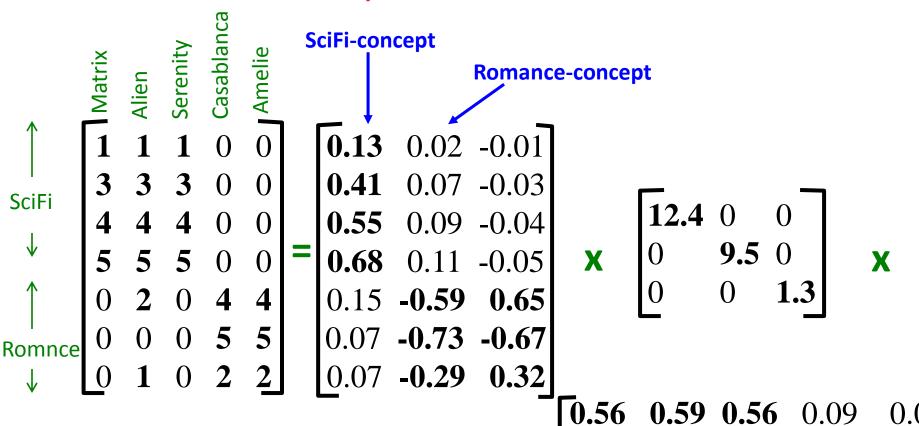


 0.56
 0.59
 0.56
 0.09
 0.09

 0.12
 -0.02
 0.12
 -0.69
 -0.69

 0.40
 -0.80
 0.40
 0.09
 10.09

• $A = U \Sigma V^T$ - example: Users to Movies

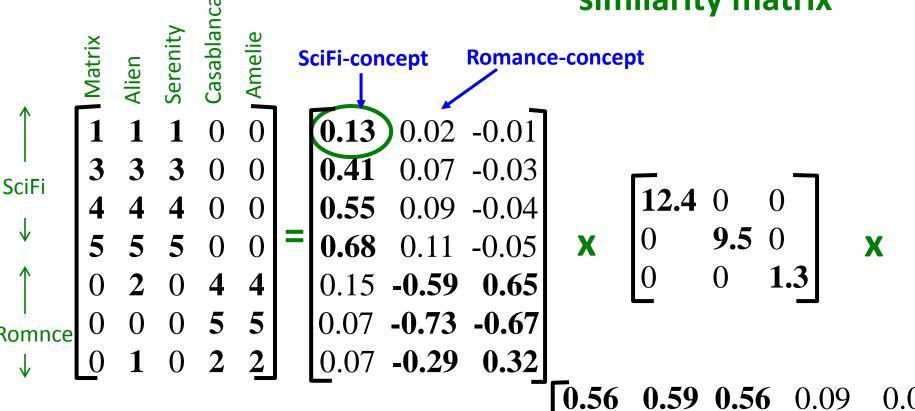


-0.02 0.12 -0.69 -0.69

0.40 0.09



• $A = U \sum V^T$ - example: U is "user-to-concept" similarity matrix

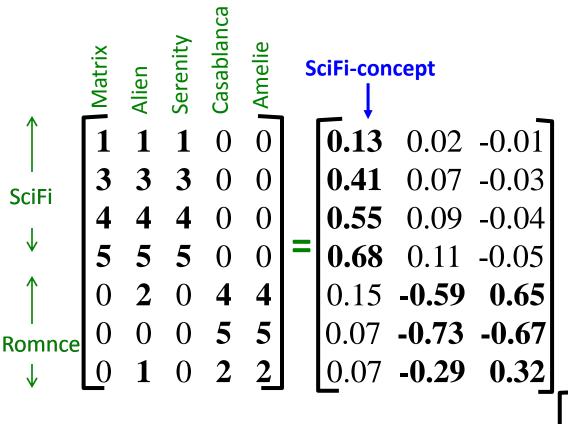


-0.02 0.12 -0.69 -0.69

0.40



• $A = U \Sigma V^T$ - example:



