Estimating changes in temperature distributions in a large ensemble of

climate simulations using quantile regression

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ABSTRACT

Understanding future changes in extreme temperature events in a transient climate is inherently challenging. A single model simulation is generally insufficient to empirically characterize the statistical properties of the underlying physical processes governing the climate. Ensembles of repeated simulations (with different initial conditions providing independence) greatly expand the amount of data available, which in turn allows new approaches for characterizing changes in extremes. We present here one such new approach, using ensembles that allow characterizing changes in temperature distributions using a continuous representation of seasonality rather than breaking the dataset into seasonal blocks. That is, we assume that temperature distributions evolve smoothly both day-to-day over an annual cycle and year-to-year over longer secular trends. To demonstrate our method's utility, we analyze an ensemble of 50 simulations of the Community Earth System Model (CESM) under a scenario of increasing radiative forcing to 2100, focusing on North America. The results both confirm aspects of climate system behavior known from previous studies and also elucidate new features. Confirming results include that daily temperature bulk variability generally decreases in wintertime in the continental mid- and high-latitudes ($>40^{\circ}$). One new result is that these same wintertime distributions, the low tails "stick", i.e. experience a lesser reduction in variability, producing a more negative skew. Although the examples above concern temperature only, the technique is sufficiently general that it can be used to generate precise estimates of distribution changes in a broad range of climate variables by exploiting the power of ensembles.

1. Introduction

ness inherent in the underlying physical processes, which we call natural variability, and climatic trends, e.g. in the form of forced secular trends that follow from increasing concentrations of greenhouse gases or seasonal trends. Recently, the degree to which natural variability may itself be changing has received significant scientific interest (e.g. Trenberth 2011; Donat and Alexander 2012; Deser et al. 2012a; Thompson et al. 2015; Kay et al. 2015). Potential changes in climate extremes, because of their heightened societal impacts, are of special concern (e.g. Davison and 39 Smith 1990; Stott et al. 2004; Chavez-Demoulin and Davison 2005; Eastoe and Tawn 2009; Otto et al. 2012; Swain et al. 2014; Singh et al. 2014; Trenberth et al. 2015; Diffenbaugh et al. 2015; Huang et al. 2015a; Jalbert et al. 2017). However, fully characterizing this evolving natural variability of rare events is intrinsically challenging due to the limited amount of available observations or simulation data. The long equilibration time of the climate system means that on the timescales of interest to human society, the climate state will be evolving, so that its statistical properties are not stationary. Studies of future climate extremes often employ statistical extreme value theory to make inferences about rare events with modest amounts of data (Swain et al. 2014). 47 In this work, we study the entire distribution of temperatures in a transient climate, including 48 rare events, by employing quantile regression on an ensemble of simulations of an identical forcing scenario from a single climate model. Given sufficient care in choosing different initial conditions, 50 such a large ensemble will reflect the natural variability of the system, since each simulation will be 51 statistically independent in terms of its natural variability. The increased data provided by multiple simulations then admits more confident statements about changes in the statistical behavior of the system than can be made with a single simulation. While the use of ensembles is a relatively recent

Climate time series have generally been assumed to be separable into two components: random-

development, it is growing rapidly (e.g. Deser et al. 2012b,a, 2014; Fischer and Knutti 2014; Kay et al. 2015; Sriver et al. 2015; Rodgers et al. 2015; Hagos et al. 2016). Deser et al. (2012b),

Deser et al. (2012a) and Fischer and Knutti (2014) in particular discuss how ensembles help in distinguishing internal climate variability from anthropogenic effects and allow more accurate estimates for the forced model response.

Ensembles of multiple simulations offer at least three advantages that are currently under-60 exploited. The most obvious advantage is that the increased data volume allows examining the entire distribution of a climate variable. Studies of climate variability to date are generally divided between those that address the center of the distribution (e.g. Semenov and Bengtsson 2002; Räisänen 2002; Kitoh and Mukano 2009; Screen 2014; Schneider et al. 2015), and those that address its tails (e.g. Katz and Brown 1992; Meehl et al. 2009; Northrop and Jonathan 2011; Davison et al. 2012; Huser and Davison 2014; Trenberth et al. 2015; Huang et al. 2015b; Jalbert et al. 2017), generally via extreme value theory. A more limited body of studies address overall distributional changes in climate variables, but these generally focus on observations or observation-based data products, which are necessarily limited in terms of data amount and therefore require spatial or temporal aggregation (Donat and Alexander 2012; Stainforth et al. 2013; Chapman et al. 2013; Huybers et al. 2014; McKinnon et al. 2016; Rhines et al. 2017). Aggregating data spatio-temporally requires stationarity assumptions of the signal or explicitly modeling 72 the spatio-temporal dependence. When studying model projections using ensembles, the large amount of data at each location allows us to accurately estimate changes in the distribution of climate variables (e.g. temperature) without spatial aggregation. 75

A second potential advantage provided by data-rich ensembles is that trends in both means and variability need not be modeled as linear in time (Franzke 2015; Gao and Franzke 2017). Typically, analyses assume linear trends, but in realistic scenarios, forcings are not linear over centennial timescales, and a linear approximation can be misleading (see for example Poppick et al. 2017). The increased data provided by ensembles means that we can consider more flexible statistical models to better represent complex climate responses. As we will show, distributions of daily temperature evolve nonlinearly, and follow different trajectories even as a function of quantiles (i.e. different parts of the distribution). Analysis methods should therefore be able to take into account nonlinearities both in time and across quantiles.

Finally, a third advantage of ensembles is that they allow a more natural treatment of seasonal variation in climate variables. In situations of limited data, it is standard practice to treat seasons separately, assuming that each season has a temporally constant average and stationary statistical properties discontinuous from neighboring seasons. With ensembles of simulations, we can allow for a smooth change in the underlying trend from day to day, using a parsimonious set of parameters. By modeling the entire year on a continuum, we can explore how each season transitions to the next and how seasonal patterns change over time, features that may be highly dependent on both geographic location and quantile.

