

Hoy: Cómo se usan los cambios de variable (más comunes) para calcular integrales dobles y triples?

Diagram illustrating the change of variables for double integrals. The region  $D$  in the  $xy$ -plane is mapped to the region  $F$  in the  $uv$ -plane via the transformation  $g$ .

The transformation is defined by:

$$\begin{cases} x = g(u, v) \\ y = h(u, v) \end{cases}$$

The transformation  $g$  is labeled as "transformación diferenciable invertible".

The Jacobian determinant is shown as:

$$\left[ \frac{\partial(x, y)}{\partial(u, v)} \right]$$

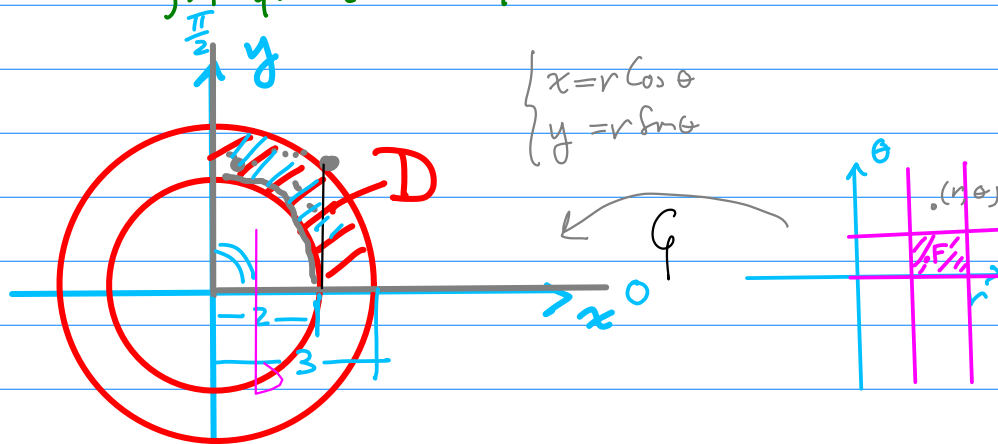
The double integral is transformed as follows:

$$\iint_D p(x, y) dA = \iint_F p(g(u, v), h(u, v)) \left[ \frac{\partial(x, y)}{\partial(u, v)} \right] du dv$$

$$\det \begin{bmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{bmatrix}$$

Teorema (del cambio de variable)

Ejemplo: Un plato tiene forma de un anillo de anillo. Está encerrado por  $x^2 + y^2 = 4$ ,  $x^2 + y^2 = 9$ ,  $x = 0$ ,  $y = 0$  en el primer cuadrante. La densidad (en  $\text{kg/m}^2$ ) del plato está dada por  $\rho(x, y) = x + y$ . Plantee una integral que calcule la masa total.



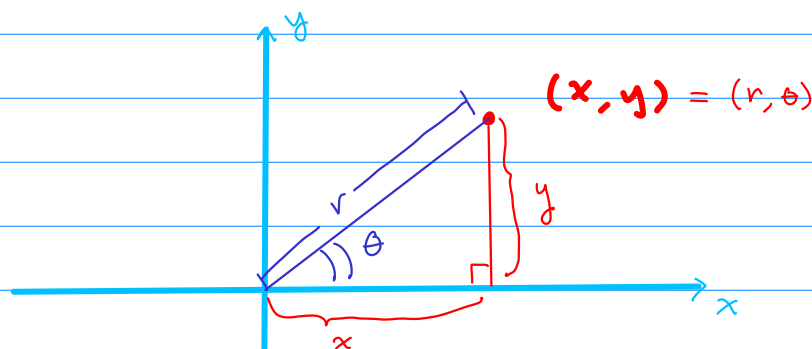
$$M = \iint_D (x + y) dA = \int_0^{\frac{\pi}{2}} \int_2^3 (r \cos \theta + r \sin \theta) r dr d\theta$$

