

By

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Mathematical Models of Hebbian Learning

Consider a synaptic weight w_{kj} of neuron k.

The respective presynaptic (input) signal is denoted by x_i .

The postsynaptic (output) signal is denoted by y_k .

The change (update) of w_{kj} at time step n has the general form

$$\Delta w_{kj}(n) = F(y_k(n), x_j(n))$$

where F(y, x) is a function of both postsynaptic and presynaptic sig- nals.

Consider two specific forms of the general Hebbian learning rule.

Standard Hebbian learning rule:

$$\Delta w_{kj}(n) = \eta y_k(n) x_j(n)$$

Here η is again the learning rate or parameter.

Repeated application of the input (presynaptic) signal x_j leads to an increase in the output signal y_k . Finally this leads to an *exponential* growth and saturation of the weight value.

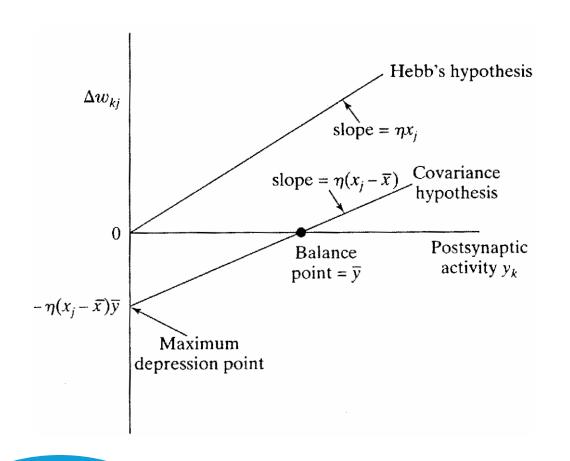
Covariance Hebbian rule:

$$\Delta w_{kj}(n) = \eta[x_j(n) - m_x][y_k(n) - m_y]$$

Here m_x and m_y are time averages of the presynaptic input signal x_j and postsynaptic output signal y_k , respectively.

Covariance rule can converge to a nontrivial state $x_j = m_x$, $y_k = m_y$

The synaptic strength can both increase and decrease.



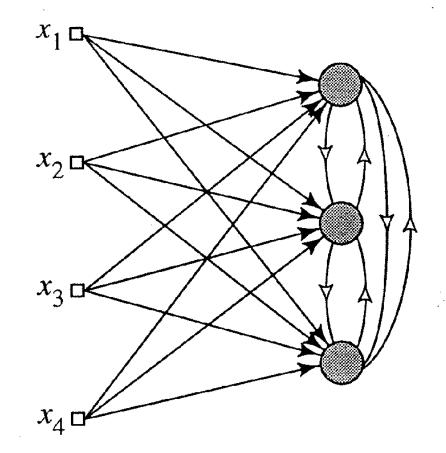
- Standard Hebbian rule and the covariance rule.
- In both cases, the weight update depends on the output signal y_k linearly.
- Hebbian learning has strong physiological evidence.



- In competitive learning, the neurons in the output layer compete to become active (fired).
- Only a single output neuron is active at any one time.
- In Hebbian learning, several output neurons may be active simulta- neously.
- Competitive learning is highly suitable for finding relevant features for classification tasks.

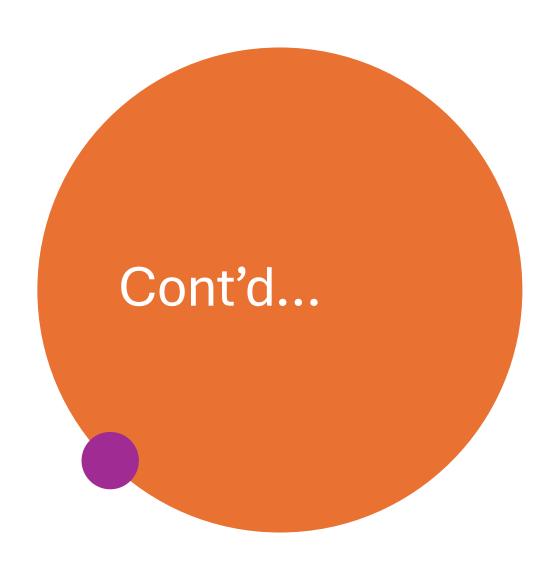
- Three basic elements of a competitive learning rule:
 - 1.A set of similar neurons except for some randomly distributed synaptic weights.
 - -Therefore the neurons respond differently to input signals.
 - 2.A *limit* imposed on the strength of each neuron.
 - 3.A competing mechanism for the neurons.
 - Only one output neuron has the right to respond to an input signal.
 - The winner of the competition is called a *winner-takes-all neu-ron*.
- As a result of competition, the neurons become specialized.
- They respond to certain type of inputs, becoming *feature detectors* for different input classes.