We describe here a methodology for exploiting ensembles to study changing climate variability that captures these advantages: we model the complete distribution of daily temperatures as a continuous function of both seasonality and secular climate change over time. Although the methodology is applied to temperature here, it is general and can be applied to other climate variables of interest. We also show how such an ensemble-based approach is well-positioned for the purposes of uncertainty quantification. Because each simulation is treated as an independent sample drawn from the ensemble of simulations, we circumvent the issue of dependency within each simulation. We can therefore obtain uncertainty quantifications for all estimates by resampling complete simulations from the ensemble.

In the sections that follow, we describe estimated changes in both bulk and tail variability as 102 differences in two quantiles; a large quantile difference implies more variability in a given region 103 of the distribution. When those quantiles lie in the high or low tails, the quantile difference is a 104 measure of the spread or thickness of the tail. Figure 1 gives a pictorial explanation of how quantile 105 differences reflect bulk and tail variability. Although the estimated model is seasonally continuous, we also present results assuming seasonally constant conditions, and show that the seasonal effect 107 on temperature can indeed be explained with a reasonably smooth function. When applied to 108 model runs of a realistic future climate scenario, results reproduce some well-understood changes (e.g. strong reduction in wintertime variability at continental mid-latitudes) and produce some new 110 insights (e.g. strong changes in skewness driven by low tail behavior).

112 **2. Data**

We apply our algorithm to an ensemble of 50 historical/future simulations of the Community
Earth System Model (CESM) (Sriver et al. 2015). The atmospheric component is the lowresolution Community Atmosphere Model version 4, with T31 spectral resolution ($\sim 3.75^{\circ} \times 3.75^{\circ}$) and 26 vertical levels. The model ocean component is the low-resolution version of the
Parallel Ocean Program version 2 (Smith et al. 2010) with a nominal horizontal grid resolution of
3°, augmented to approximately 1° at the equator. The ocean model contains 60 vertical levels,
down to a maximum depth of 5,500 m.

The ensemble is especially appropriate for the purpose of studying variability because it is based on a $\sim 10,000$ year pre-industrial control simulation. After a ~ 4000 year spin-up using constant preindustrial conditions, 50 historical hindcasts (1850-2005) are initialized from snapshots of the coupled model state taken every 100 years, so that the last hindcast is initialized after approximately 9000 years of the control simulation. Each hindcast is then extended to 2100 using the

Representative Concentration Pathway (RCP) 8.5 scenario. The 100-year gap between each new initialization ensures nearly independent ensemble members that fully capture internal variability within the coupled system. RCP8.5 corresponds to anthropogenic radiative forcing of roughly 8.5 W m⁻² by 2100 (Moss et al. 2010). More information about the model and ensemble design can be found in Sriver et al. (2015).

trends in means), but also to some extent the higher-order moments of the temperature distribution,
e.g. variance and skewness. Known model biases include reduced ocean heat transport, low north
Atlantic sea surface temperature, and excessive northern hemisphere sea ice (Shields et al. 2012).
The model generally underestimates both temperature and precipitation extremes compared with
observations, i.e. the mean of the extreme value distributions is biased, but the scale and shape are
consistent with observations for the continental United States (Sriver et al. 2015).

To evaluate whether the CESM simulations provide sufficiently realistic temperature distribu-137 tions for the purpose of this analysis, we compare CESM temperatures with those from the ERA-Interim (European Reanalysis) data product (Dee et al. 2011). Figure 2 shows the model/reanalysis 139 comparison for winter; for summer see Supplementary Online Material Figure S1. The model un-140 derestimates variability in some places, and produces excessively cold winter temperatures in the Arctic. The resulting exaggerated temperature gradients contribute to excess variability and ex-142 cessively negative skew in the northern mid-latitudes. Skewness is proportional to the cube of 143 temperature after subtracting off the average seasonal temperature; see Appendix A1. Throughout this work, we will show in-depth analysis from three locations with distinct temperature distri-145 butions to highlight our proposed method (a, b, and c shown in Figure 2). See Supplementary 146 Online Material Figure S2 for comparison of model and reanalysis temperature distributions in both summer and winter for these locations.

149 3. Methods

In the methodology presented here, we model temperature at each location as a function of both 150 seasonality and long-term change of the annual temperature distribution. We use two independent 151 variables, with seasonality represented by a variable d, the day of the year (spanning values 1 152 to 365), and change in annual temperature represented by a variable t, years elapsed since 1850 153 (spanning 0 to 250 for these scenarios). We thus assume that each temperature quantile can be described by two sets of basis functions that represent the two variables' independent relation-155 ships with temperature (called here $\{f_i(d)\}\$ and $\{g_j(t)\}\$), and interaction terms $h_i(d)s_j(t)$, where 156 f_i, g_j, h_i , and s_j are all smooth functions of the appropriate variable. The interaction terms are 157 required to capture effects in which long-term temperature evolution differs between seasons, e.g. 158 the robust projection that winter temperatures warm more than summer temperatures. To impose 159 our smoothness condition, we assume that f_i, g_j, h_i , and s_j are piecewise cubic polynomials with a continuous second derivative, also called splines. (For a review of cubic polynomial basis func-161 tions, see Hastie et al. 2009, Chapter 5.) Because the seasonality variable d is periodic, its basis 162 functions are also assumed periodic. For more details, see Appendix A2a.

We choose the number of basis functions by evaluating a metric representing model adequacy.

Our model sufficiency criterion is aimed at capturing the long term underlying signal. We do not require estimated quantile functions to capture transient events during the historical period like volcanic eruptions. Details on how we select the number of basis functions is given in Appendix A2b. In our climate simulation output, the intra-seasonal effect requires more detailed modeling than the inter-seasonal effect. In the results shown here, we fit the model with 15 terms (that is, basis functions) for the main seasonal effect $\{f_i\}$, but the interaction terms require less seasonal complexity, so we use only 3 terms for $\{h_i\}$. We use 4 terms for both the temporal change $\{g_j\}$

and the interaction terms $\{s_j\}$. That is, modeling long-term change generally requires fewer terms than modeling seasonality. In summary, we use 32 basis functions in total including an intercept term. We then fit each q quantile of temperature

$$T_{q}(d,t) = \alpha + \sum_{i} a_{i} f_{i}(d) + \sum_{j} b_{j} g_{j}(t) + \sum_{i,j} c_{i,j} h_{i}(d) s_{j}(t),$$
(1)

where all of the coefficients depend on q but we suppress the dependence for convenience. This

fit determines coefficients a_i , b_j , $c_{i,j}$ for each quantile at each location.

