



XLV CILAMCE

NOVEMBER 11 - 14 2024 - MACEIÓ | AL | BRAZIL

**Comparing Transformers and Linear models
for precipitation forecast in Rio de Janeiro**

Mauro Sérgio & Fábio Porto

Agenda

Introduction

Theoretical Background

Experiments

Results

Conclusion and Future Work

Introduction

Theoretical Background

Experiments

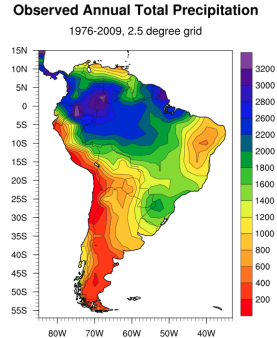
Results

Conclusion and Future Work

Precipitation forecasting

- ▶ Precipitation forecasting is a **complex and critical task** in meteorology.
- ▶ Accurate prediction is challenging due to the **unbalanced distribution** of precipitation events.
- ▶ Rain prediction involves forecasting future weather conditions based on past data, which is typically structured as a **time series**.

Figure: Rainfall in South America.

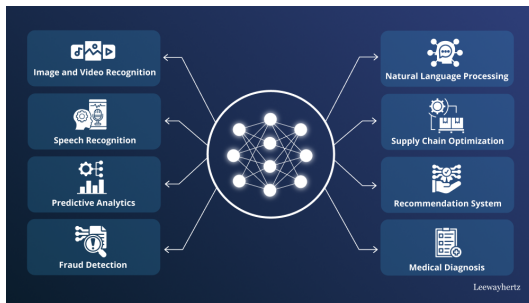


Source: [https://commons.wikimedia.org/wiki/File:South_America_Precipitation_Map_\(data_from_1976-2009\).gif](https://commons.wikimedia.org/wiki/File:South_America_Precipitation_Map_(data_from_1976-2009).gif)

Deep Learning (DL)

- ▶ Deep Learning (DL) has revolutionized various fields by enabling models to **automatically learn complex patterns** from large datasets.
- ▶ Deep learning can increase the accuracy of precipitation forecasts by capturing both **spatial and temporal dependencies** in the data, as well as taking advantage of neural network architectures, especially those based on the **Transformer**.

Figure: Deep Learning.



Source: <https://www.leewayhertz.com/what-is-deep-learning/>

Problem Formalization

In this work, we deal with **Tabular Multivariate Time Series Data and Multivariated models.**

With this we aim to: **Evaluate the performance of Linear and Transformer architectures** in predicting precipitation, contributing to the understanding of their effectiveness in regression tasks involving unbalanced datasets.

Introduction

Theoretical Background

Experiments

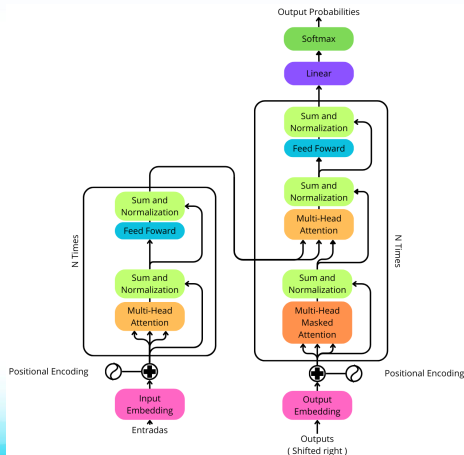
Results

Conclusion and Future Work

Transformer models are a major advancement in deep learning, they use a self-attention mechanism to **process entire sequences at once**. Some Key features are:

- ▶ **Self-Attention Mechanism:** Helps the model focus on important parts of the input, capturing long-range dependencies.
- ▶ **Parallel Processing:** Allows faster training and more efficient handling of large datasets compared to recurrent models.

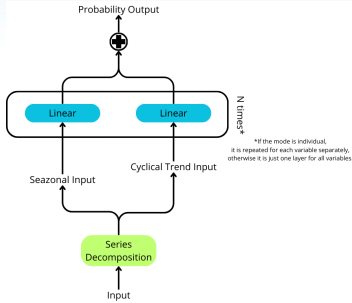
Figure: Transformer Architecture.



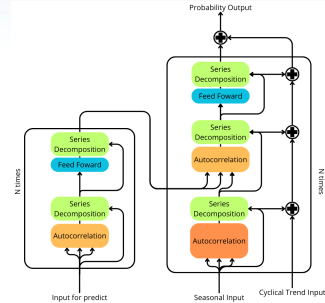
Learners

Table: Distinguish features between learners.

| Learners | Distinctions | Architecture Type | Prediction Type |
|------------|---|-------------------|------------------------|
| Autoformer | Decomposition layer, Auto-correlation, Time Delay Aggregation | Transformer | Temporal Multi-variate |
| DLinear | Linear model with Seasonal Decomposition | Linear | Multivariate |
| SARIMAX | Linear Seasonal model highly utilized in TSF | Linear | Multivariate |



(a) DLinear architecture.



(b) Autoformer architecture.

Figure: Models architectures.

