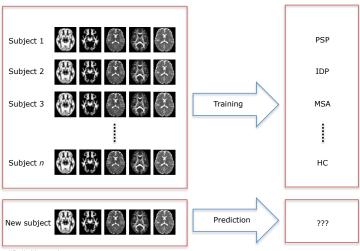
Pseudo-Marginal Bayesian Inference for Gaussian Processes

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Motivating Application



HC - Healthy control

MSA - Multiple system atrophy

PSP - Progressive Supranuclear Palsy

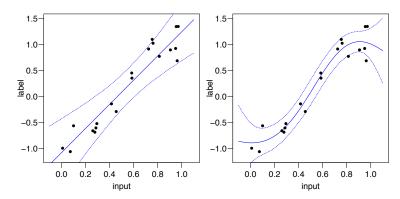
IDP - Idiopathic Parkinson's disease

Models

Mapping input to labels

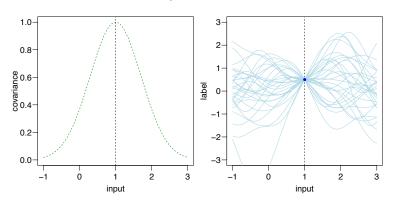
label = function(input, par, noise)

• We may have no clue about function - we need assumptions



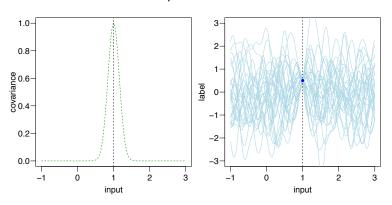
Gaussian Processes

• Gaussians with distance dependent covariance



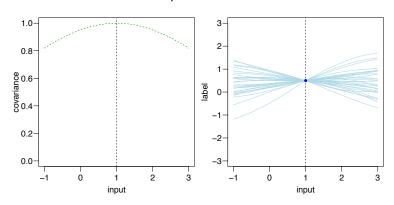
Gaussian Processes

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Gaussian Processes

• Gaussians with distance dependent covariance

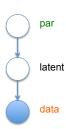


Gaussian Process Models

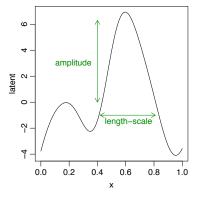
Class of hierarchical models

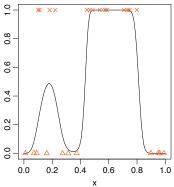
$$p(\text{data}|\text{latent})$$
 $p(\text{latent}|\text{par})$ $p(\text{par})$

• p(latent|par) = Gaussian Process

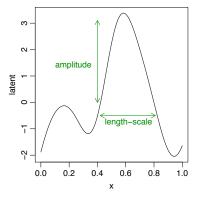


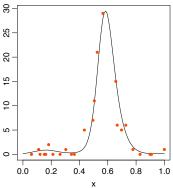
Gaussian Process Models - Classification example





Gaussian Process Models - Count data example

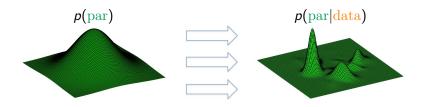




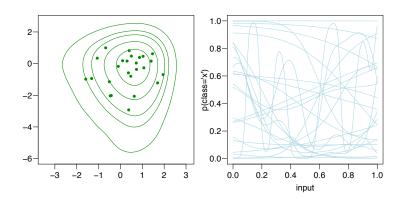
Bayesian Inference

• Inference using Bayes theorem:

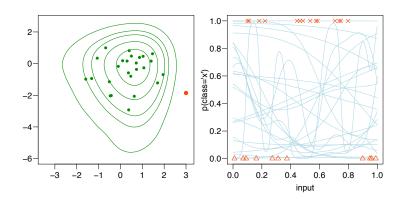
$$p(\operatorname{par}|\operatorname{data}) = \frac{p(\operatorname{data}|\operatorname{par})p(\operatorname{par})}{\int p(\operatorname{data}|\operatorname{par})p(\operatorname{par})d\operatorname{par}}$$



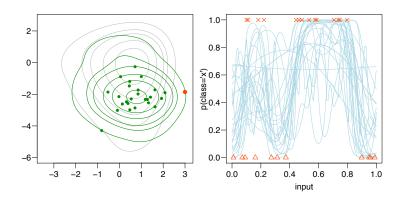
Bayesian Inference - Prior



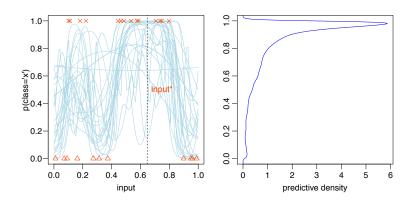
Bayesian Inference - Data



Bayesian Inference - Posterior



Bayesian Inference and Predictions



Bayesian Inference and Predictions

Predictions for new data

$$p(\text{label}_*|\text{label}) = \int p(\text{label}_*|\text{par})p(\text{par}|\text{label}) d\text{par}$$

