

proj2

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Chapter 1

Class Index

1.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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Chapter 2

File Index

2.1 File List

Here is a list of all files with brief descriptions:

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Chapter 3

Class Documentation

3.1 BSTTree< T > Class Template Reference

Binary search tree implementation, accepting elements of type T.

```
#include <BSTTree.hpp>
```

Public Member Functions

- [BSTTree](#) (const T &element)
Constructs a [BSTTree](#) with an initial element.
- [BSTTree](#) ()
Constructs an empty [BSTTree](#).
- [~BSTTree](#) ()
Destructor to clean up dynamically allocated nodes in the tree.
- void [add](#) (const T &element)
Adds an element to the tree.
- void [delete_tree](#) ()
Deletes all nodes in the tree, resetting it to an empty state.
- std::vector< T > [traverse_preorder](#) () const
Traverse the tree in the preorder direction and return a vector the contents of each node.
- std::vector< T > [traverse_inorder](#) () const
Traverse the tree in the inorder direction and return a vector the contents of each node.
- std::vector< T > [traverse_postorder](#) () const
Traverse the tree in the postorder direction and return a vector the contents of each node.
- int [delete_element](#) (T value)
Delete an element of a given value.
- std::vector< T > [find_path](#) (const T &value)
Finds the path to a value in a binary search tree.

3.1.1 Detailed Description

```
template<typename T>  
class BSTTree< T >
```

Binary search tree implementation, accepting elements of type T.

3.1.2 Constructor & Destructor Documentation

3.1.2.1 BSTTree() [1/2]

```
template<typename T >
BSTTree< T >::BSTTree (
    const T & element) [inline]
```

Constructs a [BSTTree](#) with an initial element.

Parameters

<i>element</i>	The initial element to be stored in the root node.
----------------	--

3.1.2.2 BSTTree() [2/2]

```
template<typename T >
BSTTree< T >::BSTTree () [inline]
```

Constructs an empty [BSTTree](#).

3.1.2.3 ~BSTTree()

```
template<typename T >
BSTTree< T >::~~BSTTree () [inline]
```

Destructor to clean up dynamically allocated nodes in the tree.

3.1.3 Member Function Documentation

3.1.3.1 add()

```
template<typename T >
void BSTTree< T >::add (
    const T & element) [inline]
```

Adds an element to the tree.

Parameters

<i>element</i>	The element to insert into the tree.
----------------	--------------------------------------

This operation is performed recursively.

3.1.3.2 delete_element()

```
template<typename T >
int BSTTree< T >::delete_element (
    T value) [inline]
```

Delete an element of a given value.

Parameters

<i>value</i>	The value of the element to be deleted.
--------------	---

This does not differentiate between unique elements of the same value.

Returns

0 if the element was successfully deleted, -1 if the element was not found.

3.1.3.3 delete_tree()

```
template<typename T >
void BSTree< T >::delete_tree () [inline]
```

Deletes all nodes in the tree, resetting it to an empty state.

3.1.3.4 find_path()

```
template<typename T >
std::vector< T > BSTree< T >::find_path (
    const T & value) [inline]
```

Finds the path to a value in a binary search tree.

Template Parameters

<i>T</i>	The type of the tree values.
----------	------------------------------

Parameters

<i>value</i>	The value to find.
--------------	--------------------

Returns

std::vector<T> Path to the value or empty if not found.

3.1.3.5 traverse_inorder()

```
template<typename T >
std::vector< T > BSTree< T >::traverse_inorder () const [inline]
```

Traverse the tree in the inorder direction and return a vector the contents of each node.

Returns

Inordered vector of the elements of the tree.

3.1.3.6 traverse_postorder()

```
template<typename T >
std::vector< T > BSTTree< T >::traverse_postorder () const [inline]
```

Traverse the tree in the postorder direction and return a vector the contents of each node.

Returns

Postordered vector of the elements of the tree.

3.1.3.7 traverse_preorder()

```
template<typename T >
std::vector< T > BSTTree< T >::traverse_preorder () const [inline]
```

Traverse the tree in the preorder direction and return a vector the contents of each node.

