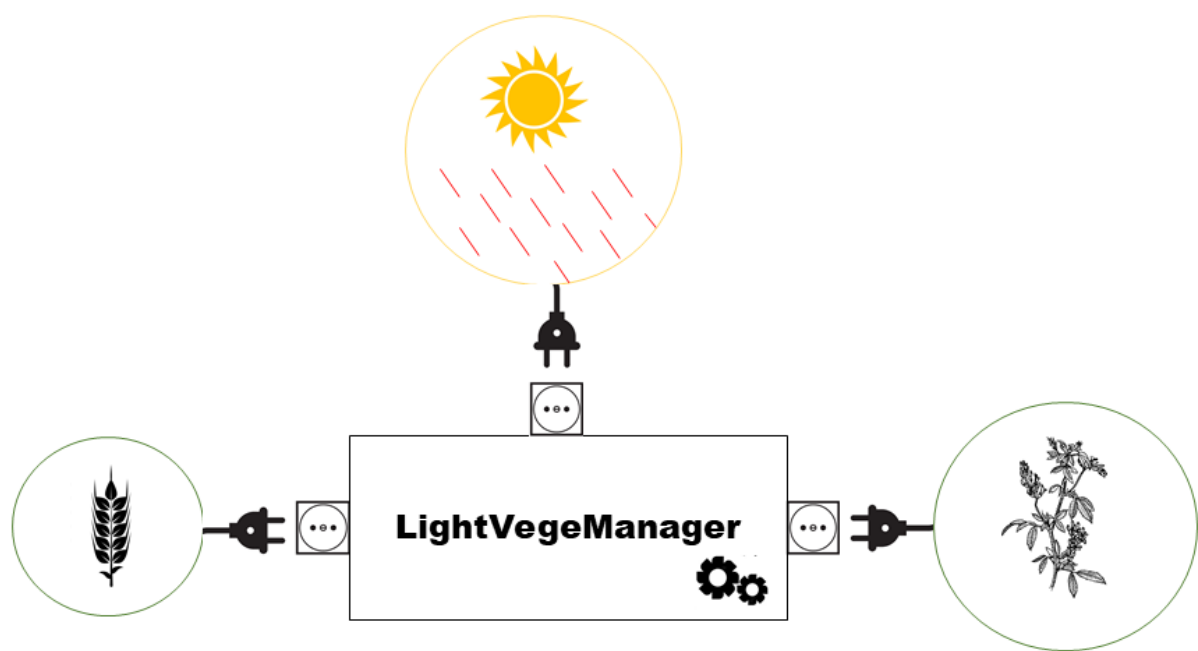

LightVegeManager

Release 0.0.0

INRAE P3F

Nov 27, 2023

USER GUIDE



MODULE DESCRIPTION

Summary

Version**Date**

Nov 27, 2023

Author

See *Authors* section

Overview

LightVegeManager is a Python package made for plant modeling and manage enlightenment. It serves as an interface to merge several plant models and a light model. Applications involved by this tools are part of OpenAlea platform.

DOCUMENTATION

2.1 Presentation

2.1.1 Context

This package was born in the framework of the research project MobiDiv (<https://anr.fr/ProjetIA-20-PCPA-0006>), which aims to find solutions for pesticide-free agriculture. One of the targets of this project is to model coupled crops between wheats, modelled by CN-Wheat (<https://www.quantitative-plant.org/model/CN-Wheat>), and alfalfas, thanks to l-egume model (<https://github.com/glouarn/l-egume>). Thus, LightVegeManager was created to manage the lighting in a vegetal simulation, in formats understandable by the tools proposed on the OpenAlea platform (<https://github.com/openalea>).

2.1.2 Intentions

We want to simplify the light management when several models, plant and lighting, are involved. The tool manages many input and output formats, in order to match a wide variety of situations.

2.1.3 How

It reads the following input formats:

- PlantGL scene
- MTG table
- VGX file
- Caribu scene, dict storing a triangulation
- Dict storing a grid of voxels with leaf area and leaf angle distribution

More details about the input formats here *Scenes format*.

And it can return the outputs in the following formats:

- Pandas Dataframe, in multiple scales (triangles, voxels, elements) depending on the light model.
- updates a MTG table
- returns two tables compatible with l-egume

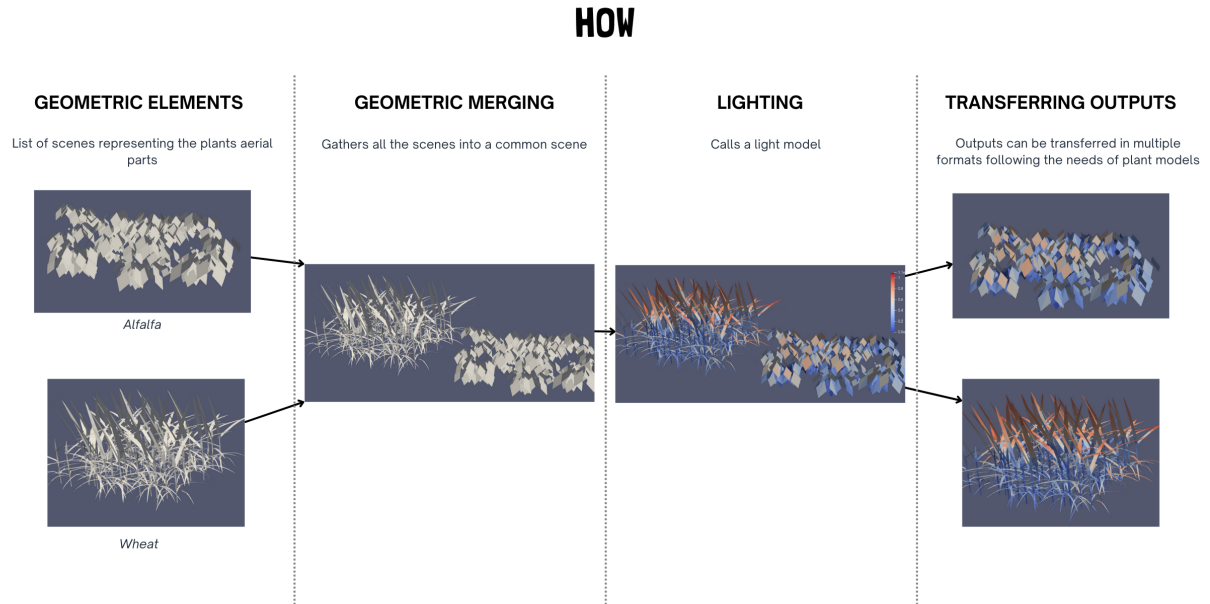


Fig. 1: General Functionning

2.1.4 Lighting

At the moment, LightVegeManager can handle three lighting models, CARIBU (<https://github.com/openalea-incubator/caribu>), PyRATP (<https://github.com/openalea-incubator/PyRATP>), and RiRi modified in l-egume (<https://github.com/glouarn/riri5>). Those models are adjusted for virtual plant canopies with considerations, like infinitisation of the scene, which are preferred for simulating large crop fields.

They offers two different approach for light modelling:

Surfacic approach (CARIBU)

The radiations are computed on a set of triangles. This approach offers a high precision of lighting on the different organs, but has a high cost in time computation.