(1) ← FÁCIL

Idea: Usar polares.  $(r, \theta)$

En polares  $F = \{(r, \theta) : 0 \leq \theta \leq \frac{\pi}{2}, 2 \leq r \leq 3\}$

$$D = f(F)$$



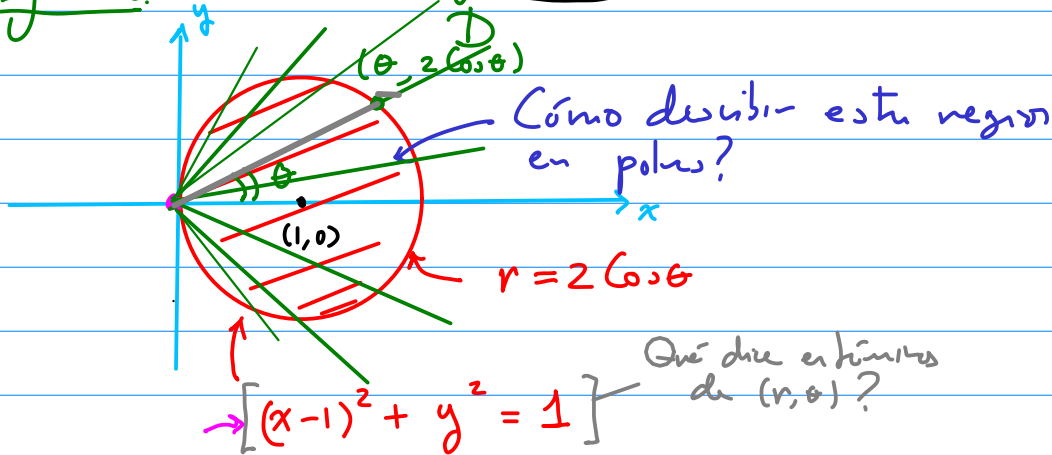
$$\begin{aligned} \cos \theta &\equiv \frac{x}{r} \Rightarrow x = r \cos \theta \\ \sin \theta &= \frac{y}{r} \Rightarrow y = r \sin \theta \end{aligned}$$

en dónde?  $\int \int_D f(x,y) dx dy$

Ejercicio:

Calcule

$$\int \int_D \underbrace{x^2 + y^2}_{r^2} dA \text{ donde}$$



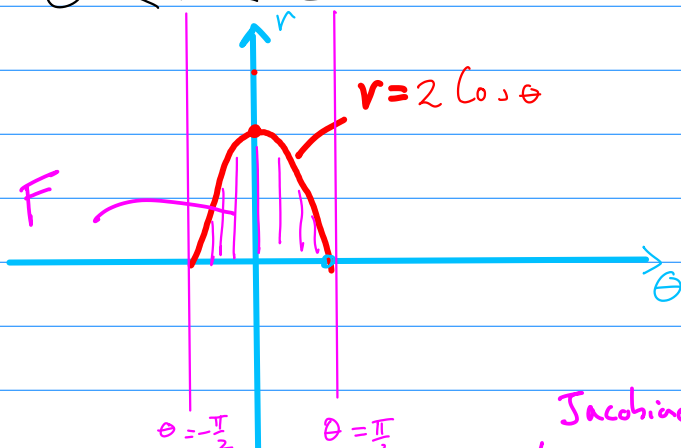
Si  $\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$  la función se vuelve  $x^2 + y^2 = r^2 \cos^2 \theta + r^2 \sin^2 \theta = r^2 (\cos^2 \theta + \sin^2 \theta) = r^2$

$$(x-1)^2 + y^2 = 1$$

$$\begin{cases} (r \cos \theta - 1)^2 + (r \sin \theta)^2 = 1 \\ r^2 \cos^2 \theta - 2r \cos \theta + 1 + r^2 \sin^2 \theta = 1 \\ r^2 [\cos^2 \theta + \sin^2 \theta] - 2r \cos \theta = 0 \\ r^2 - 2r \cos \theta = 0 \\ r [r - 2 \cos \theta] = 0 \Rightarrow r = 2 \cos \theta \end{cases}$$