Returns

Preordered vector of the elements of the tree.

3.2 FileTree< T > Class Template Reference

```
#include <FileTree.hpp>
```

Public Member Functions

- void [save_to_text](#) (const std::string &filename, const std::vector< T > &elements)
Save the tree's elements to a text file.
- void [load_from_text](#) (const std::string &filename, [BSTTree](#)< T > &tree, std::vector< T > &elements, bool append=false)
Load elements from a text file into a tree.
- void [save_to_binary](#) (const std::string &filename, const std::vector< T > &elements)
Save the tree's elements to a binary file.
- void [load_from_binary](#) (const std::string &filename, [BSTTree](#)< T > &tree, std::vector< T > &elements, bool append=false)
Load elements from a binary file into a tree.

3.2.1 Member Function Documentation

3.2.1.1 load_from_binary()

```
template<typename T >
void FileTree< T >::load_from_binary (
    const std::string & filename,
    BSTTree< T > & tree,
    std::vector< T > & elements,
    bool append = false) [inline]
```

Load elements from a binary file into a tree.

Parameters

<i>filename</i>	The name of the binary file to read.
<i>tree</i>	The tree to populate.
<i>elements</i>	A list to store the loaded elements.
<i>append</i>	Whether to add to an existing tree or start fresh. Without this, tree would have to be deleted manually.

3.2.1.2 load_from_text()

```
template<typename T >
void FileTree< T >::load_from_text (
    const std::string & filename,
    BSTTree< T > & tree,
    std::vector< T > & elements,
    bool append = false) [inline]
```

Load elements from a text file into a tree.

Parameters

<i>filename</i>	The name of the file to read from.
<i>tree</i>	The tree to populate.
<i>elements</i>	A list to store the loaded elements.
<i>append</i>	Whether to add to an existing tree or start fresh.

3.2.1.3 save_to_binary()

```
template<typename T >
void FileTree< T >::save_to_binary (
    const std::string & filename,
    const std::vector< T > & elements) [inline]
```

Save the tree's elements to a binary file.

Parameters

<i>filename</i>	The name of the binary file.
<i>elements</i>	A list of tree elements.

3.2.1.4 save_to_text()

```
template<typename T >
void FileTree< T >::save_to_text (
    const std::string & filename,
    const std::vector< T > & elements) [inline]
```

Save the tree's elements to a text file.

Parameters

<i>filename</i>	The name of the file to save to.
<i>elements</i>	A list of tree elements.

Chapter 4

File Documentation

4.1 src/BSTTree.hpp File Reference

```
#include <ranges>
#include <vector>
#include <algorithm>
```

Classes

- class [BSTTree< T >](#)

Binary search tree implementation, accepting elements of type T.