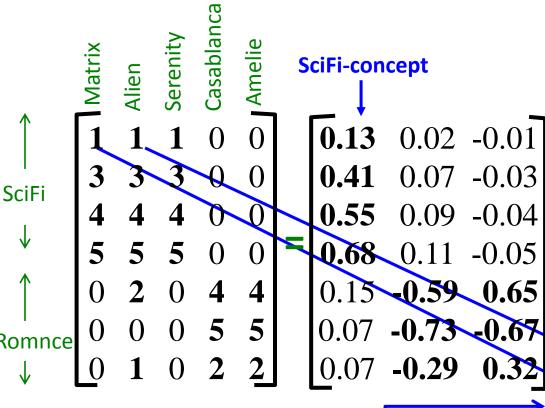
"strength" of the SciFi-concept

0.59 0.56





• $A = U \Sigma V^T$ - example:



SciFi-concept

V is "movie-to-concept" similarity matrix

$$\begin{array}{c|cccc}
\mathbf{X} & \begin{bmatrix} \mathbf{12.4} & 0 & 0 \\ 0 & \mathbf{9.5} & 0 \\ 0 & 0 & \mathbf{1.3} \end{bmatrix} & \mathbf{X}
\end{array}$$

0.56) **0.59 0.56** 0.09 0.09 0.12 -0.02 0.12 -**0.69**



'movies', 'users' and 'concepts':

- *U*: user-to-concept similarity matrix
- V: movie-to-concept similarity matrix
- Σ: its diagonal elements: 'strength' of each concept



"Simple" concept

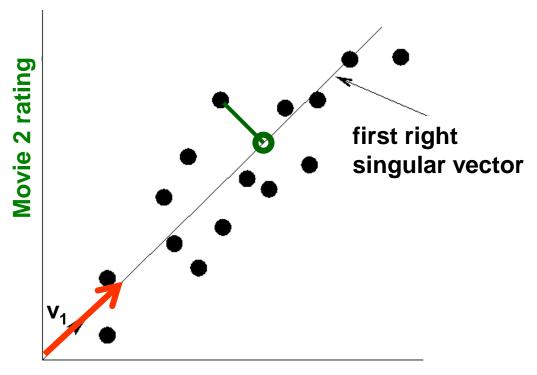
```
Casablanca
        Serenity
                  Amelie
Matrix
    Alien
                                sci-fi
                                        romance
                  0u\u00e4er 1
                                .14
                  0user 2
                                .42
                                                 strength
                  Ouser 3
                                .56
                                                                           .58 .58 0
0 0 .71
                                                                     0
                                                  12.4
    5 5
                                .70
                  0u$e<del>r</del>4
                                0
                  4user 5
                                       .60
                  5user 6
             5
                                      .75
                                       .30
                                                                                      V^T
         M
                                    U
                                                         \sum
```





Dimensionality Reduction with SVD

SVD - Dimensionality Reduction



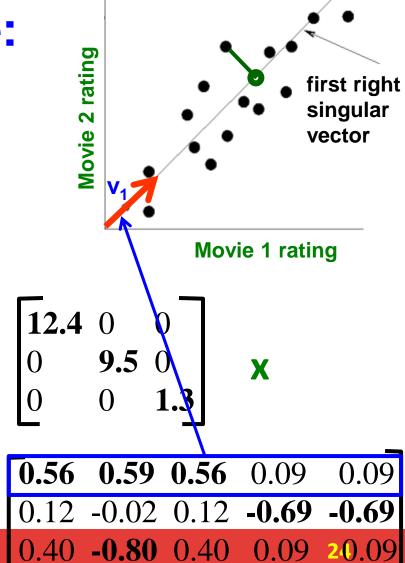
Movie 1 rating

- Instead of using two coordinates to describe point locations, let's use only one coordinate
- Point's position is its location along vector
- How to choose ? Minimize reconstruction error