Volumic approach (PyRATP, RiRi)

The geometric scene is represented by a set of voxels, which contains a leaf area and a leaf angle informations. Then, the models solves turbid medium equations from the rays inside the grid. This approach has a higher approximation of geometry, but is well adapted for dense canopy. The computation cost is highly reduced regarding the surfacic approach but the geometric scene must matches the turbid medium representation and hypothesis.

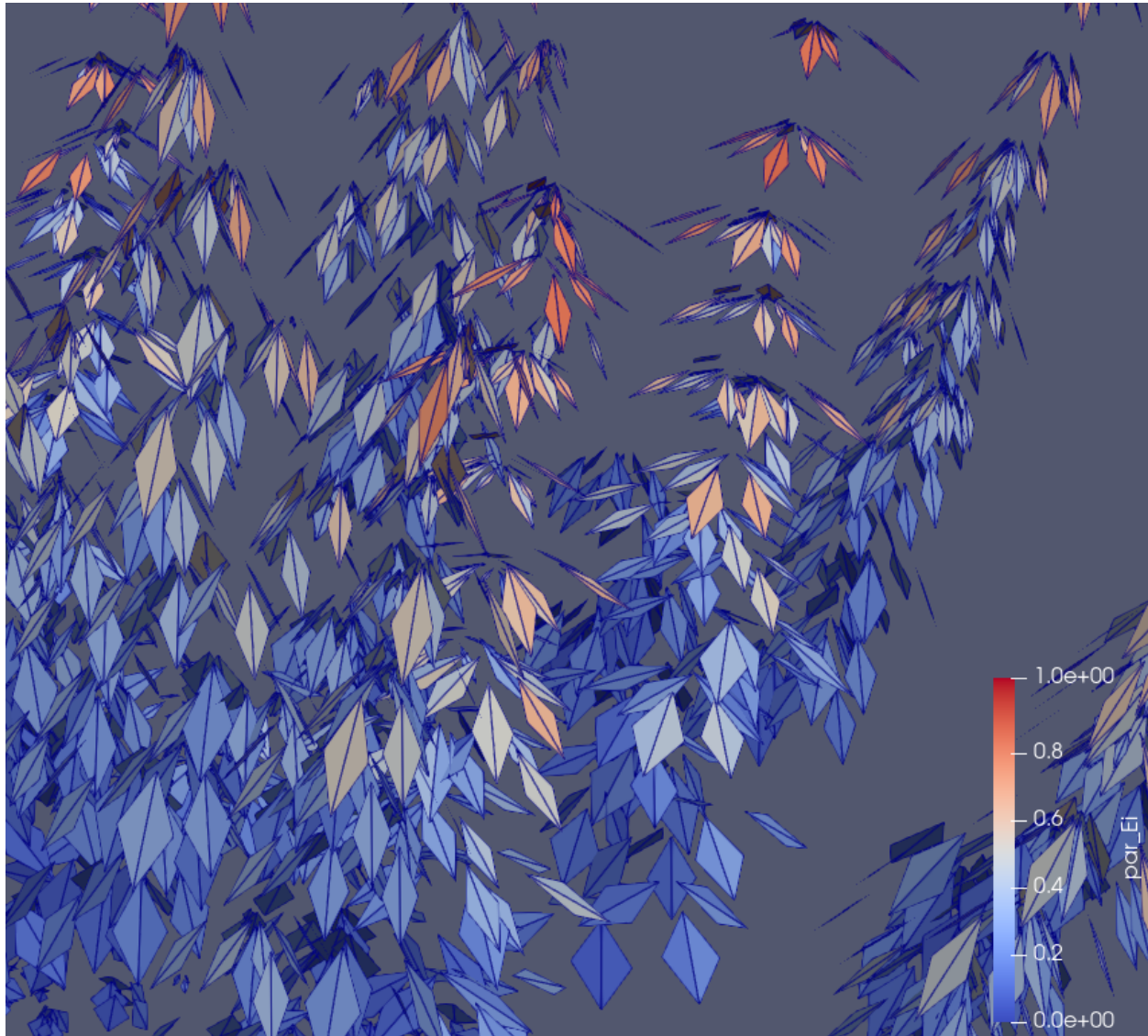


Fig. 2: Example of a triangulation

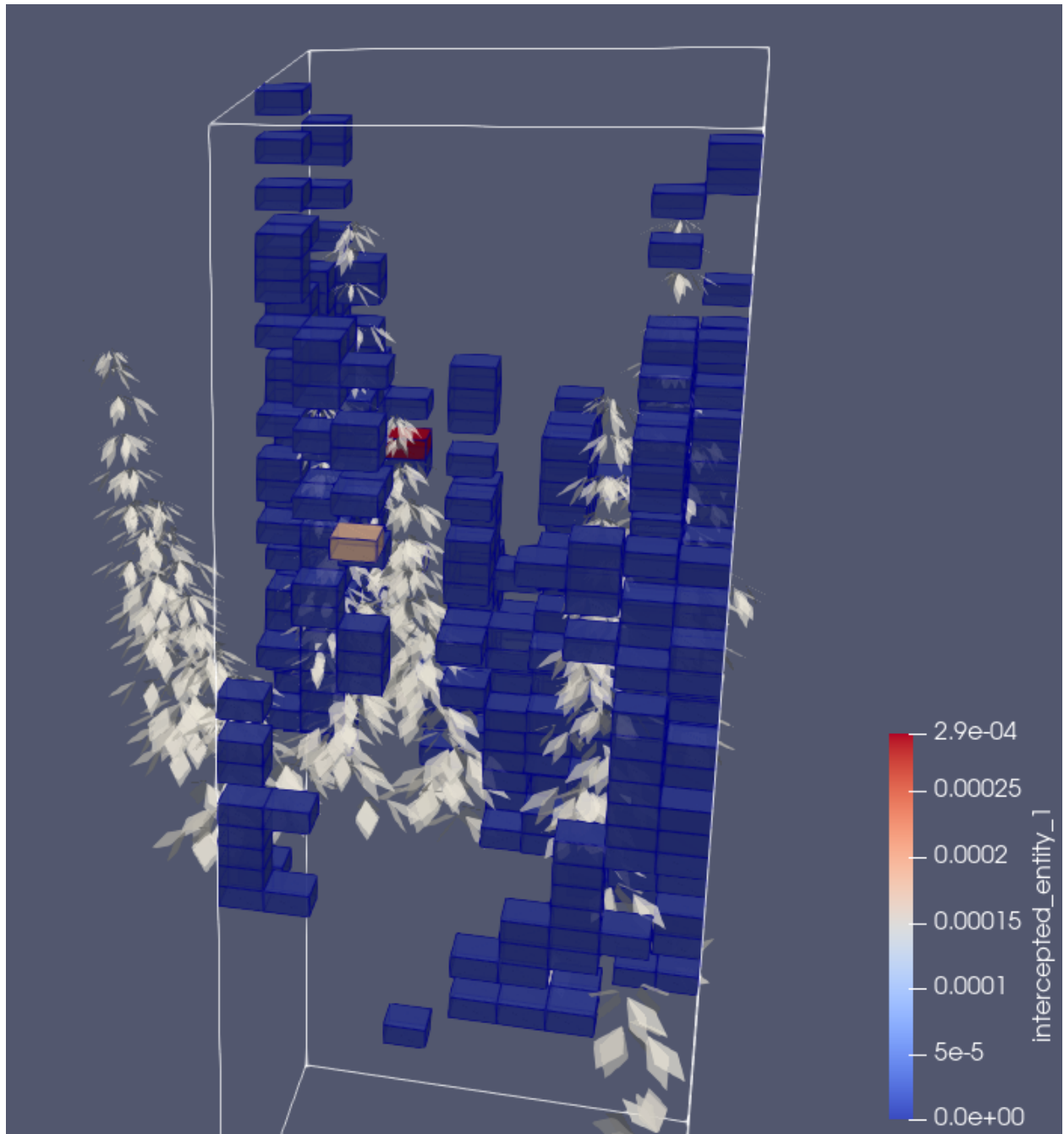


Fig. 3: Example of a grid of voxels

2.2 Installation

2.2.1 Setting a Python environment

We recommend an installation with conda.