To simplify notation, we construct a matrix X where each column contains a basis function and each row refers to a unique value of d and t. Using this matrix, X, we construct our temperature model in vectorized form,

$$T_q = X\beta_q, (2)$$

where β_q contains the basis coefficients $a_i, b_j, c_{i,j}$. The predictor matrix X will have 32 columns, each corresponding to one basis function, and $365 \times 250 \times 50$ rows, where each row is a daily average temperature. Similarly, β_q will be a 32-length vector. To get a confidence interval around T_q , we re-estimate the coefficients, β_q , using a resampled data set. Because we have 50 simulations we resample the data by drawing whole simulations from our ensemble of 50 simulations. By resampling complete realizations, the dependency structure within realizations is maintained in the resampled data. Thus, repeating this resampling and re-estimation procedure 100 times yields pointwise confidence bands around each estimated T_q . Appendix A2c provides further details about uncertainty quantification.

As an example of a typical model fit, we show in Figure 3 the seasonal cycle in CESM daily temperatures for three locations, along with estimates of low, median and high quantiles. We show here data from 1850 to demonstrate the seasonal fit rather than that of the long-term trend. All locations show strong seasonal differences in variance that are well-represented by our smooth

estimates. Relevant features that are captured include an asymmetrical seasonal cycle in all locations; a clear left skewness in wintertime in all three locations (although most pronounced in the
higher-latitude **a** and **b**); and a distinct springtime shoulder in the higher-latitude locations. These
characteristics show the benefit of explicitly modeling seasonal variations as smoothly varying
functions as opposed to a set of four constant functions changing value with season. Nuances
like the decrease in winter temperature spread (variability) from early to late winter would not be
captured by a piecewise constant model.

200 4. Results

To facilitate comparison to previous studies, we first perform a preliminary analysis where we 201 replicate more standard methods. That is, we examine changes in the aggregate distribution of 202 temperatures over multi-week and multi-month intervals, before we show results from our new approach that calculates responses for individual days. Even the standard analysis readily shows 204 that temperature distributions in the CESM ensemble change over the RCP 8.5 scenario (Figures 205 4, 5, and 6, which compare the initial and final time windows 1850-1864 and 2086-2100). Means uniformly shift warmer, but the shapes of the distributions also change in terms of variance and 207 skewness. Figure 4 shows initial and final distributions in our example locations for aggregated 208 15-day periods in winter and summer. In at least two of the three depicted locations, it is clear that the distributions are becoming narrower, although quantifying exactly how the tails are changing 210 requires a quantification of the tail size and shape. 211

Regarding the spatial characteristics of temperature distributions, we see the expected strong decrease in variance in winter over land, especially in the northern mid-latitudes (Figures 5 and 6).

By contrast, summer variance changes are much smaller and differ in sign in different locations.

Temperature skewness, i.e. the asymmetry of the distribution, shows strong changes in winter

over land in a dipole pattern. Winter temperature distributions are in all time periods negatively
skewed throughout most of the domain, but in the north (including locations **a** and **b**), they become
more negatively skewed in the future, while in the south (including location **c**), they become more
symmetric. Summer skewness changes are again smaller and with less spatial coherence, other
than the strong transitions in the Southern Great Plains and in Mexico/Central America, where
skewness in temperature distributions actually changes sign.

With a smooth estimate of quantiles of average temperature, we show that the onset of spring, as 222 measured by the first day of the year where the .5 quantile estimate reaches -2.2° C (Pearse et al. 2017), occurs earlier in the year as the climate warms in the Detroit area (see Figure 7). The lower 224 quantiles seem to be progessing faster than the .5 quantile, with the .25 quantile hitting the -2.2° C mark at a rate of approximately 15 days earlier per decade at present times. Note also that the .5 quantile never goes below the threshold after year 2080. It is unclear how to produce the equivalent 227 results using existing methods of segmenting average temperature into seasons. For instance, if we 228 were to look at quantiles of average temperature during winter the edges of the season would pull the overall quantile estimates up and prematurely estimate the onset of spring. Moreover getting 230 information regarding the average temperature of a specific day would be impossible with seasonal 231 averaging. 232

Our methodology for quantile estimation provides additional information that helps to quantify how temperature distributions are changing and to estimate the uncertainty associated with each change. We can evaluate not only bulk variability – the interquartile range (IQR), the difference between the 0.25 and 0.75 quantiles – but differences between any two quantiles. We therefore evaluate the difference between two low or high quantiles, denoted Δq_{low} and Δq_{high} , which measure tail variability in the same way that interquartile range measures the variability of the bulk distribution. If the skewness of a distribution changes over time, then future distributions are not simply scaled versions of present distributions. That is, their tail variabilities must change differently than does the IQR. In the case of the northern mid-latitudes winter temperatures shown in Figure 5, where distributions become more negatively skewed as bulk variability decreases in the future, the effect could result from either/both a low tail contracting less than the bulk (or actually increasing), or a high tail contracting more than the bulk. Our methodology allows readily differentiating these cases.