Concluimos que  $D$  está dada por

$$-\frac{\pi}{2} \leq \theta \leq \frac{\pi}{2}$$

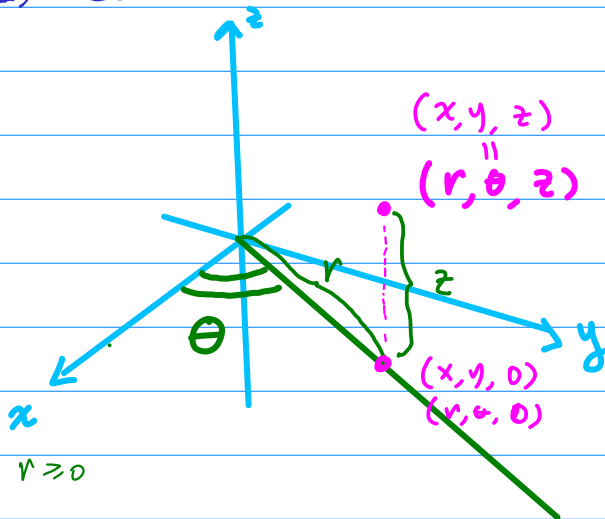
$$0 \leq r \leq 2 \cos \theta$$


$$\int \int_D x^2 + y^2 dA = \int_{-\frac{\pi}{2}}^{\frac{\pi}{2}} \int_0^{2 \cos \theta} r^2 \cdot \underbrace{r}_{\text{Jacobiano}} dr d\theta \left[ \frac{\pi}{2} \right]$$

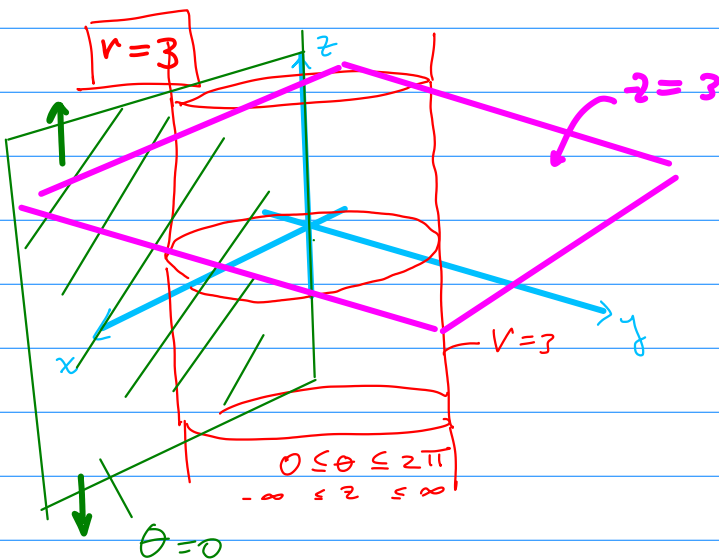
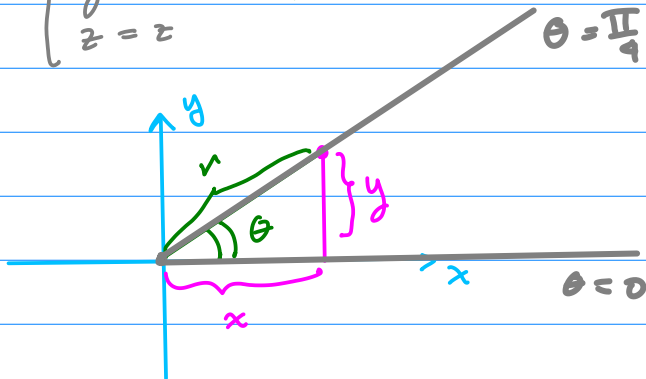
## (2) Sistemas de coordenados en 3D