• $A = U \Sigma V^T$ - example:

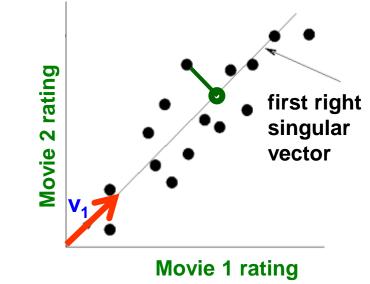
- V: "movie-to-concept" matrix
- U: "user-to-concept" matrix



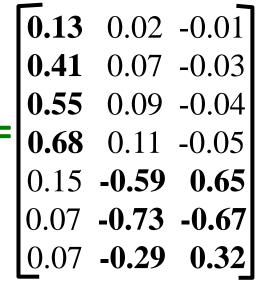


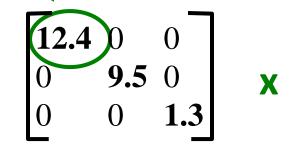


variance ('spread') on the v₁ axis



1	1	1	0	0	
3	3	3	0	0	
4	4	4	0	0	
5	5	5	0	0	:
0	2	0	4	4	
0	0	0	5	5	
0	1	()	2	2	

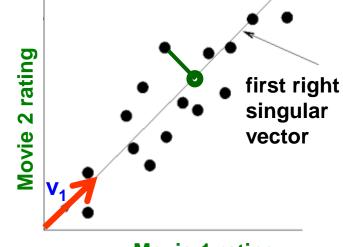






$A = U \Sigma V^{T}$ - example:

 U Σ: Gives the coordinates of the points in the projection axis



1	1	0	0
3	3	0	0
4	4	0	0
5	5	0	0
2	0	4	4
0	0	5	5
1	0	2	2
	3 4 5 2 0	3 3 4 4 5 5 2 0 0 0	3 3 0 4 4 0 5 5 0 2 0 4 0 0 5

Projection of users on the "Sci-Fi" axis $(U \Sigma)^T$:

Movie 1 rating

1.61	0.19	-0.01
5.08	0.66	-0.03
6.82	0.85	-0.05
8.43	1.04	-0.06
1.86	-5.60	0.84
0.86	-6.93	-0.87
0.86	-2.75	0.412



More details

Q: How exactly is dim. reduction done?

12.4 0 0 0 9.5 0 0 0 1.3



More details

- Q: How exactly is dim. reduction done?
- A: Set smallest singular values to zero



More details

- Q: How exactly is dim. reduction done?
- A: Set smallest singular values to zero

-0.02 0.12 **-0.69 -0.69**

-0.80 0.40 0.09



More details

- Q: How exactly is dim. reduction done?
- A: Set smallest singular values to zero



More details

- Q: How exactly is dim. reduction done?
- A: Set smallest singular values to zero

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 2 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 1 & 0 & 2 & 2 \end{bmatrix} \begin{bmatrix} 0.13 & 0.02 \\ 0.41 & 0.07 \\ 0.55 & 0.09 \\ 0.68 & 0.11 \\ 0.15 & -0.59 \\ 0.07 & -0.73 \\ 0.07 & -0.29$$

12.4 0 0 9.5

0.56 0.59 0.56 0.09

0.12 -0.02 0.12 **-0.69**



More details

- Q: How exactly is dim. reduction done?
- A: Set smallest singular values to zero

```
      1
      1
      1
      0
      0

      3
      3
      3
      0
      0

      4
      4
      4
      0
      0

      5
      5
      5
      0
      0

      0
      2
      0
      4
      4

      0
      0
      0
      5
      5

      0
      1
      0
      2
      2
```

 \approx

```
      0.92
      0.95
      0.92
      0.01
      0.01

      2.91
      3.01
      2.91
      -0.01
      -0.01

      3.90
      4.04
      3.90
      0.01
      0.01

      4.82
      5.00
      4.82
      0.03
      0.03

      0.70
      0.53
      0.70
      4.11
      4.11

      -0.69
      1.34
      -0.69
      4.78
      4.78

      0.32
      0.23
      0.32
      2.01
      2.01
```



Q: How many σs to keep?