To assess whether the high tail and/or the low tail is driving changes in skewness, we consider the fractional changes in low, high, and bulk variability. If we denote the initial and final quantile difference as $\Delta q_{q,i}$ and $\Delta q_{q,f}$ at the q quantile, the temporal change in quantile differences relative to the initial year is then

Because we model the complete temperature distribution for each day of the year for all years,

we choose a representative day to understand winter and summer changes (Jan 1 and July 5,

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$$\rho = \frac{\Delta q_{q,f} - \Delta q_{q,i}}{\Delta q_{q,i}}.$$
(3)

respectively), and consider the difference between the beginning and end of the scenarios, the years 1850 and 2000. For these representative days, we show in Figure 8 the fractional variability 253 changes of ρ for low and high tails as well as the IQR. 254 Results show that tail changes can indeed differ strongly from changes in the bulk of the distribution. In wintertime (Figure 8, top row), in much of the northern mid-latitudes (including locations 256 **a** and **b**), low tails change in a way that contributes to a more negative skew. Low tail variability 257 contracts less than does the IQR, while high tail variability contracts more strongly. (High tails would contribute to more negative winter skew predominantly in the Hudson Bay region, where 259 the model shows distinct bias.) In summertime (Figure 8, bottom row), the high tail dominates the 260 transition to positive skew in the Southern Great Plains region (including location c).

To clarify the relative contributions of high and low tails to skewness changes, we also examine 262 evolving temperature variability in the bulk and tails as a function of seasonality as well as long 263 term change. Figure 9 shows absolute variability changes for the three example locations a, b, 264 and c estimated using our quantile model, and for fractional changes see Supplementary Online Material Figure S6. The uncertainty around our estimates is quantified by resampling the original simulations (with replacement) and recomputing the estimates using this new set of simulations 267 (see Appendix A2c for details). In all locations, wintertime skewness changes are driven by the 268 relative changes in IQR and low tails. In the higher-latitude locations **a** and **b**, more negative winter skew results because the IQR contracts even more strongly than does the low tail variability. In 270 other words, the low tails "stick". In the lower-latitude location c, more positive winter skew results because the IQR barely changes while the low tail variability contracts strongly.

The complexity of the relationships in Figure 9 also shows how misleading it may be to use a
three-month block to represent a season. While all three locations show larger IQR in winter than
summer, the transition from winter to summer happens more quickly in some locations than at
others, more abruptly in the northernmost location **a** and more gradually in **c**. Low-tail variability
seasonal transitions are even sharper than those of IQR in **a** and **b**, but more gradual in **c**. In
contrast, high-tail variability is more seasonally constant overall than low-tail variability. Through
these examples, we see how our method offers detailed information about changes in variability
across seasons and annual change, usually unavailable when analyzing each season separately.

similar in-depth examination of changes in model temperature distributions at all locations within
North America, available at https://matzhaugen.com/links.html. The application allows the user to

While we show only three locations in the text here, an online interactive application allows

year and quantile difference. We include temperature histograms of the first and last simulation
year for the designated location, as well as maps that show the variability change spatially.

5. Conclusions

We present a method to quantify changes in tail variability of temperature with high precision 288 in a transient climate model. Using data from the whole year and the whole span from 1850-2100 289 we estimate temperature quantiles as a function of seasonality and long term change. Analyzing 290 the whole year simultaneously as opposed to analyzing each season separately allows for more 291 flexible modeling of seasonality. The large ensemble makes it possible to fit such models stably. By resampling entire simulations from the ensemble of climate simulations and recalculating 293 the quantiles, we obtain confidence bands that do not require any assumptions of independence 294 within any one simulation. We show that the smooth quantile estimates are accurate even across small intervals of the domain of the predictors. The fidelity of these intervals serves as a criterion 296 to determine the required complexity in the statistical model. 297

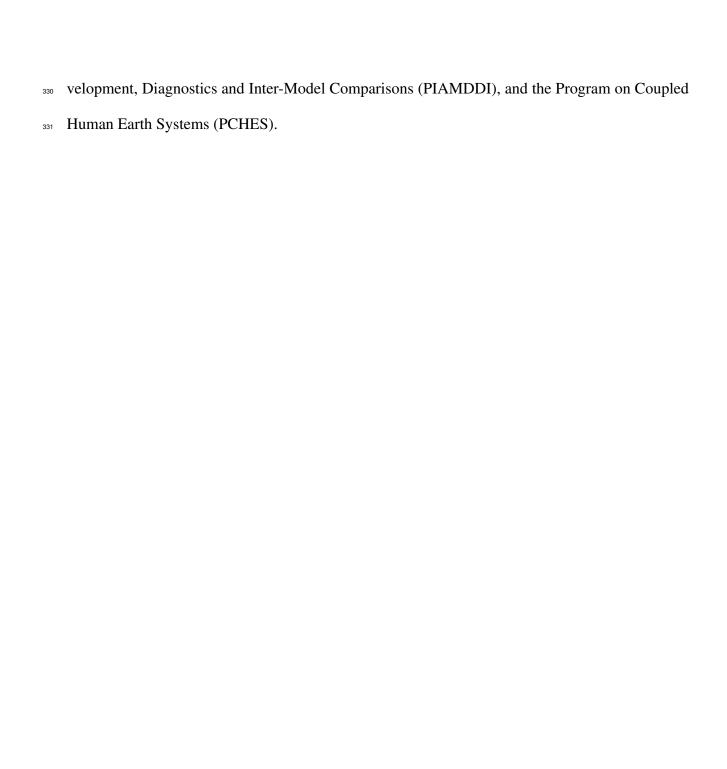
The techniques presented in this study are validated in part by the fact that they replicate several prior conclusions made in the literature, e.g. the well-known projected decrease in winter variabil-299 ity in the northern mid-latitudes (e.g. Schneider et al. 2015) most likely due to amplified warming 300 in the arctic (Screen 2014). Our approach furthermore allows us to quantify tail variability and give corresponding confidence intervals around our estimates. In the case study of CESM runs 302 analyzed here, we relate the changes in tail variability to changes in skewness of the tempera-303 ture distributions, and find that in most of the domain analyzed, wintertime skewness changes are driven largely by the relative behavior of IQR and low tails. For example, in much of the conti-305 nental northern U.S. and Canada, the low tail of temperature contracts substantially less than does 306 the overall temperature variability.

These results may inform physical explanations for the projection that skewness in winter temperature changes in a dipole pattern across North America. It is possible that the skewness change
is a result of a change in the mean location and variability of the mid-latitude jet stream (e.g.
Barnes and Polvani 2013); this possibility may warrant further study.