Hay dos generalizaciones distintas, de coords polares

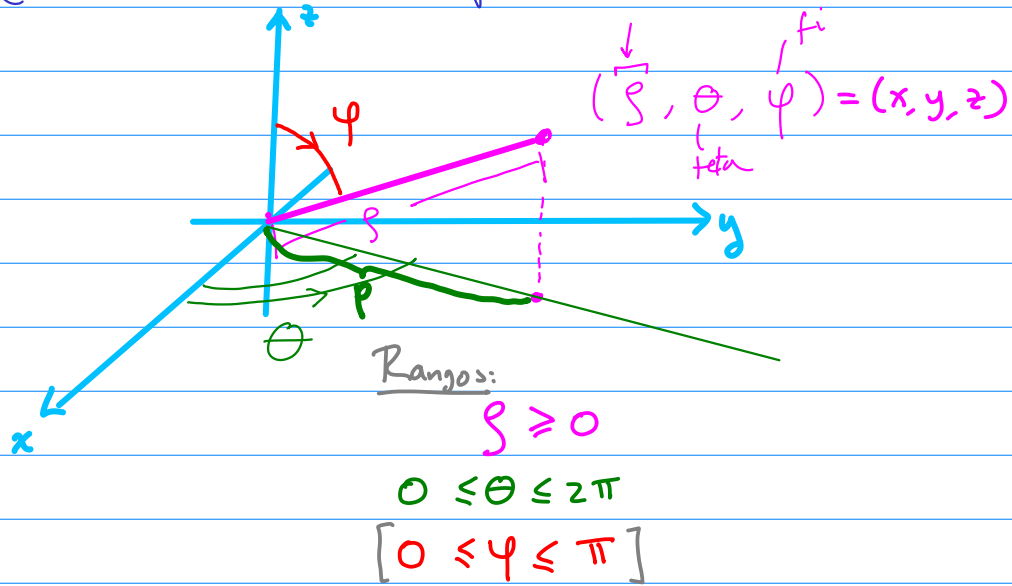
### (2.1) Coords cilíndricas



$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases} \checkmark$$



(2.2) Coordenadas esféricas.  $\rho$

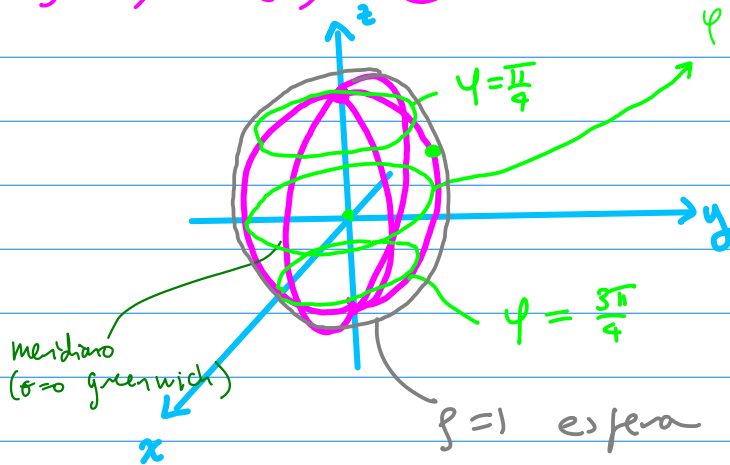


$$\rho = 1, \quad \theta = \frac{\pi}{2}, \quad 0 \leq \varphi \leq \pi$$

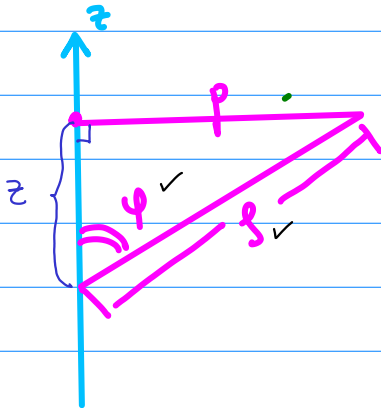
$$\rho = 1, \quad 0 \leq \theta \leq 2\pi$$

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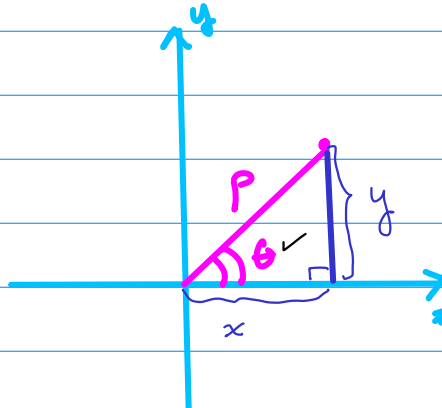
$$\varphi = \frac{\pi}{2}$$



Cómo son  $x, y, z$  dados  $\rho, \theta, \varphi$



$$\begin{aligned}\cos \varphi &= \frac{z}{\rho} \Rightarrow z = \rho \cos \varphi \\ \sin \varphi &= \frac{p}{\rho} \Rightarrow p = \rho \sin \varphi\end{aligned}$$



$$\begin{aligned}\cos \theta &= \frac{x}{r} \Rightarrow x = r \cos \theta \\ \sin \theta &= \frac{y}{r} \Rightarrow y = r \sin \theta\end{aligned}$$

$$\begin{cases} x = \rho \sin \varphi \cos \theta \\ y = \rho \sin \varphi \sin \theta \\ z = \rho \cos \varphi \end{cases}$$

Cambio de variable a coords  
esféricas.

\* Ejercicio: Demuestra que

(1) Jacobiano a cilíndricos es

(2) Jacobiano a esféricas es

$$\rho^2 \sin \varphi$$

$$\det \begin{bmatrix} \frac{\partial x}{\partial \rho} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \varphi} \\ \frac{\partial y}{\partial \rho} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \varphi} \\ \frac{\partial z}{\partial \rho} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial \varphi} \end{bmatrix} //$$