4.2 BSTTree.hpp

[Go to the documentation of this file.](#)

```
00001
00002 #pragma once
00003
00004 #include <ranges>
00005 #include <vector>
00006 #include <algorithm>
00007
00011 template <typename T>
00012 class BSTTree {
00013 private:
00014     struct Tree {
00015         T contents;
00016         Tree* parent;
00017         Tree* left;
00018         Tree* right;
00019
00020         Tree(T _contents, Tree* _parent = nullptr, Tree* _left = nullptr, Tree* _right = nullptr) :
00021             contents{ _contents }, parent{ _parent }, left{ _left }, right{ _right } {
00022         }
00023
00024         ~Tree() {
00025             delete left;
00026             delete right;
00027         }
00028     };
00029
00030     Tree* root;
00031
00032     void recursive_add(const T& element, Tree*& node, Tree* parentNode = nullptr) {
00033         if (node == nullptr) {
00034             node = new Tree(element);
```

```

00035         if (parentNode == nullptr) {
00036             return;
00037         }
00038         node->parent = parentNode;
00039         if (node->contents >= parentNode->contents) {
00040             parentNode->right = node;
00041         }
00042         else {
00043             parentNode->left = node;
00044         }
00045         return;
00046     }
00047     if (element >= node->contents) {
00048         recursive_add(element, node->right, node);
00049     }
00050     else {
00051         recursive_add(element, node->left, node);
00052     }
00053 }
00054
00055 void preorder_traverse_recursive(Tree* node, std::vector<Tree*>& traversedTrees) const {
00056     if (node == nullptr) {
00057         return;
00058     }
00059     traversedTrees.push_back(node);
00060     preorder_traverse_recursive(node->left, traversedTrees);
00061     preorder_traverse_recursive(node->right, traversedTrees);
00062 }
00063
00064 void inorder_traverse_recursive(Tree* node, std::vector<Tree*>& traversedTrees) const {
00065     if (node == nullptr) {
00066         return;
00067     }
00068     inorder_traverse_recursive(node->left, traversedTrees);
00069     traversedTrees.push_back(node);
00070     inorder_traverse_recursive(node->right, traversedTrees);
00071 }
00072
00073 void postorder_traverse_recursive(Tree* node, std::vector<Tree*>& traversedTrees) const {
00074     if (node == nullptr) {
00075         return;
00076     }
00077     postorder_traverse_recursive(node->left, traversedTrees);
00078     postorder_traverse_recursive(node->right, traversedTrees);
00079     traversedTrees.push_back(node);
00080 }
00081
00082 public:
00083 BSTree(const T& element) : root{ new Tree(element) } {}
00084
00085 BSTree() : root{ nullptr } {}
00086
00087 ~BSTree() { delete root; }
00088
00089 void add(const T& element) {
00090     recursive_add(element, root);
00091 }
00092
00093 void delete_tree() {
00094     delete root;
00095     root = nullptr;
00096 }
00097
00098 std::vector<T> traverse_preorder() const {
00099     std::vector<Tree*> traversedTrees;
00100     preorder_traverse_recursive(root, traversedTrees);
00101     return traversedTrees | std::ranges::views::transform([](const Tree* tree) { return
00102 tree->contents; }) | std::ranges::to<std::vector>();
00103 }
00104
00105 std::vector<T> traverse_inorder() const {
00106     std::vector<Tree*> traversedTrees;
00107     inorder_traverse_recursive(root, traversedTrees);
00108     return traversedTrees | std::ranges::views::transform([](const Tree* tree) { return
00109 tree->contents; }) | std::ranges::to<std::vector>();
00110 }
00111
00112 std::vector<T> traverse_postorder() const {
00113     std::vector<Tree*> traversedTrees;
00114     postorder_traverse_recursive(root, traversedTrees);
00115     return traversedTrees | std::ranges::views::transform([](const Tree* tree) { return
00116 tree->contents; }) | std::ranges::to<std::vector>();
00117 }
00118
00119 int delete_element(T value) {
00120     std::vector<Tree*> traversedTrees;
00121     inorder_traverse_recursive(root, traversedTrees);

```



```

00157
00158     auto elementOfValueIterator = std::find_if(traversedTrees.begin(), traversedTrees.end(),
00159 [&value](const Tree* tree) { return tree->contents ==
value; });
00160
00161     if (elementOfValueIterator == traversedTrees.end()) {
00162         return -1;
00163     }
00164
00165     Tree* elementOfValue{ *elementOfValueIterator };
00166     if (elementOfValue->left == nullptr && elementOfValue->right == nullptr) {
00167         if (elementOfValue->parent != nullptr) {
00168             if (elementOfValue->parent->left == elementOfValue) {
00169                 elementOfValue->parent->left = nullptr;
00170             } else {
00171                 elementOfValue->parent->right = nullptr;
00172             }
00173         }
00174
00175         delete elementOfValue;
00176     } else {
00177         Tree* successor = *std::next(elementOfValueIterator);
00178         if (successor->parent != nullptr) {
00179             if (successor->parent->left == successor) {
00180                 successor->parent->left = nullptr;
00181             } else {
00182                 successor->parent->right = nullptr;
00183             }
00184         }
00185         elementOfValue->contents = successor->contents;
00186         delete successor;
00187     }
00188
00189     return 0;
00190 }
00191
00192
00193
00201 std::vector<T> find_path(const T& value) {
00202     std::vector<T> path;
00203     Tree* curr = root;
00204
00205     while (root != nullptr) {
00206         path.push_back(curr->contents);
00207
00208         if (curr->contents == value) {
00209             return path;
00210         }
00211         else if (value < curr->contents) {
00212             curr = curr->left;
00213         }
00214         else {
00215             curr = curr->right;
00216         }
00217     }
00218     return {};
00219 }
00220
00221 };