The abundance of data available in ensemble simulations relative to single simulations allows 312 using quantile regression to accurately estimate high quantiles, avoiding some of the limitations 313 of extreme value theory. Unlike quantile regression, methods using extreme value theory require 314 making assumptions about the shape of the tail of the distribution. By parameterizing the seasonally time-varying distribution of temperature through smooth functions using the whole year as 316 our domain, we also reveal previously unavailable details about seasonal transitions. For example, we show here that springtime variability decreases occur later in the year at lower latitudes, and that seasonal transitions in tail variability differ from those in IQR. While we analyze only tem-319 perature here, our method is intended to be general enough to be applied to other climate variables 320 such as precipitation or humidity. These detailed insights into climate variable distributions may 321 be valuable for risk assessment studies that emphasize extreme events.

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332 APPENDIX

333 A1. Model and reanalysis comparisons

Following the discussion on the paper, we define sample mean, variance and skewness as

$$\bar{x} = \frac{1}{n} \sum_{i=1}^{n} x_i$$

$$s^2 = \frac{1}{n} \sum_{i=1}^{n} (x_i - \bar{x})^2$$

$$\gamma = \frac{1}{n} \sum_{i=1}^{n} \left(\frac{x_i - \bar{x}}{s} \right)^3.$$
(A1)

These definitions are used in Figures 2, 5, and 6 in the main text and in Supplementary Online Material Figures S1 and S2. We plot the standard deviation s rather than the variance s^2 .

337 A2. Model Details

In the following, we first give details regarding the regression of temperature quantiles on a fixed set of basis functions. We then discuss how to select the number of basis functions, through a "sufficiency criterion". Lastly, we describe how we quantify uncertainty in the quantile estimates.

a. Model estimation

Given the number of basis functions in our model, represented by the columns in a matrix X with number of rows equal to the number of observations in the data set, we construct our temperature quantile estimate, \hat{T}_q , and corresponding coefficients, $\hat{\beta}_q$, viz.

$$\hat{T}_q = X\hat{\beta}_q \tag{A2}$$

such that the q^{th} fraction of residuals between the observations T at a particular location and their estimates, $T - \hat{T}_q$, are greater than zero and a fraction 1 - q are less than zero. With the

temperature model in Equation 2, our coefficient vector estimate, $\hat{\beta}$, contains the estimates of $a_i, b_j, c_{i,j}$. Note that the seasonal interaction terms corresponding to the coefficients $c_{i,j}$ are not necessarily the same as the main seasonal terms corresponding to a_i . In fact, we find that fewer seasonal interaction terms are needed to describe the interaction behavior.

Computationally, obtaining the above quantile is equivalent to solving the following optimization problem (Koenker and Bassett Jr 1978),

$$\min_{\beta} \left\{ \sum_{d,t: T(d,t) \geq X(d,t)\beta} q | T(d,t) - X^T(d,t)\beta | \right. \\ \left. \qquad \qquad \sum_{d,t: T(d,t) < X(d,t)\beta} (1-q) | T(d,t) - X^T(d,t)\beta | \right\}, \quad (\mathrm{A3})$$

and can be implemented in either R or MATLAB using existing libraries¹. Because we have access to 50 simulations, each location provides us with $365 \times 250 \times 50$ or approximately 4.5 million observations. Consequently, even fairly high quantiles can be accurately estimated without borrowing data from neighboring locations through a spatial model as done by e.g. Reich et al. (2011). However, making inferences about more extreme quantiles, such as the quantiles .001 or .999, cannot be guaranteed to work as well with our methods.

We do not experience issues with quantile estimates crossing in our study area even though the optimization framework above does not explicitly enforce monotonicity with increasing quantile estimates. The absence of crossing quantiles is likely also due to the large sample size. For strict enforcement of monotonicity in the quantile curves see e.g. Bondell et al. (2010).

¹We use the R library rq and the function rq.fit.pfn, developed by Portnoy and Koenker (1997). Basis functions are created using pbs for periodic spline basis functions and ns for non-periodic splines. The non-periodic splines are constrained to be linear beyond the domain, 1850-2100, and are called *natural splines*.

b. Model selection

We describe our approach to selecting a modest set of basis functions that can accurately represent the temperature data. If the model chosen has too many basis functions we run the risk of overfitting out-of-sample observations. To make sure this does not happen we need a metric to quantify the goodness-of-fit of the model.

Any reasonable temperature model we fit to the data will by definition contain the desired amount of positive and negative residuals *globally* according to the desired quantile q. A more stringent requirement would be that the smooth temperature estimate contains approximately an appropriate fraction of positive and negative residuals on a *daily* basis: for each d and t,

$$S(d,t) = \frac{1}{n} \sum_{i=1}^{n} I\left[\hat{T}_{i}(d,t) - T_{i}(d,t) > 0\right] \approx q,$$
(A4)

where I is the indicator function and n is the total number of samples (i.e. 50 for our CESM ensemble data set). If S(d,t) is close to the value q for each d and t, the model would accurately describe the data and the number of basis functions is sufficient. In reality, we are looking basis functions that obey A4 with d averaged over blocks of days to increase the sample size, e.g. 10 days blocks. It is also not the goal to capture the quantile at too short a timescale as events like volcanic eruptions would interfere with the estimate.

In order to estimate the appropriate number of basis functions, we hold out 5 simulations from the fitting process and use these to calculate our exceedences, which we call $S_{test}(d,t)$. We repeat this 10 times so that all the simulations are eventually held out, giving 10 samples of $S_{test}(d,t)$. As we increase model complexity through degrees of freedom in the basis functions, the variability of S_{test} should reach a minimum when the necessary number of basis functions is reached and the quantile estimate is the same for each time point. If the number of basis functions is increased beyond this point, we start to overfit the data and the out-of-sample variability of S_{test} will increase. To estimate S_{test} , we block the variables in two ways, one for each variable. First, we divide each year in 10-day bins and calculate the average exceedence estimate, \hat{S}_{test} , in each bin. We sum over the whole domain of long term change, t, and a subset of the seasonality variable, d. Specifically, let A be a set of non-overlapping contiguous blocks of days that together cover the whole year, where a_j , j = 1,...,m are the elements of the set. Also let T be the index set for long term change, T = [1850, 2100], measured in years. Then, for all $a_j \in A$,

$$\hat{S}_{test}(a_j) = \frac{1}{n} \sum_{i=[1,n], d \in a_j, t \in T} I\left[\hat{T}_i(d,t) - T_i(d,t) > 0\right]. \tag{A5}$$

To get an equal number of days in each bin we use the first 360 days of the year only.