1. Create a conda environment with miniconda3

```
conda create -n myenvname python=3 openalea.mtg openalea.plantgl alineal.
caribu alineal.astk numpy=1.20.3 pandas pytest sphinx sphinx-rtd-theme -c
conda-forge -c openalea3
```

2. Place yourself in the created environment: `conda activate myenvname`

Note: virtual sensors and soilmesh in Caribu > 8.0.10 are working correctly

2.2.2 Installation of Needed Packages

PyRATP

1. Git console:

```
git clone -b update_mobidiv https://github.com/mwoussen/PyRATP
```

2. Installation in the conda environment (in folder PyRATP)

```
make mode=develop
make clean
```

RiRi5

1. Git console:

```
git clone https://github.com/glouarn/riri5
```

2. Installation in the conda environment (in folder riri5)

```
python setup.py develop
```

LightVegeManager

1. Git console:

```
git clone https://github.com/mwoussen/lightvegemanager
```

2. Installation in the conda environment (in folder lightvegemanager)

```
python setup.py develop
```

2.2.3 Quickstart

Small test to quickly test the tool. LightVegeManager needs at least a geometric information and a light model to call between "ratp", "caribu" or "riri5".

```
from lightvegeamanger.LVM import LightVegeManager

# one triangle as a geometric element
# we write our triangle in a CaribuScene format
organ_id = 001
triangle_vertices = [(0,0,0), (1,0,0), (1,1,1)]
triangle = {organ_id : [triangle_vertices]}
geometry = { "scenes" : [triangle] }

# surfacic lighting with CARIBU
lighting = LightVegeManager(lightmodel="caribu")

# build the scene
lighting.build(geometry)

# compute lighting
energy = 500
hour = 15
day = 264 # 21st september
lighting.run(energy, hour, day)

# output
print(lighting.elements_outputs)
```

See also:

For more details on default values, see `LightVegeManager_defaultvalues`

2.3 Architecture of the tool

2.3.1 Package Content

The package has 8 folders and 4 files in its root:

- data: data files used in some the use examples in the package
- doc: user and reference documentations
- notebooks: jupyter notebooks with documented tutorials exploring the tool features
- s2v and s5: sources of analysis tools
- src: sources of LightVegeManager
- tests: unit testing files written in pytest format
- .gitignore: files and folders to ignore by git
- .readthedocs.yaml: config file for read-the-docs
- requirements.txt: packages needed for read-the-docs in order to compile
- README.md: Read Me file

- pytest.ini: config file for pytest
- setup.py: setup script used for installation

2.3.2 Code structure

The code structure of the tool is designed with a main class `LightVegeManager`, which calls modules for computing specific parts depending on the inputs.

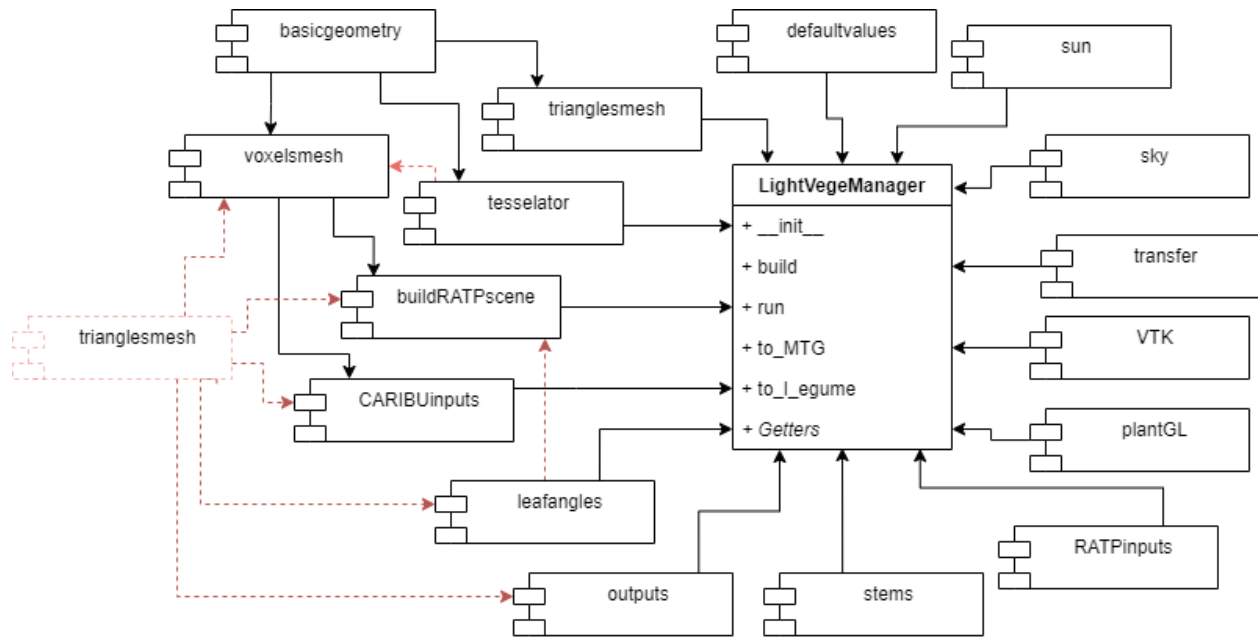


Fig. 4: Dependences between modules

Modules are:

- `LightVegeManager_tool` Main class of the tool. Calls all the other modules in `src`.
- `LightVegeManager_CARIBUinputs` Manages and prepares input information for CARIBU.
- `LightVegeManager_RATPinputs` Manage vegetation and meteo input informations for RATP
- `LightVegeManager_RiRi5inputs` Manage grid of voxels for RiRi5
- `LightVegeManager_VTK` Writes VTK files from `LightVegeManager` geometry and lighting data. Used for visualisation
- `LightVegeManager_basicgeometry` Provides basic geometric operations in 3D used by `LightVegeManager`.
- `LightVegeManager_buildRATPscene` Build a `PyRATP.grid` from inputs.
- `LightVegeManager_defaultvalues` Default for simulation fixed parameters
- `LightVegeManager_leafangles` Handles leaf angle distribution, both in its dynamic computing or reading a file
- `LightVegeManager_outputs` Manages and reformats output results from the light models in `pandas.DataFrame` with similar columns names
- `LightVegeManager_plantGL` Visualisation with `plantGL`
- `LightVegeManager_sky` Build a sky from `LightVegeManager` input informations

- `LightVegeManager_stems` Manages stems element
- `LightVegeManager_sun` Build a sun respecting each light model format
- `LightVegeManager_tesselator` Manages subdivision of a triangulation
- `LightVegeManager_transfer` Manages transfer of `LightVegeManager` results to plant Models
- `LightVegeManager_trianglesmesh` Builds and handles triangulation mesh.
- `LightVegeManager_voxelsmesh` Builds and handles axis oriented voxels mesh

2.3.3 Front End: the main commands

th tool is used through the class `LightVegeManager` and the following methods:

- constructor `__init__` builds the sky, which stays the same throughout all the simulation. It sets also default values if not precised in the inputs.
- `build()` creates a common geometric scene from inputs and set parameters for the light model.
- `run()` computes the lighting.