```

4.3 src/FileTree.hpp File Reference

A simple class to save and load a Binary Search Tree ([BSTTree](#)) from files.

```

#include "BSTTree.hpp"
#include <fstream>
#include <vector>
#include <iostream>

```

Classes

- class [FileTree< T >](#)

4.3.1 Detailed Description

A simple class to save and load a Binary Search Tree ([BSTTree](#)) from files.

4.4 FileTree.hpp

[Go to the documentation of this file.](#)

```

00001
00006 #pragma once
00007
00008 #include "BSTTree.hpp"
00009 #include <fstream>
00010 #include <vector>
00011 #include <iostream>
00012
00013 template <typename T>
00014 class FileTree {
00015 public:
00021     void save_to_text(const std::string& filename, const std::vector<T>& elements) {
00022         std::ofstream file(filename);
00023         if (!file) {
00024             std::cerr << "Error: Could not open file for writing.\n";
00025             return;
00026         }
00027         for (const auto& elem : elements) {
00028             file << elem << " ";
00029         }
00030     }
00031
00039     void load_from_text(const std::string& filename, BSTTree<T>& tree, std::vector<T>& elements, bool
append = false) {
00040         std::ifstream file(filename);
00041         if (!file) {
00042             std::cerr << "Error: Could not open file for reading.\n";
00043             return;
00044         }
00045         if (!append) {
00046             tree.delete_tree();
00047             elements.clear();
00048         }
00049         T value;
00050         while (file >> value) {
00051             elements.push_back(value);
00052             tree.add(value);
00053         }
00054     }
00055
00061     void save_to_binary(const std::string& filename, const std::vector<T>& elements) {
00062         std::ofstream file(filename, std::ios::binary);
00063         if (!file) {
00064             std::cerr << "Error: Could not open file for binary writing.\n";
00065             return;
00066         }
00067         size_t size = elements.size();
00068         file.write(reinterpret_cast<const char*>(&size), sizeof(size));
00069         for (const auto& elem : elements) {
00070             file.write(reinterpret_cast<const char*>(&elem), sizeof(T));
00071         }
00072     }
00073
00081     void load_from_binary(const std::string& filename, BSTTree<T>& tree, std::vector<T>& elements,
bool append = false) {
00082         std::ifstream file(filename, std::ios::binary);
00083         if (!file) {
00084             std::cerr << "Error: Could not open file for binary reading.\n";
00085             return;
00086         }
00087         if (!append) {
00088             tree.delete_tree();
00089             elements.clear();
00090         }
00091         size_t size = 0;
00092         file.read(reinterpret_cast<char*>(&size), sizeof(size));
00093         for (size_t i = 0; i < size; ++i) {
00094             T elem;
00095             file.read(reinterpret_cast<char*>(&elem), sizeof(T));
00096             elements.push_back(elem);
00097             tree.add(elem);
00098         }
00099     }
00100 };

```

4.5 src/main.cpp File Reference

```
#include "BSTTree.hpp"  
#include "FileTree.hpp"  
#include <print>  
#include <iostream>  
#include <string>
```

Functions

- bool [lauf](#) ()
- int [main](#) (int argc, char *argv[])

4.5.1 Function Documentation

4.5.1.1 [lauf\(\)](#)

```
bool lauf ()
```

4.5.1.2 [main\(\)](#)

```
int main (  
    int argc,  
    char * argv[])
```


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