Second, we divide the long term change variable, t, in bins and repeat the process by flipping the role of the variables in Equation A5 to get a set of $\hat{S}_{test}(b_j)$ with $b_j \in B$, a set of non-overlapping contiguous blocks of long-term change indices in T. An example of the blocked exceedence estimate is shown in Figure 10. Note that the pointwise quantile estimate is contained between the error bars, suggesting that the model is sufficiently complex. The standard deviation of these estimates of \hat{S}_{test} is our measure of exceedence variability. We seek the simplest model that gives good calibration of the quantile estimates (so close to 0.05

in Figure 10). At the same time we have to watch out to not overfit the data so we also want to minimize out-of-sample variability. We find that a model with 15 seasonal, 3 seasonal-interaction and 4 temporal degrees of freedom minimizes the variability of exceedences \hat{S}_{test} , shown in Figure 11, where seasonality has been binned. The out-of-sample fit when binning long-term change is shown in Figure S7 in the supplement. Here, models 4-6 have approximately equal test error, so since binning seasonality suggests the complexity of model 6, we chose model 6 as the overall model. Including the possible interaction terms, the full model has 32 free parameters to be fitted,

or $\hat{\beta} \in \mathbb{R}^{32}$. All model candidates are shown in Table 1. We reach the same conclusion when blocking the long term change, t, and when analyzing different spatial locations (see Figure S7).

os c. Uncertainty Estimation

With a reasonable model chosen through cross-validation, we present a way to quantify its uncer-409 tainty. Because we are using multiple simulations that are assumed independent, we resample entire simulations from the set of 50 simulations. Resampling 50 new simulations with replacement 411 from the original set of simulations yields a new dataset. From the new data set we obtain another 412 temperature estimate with the same model basis functions but different coefficients, β^* . After repeating this resampling and re-estimating procedure 100 times we generate pointwise confidence 414 intervals for temperature quantiles. For example, in Figure 9 we show the 90% confidence interval 415 by selecting the pointwise .05 and .95 quantiles of temperature variability estimates. Because the confidence intervals are quite tight we deem the 100 new estimates (or bootstraps) sufficient to 417 indicate that the results we describe in section 4 are not due to random variation. Larger number 418 of bootstrap replicates might give slightly more accurate intervals but would not change our conclusions. One might also consider fewer simulations as a compromise between computation time 420 and quality of the estimates. Assuming normally distributed confidence intervals, we would expect 421 the standard error to scale as $1/\sqrt{n}$. Thus, if one is willing to widen the confidence intervals by 422 a factor of 2 (approximately) only 10 simulations would suffice. However, one could compensate 423 for this greater variability by using fewer basis functions at a cost, of course, of obtaining less 424 resolved estimates of seasonal patterns and long-term trends in the quantiles.

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554		the same in both the main and interaction terms.	3(

	Seasonal	Seasonal-Int.	Temporal
1	5	3	3
2	7	3	3
3	10	3	3
4	10	3	4
5	12	3	4
6	15	3	4
7	15	3	5
8	15	5	5
9	18	5	5

TABLE 1. Degrees of freedom in the spline basis for each independent variable, with the interaction terms including the reduced set of seasonal polynomials with degrees of freedom listed in the middle column. The temporal polynomials are the same in both the main and interaction terms.

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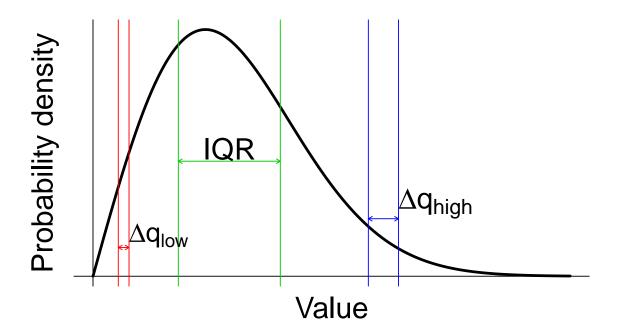


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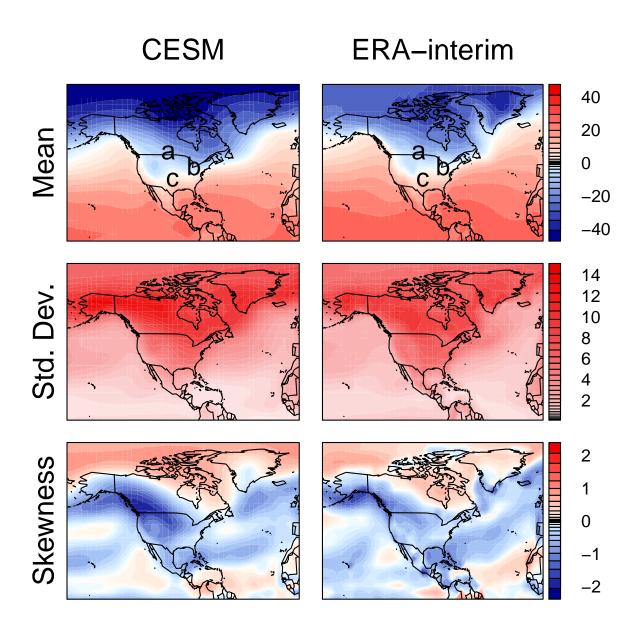