Simplest form of a competitive neural network

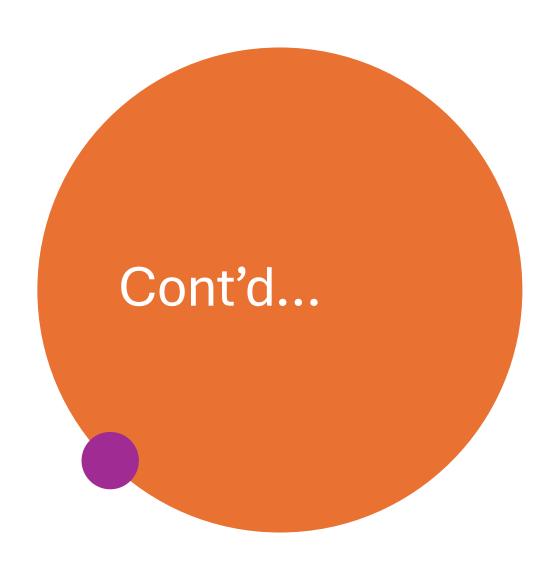


Layer of source nodes

Single layer of output neurons

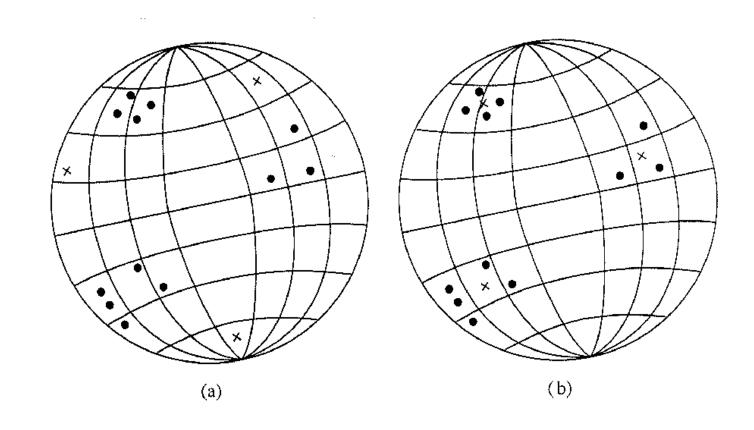


- Feedback connections between the competing output neurons perform
- lateral inhibition.
- Each neuron tends to inhibit the neuron to which it is laterally con- nected.
- A neuron k is the winning neuron if its induced local field v_k for a given input pattern \mathbf{x} is the largest one.
- Mathematically, the output signal
- $y_k = 1$, if $v_k > v_j$ for all $j, j \neq k$.
- For other than the winning neuron, the output signal $y_k = 0$.
- The local field v_k represents the combined action of all the forward and feedback inputs to neuron k.
- Typically, all the synaptic weights w_{kj} are positive.

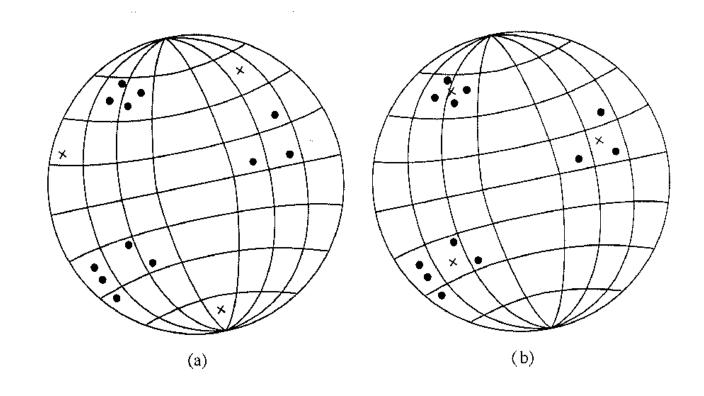


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- Here both the input vectors \mathbf{x} and the weight vectors \mathbf{w}_k are scaled to have unit length (Euclidean norm).
- Then they are points on the surface of an N-dimensional hypersphere (assuming Ndimensional vectors).
- Initial state (Fig. a) shows three clusters of data points (black dots) and initial values of three weight vectors (crosses).



- Figure b shows a typical final state of a network resulting from com- petitive learning.
- The weight vectors have moved to the gravity centers of clusters.
- In more difficult cases, competitive learning algorithms may fail to find stable clusters.



Boltzmann Learning

- In a Boltzmann machine the neurons constitute a recurrent structure, and they operate in a binary manner (either "on" state or in "off" state)
- The machine is characterized by an energy function, E, the value of which is determined by the particular states occupied by the individual neurons of the machine, as shown by

 where xj is the state of neuron j and wkj is the synaptic weight connecting neuron j to neuron k and j ≠ k means no self-feedback.

$$E = -\frac{1}{2} \sum_{j} \sum_{k} w_{kj} x_{k} x_{j}$$

$$j \neq k$$

• The machine operates by choosing a neuron k at some step of the learning process, then flipping the state of neuron k from state x_k state to $-x_k$ at some temperature T with probability

$$P(x_k \to -x_k) = \frac{1}{1 + exp\left(-\frac{\Delta E_k}{T}\right)}$$

- Let ρ_{kj}^+ denote the *correlation* between the states of neurons j and k, with the network in its clamped condition. Let ρ_{kj}^- denote the *correlation* between the states of neurons j and k with the network in its free-running condition.
- The Δw_{kj} change applied to the synaptic weight w_{kj} from neuron j to neuron k is defined by

$$\Delta\omega_{kj} = \eta(\rho_{k_j}^+ - \rho_{k_j}^-)$$