GuideDroid: Low Cost Indoor Navigation Assistant for the Visually Impaired

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Abstract

This paper presents an innovative, low cost indoor navigation system for the visually impaired which takes advantage of the emerging communication technology Near Field Communication (NFC). The main idea is to orient users by NFC enabled mobile phones that gathers the current position from NFC tags and tells user the way to follow to reach her desired destination possibly using intermediate checkpoints. The system also provides a collision detection mechanism that warns user for near obstacles. Since it was implemented on Android and behaves like a guide dog, we named it GuideDroid.

Problem statement

Among the many challenges faced by the visually challenged persons are the constraints of independent mobility and navigation in an unfamiliar indoor environment. Finding the location and path to some desired location including public utilities inside the building can be an arduous task. Besides, constant changes in the workplace and on the street offer collision risks much higher than the familiar environment for the visually impaired.

GPS based navigation that is now getting widely used is not feasible in an indoor environment due the weakness of satellite signal. Variety of technologies is tested and new designs are generated for indoor navigation in order to circumvent the lack of excellence.

The existing solutions for indoor navigation systems typically require the use of expensive and heavy sensors, or equipping rooms and hallways with radio-frequency technologies such as A-GPS, Bluetooth, Ultra Wide Band (UWB), Wi-Fi or RFID which are used to determine the user's location and most of them are not suitable for the visually impaired.

Although several attempts have been made at making such indoor navigation systems, none of them have found wide acceptance. There is an opportunity that spreads between different areas such as providing HP mobile devices with embedded assistance features, offering services and products in the via HP eHealth Center and improving the brand image to both external and internal people.

Our solution

GuideDroid was designed to help the visually impaired in their locomotion by unknown places or collision risky environments, keeping in mind to be cheap, easy to use and with a very small investment on infrastructure.

It is accomplished through the extensive use of sensors and location features existing in smartphones and other mobile devices, to assist people in tasks such as locomotion, identification of places and services available, and indoor navigation. The below design requirements were defined according the identified necessities.

**Design constraints**

* Uniformity of the geographic location model (latitude/longitude) to enable integration with existing outdoor navigation systems and its mechanisms.
* Cheap and off-the-shelf components.
* No changes in buildings infrastructure (no wireless network needed).
* Should be useful for both visually impaired or not.
* The user should not be obligated to start the navigation by some initial point; she should be able to start at any point when she feels lost, thus avoiding unnecessary help for well know paths.

Since it is necessary to maintain the same location model (latitude/longitude) widely used in outdoor navigation and indoor GPS signal is insufficient to obtain such information, how to solve the issue?

Our solution is to spread strategically NFC tags inside the buildings, providing their precisely calculated coordinates and thus serving as landmarks for orientation (waypoints) in the same way as an open environment (outdoor). And the existing compass in the smartphones is used to point out the right direction to the user. This is the main aspect of this innovative solution.

**How it works**

The main idea is to guide the user turn-by-turn instructions between waypoints. Let us consider the case where the user needs to reach a particular room in a building unknown. This building is represented in Figure 1.