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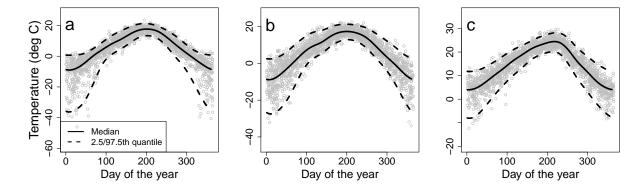


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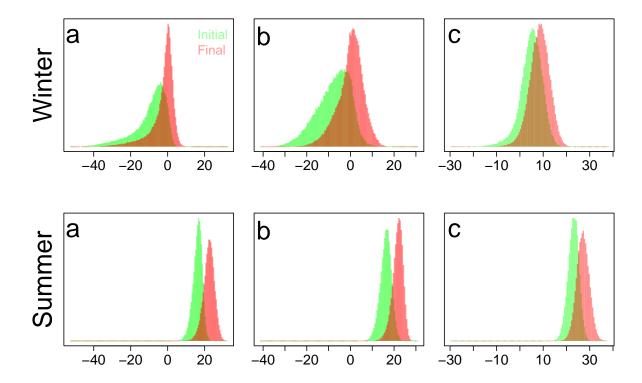


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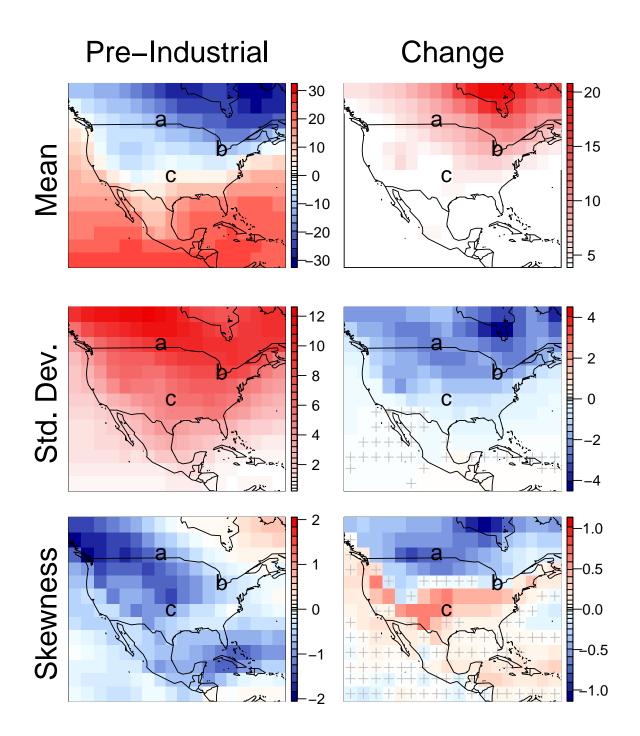


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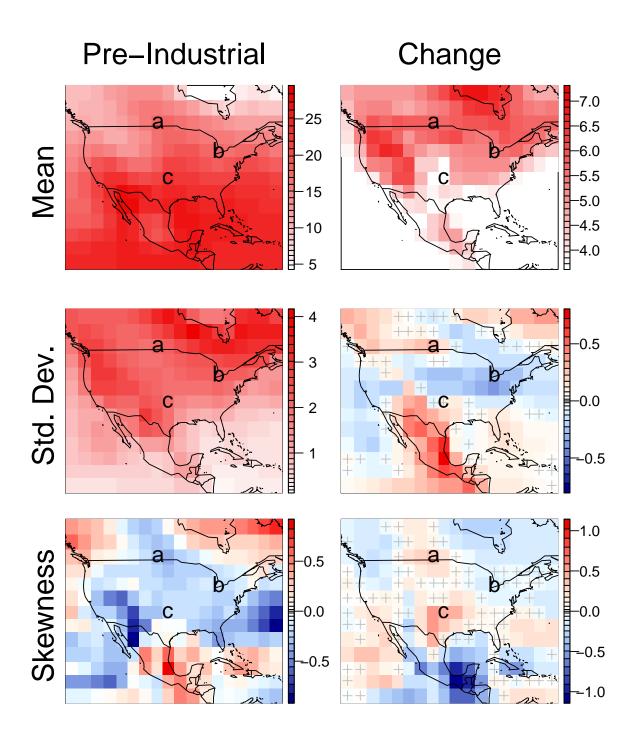


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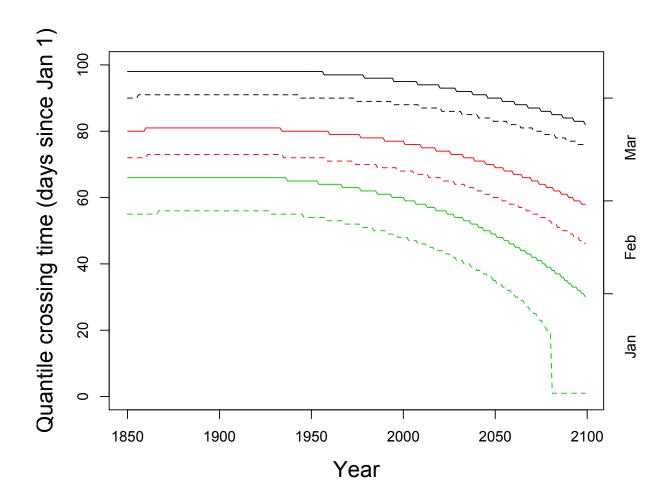


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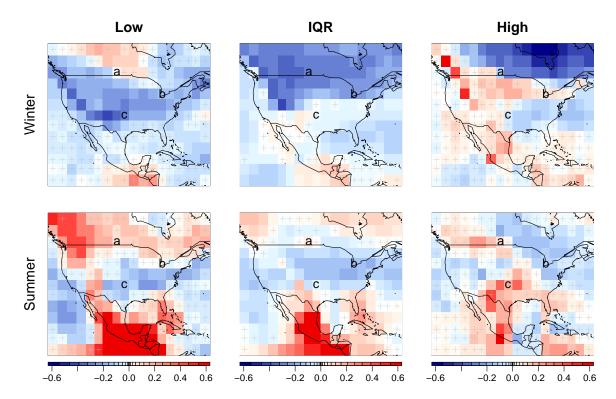