The outputs from radiations are automatically gathered in a pandas Dataframe and accessible from the getters `elements_outputs()`, `triangles_outputs()` and `voxels_outputs()`.

As part of our initial objective, we added two methods in order to convert the results in formats understandable by CN-Wheat and l-egume:

- `to_MTG()`, which updates a MTG table read by CN-Wheat
- `to_l_egume()`, which updates two tables read by l-egume

Note: l-egume needs a local information of transmitted lighting among a voxel grid. Then, you need to provide the grid dimensions to `LightVegeManager`.

The other getters available are:

- `sensors_outputs()`, outputs of virtual sensors, only with CARIBU
- `soilenergy()`, radiation received by the soil, only with CARIBU
- `sun()`, object containing sun position xyz
- `maxtrianglearea()`, if you entered a triangle mesh, return the largest triangle
- `tesselationtime()`, if you activated tessellation of a triangle mesh (redraw of triangles), return computation time
- `modelruntime()`, return the computation time of the light model

Finally, you also have additional tools available for analysing the inputs and visualising the outputs (*additional tools*).

2.3.4 Back End: More details about how the tool works

First of all, the geometric merging is set in a Caribu scene format. It is a dict where keys are indices and values are list of triangles, one triangle is list of 3 3-tuple representing the vertices. Here is an example:

```
# organ 1
triangle1 = [(0,0,0), (0,1,0), (1,1,0)]
triangle2 = [(0,0,0), (0,1,1), (1,1,1)]

# organ 2
triangle3 = [(0,0,2), (0,1,2), (1,1,2)]

caribuscene = { 1 : [triangle1, triangle2] ,
                2 : [triangle3] }
```

We choose this format for its low processing cost, because it uses basic python objects.

We also save and recreate a dict to organize the indices inside each input scene called `matching_ids` (*index management*).

The input parameters defines a common way for setting each light model parameters.

Geometric merging

We built a module to tessellate one triangle into four smaller triangles. The tessellation is applied either uniformly among all the triangle mesh or on a sides of a voxels grid. The tessellation following a grid is made in order to have a better matching of triangles in a voxels grid and attenuate the error of converting the mesh type.

We also built the possibility to compute dynamicaly the leaf angle distribution, either globally among all triangles, or locally inside each voxel.

Managing indexes

LightVegeManager expects a list of geometric scenes in its inputs. Each scene represents a plant specy. Each scene can also be sorted by elements, which can represent plant organs or just sets of triangles. The tool will then reorder all the indexes in order to avoid any confusion. The correspondance between input indices and new indices is stored in the dict attribute `matching_ids`.

Example of reordering:

Triangle subdivision

We implemented an algorithm for subdividing a triangle in 4 triangles according to triangle position in a grid of voxels. The goal was to have a better matching between a triangulation and a grid of voxels. Triangles are subdivided if they are between several voxels.

