# Definicja równania

$$\frac{d^{2}u}{dx^{2}} = 4 \pi G \rho(x)$$

$$u(0) = -5$$

$$u(3) = -4$$

$$I = [0,3]$$

$$\rho(x) = \begin{cases} 0 & \text{dla } x \in [0, 1] \\ 10^{11} & \text{dla } x \in \mathcal{C} \\ 0 & \text{dla } x \in \mathcal{C} \end{cases}$$

## Sformułowanie słabe

$$\int_{0}^{3} u''v dx = \int_{0}^{34} \pi G \rho(x) v dx$$

$$u'v \partial_{0}^{3} - \int_{0}^{3} u'v' dx = \int_{0}^{34} \pi G \rho(x) v dx$$

$$u'(3)v(3) - u'(0)v(0) - \int_{0}^{3} u'v' dx = \int_{0}^{34} \pi G \rho(x) v dx$$

$$u'(3)v(3) - u'(0)v(0) - \int_{0}^{3} u'v' dx = 4\pi G \left( \int_{0}^{1} \rho(x) v dx + \int_{1}^{2} \rho(x) v dx + \int_{2}^{3} \rho(x) v dx \right)$$

$$u'(3)v(3) - u'(0)v(0) - \int_{0}^{3} u'v' dx = 4\pi G \left( \int_{0}^{10} v dx + \int_{1}^{2} 10^{11} v dx + \int_{2}^{30} v dx \right)$$

$$u'(3)v(3) - u'(0)v(0) - \int_{0}^{3} u'v' dx = 4\pi G \left( \int_{0}^{10} v dx + \int_{1}^{2} 10^{11} v dx + \int_{2}^{30} v dx \right)$$

$$u'(3)v(3) - u'(0)v(0) - \int_{0}^{3} u'v' dx = 4\pi G \int_{1}^{10} v dx + \int_{1}^{2} 10^{11} v dx + \int_{2}^{30} v dx dx$$

$$B(u,v) = L(v)$$

$$B(u,v)=u'(3)v(3)-u'(0)v(0)-\int_{0}^{3}u'v'dx$$
  
$$L(v)=4*10^{11}*\pi G\int_{1}^{2}vdx=k\int_{1}^{2}vdx$$

$$\lambda \left( \sin \right) = -5e_0 - 4e_n$$
  
$$B(w,v) = L(v) - B\left( \frac{x}{3} - 5 \right)$$

$$B(w,v) = -\int_{0}^{3} u'v'dx$$

$$\tilde{L}(v) = k \int_{1}^{2} v dx - 5B(e_{0},v) - 4(e_{n},v)$$

#### Parametry obliczeń

N = 20 # liczba elementów
left, right = 0.0, 3.0 # zakres
m = 1000 # liczba punktów użyta podczas wyliczania całek

#### Kod początkowy

import numpy as np
import matplotlib.pyplot as plt

k = 4 \* np.pi \* 6.67259
n = N # liczba elementów podprzestrzeni, po uwzględnieniu warunków
brzegowych
w = (right - left) / (n+1) # szerokość elementu

## Elementy skończone

$$e_{i} = \begin{cases} x - \frac{(p_{i} - p_{i-1}) * 1}{p_{i} - p_{i-1}} & \operatorname{dla} x < p_{i} \\ x - \frac{p_{i} * - 1}{p_{i} - p_{i-1}} & \operatorname{dla} x > \dot{c} p_{i} \end{cases}$$

def e(center, w, first=False, last=False):

a = 1/wf = lambda x: (x - (center - w)) \* a if x < center else (x - center) \* (-a) + 1

if first: return (lambda x: 0.0 if x < center or x > center + w else f(x))

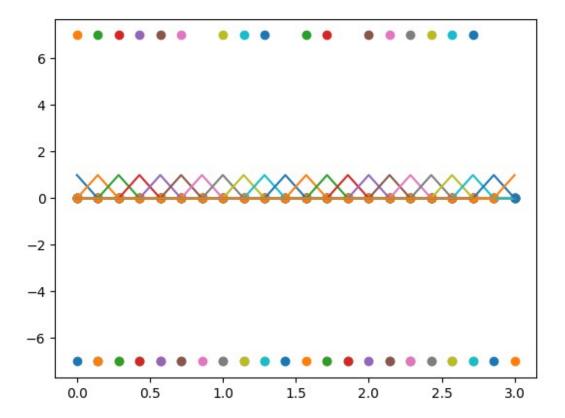
elif last:
 return (lambda x: 0.0 if x < center - w or x > center else
f(x))

return (lambda x: 0.0 if x < center - w or x > center + w else f(x))