FIG. 8. Changes in daily temperature variability (quantile differences) over time in CESM ensemble RCP8.5 runs estimated using our statistical approach. Because our approach removes the need to aggregate over time when presenting changes, we show here differences in distributions for a single day and year: Jan 1 for winter (top) and July 5 for summer (bottom), with differences evaluated between the years 1850 and 2100. Changes are expressed as fractions of initial variability, so that the value 0 indicates no change with respect to the initial year. Left, middle, and right columns show, respectively, changes in low tail variability, IQR, and high tail variability, as previously defined. Gray crosses mark grid points where the change is less than 3 standard deviations from the original estimate. As expected, estimated changes in IQR (middle) are similar to changes in standard deviation seen in Figures 5 and 6. Changes in tail variability are clearly different from those in IQR, meaning that future distributions are not simply a rescaling of the present-day distributions.

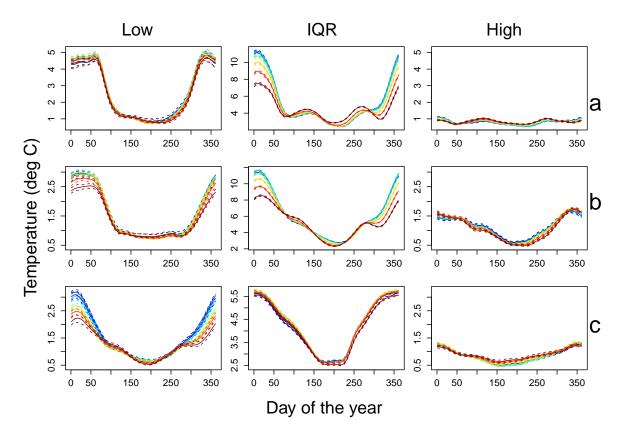


FIG. 9. Evolving daily temperature variability (quantile differences) over time in CESM ensemble RCP8.5 runs estimated using our statistical approach, for locations **a**, **b**, and **c**. Using the analysis described in Figure 8, we show absolute IQR and tail variability as a function of seasonality, with different years (at 40 year intervals) shown as different colored lines, from 1850 (dark blue) to 2090 (dark red). Dashed lines represent pointwise 90% confidence intervals. Note the complexity of seasonal cycles in variability at different locations. These results show that the dipole pattern of changes in wintertime skewness changes seen in Figure 5 is driven by low rather than high tail behavior. In wintertime, in the more northern locations **a** and **b**, IQR reduces more strongly than does low tail variability, making skew more negative. In the more southern location **c**, IQR change is negligible while low tail variability reduces strongly, making skew more positive. In all locations, absolute changes in wintertime low tail variability are larger than changes in high tails. For fractional changes, see Supplementary Online Material Figure S6.

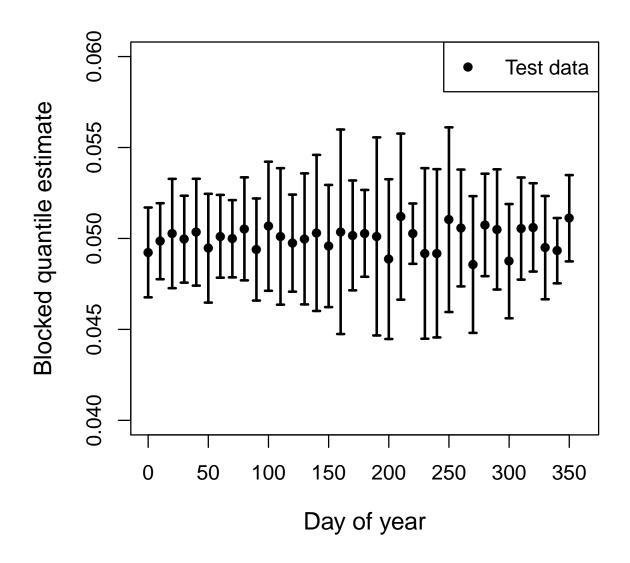


FIG. 10. Exceedence probability of temperature events above the .95 quantile estimate. The density is obtained by making 10-day bins and counting the number of observations that are above the quantile estimate and normalizing by the total number of exceedences aggregated across all model runs. Each bin is represented by the bin start day, i.e. an x-axis value of 0 includes the interval (0,10]. We hold out 10 different sets of simulations to obtain 10 different estimates for each block of time, from which we calculate their mean shown as points and standard deviation shown as error bars around \hat{S}_{test} .

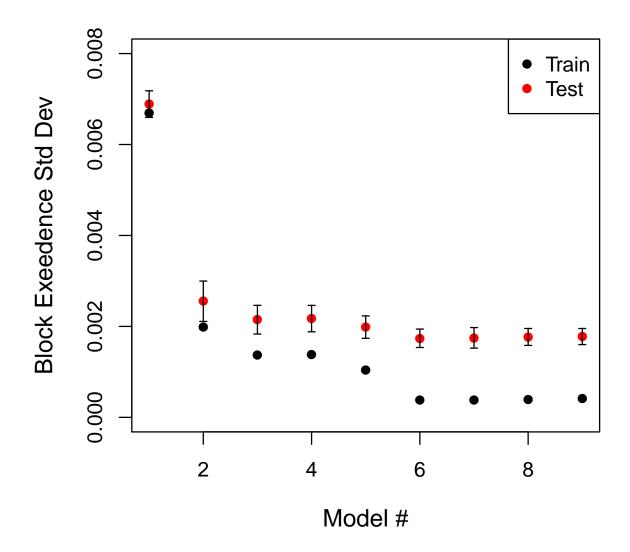


FIG. 11. Training and test exceedence standard deviation as a function of model number, where increasing model number signifies increasing degrees of freedom in the spline basis functions. The data were extracted from the gridbox located at (lat, lon) = (31.5, -93.8). The exceedence is calculated by binning seasonality in 10-day blocks and summing over the long term change.