A: Rule-of-a thumb:

keep 80-90% of 'energy' $\ddot{a} Q_i^2$

$$\overset{\circ}{a} O_i^2$$



SVD - Conclusions so far

- SVD: $A = U \Sigma V^T$: unique
 - U: user-to-concept similarities
 - V: movie-to-concept similarities
 - $-\Sigma$: strength of each concept
- Dimensionality reduction:
 - keep the few largest singular values (80-90% of 'energy')
 - SVD: picks up linear correlations

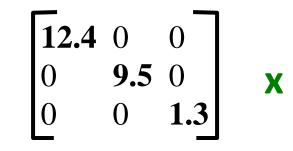




Example of SVD & Conclusion

Case study: How to query?

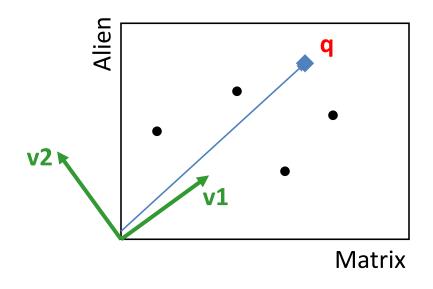
- Q: Find users that like 'Matrix'
- A: Map query into a 'concept space' how?



- Q: Find users that like 'Matrix'
- A: Map query into a 'concept space' how?

Project into concept space:

Inner product with each 'concept' vector **v**_i

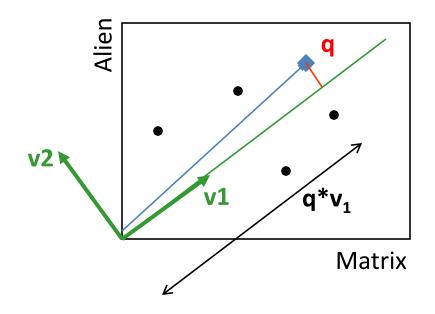




- Q: Find users that like 'Matrix'
- A: Map query into a 'concept space' how?

Project into concept space:

Inner product with each 'concept' vector **v**_i





Compactly, we have:

$$q_{concept} = q V$$

E.g.:

$$\mathbf{q} = \begin{bmatrix} 5 & 0 & 0 & 0 & 0 \\ 5 & 0 & 0 & 0 & 0 \end{bmatrix} \mathbf{X}$$

$$\begin{bmatrix} 0.56 & 0.12 \\ 0.59 & -0.02 \\ 0.56 & 0.12 \\ 0.09 & -0.69 \\ 0.00 & 0.60 \end{bmatrix}$$

movie-to-concept similarities (V)

SciFi-concept
$$= \begin{bmatrix} 2.8 & 0.6 \end{bmatrix}$$



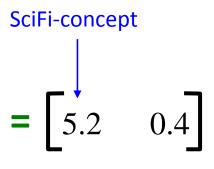
 How would the user d that rated ('Alien', 'Serenity') be handled? $d_{concept} = d V$

E.g.:

$$\mathbf{q} = \begin{bmatrix} 0 & 4 & 5 & 0 & 0 \end{bmatrix} \mathbf{X}$$

$$\begin{bmatrix} 0.56 & 0.12 \\ 0.59 & -0.02 \\ 0.56 & 0.12 \\ 0.09 & -0.69 \end{bmatrix}$$

movie-to-concept similarities (V)





Observation: User d that rated ('Alien', 'Serenity')
will be similar to user q that
rated ('Matrix'), although d and q have
zero ratings in common!

$$\mathbf{d} = \begin{bmatrix} 0 & 4 & 5 & 0 & 0 \\ 5 & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\text{SciFi-concept}} \begin{bmatrix} 5.2 & 0.4 \end{bmatrix}$$

$$\mathbf{q} = \begin{bmatrix} 5 & 0 & 0 & 0 & 0 \\ 2.8 & 0.6 \end{bmatrix}$$
Zero ratings in common





SVD in Latent semantic indexing and analysis

Latent Semantic Indexing

- Term-document matrices are very large
- But the number of topics that people talk about is small (in some sense)
 - -Clothes, movies, politics, ...
- Can we represent the term-document space by a lower dimensional latent space?