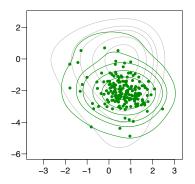
Monte Carlo integration:

$$\int p(\text{label}_*|\text{par})p(\text{par}|\text{label}) d\text{par} \simeq \frac{1}{N} \sum_{i=1}^{N} p(\text{label}_*|\text{par}^{(i)})$$

with $par^{(i)}$ drawn from p(par|data)

Bayesian Inference and Predictions

• Draw samples according to the posterior density

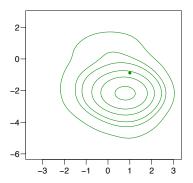


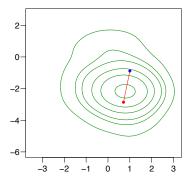
Bayesian inference

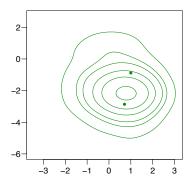
$$p(\text{par}|\text{data}) = \frac{p(\text{data}|\text{par})p(\text{par})}{\int p(\text{data}|\text{par})p(\text{par})d\text{par}}$$

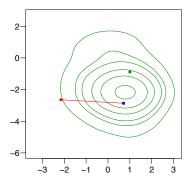
Random walk sampler - accept a proposal with probability

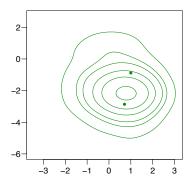
$$\min\left(1, \frac{p(\operatorname{par}'|\operatorname{data})}{p(\operatorname{par}|\operatorname{data})}\right)$$

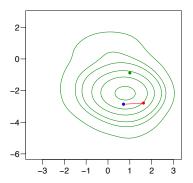


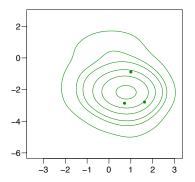


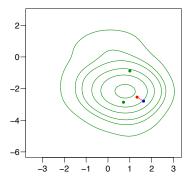


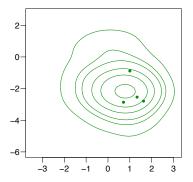


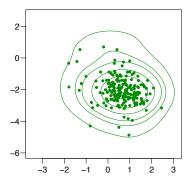












How can we draw from p(par|data) in GPMs?

Marginal likelihood

$$p(\text{data}|\text{par}) = \int p(\text{data}|\text{latent})p(\text{latent}|\text{par})d\text{latent}$$

is unavailable analytically. Options:

- Approximate $p(\frac{\text{data}}{\text{par}})$ within MCMC
- Sample from p(par, latent|data)
- Pseudo-Marginal MCMC

Gaussian Approximations for marginal likelihood

Gaussian approximation to p(|atent|data, par)

- Laplace Approximation
- Expectation Propagation
- Variational Bayes
- . .

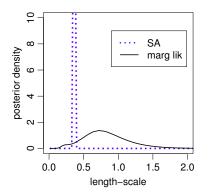
Challenges in MCMC for GPMs - Cost & exploration

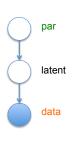
- No exact Gibbs steps need to employ Metropolis within Gibbs steps - waste of computations when rejecting
- Updates of par cost $O(n^3)$
- par can be large dimensional (e.g., Automatic Relevance Determination (ARD) covariance function)
- There are n latent variables (as many as the number of observations)

Challenges in MCMC for GPMs - Structure

Obvious iterative scheme (aka Sufficient Augmentation (SA) scheme). Alternate between:

- Drawing from p(latent|par, data)
- Drawing from p(par|latent) (bad idea see figure)



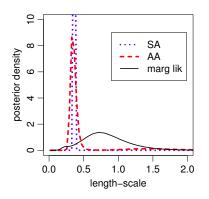


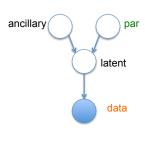
Mitigating coupling effect through reparameterization

Ancillary Augmentation (AA) scheme - reparametrization:

$$K = LL^{T}$$
 ancillary $= L^{-1}$ latent

• Replace sampling of par with p(par|ancillary, data)

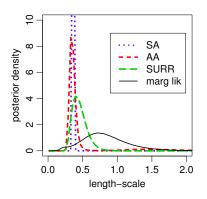




Mitigating coupling effect through reparameterization

Surrogate data model (SURR):

 Introduce set of auxiliary variables informed by the posterior over latent



surrogate = f(latent, par)

Pseudo-Marginal MCMC

• Replace posterior by unbiased estimate

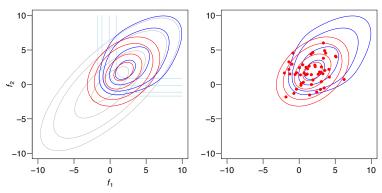
$$\min\left(1, \frac{\tilde{p}(\operatorname{par}'|\operatorname{data})}{\tilde{p}(\operatorname{par}|\operatorname{data})}\right)$$

• Achieved by using an unbiased estimate of $\tilde{p}(\frac{\text{data}}{\text{par}})$