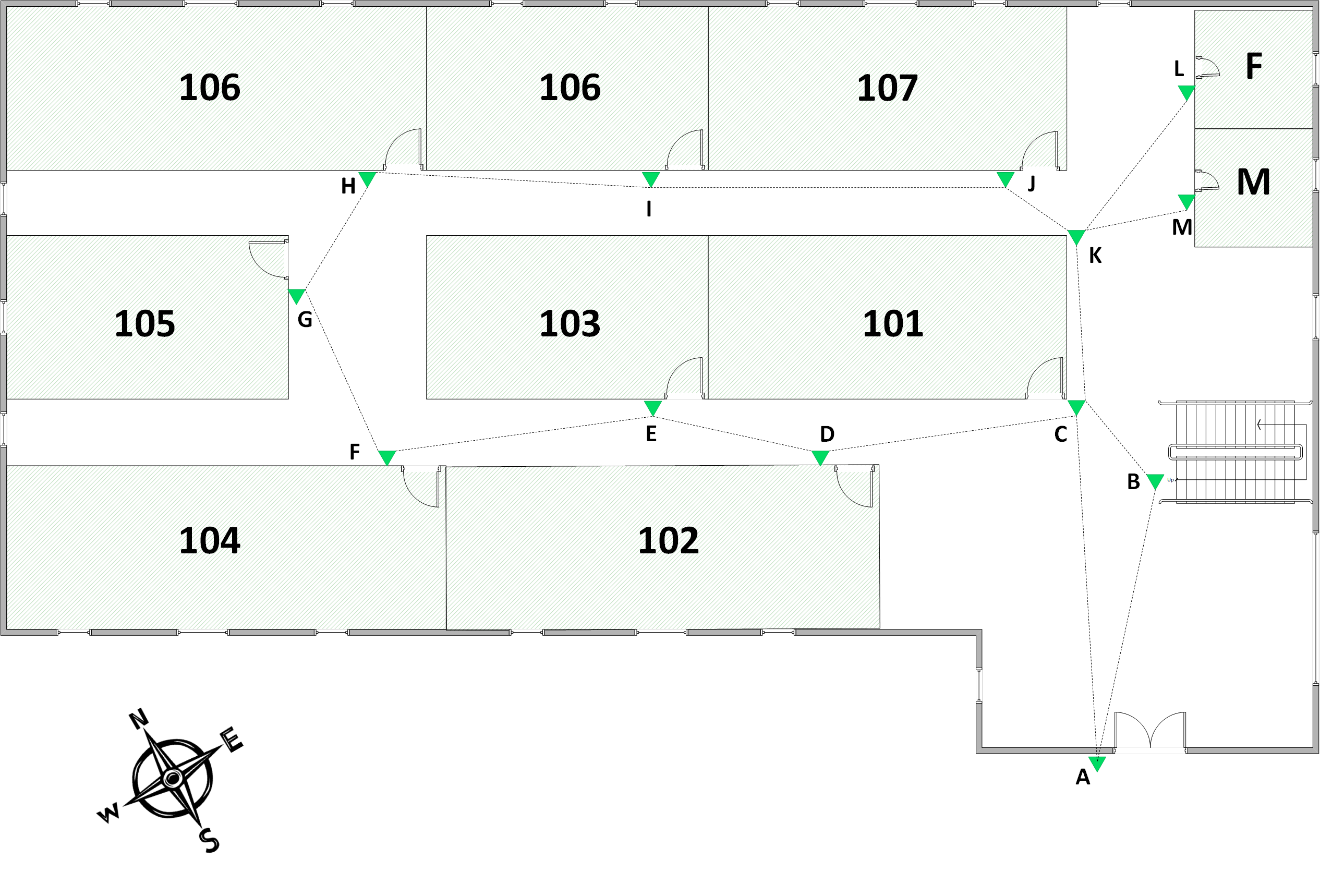
At the entrance door, the user touches with her phone a poster with the NFC tag. Then the detection of a special URL that starts with "guidedroid://" triggers GuideDroid application that identifies the building and then downloads the XML file that describes it. Following, the application asks the user the desired room destination, presenting a list with the names of existing rooms in the building. Once chosen the destination, the application calculates the route using the Dijkstra's algorithm and asks the user to rotate the phone horizontally (see Figure 2) to determine the magnetic orientation of the first stretch of the route. When the magnetic orientation is found, the phone vibrates and announces the distance the user should walk in that direction. At the end of this passage, she will found another NFC tag that corresponds to the destination or an intermediate point (waypoint) where the process is repeated to determine a new stretch.

Figure 1- Navigating with NFC tags

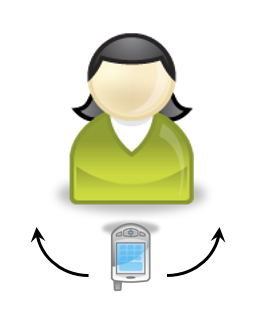
Exemplifying with Figure 1, we assume that the destination is the room 106. The user touches the NFC tag at the entrance with her phone and after any necessary initialization, the application determines the smallest path A, C, K, J, I to reach room 106. Then the user rotates her mobile phone that will vibrate when the direction that points to the tag C is reached and says "walk this direction by 4 meters." When she reaches this new tag C, the process repeats for the section between C and K, and so on until reaching the point I that represents the entrance of the room 106.

Figure 2- Searching direction

This process based on short stretches can be tedious at first, but it need not be repeated every time the user go through this same building. Once she learned the environment, she will only need the ask help to GuideDroid when the route is unknown. Semantically all the NFC tags are equal and the process can start at any of them.

There is also a component that helps the user to avoid collisions by warning her through sound signals (beeps) or pulsed vibrations. This component is made of a ultrasonic sensor that constantly checks the way ahead and will start beeping when some obstacle is detected within the configured range.

Evidence the solution works

The solution is already implemented and available for test and evaluation, currently being in use on some buildings at the site of HP Brazil R&D in Porto Alegre/RS. (falar sobre o aplicativo Android, onde está disponível e também falar sobre o servidor que fornece os arquivos que descrevem cada prédio).

Provide either results from end users of the solution demonstrating that you effectively addressed the original problem, or other convincing demonstrations that the proposal has substantiated merit.

Competitive approaches

Identify other approaches from external literature or HP competitors addressing similar problems. Including comparisons between your solution and theirs (noting both advantages and disadvantages).

Current status

(Aspecto de segurança: as tags contêm identificadores calculados – hash – para o prédio e cada cartaz; suas coordenadas geográficas são fornecidas pelo arquivo XML obtido seguramente do servidor. Isso garante algum nível de segurança contra adulterações das tags pois elas não contém informação que possa ser usada para adulteração, apenas as chaves.)

How far along are you in putting this solution to use in our business? Where might it be by the time Tech Con takes place?

Next steps

(aprimorar as garantias de calibração da orientação magnética – bússola – para evitar erros de orientação; trabalhar mecanismos de segurança que protejam as tags NFC de alteração/apagamento; incrementar as possibilidades de fornecer assistência através da interação entre o aplicativo e o servidor na Cloud; etc.)

What are interesting ways to use this solution in solving real business problems? Where is further work still required?

References

Cite any sources used in generating your ideas or preparing your abstract. You may also include pointers which provide additional background on the problem solved or detail of your solution. However, do not *assume* that reviewers will look at any sources other than the submission itself.