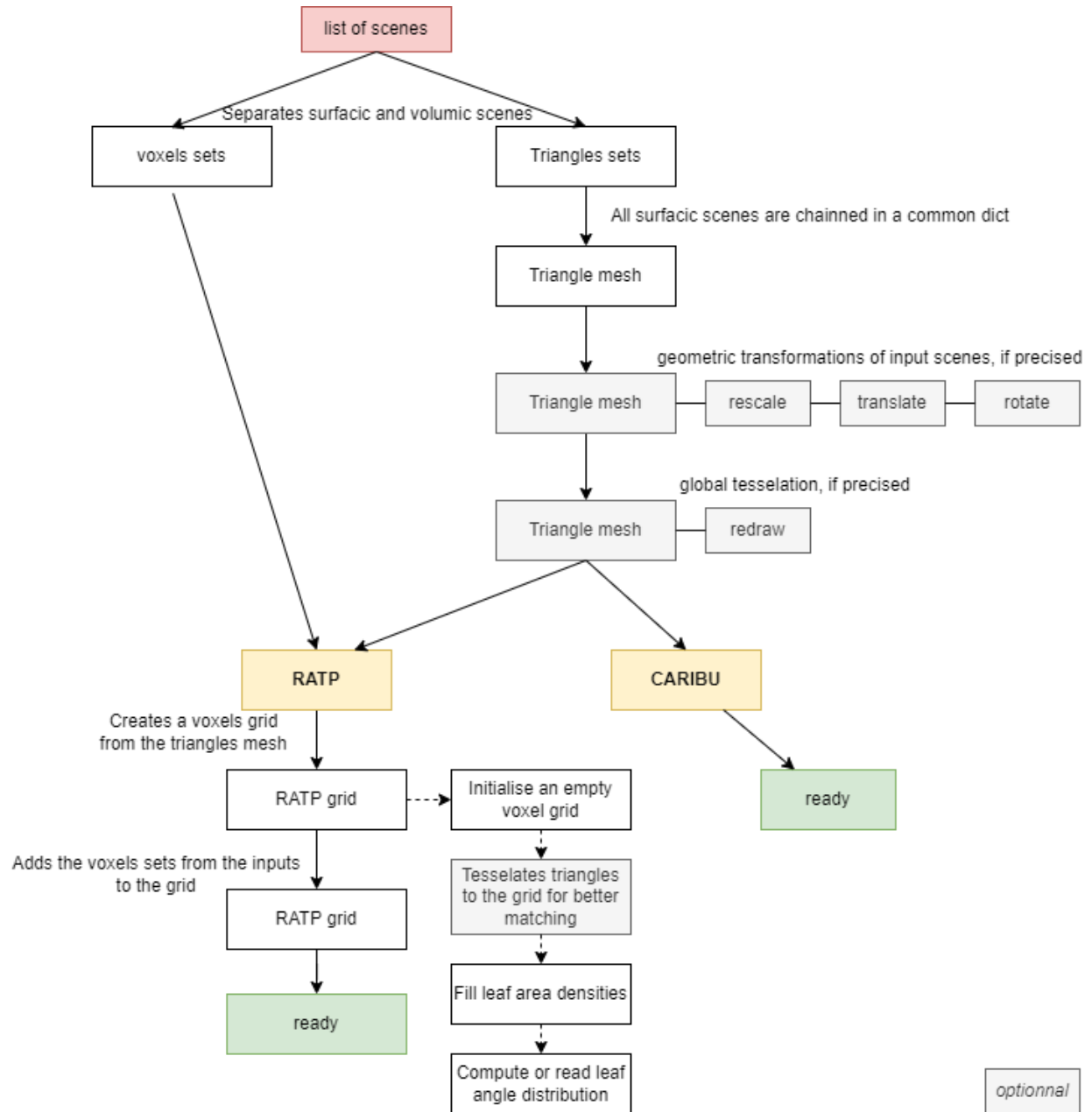


Fig. 5: Tool workflow for geometry

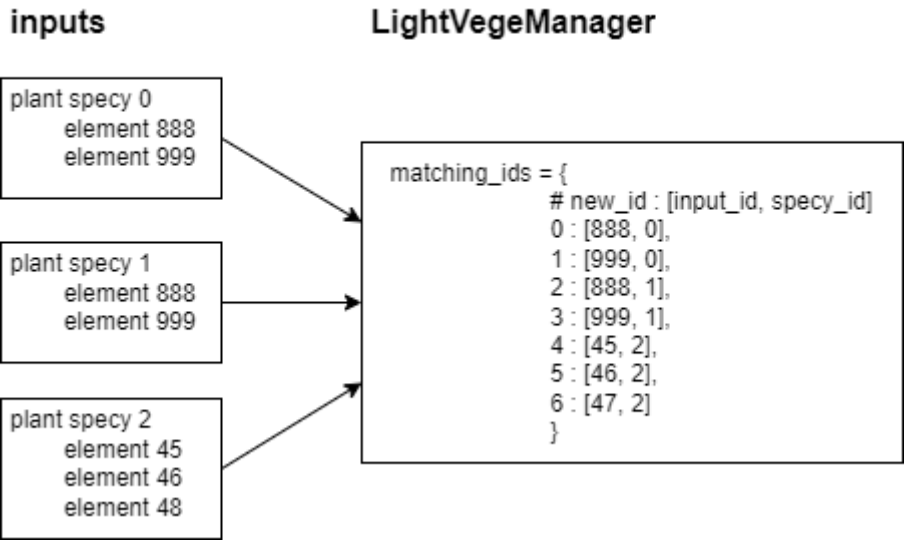


Fig. 6: Reordering indices in LightVegeManager

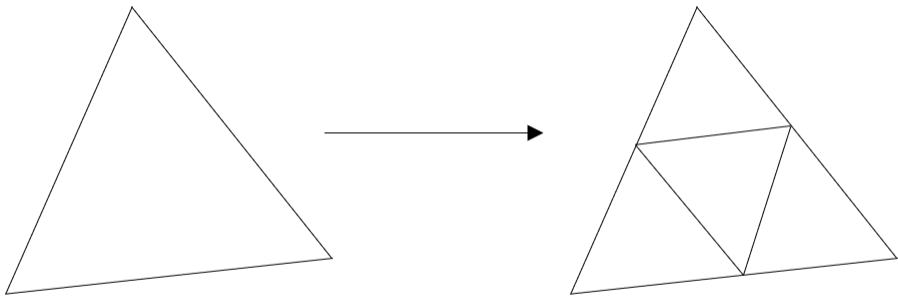


Fig. 7: Subdivision of a triangle

CARIBU, l-egume and virtual sensors

l-egume needs two different values to understand lighting results:

- total intercepted radiation for each plant
- local transmitted radiation following a voxel grid

In order to use CARIBU with l-egume, you need to retrieve transmitted radiations for each position of a voxel grid. LightVegeManager implements functions which can create a set of virtual sensors following a voxel grid. Then, with the virtual sensors and the soilmesh options activated, you can calculate the local transmitted radiation. Make sure to have the same grid dimensions as l-egume intern grid.

2.4 Inputs

In LightVegeManager, we choose to organize the input parameters in 3 python dict: geometric, environment and light model parameters.

2.4.1 Geometric inputs

```
geometry = {  
    "scenes" : [scene0, scene1, scene2, ...] ,  
    "domain" : ((xmin, ymin), (xmax, ymax)),  
    "stems id" : [(id_element, id_scene), ...],  
    "transformations" : {  
        "scenes unit" : 1,  
        "rescale" : kwarg ,  
        "translate" : kwarg ,  
        "xyz orientation" : 1,  
    }  
    kwarg ,  
    kwarg  
}
```

It contains the geometric scenes and directives to operate on them. You can also add descriptions on the scenes, especially if you have a large numbers of scenes and plant model evolved. Each scene must contains only one specy of plant, except for l-egume grid format, which can contains multiple species. As the geometric informations are likely to change during a simulation, this dict is not read by the constructor but rather by the `build()` method.

Scenes

"scenes" key needs a list of the geometric scenes. Each scene represents one plant specie, except for voxel grid format. There is no restrictions on the numbers of input scenes. Possible format are:

- PlantGL scene
- MTG table
- VGX file
- CaribuScene dict

```
# a vertice is a 3-tuple of float
triangle1 = [ (x1, y1, z1), (x2, y2, z2), (x3, y3, z3) ]
triangle2 = [ (x4, y4, z4), (x5, y5, z5), (x6, y6, z6) ]
mycaribuscene = { 888 : [ triangle1, triangle2 ] }

# 888 is the id of the element composed by triangle1 and triangle2
```

- Voxels grid: a dict with two keys:
 - "LA": a `scipy.array` of dimension [number of species, nz, ny, nx] and stores for each voxel of each specie a leaf area
 - "distrib": a list of `scipy.array` for each specy storing a leaf angle distribution

"domain" is necessary for CARIBU and infinite scene, it defines the xy square to replicate. "stems id" indicates the organ id of possible stems. They will be considered as strictly opaque element.

Geometric transformations

There is an optional fourth input key in the geometric dict, used to specify geometric transformations on several scenes. For example, you can arrange your inputs scenes in a specific pattern by translating them. The value of each entry is a dict:

```
"transformation" : { index_from_input_scenes : transformation_value }
```

Possible keys are the following:

"scenes unit"

Associates a measure unit among this list ['mm', 'cm', 'dm', 'm', 'dam', 'hm', 'km'] with a scene. You can also assign a unit to the inside global scene, the tool will rescale all the scenes in the same unit.

example:

```
transformations["scenes unit"] = {0 : 'm',
                                  1 : 'cm',
                                  2 : 'hm'}
```

"rescale"

Multiply all the lengths of a scene by a ratio.

example:

```
transformations["rescale"] = {0 : 0.5,
                              2 : 5}
```

"translate"

Apply a translation vector to a scene. A vector is 3-tuple.

example:

```
transformations["translate"] = {0 : (5, 0.2, 1),  
                                1 : (0, 5, 0)}
```

"xyz orientation"

Change the orientation of a scene among the xyz axis. When a model creates a scene in a different convention used by the light models, LightVegeManager allows for a common convention. RATP and CARIBU use the convention x+ matches to North.

Possible convention:

- "x+ = S": x+ matches to South
- "x+ = W": x+ matches to West
- "x+ = E": x+ matches to East

example:

```
transformations["xyz orientation"] = {0 : "x+ = S",  
                                       1 : "x+ = W"}
```

2.4.2 Environment parameters

```
environment = {  
    "coordinates" : [latitude, longitude, timezone] ,  
  
    "sky" : "turtle46" ,  
    "sky" : ["file", filepath] ,  
    "sky" : [nb_azimut, nb_zenith, "soc" or "uoc"] ,  
  
    "direct" : bool, # sun radiations  
    "diffus" : bool, # sky radiations  
    "reflected" : bool, # reflected radiation in the canopy  
    "infinite" : bool, # infinitisation of the scene  
}
```

Contains parameters related to the environment of modelling and static parameters during all the simulation.

