

# Matthew Wilson

RESEARCHER

✉ mattwilsonmbw@gmail.com | 🏠 matwilso.github.io | 📷 matwilso | 🌐 matwilso

## Education

### University of British Columbia

M.S. IN COMPUTER SCIENCE

Vancouver, BC, CA

Sep. 2019 -

### University of Utah

B.S. IN COMPUTER ENGINEERING

Salt Lake City, UT, USA

Aug. 2015 - May 2019 (4 years)

- GPA: 3.82

## Research Experience

### University of British Columbia, Vancouver, BC

GRADUATE RESEARCHER

MOCCA Lab

September 2019 -

- Advisor: Michiel van de Panne

### University of Utah, Salt Lake City, UT

UNDERGRADUATE RESEARCHER

LL4MA Lab

January 2018 - August 2019 (1.5 years)

- Advisor: Tucker Hermans

### Carnegie Mellon University, Pittsburgh, PA

ROBOITCS INSTITUTE SUMMER SCHOLAR (REU)

MSL Lab

June 2017 - August 2017 (3 months)

- Advisors: Ralph Hollis, Jean Oh

## Research Projects

### Learning to Manipulate Object Collections Using Grounded State Representations

Conference on Robot Learning (CoRL 2019) (Oral)

UNDERGRADUATE RESEARCHER, LL4MA LAB

November 2018 - June 2019 (7 months)

- See website: [https://matwilso.github.io/projects/object\\_collections](https://matwilso.github.io/projects/object_collections)

### Sim-to-Real Adaptation via Meta-Learning

GitHub repo

UNDERGRADUATE RESEARCHER, LL4MA LAB

July 2018 - November 2018 (4 months)

- Worked on applying meta-learning to improve performance for simulation to real adaptation in robotics vision tasks
- Successfully reproduced results of domain randomization for object localization as in [Tobin et al. 2017]
- Implemented Model Agnostic Meta-Learning (MAML) and domain randomization to train object localization model to handle greater scene variation (e.g., camera view point and varied table configurations)
- Learned a lot, but unfortunately saw negative results of my approach over a baseline

### Guided Policy Search Reproducing

UNDERGRADUATE RESEARCHER, LL4MA LAB

Jan 2018 - Jul 2018 (5 months, as side-project)

- Adapted Guided Policy Search algorithm code to work on LL4MA Lab KUKA robot in simulation
- Learned about trajectory optimization and model-based reinforcement learning

### Go, Look, and Tell: Natural Language Communication with a Ballbot

Paper | Poster

ROBOTICS INSTITUTE SUMMER SCHOLAR, MSL LAB

June 2017 - August 2017 (3 months)

- Developed system for a user to give natural language commands and ask questions of dynamically balancing mobile robot (Ballbot)
- Integrated vision system, natural language processing via Amazon Echo, world model (database), and mobile robot navigation system
- Communicated work as a paper and poster

## Open Source and Engineering Projects

### Implementation of Model-Agnostic Meta-Learning (MAML) algorithm

[https://github.com/matwilso/maml\\_numpy](https://github.com/matwilso/maml_numpy)

ALGORITHM IMPLEMENTATION

June 2018

- Derived forward and backward passes of MAML (meta-learning algorithm) and implemented them in numpy

## Reinforcement Learning (RL) Implementations

<https://github.com/matwilso/rl-implementations>

ALGORITHM IMPLEMENTATION

Spring 2018

- Implemented deep reinforcement learning algorithms (mainly just REINFORCE) in both numpy and TensorFlow

## Utah Student Robotics Team

[Website](#) | [GitHub](#)

ELECTRICAL & PROGRAMMING TEAM MEMBER

Nov 2015 - Aug 2018 (2 years 8 months)

- Helped design, build, and program robots to compete in NASA Robotic Mining Competition for 3 years of competition
- Started on the mechanical subteam, but contributed most to electrical and software
- Developed simulation of robot for testing, using Gazebo and ROS
- Was software team lead in 2017-18 year and developed low-level motor controller code and autonomy components such as vision system, position controllers for actuators, and finite state machine
- Wrote technical paper on Systems Engineering for NASA competition, getting 3rd and 4th places in 2017, 2018
- Attended outreach events for K-12 students. Talked to kids about robotics and space exploration
- It was all pretty fun

## Writing

### Explanation of Proximal Policy Optimization (PPO) on Stack Overflow

<https://stackoverflow.com/questions/46422845>

STACK OVERFLOW

June 2018

- Wrote explanation of a popular reinforcement learning algorithm, Proximal Policy Optimization (PPO)
- Top answer on Stack Overflow, with 80+ upvotes
- Cited by popular blog post and used in popular YouTube video with 30k+ views

## Honors & Awards

### Presidential Scholarship

*University of Utah*

2015-2019

### Dean's List

*College of Engineering*

2015-2018

### UROP Undergraduate Research Award

*University of Utah*

Summer 2018

**3rd Place / 50**, NASA Robotic Mining Competition (RMC)

*NASA Kennedy Space Center*

May 2018

**3rd Place / 50**, NASA Robotic Mining Competition (RMC)

*NASA Kennedy Space Center*

May 2017

**3rd Place / 50**, Systems Engineering Paper, NASA RMC

*NASA Kennedy Space Center*

May 2017

**Judges' Innovation Award**, NASA RMC

*NASA Kennedy Space Center*

May 2016

**3rd Place**, Hackathon

*HackTheU Hackathon*

Nov 2016