# Pochodne elementów skończonych

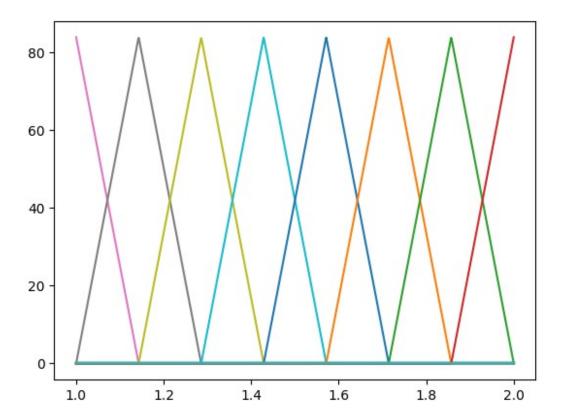
$$e'_{i} = \begin{cases} \frac{1}{p_{i} - p_{i-1}} & \text{dla } x < p_{i} \\ \frac{-1}{p_{i} - p_{i-1}} & \text{dla } x > \lambda p_{i} \end{cases}$$

```
def de(center, w, first=False, last=False):
     a = 1/w
     f = lambda x: a if x < center else -a
     if first:
          return (lambda x: 0.0 if x < center or x > center+w else f(x))
          return (lambda x: 0.0 if x < center-w or x > center else f(x))
     else:
          return (lambda x: 0.0 if x < center-w or x > center+w else
f(x)
B(u, v)
def b(up, vp, m, left=0, right=3):
     xs = np.linspace(left, right, m)
     ys = np.array([up(x)*vp(x) for x in xs]).reshape(1, -1)[0]
     b = np.trapz(ys, x=xs)
     return -b
g(x)
\frac{d^2u}{dx^2} = 4\pi G \rho(x)
u(0) = -5
u(3) = -4
I = [0,3]
\rho(x) = \begin{cases} 4\pi G \rho(x) * 10^{11} & dla x \in   \\ 0 & dla x \notin   \end{cases}
def g(x):
     if x > 1 and x \le 2:
          return k
     else:
          return 0
Matrix of b_{i,j} = B(e_i, e_j)
xs = np.linspace(0, 3, N + 2)
dV = np.array([de(xs[i], w, i==0, i==n-1) for i in range(0, N+2)])
V = np.array([e(xs[i], w, i==0, i==n-1) \text{ for } i \text{ in } range(0, N+2)])
for i in range(n+2):
     plt.plot(xs, [V[i](x) for x in xs ])
     plt.scatter(xs, [dV[i](x) for x in xs ])
plt.show()
B = [[b(dV[i], dV[j], m) \text{ for } i \text{ in } range(1, n+1)] \text{ for } j \text{ in } range(1, n+1)]
n+1)]
```



```
Vector of l_i = L(e_i) + 5B(e_0, e_i) + 4B(e_n, e_i)
\tilde{L}(v) = k \int_1^2 v \, dx + 5B(e_0, v) + 4B(e_n, v)
\text{def l(v, m):} \\ \text{xs = np.linspace(1,2,m)} \\ \text{ys = np.array([v(x)*k for x in xs]).reshape(1, -1)[0]} \\ \text{i = np.trapz(ys, x=xs)} \\ \text{plt.plot(xs, ys)} \\ \text{return i}
L = \text{np.array([l(V[i], m) + 5*b(dV[0], dV[i], m) + 4*b(dV[n+1], dV[i], m)} \\ \text{for i in range(1,n+1)]}
```

plt.show()



```
Kalkulacja wektora u_i
Bm = np.matrix(B)
Bmi = Bm.getI()
Lm = np.matrix([L]).getT()
U = np.array(Bm * Lm).reshape(1, -1)[0]
print(Bm)
print(Bmi)
print(Lm)
print(U)
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[-4.91100842e+02 2.46836025e+02
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                                 4.23032471e+01 0.00000000e+00
  0.00000000e+00 0.0000000e+00
                                 0.00000000e+00 -3.86709773e+021
Prezentacja funkcji u(x)
u = lambda x: sum([U[i] * V[i](x) for i in range(n)]) - 5 * V[0](x) -
4 * V[n+1](x)
xs = np.linspace(0, 3, 100)
ys = np.array([u(x) for x in xs]).reshape(1, -1)[0]
# plt.scatter
plt.plot(xs, ys)
ys = plt.gca()
ys.set ylim([-100, 100])
plt.savefig('plot n'+ str(N) +'.png')
plt.show()
```