Idea

- From term-doc matrix A, we compute the approximation A_k .
- There is a row for each term and a column for each doc in A_k
- Thus docs live in a space of k<<r dimensions
 - -These dimensions are not the original axes
- But why?

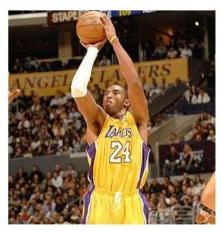




Image compression using SVD

Image as matrix

Reduced SVD applied to keep most features



300 terms (rank)



Original image





10 terms

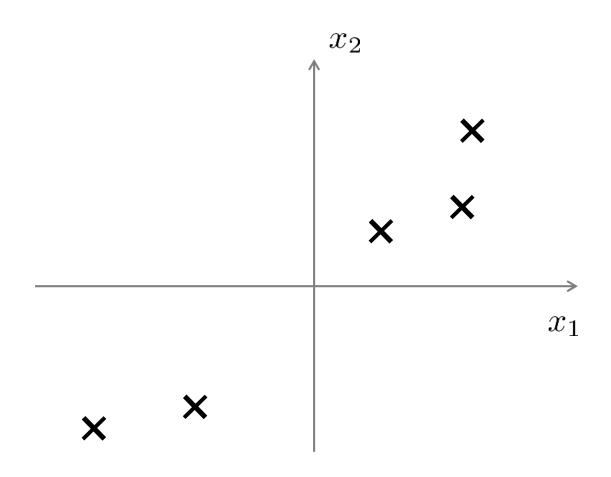
50 terms





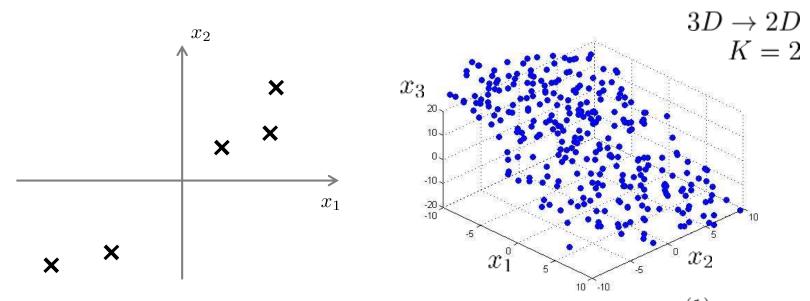
Principle component analysis

Problem formulation





Problem formulation



Reduce from 2-dimension to 1-dimension: Find a direction (a vector $u^{(1)} \in \mathbb{R}^n$) onto which to project the data so as to minimize the projection error.

Reduce from n-dimension to k-dimension: Find k vectors $u^{(1)}, u^{(2)}, \ldots, u^{(k)}$ onto which to project the data, so as to minimize the projection error.



PCA algorithm

Reduce data from n-dimensions to k-dimensions Compute "covariance matrix":

$$\frac{1}{m}\sum_{i=1}^m (x^{(i)})(x^{(i)})^T$$
 Compute "eigenvectors" of matrix Σ :

$$[U,S,V] = svd(Sigma);$$



From [U,S,V] = svd(Sigma), we get:

$$U = \begin{bmatrix} | & | & | & | \\ u^{(1)} & u^{(2)} & \dots & u^{(n)} \\ | & | & | \end{bmatrix} \in \mathbb{R}^{n \times n}$$