Introduction

Theoretical Background

Experiments

Results

Conclusion and Future Work

Dataset (Rionowcast)

This dataset was obtained from the Rionowcast DataLake project and consists of weather station data collected from INMET weather stations in Rio de Janeiro city. It includes:

- ▶ Data from 2002 to 2023.

Dataset (Rionowcast)

This dataset was obtained from the Rionowcast DataLake project and consists of weather station data collected from INMET weather stations in Rio de Janeiro city. It includes:

- ▶ Data from 2002 to 2023.
- ▶ Time resolution: 1 hour.

Dataset (Rionowcast)

This dataset was obtained from the Rionowcast DataLake project and consists of weather station data collected from INMET weather stations in Rio de Janeiro city. It includes:

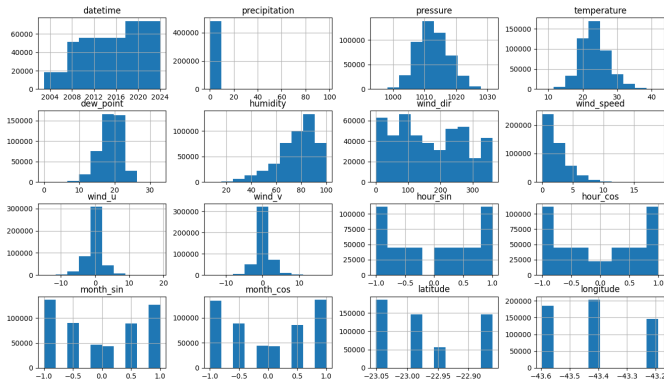
- ▶ Data from 2002 to 2023.
- ▶ Time resolution: 1 hour.
- ▶ Task: Precipitation regression.

Rionowcast Variables

| Variable name | Description | Unity |
|-------------------|---|-------|
| datetime | Datetime of the measurement | |
| station_id | ID of the weather station | |
| precipitation | Amount of rainfall recorded by the stations aggregated by hour | mm |
| pressure | Atmospheric pressure | mB |
| temperature | Temperature | °C |
| dew_point | Dew point temperature | °C |
| humidity | Relative humidity | % |
| wind_dir | Clockwise wind direction | ° |
| wind_speed | Wind speed | m/s |
| wind_u | Cyclic U component from the wind | |
| wind_v | Cyclic V component from the wind | |
| datetime encoding | Sine and cosine components for hour (hour_sin, hour_cos) and month (month_sin, month_cos) | |
| stations | Station name | |
| latitude | Station Latitude | |
| longitude | Station Longitude | |

Figure: Histogram of numerical variables.

Histogram of the Kaggle dataset.



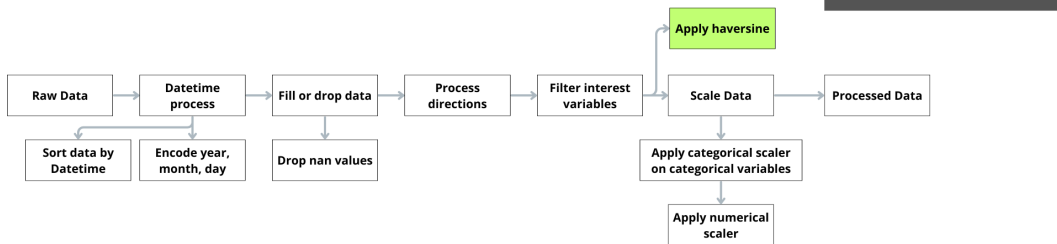
Datasets Considerations

In addition to the previously mentioned analyses, further evaluations were conducted to assess the quantity of **missing values** in the dataframe, as well as the **starting date of operations** for each station.

It is important to highlight that the locations **had different starting dates per station**, and there were **numerous missing values**.

Data Processing Pipeline

Figure: Data preprocessing pipeline.



Data Split

- The dataset was split as: 60% for training, 20% for validation and 20% for test sequentially.

Figure: Training Split.



Learner parameters

- ▶ Input Sequence: 96
- ▶ Output Sequence: 96
- ▶ Epochs: 50
- ▶ Optimizer: Adam with Learning Rate of 0.005.
- ▶ Callbacks: EarlyStopping, ReduceLROnPlateau, with patiences of 3 and 1 sequentially.

The learner training process was conducted on the DEXL laboratory machine Netuno, a Dell Precision T7820 With:

- ▶ 2× CPU Intel Xeon Silver 4216 (16 CPU-core each)
- ▶ 126GB of RAM DDR4
- ▶ 2× NVIDIA RTX A5000 with 24GB of VRAM GDDR6 with NVLink.

Metrics

Mean Squared Error:

$$MSE = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2. \quad (1)$$

Metrics

The MSE metric accounts for the mean of squared errors, which, although **not ideal for unbalanced problems**, is commonly used in the literature and is thus considered a suitable metric for this study.

Currently, there is no widely accepted loss function specifically designed for dealing with unbalanced regression tasks. **As part of future work, this study aims to explore alternative metrics** to better handle unbalanced data in regression problems.