The sky is defined by the "sky" key and has 3 different possibilities:

- "turtle46": SOC sky with 46 directions in "turtle" shape
- ["file", filepath]: sky defined by the file filepath
- [nb_azimut, nb_zenith, "soc" ou "uoc"]: computes dynamically the source directions

2.4.3 Light model parameters

Specific parameters for each light model, as they use very different syntax and approach.

CARIBU: surfacic approach

```
caribu_args = {
    "sun algo" : "ratp",
    "sun algo" : "caribu",

    "caribu opt" : {
        band0 = (reflectance, transmittance),
        band1 = (reflectance, transmittance),
        ...
    },
    "debug" : bool,
    "soil mesh" : bool,
    "sensors" : ["grid", dxyz, nxyz, orig, vtkpath, "vtk"]
}
```

The key "sun algo" specifies how to calculate the sun position. Possibilities are "ratp" or "caribu", which will call the function related to either one of the light models.

"caribu opt" defines the optical parameters in CARIBU format. For example:

```
caribu_parameters["caribu opt"] = {
    "par" = (0.10, 0.07) ,
    "nir" = (0.15, 0.05)
}
```

For virtual sensors, we propose the construction following a grid of voxels, where a sensor is the bottom side of a voxel.

```
caribu_parameters["sensors"] = ["grid", dxyz, nxyz, orig, path, "vtk"]
```

Where:

- dxyz = [x, y, z] : list of size of each side of a voxel
- nxyz = [nx, ny, nz] : list of number of voxels in each direction
- path : string of file path where to save the vtk file of the sensors
- "vtk" : flag to specify you want to write sensors in VTK format for visualisation

path and "vtk" are optional elements in the list

Note: At the moment, only grid option is available for sensors

RATP: volumic approach

```
ratp_args = {  
    # Grid specifications  
    "voxel size" : [dx, dy, dz],  
    "voxel size" : "dynamic",  
  
    "full grid" : bool,  
  
    "origin" : [xorigin, yorigin, zorigin],  
    "origin" : [xorigin, yorigin],  
  
    "number voxels" : [nx, ny, nz],  
    "grid slicing" : "ground = 0."  
    "tessellation level" : int  
  
    # Leaf angle distribution  
    "angle distrib algo" : "compute global",  
    "angle distrib algo" : "compute voxel",  
    "angle distrib algo" : "file",  
  
    "nb angle classes" : int,  
    "angle distrib file" : filepath,  
  
    # Vegetation type  
    "soil reflectance" : [reflectance_band0, reflectance_band1, ...],  
    "reflectance coefficients" : [reflectance_band0, reflectance_band1, ...],  
    "mu" : [mu_scene0, mu_scenel, ...]  
}
```

Grid specifications

- "voxel size": defines the size of one voxel, 2 possibilities
 - [float, float, float]: for a length on each direction (xyz)
 - "dynamic": create squared voxels where the length of a side is $l = 5 \cdot \max(\text{area}(\text{triangle}))$
- "number voxels": [nx, ny, nz], defines the number of voxels on each xyz axis. If not specified, the tool computes dynamically the grid size according to input geometries.
- "origin": possibility to define the grid origin.
 - [xorigin, yorigin, zorigin]
 - [xorigin, yorigin] and zorigin = -zmin
- "grid slicing": if "grid slicing" : "ground = 0." and "number voxels" is not specified and there are triangles in the input geometries, it rescales the grid to avoid the soil layer < 0
- "tessellation level": if there are triangles in the input geometries, you can tessellate them a certain number of times to match the voxel grid.
- "full grid": option to fill all empty voxels with a $1e-10$.

Leaf angle distribution

You can specify how the leaf angle distribution is computed. It can be computed dynamically from a triangulation.

- "angle distrib algo": 3 possibilities
 - "compute global": LightVegeManager computes a global leaf angle distribution
 - "compute voxel": LightVegeManager computes a local leaf angle distribution in each voxel of the grid
 - file: LightVegeManager reads a global leaf angle distribution in a file
- "nb angle classes": if "angle distrib algo" = "compute global" or "angle distrib algo" = "compute voxel", number of angle classes in the distribution
- "angle distrib file": if "angle distrib algo" = file" string precising the file path to read

Vegetation type

- "soil reflectance": if precised, soil reflects rays by a coefficient, one float by wavelength [coef_par, coef_nir]
- "reflectance coefficients": if precised, leaf reflects rays by a coefficient, one float by wavelength [coef_par, coef_nir]
- "mu": clumping effect for each input species

2.5 Additionnal Functionalities

Here are more functionalities implemented in the tool.

2.5.1 Inputs analysis Tool

For computing a leaf area distribution, you can run s5 or s2v tools, which was developped in previous projects. This tools are accessible with the methods s5() and s2v(). Those tools will create output files with leaf angle distribution, leaf area density and other informations related to turbid medium, from a triangles mesh inside a LightVegeManager object.

2.5.2 Visualisation

VTK files

You can create VTK files from the geometric information you have in the inputs. Files can be either triangles or voxels mesh. Available methods

- VTK_nolight(): write only geometric informations from the common scene
- VTK_light(): write geometric informations associated with radiation values for each element
- VTK_sun(): write a line representing the sun position

PlantGL visualizer

You can export a plantGL scene from geometric scene inside an instance. Available methods

- `plantGL_nolight()`: write only geometric informations from the common scene
- `plantGL_light()`: write geometric informations associated with radiation values for each element
- `plantGL_sensors()`: write virtual sensors stock in the instance

2.6 Tutorials with jupyter notebooks

Jupyter notebooks are available with documented tutorials exploring the tool features.

2.6.1 LightVegeManager first steps

Content:

- One triangle
 - CARIBU
 - RATP
- Set of triangles
 - CARIBU
 - RATP

Introduction

This notebook provides an introduction to the tool and its default parameters. Visualization is provided with PlantGL and its adaptation to jupyter notebook `plantgl-jupyter`.