Importance Sampling estimator

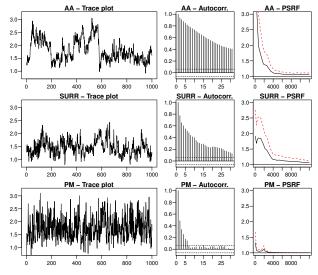
- Approximate posterior over latent variables using q(latent)
- Then

$$\tilde{p}(\frac{\text{data}|\text{par}}{}) = \frac{1}{N} \sum_{i=1}^{N} \frac{p(\frac{\text{data}}{|\text{latent}^{(i)})} p(\text{latent}^{(i)}|\text{par})}{q(\text{latent}^{(i)})}$$



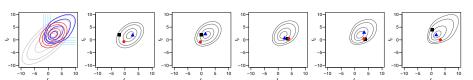
Mixing

Abalone data set (two classes) n=2835 - inference of length-scale



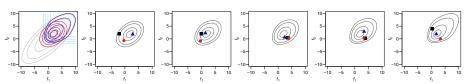
Annealed Importance Sampling estimator

• Annealing from an approximation

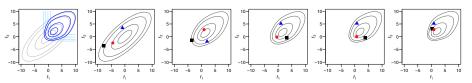


Annealed Importance Sampling estimator

• Annealing from an approximation



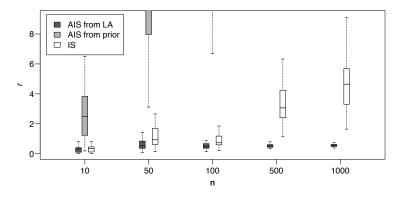
Annealing from the prior



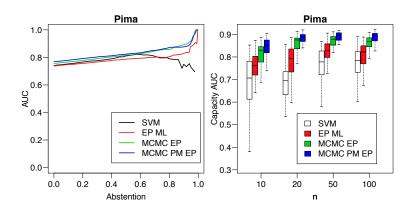
Comparison between AIS with IS

Analysis of the variance of the AIS and IS estimators

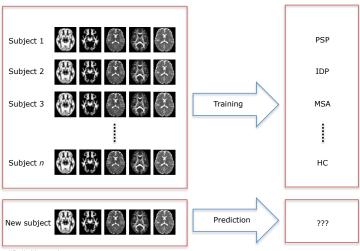
r is the variance of the log₁₀ marginal likelihood



Some Results



Motivating Application



HC - Healthy control

MSA - Multiple system atrophy

PSP - Progressive Supranuclear Palsy

IDP - Idiopathic Parkinson's disease

Multiclass classification with multiple sources

Multiclass classification based on GPs

$$p(\text{disease} = c | \text{sources}) = \text{unknown function}$$

unknown function modeled using GPs

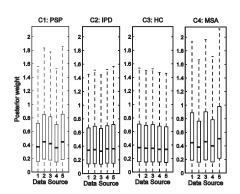
Multiclass classification with multiple sources

ullet Covariance based on source-dependent covariances S_k

$$\sum_{k=1}^{K} w_{ck} S_k(subject_i, subject_j)$$

Parkinson syndromes data - multi source

Method	Accuracy
GP classifier	0.598
SimpleMKL	0.418



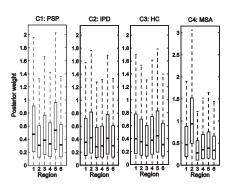
Multiclass classification with multiple regions

Analysis of brain regions

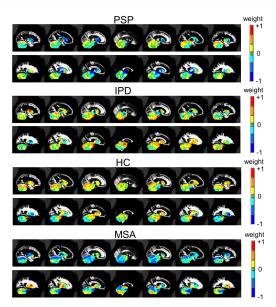
- brainstem
- bilateral cerebellum
- bilateral caudate
- bilateral middle occipital gyrus
- bilateral putamen
- all other regions

Multiclass classification with multiple regions

Method	Accuracy
GP classifier	0.614
SimpleMKL	0.229



Brain Maps



Gaussian Processes yield flexible and interpretable nonparametric models

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- Bayesian inference to accurately quantifying uncertainty in such models

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- Bayesian inference to accurately quantifying uncertainty in such models
- Pseudo-Marginal MCMC offers a practical way to carry out exact Bayesian computations
- How to make exact Bayesian computations for Gaussian Processes scalable?

Acknowledgements

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- [1] M. Filippone and M. Girolami. Pseudo-Marginal Bayesian inference for Gaussian processes, IEEE Transactions on Pattern Analysis and Machine Intelligence, to appear.
- [2] M. Filippone. Bayesian inference for Gaussian process classifiers with annealing and pseudo-marginal MCMC, In *ICPR*, 2014.
- [3] M. Filippone et al. Probabilistic prediction of neurological disorders with a statistical assessment of neuroimaging data modalities. *Annals of Applied Statistics*, 6(4):1883-1905, 2012.
- [4] A. F. Marquand et al. Automated, high accuracy classification of Parkinsonian disorders: a pattern recognition approach. *PLoS ONE*, 2013.
- [5] M. Filippone et al. A comparative evaluation of stochastic-based inference methods for Gaussian process models. Machine Learning, 93(1):93-114, 2013.