Introduction

Theoretical Background

Experiments

Results

Conclusion and Future Work

Experimental Setup

- ▶ Three models were selected for evaluation:
 - ▶ **DLinear**: Chosen for its simplicity and low computational requirements.
 - ▶ **Autoformer**: Selected as a Transformer-based extension of DLinear.
 - ▶ **SARIMAX**: Included as a widely used model for time series forecasting.
- ▶ Results are presented in the following format:
 - ▶ Actual and predicted values are segmented into four precipitation bins, with MSE calculated for each bin and presented in tabular form.

First Execution

Table: MSE per bins for first execution

| Model | MSE | MSE 0-10mm | MSE 10-25mm | MSE 25-50mm | MSE 50mm+ |
|------------|---------------|--------------|-----------------|-----------------|------------------|
| DLinear | 1.5028 | 0,325 | 156,2437 | 863,8895 | 2806,2461 |
| Autoformer | 1.9089 | 0,4345 | 207,7265 | 1053,6511 | 3390,4949 |
| SARIMAX | 2.1189 | 0,4903 | 243,2032 | 1147,6152 | 3566,6263 |

Second Execution (With Distances)

Table: MSE per bins for second execution

| Model | MSE | MSE 0-10mm | MSE 10-25mm | MSE 25-50mm | MSE 50mm+ |
|------------|---------------|--------------|-----------------|-----------------|------------------|
| DLinear | 1,5028 | 0,325 | 156,2437 | 863,8895 | 2806,2461 |
| Autoformer | 1,9110 | 0,4362 | 207,83 | 1053,8129 | 3392,0891 |
| SARIMAX | 2,1291 | 0,4991 | 243,5218 | 1148,3915 | 3568,1091 |

Lastly, we attempted to use Autoformer with a single variable to see if the results would improve, but it resulted in an **MSE of 1.8741**.

The MSE per bin was 0.43073 for 0-10mm, 203.6539 for 10-25mm, 1036.6064 for 25-50mm, and 3289.4680 for 50mm+. In general, this approach had **better results per bin than the others for Autoformer only**.

Implementation of Various Models

Table: Baseline Models and Transformer-based Models.

| Model | MSE | MSE 0-10mm | MSE 10-25mm | MSE 25-50mm | MSE 50mm+ |
|-------------|------------------|------------|-------------|-------------|-----------|
| DLinear | 1.5028 | 0.3250 | 156.2437 | 863.8895 | 2806.2461 |
| SARIMAX | 2.1189 | 0.4903 | 243.2032 | 1147.6152 | 3566.6263 |
| Mamba | 1.9717 | 0.3596 | 237.7751 | 1136.0001 | 3557.9128 |
| TSMixer | 2.3053 | 0.8463 | 203.8534 | 1053.0809 | 3353.6857 |
| PrecipLSTM | 1051.6258 | | | | |
| Transformer | 1.9931 | 0.4018 | 232.5584 | 1124.3771 | 3538.4458 |
| Autoformer | 1.9089 | 0.4345 | 207.7265 | 1053.6511 | 3390.4949 |
| Informer | 2.0064 | 0.4200 | 231.4138 | 1121.9215 | 3532.7129 |
| Mambaformer | 1.9693 | 0.3599 | 237.1345 | 1134.4648 | 3554.9453 |

Execution Time of Various Models

Table: Training time by model.

| Models | Total Execution Time | Number of Epochs | Time per Epoch |
|-------------|----------------------------|------------------|--------------------|
| DLinear | 10 minutes | 15 | 43 seconds |
| Mamba | 20 minutes | 12 | 1 minute |
| TSMixer | 29 minutes | 15 | 2 minutes |
| PrecipLSTM | 33 hours 41 minutes | 8 | 4 hours 30 minutes |
| Transformer | 21 minutes | 4 | 5 minutes |
| Autoformer | 1 hour 35 minutes | 17 | 7 minutes |
| Informer | 28 minutes | 5 | 5 minutes |
| Mambaformer | 53 minutes | 14 | 3 minutes |

Introduction

Theoretical Background

Experiments

Results

Conclusion and Future Work

Conslusions

In this work, we:

- ▶ Applied Transformer-based and Baseline state of the art Deep Learning models to the challenge of precipitation prediction.
- ▶ Assessed various data sources and evaluated the **reliability of meteorological stations** in supporting accurate predictions.

Conslusions

- ▶ The models faced difficulties in accurately predicting extreme precipitation events.
- ▶ Modifying the data representation had a low effect on performance, reinforcing that addressing the unbalanced data distribution remains crucial.
- ▶ The primary challenge in rainfall prediction lies in the unbalanced nature of the data, rather than in the architecture or data representation itself.

Future Work

- ▶ Explore data augmentation techniques for time series and refine loss functions to better address data imbalance.
- ▶ Integrate additional data sources (e.g., radar, weather balloons, ERA5), incorporating atmospheric variables and altitude information.
- ▶ Investigate the impact of different temporal scales to enhance predictive performance.
- ▶ Evaluate alternative approaches, such as classification or extreme event detection.
- ▶ Implement specialized models for spatiotemporal time series forecasting.

Acknowledgments



Thank You for the Attention

Contact:
mauro@posgrad.lncc.br