The main methods of a `LightVegeManager` instance are : - constructor `__init__`: returns an instance and initialize static parameters such as sky and default parameters - `build`: build and arrange the geometric scene following the chosen light model format - `run`: compute lighting - DataFrame outputs are stored in `triangles_ouputs`, `voxels_ouputs` and `elements_ouputs`

```
[1]: # imports the LightVegeManager object and SceneWidget for visual representation
from lightvegemanager.LVM import LightVegeManager
from pgljupyter import SceneWidget
```

One triangle

As a first example, we can compute lighting on a single 3D triangle. A triangle is represented with a list of 3 cartesian points (x, y, z)

```
[2]: t = [(0., 0., 0.), (1., 0., 0.), (1., 1., 1.)]
```

CARIBU (surfarcic modelling)

- 1) Initialize the instance. The `lightmodel` must be entered, at the moment you can choose between "caribu", "ratp" and "riri5"

```
[3]: # initialize the instance
lighting = LightVegeManager(lightmodel="caribu")
```

2) Build the geometry. The triangle will be save inside the instance.

```
[4]: # build the scene
      lighting.build(geometry=t)
```

In order to visualize the scene in the instance, you can give a plantGL Scene in SceneWidget through two methods: - `plantGL_nolight`: plots only geometric elements - `plantGL_light`: plots geometric elements and colors the scene according to PAR values

```
[5]: SceneWidget(lighting.plantGL_nolight(), size_display=(600, 400), plane=True, size_world_u= 4, axes_helper=True)
```

```
[5]: SceneWidget(axes_helper=True, scenes=[{'id': 'F8IKbCRRTrC164vqQvjmt6n0', 'data': b'x\
↳ xdaSLrw\xaf5\xaf7e`Pp\xe0`...
```

3) Compute the lighting. By default it will compute direct and diffuse lighting.

```
[6]: energy = 500.  
hour = 15  
day = 264  
lighting.run(energy=energy, hour=hour, day=day)
```

Then, you can print the Dataframe outputs

```
[7]: # print the outputs
print(lighting.triangles_outputs)
```

[illegible]**RATP**

To use RATP, you need to create a new instance. The others methods can be used in the same way as with CARIBU

```
[9]: # initialize the instance
lighting = LightVegeManager(lightmodel="ratp")

# build the scene
lighting.build(geometry=t)
```

With `plantGL_nolight` you can precise if you want to plot the voxels. By default, if not precised, a voxel side is set as 3 times the longest triangle side.

```
[11]: # visualisation
SceneWidget(lighting.plantGL_nolight(printvoxels=True),
            size_display=(600, 400),
            plane=True,
            size_world = 4,
            axes_helper=True)

[11]: SceneWidget(axes_helper=True, scenes=[{'id': '7Btw3DEYYw3MHgwE602FD7CTm', 'data': b'x\
↳ xdaSLrw\x5\x7e`Pp\xe0\...
```

```
[12]: # compute the lighting
energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)
```

You can get the outputs of the voxels or the triangles

```
[13]: # print the outputs
print(lighting.voxels_outputs)
```

	VegetationType	Day	Hour	Voxel	Nx	Ny	Nz	ShadedPAR	SunlitPAR	\
0	1.0	264.0	15.0	1.0	1	1	1	380.635895	473.640411	

	ShadedArea	SunlitArea	Area	PARa	Intercepted	Transmitted
0	0.010761	0.696346	0.707107	472.225067	0.667827	8.742233

```
[14]: # print the outputs
print(lighting.triangles_outputs)
```

	Triangle	Organ	Voxel	VegetationType	primitive_area	Day	Hour	Nx	\
0	0	0	1.0	1	0.707107	264.0	15.0	1	

	Ny	Nz	ShadedPAR	SunlitPAR	ShadedArea	SunlitArea	Area	\
0	1	1	380.635895	473.640411	0.010761	0.696346	0.707107	

	PARa	Intercepted	Transmitted
0	472.225067	0.667827	8.742233

Set of triangles

For this second example, we will generate a set of random 3D triangles. A function is already implemented in the package.

```
[8]: from lightvegeanager.trianglesmesh import random_triangle_generator
```

```
[9]: nb_triangles = 5000
spheresize = (10., 2.) # vertices of the triangles are on the sphere surface
triangles = []
for i in range(nb_triangles):
    triangles.append(random_triangle_generator(spheresize=spheresize))
```

```
[10]: # initialize the instance
      lighting = LightVegeManager(lightmodel="caribu")

      # build the scene
      lighting.build(geometry=triangles)

      # visualisation
      SceneWidget(lighting.plantGL_nolight(),
                  position=(-50.0, -50.0, 0.0),
                  size_display=(600, 400),
                  plane=True,
                  size_world = 100,
                  axes_helper=True)
```

```
[14]: # compute the lighting
      energy = 500.
      hour = 15
      day = 264
      lighting.run(energy=energy, hour=hour, day=day)

      # print the outputs
      print(lighting.triangles_outputs)
```

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4999 2.405607

[5000 rows x 8 columns]

```
[13]: SceneWidget(lighting.plantGL_light(),
                  position=(-50.0, -50.0, 0.0),
                  size_display=(600, 400),
                  plane=True,
                  size_world = 100,
                  axes_helper=True)
```

```
[13]: SceneWidget(axes_helper=True, scenes=[{'id': 'OGd2X5hD1gviccEoC1jTR7rLb', 'data': b'x\
↳ xda\x8c}\x07X\x15\xd7\xfb...
```

RATP

Now, we will set the voxels size. It needs to be specified in a dict which stores all RATP parameters. Here, you need to precise the length on each axis of one voxel.

```
[9]: ratp_parameters = { "voxel size": [20.] * 3 }
```

Then, the dict is an argument in the instance creation.

```
[10]: # initialize the instance
lighting = LightVegeManager(lightmodel="ratp", lightmodel_parameters=ratp_parameters)

# build the scene
lighting.build(geometry=triangles)

# visualisation
SceneWidget(lighting.plantGL_nolight(printtriangles=True, printvoxels=True),
            position=(-50.0, -50.0, 0.0),
            size_display=(600, 400),
            plane=True,
            size_world = 100,
            axes_helper=True)
```

```
[10]: SceneWidget(axes_helper=True, scenes=[{'id': 'llGi0BzghQcYBBjj3iUAJ4Iks', 'data': b'x\
↳ xda\x8c}\x07|0\xd9\xd6v...
```

```
[11]: # compute the lighting
energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)

# print the outputs
print(lighting.voxels_outputs)
```

	VegetationType	Day	Hour	Voxel	Nx	Ny	Nz	ShadedPAR	SunlitPAR	\
0	1.0	264.0	15.0	1.0	3	3	5	40.732689	136.623886	
1	1.0	264.0	15.0	2.0	5	6	6	28.347637	124.238831	

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2	1.0	264.0	15.0	3.0	1	4	3	137.707138	233.598343
3	1.0	264.0	15.0	4.0	3	3	2	183.874008	279.765198
4	1.0	264.0	15.0	5.0	2	6	5	41.833862	137.725067
..
213	1.0	264.0	15.0	214.0	4	2	4	63.669552	159.560745
214	1.0	264.0	15.0	215.0	1	7	6	146.115402	242.006592
215	1.0	264.0	15.0	216.0	6	3	7	82.600769	178.491959
216	1.0	264.0	15.0	217.0	1	7	2	339.311615	435.202850
217	1.0	264.0	15.0	218.0	4	5	1	375.165588	471.056763

	ShadedArea	SunlitArea	Area	PARa	Intercepted	\
0	1024.282715	10.943428	1035.226196	41.746357	86.433853	
1	1377.175171	283.350006	1660.525146	44.710396	148.485474	
2	172.634308	291.246674	463.880981	197.912231	183.615433	
3	486.705994	360.075684	846.781677	224.649658	380.458435	
4	1375.770874	41.413651	1417.184570	44.636040	126.515022	
..	
213	626.312683	157.908005	784.220703	82.977875	130.145935	
214	57.020470	86.957054	143.977524	204.030106	58.751499	
215	197.366257	156.226395	353.592651	124.967972	88.375519	
216	4.840422	17.089012	21.929434	414.037079	18.159195	
217	0.815029	39.664459	40.479488	469.126038	37.979965	

