



$T_1: (0.0, -0.15, -1.0)$
 $T_2: (\text{coche}_x, 0.0, \text{coche}_z)$
 $R_1: (\text{coche_rotation}, 0.0, 1.0, 0.0)$
 $S_1: (0.1, 0.1, 0.1)$
 $T_3: (0.0, -0.5, 1.0)$
 $T_4: (\text{sims}_x, 0.0, \text{sims}_z)$
 $R_2: (\text{sims_rotation}, 0.0, 1.0, 0.0)$
 $S_2: (0.5, 0.5, 0.5)$
 $T_5: (-0.4, 1.5, -0.1)$
 $S_3: (0.1, 0.1, 0.1)$
 $T_6: (0.0, \text{cursor}_y, 0.0)$
 $R_3: (180.0, 1.0, 0.0, 0.0)$
 $R_4: (270.0, 0.0, 0.0, 0.0)$
 $S_4: (0.1, 0.1, 0.1)$
 $T_7: (0.0, -2.0, 0.0)$
 $R_5: (180.0, 1.0, 0.0, 0.0)$
 $R_6: (\text{arm_l_rot}, 0.5, 0.0, 0.5)$
 $R_7: (\text{arm_r_rot}, 0.5, 0.0, 0.5)$
 $R_8: (\text{leg_l_rot}, 1.0, 0.0, 0.0)$
 $R_9: (\text{leg_r_rot}, 1.0, 0.0, 0.0)$