

$$\sigma_{l+\bar{l}} = A_0 + A_1 P_1(\cos\theta) + A_2 P_2(\cos\theta) + A_3 P_3(\cos\theta) + A_4 P_4(\cos\theta)$$

$$\sigma_{t\bar{t}} = C_0 + C_1 P_1(\cos\theta)$$

$$\sigma_{l\bar{l}} = D_0 + D_1 P_1(\cos\theta) + D_2 P_2(\cos\theta)$$

$$Q^2 = 2.4$$

