

Operations With Vector Data I

HES 505 Fall 2023: Session 11

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Today's Plan

Objectives

By the end of today, you should be able to:

- Recognize the unary, binary, and n-ary transformers
- Articulate common uses for unary and binary transformers
- Use unary transformations to fix invalid geometries
- Implement common binary transformers to align and combine data

Revisiting **predicates** and **measures**

- **Predicates:** evaluate a logical statement asserting that a property is **TRUE**
- **Measures:** return a numeric value with units based on the units of the CRS
- Unary, binary, and n-ary distinguish how many geometries each function accepts and returns

Transformations

- **Transformations:** create new geometries based on input geometries

Original Data



Simplified



Unary Transformations

transformer	returns a geometry ...
centroid	of type POINT with the geometry's centroid
buffer	that is this larger (or smaller) than the input geometry, depending on the buffer size
jitter	that was moved in space a certain amount, using a bivariate uniform distribution
wrap_dateline	cut into pieces that do no longer cover the dateline
boundary	with the boundary of the input geometry
convex_hull	that forms the convex hull of the input geometry
line_merge	after merging connecting LINESTRING elements of a MULTILINESTRING into longer LINESTRINGs .
make_valid	that is valid
node	with added nodes to linear geometries at intersections without a node; only works on individual linear geometries
point_on_surface	with a (arbitrary) point on a surface
polygonize	of type polygon, created from lines that form a closed ring

Unary Transformations (cont'd)

transformer	returns a geometry ...
<code>segmentize</code>	a (linear) geometry with nodes at a given density or minimal distance
<code>simplify</code>	simplified by removing vertices/nodes (lines or polygons)
<code>split</code>	that has been split with a splitting linestring
<code>transform</code>	transformed or convert to a new coordinate reference system (chapter @ref(cs))
<code>triangulate</code>	with Delauney triangulated polygon(s) (figure @ref(fig:vor))
<code>voronoi</code>	with the Voronoi tessellation of an input geometry (figure @ref(fig:vor))
<code>zm</code>	with removed or added Z and/or M coordinates
<code>collection_extract</code>	with subgeometries from a GEOMETRYCOLLECTION of a particular type
<code>cast</code>	that is converted to another type
<code>+</code>	that is shifted over a given vector
<code>*</code>	that is multiplied by a scalar or matrix

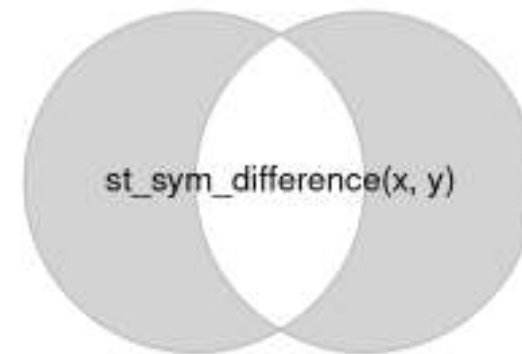
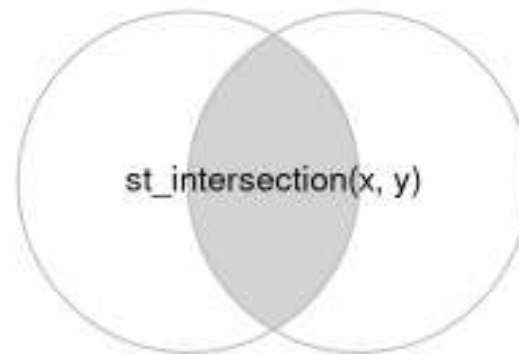
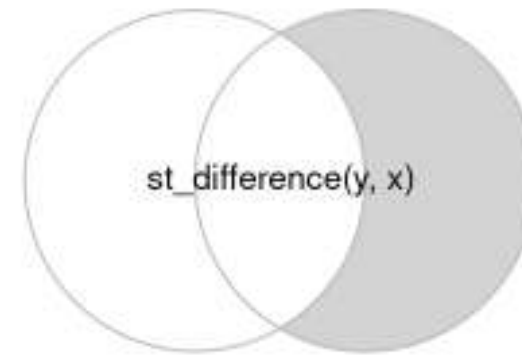
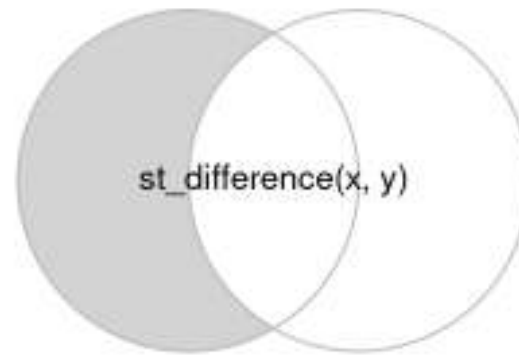
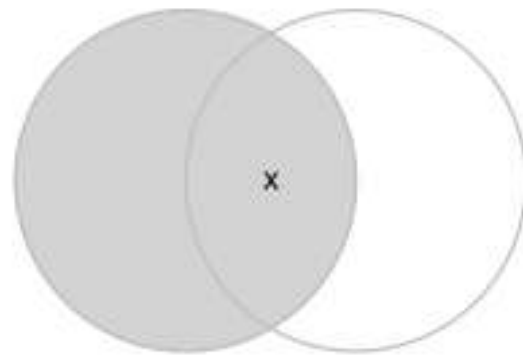
Common uses of Unary Transformers

- Creating valid geometries
- Reprojecting your data
- Combining or changing geometries

Binary Transformers

function	returns	infix operator
<code>intersection</code>	the overlapping geometries for pair of geometries	<code>&</code>
<code>union</code>	the combination of the geometries; removes internal boundaries and duplicate points, nodes or line pieces	<code> </code>
<code>difference</code>	the geometries of the first after removing the overlap with the second geometry	<code>/</code>
<code>sym_difference</code>	the combinations of the geometries after removing where they intersect; the negation (opposite) of <code>intersection</code>	<code>%/%</code>
<code>crop</code>	crop an sf object to a specific rectangle	

Binary Transformers



Common Uses of Binary Transformers

- Relating partially overlapping datasets to each other
- Reducing the extent of vector objects

N-ary Transformers

- Similar to Binary (except `st_crop`)
- `union` can be applied to a set of geometries to return its geometrical union
- `intersection` and `difference` take a single argument, but operate (sequentially) on all pairs, triples, quadruples, etc.