	Transmitted
0	31.874031
1	18.599306
2	119.887787
3	101.195755
4	33.631508
..	...
213	52.329762
214	128.099014
215	82.136887
216	328.422760
217	385.791229

[218 rows x 15 columns]

```
[23]: # print the outputs
print(lighting.triangles_outputs)
```

	Triangle	Organ	Voxel	VegetationType	primitive_area	Day	Hour	Nx	\
0	0	0	1.0	1	6.008933	264.0	15.0	5	
49	1	0	2.0	1	64.911050	264.0	15.0	4	
77	2	0	3.0	1	48.494517	264.0	15.0	3	
84	3	0	4.0	1	5.762879	264.0	15.0	1	
91	4	0	5.0	1	21.321846	264.0	15.0	3	
...
586	4995	0	21.0	1	21.090689	264.0	15.0	5	
3641	4996	0	136.0	1	32.577000	264.0	15.0	4	
1051	4997	0	37.0	1	76.699258	264.0	15.0	6	
1822	4998	0	63.0	1	1.464895	264.0	15.0	2	

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3443	4999	0	129.0	1	51.065793	264.0	15.0	5
	Ny	Nz	ShadedPAR	SunlitPAR	ShadedArea	SunlitArea	Area	\
0	6	3	48.783260	144.457764	1669.359253	307.066376	1976.425659	
49	2	6	50.222652	145.897171	639.340942	467.153961	1106.494873	
77	7	7	76.529640	172.204147	131.880585	49.266487	181.147064	
84	7	4	162.029709	257.704224	114.480240	108.982895	223.463135	
91	5	5	36.165016	131.839523	1061.264648	3.100358	1064.364990	
...	
586	4	6	28.958939	124.633453	982.723572	278.425110	1261.148682	
3641	4	4	20.419191	116.093712	1379.531006	34.760368	1414.291382	
1051	6	5	68.352638	164.027176	1125.141846	1.110655	1126.252441	
1822	5	5	39.313770	134.988281	1225.665894	14.276536	1239.942383	
3443	2	6	60.735207	156.409714	431.796021	383.754333	815.550354	
			PARa	Intercepted	Transmitted			
0			63.647678	251.589828	31.452011			
49			90.615723	200.531677	35.146641			
77			102.550201	37.153339	72.656891			
84			208.690125	93.269104	155.314255			
91			36.443703	77.578804	28.307266			
...					
586			50.081097	126.319427	21.615057			
3641			22.770676	64.408737	13.644242			
1051			68.446991	154.177170	60.248528			
1822			40.415356	100.225418	28.215555			
3443			105.754509	172.496262	47.396954			
[5000 rows x 18 columns]								

[13]: # visualisation

```
SceneWidget(lighting.plantGL_light(printtriangles=True, printvoxels=False),
             position=(-50.0, -50.0, 0.0),
             size_display=(600, 400),
             plane=True,
             size_world = 100,
             axes_helper=True)
```

```
[13]: SceneWidget(axes_helper=True, scenes=[{'id': '0aYtClMfKtSXFShXk1ESHgnYz', 'data': b'x\
↪xda\x84]\x07xMY\x07\x0e\...
```

[14]: # visualisation

```
SceneWidget(lighting.plantGL_light(printtriangles=False, printvoxels=True),
             position=(-50.0, -50.0, 0.0),
             size_display=(600, 400),
             plane=True,
             size_world = 100,
             axes_helper=True)
```

```
[14]: SceneWidget(axes_helper=True, scenes=[{'id': 'jWP5jHrIFv0YocDTC7u66AES2', 'data': b'x\
↪xda\x95]K\x8f\xa6\xc7U\x...
```


2.6.2 Environment parameters: ways to set the simulation environment

Content

- Coordinates and other boolean options
- sky
 - turtle of 46 directions
 - file
 - custom number of sky directions

Introduction

Environment parameters are stored in a dict and transferred as an input argument for a LightVegeManager instance. It defines all static parameters during a simulation, such the sky type, radiative options etc...

```
environment = {
    "coordinates" : [latitude, longitude, timezone] ,

    "sky" : "turtle46" ,
    "sky" : ["file", filepath] ,
    "sky" : [nb_azimut, nb_zenith, "soc" or "uoc"] ,

    "direct" : bool, # sun radiations
    "diffus" : bool, # sky radiations
    "reflected" : bool, # reflected radiation in the canopy
    "infinite" : bool, # infinitisation of the scene
}
```

```
[1]: from lightvegemanager.LVM import LightVegeManager
     from pgljupyter import SceneWidget
```

As a geometric example, we will use a random set of 3D triangles

```
[2]: from lightvegemanager.trianglesmesh import random_triangle_generator

nb_triangles = 50
spheresize = (10., 2.) # vertices of triangles are the sphere surface
triangles = []
for i in range(nb_triangles):
    triangles.append(random_triangle_generator(spheresize=spheresize))
```

First options

- "coordinates": sets the coordinates of the simulation, this matters if you want direct radiations
- "infinite": activates infinite reproduction
- "reflected": activates the reflections in the scene
- "direct": activates the direct radiations (sun)
- "diffuse": activates the diffuse radiations (sky)

An example of use

```
[3]: longitude = 2.
latitude = 46.
timezone = 1
coordinates = [latitude, longitude, timezone]
infinite = False
reflected = False
direct = False
diffuse = True

environment = {
    "coordinates": coordinates ,
    "infinite": infinite,
    "reflected": reflected,
    "direct": direct,
    "diffuse": diffuse
}
```

```
[4]: lighting = LightVegeManager(lightmodel="caribu", environment=environment)
lighting.build(geometry=triangles)

energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)
print(lighting.triangles_outputs)
```

	Day	Hour	Triangle	Organ	VegetationType	Area	par	Eabs	\
0	264	15	0	0	0	99.480976	313.1030		
1	264	15	1	0	0	140.415211	318.7210		
2	264	15	2	0	0	20.519232	384.2305		
3	264	15	3	0	0	23.926310	372.2110		
4	264	15	4	0	0	5.986450	414.9295		
5	264	15	5	0	0	10.845583	389.0330		
6	264	15	6	0	0	0.882299	385.6705		
7	264	15	7	0	0	32.812203	350.8225		
8	264	15	8	0	0	36.321775	375.5740		
9	264	15	9	0	0	5.071856	409.3300		
10	264	15	10	0	0	52.628089	366.5175		
11	264	15	11	0	0	103.885213	365.5105		
12	264	15	12	0	0	65.457326	362.9340		
13	264	15	13	0	0	0.567605	371.0460		
14	264	15	14	0	0	7.122030	398.2765		

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15	264	15	15	0	0	5.181860	342.8800
16	264	15	16	0	0	271.820976	384.4815
17	264	15	17	0	0	91.585066	382.0960
18	264	15	18	0	0	36.315518	352.2335
19	264	15	19	0	0	31.149412	375.1325
20	264	15	20	0	0	35.587854	371.4830
21	264	15	21	0	0	14.172730	387.1420
22	264	15	22	0	0	31.918145	306.4970
23	264	15	23	0	0	76.036115	360.8220
24	264	15	24	0	0	13.932378	348.0675
25	264	15	25	0	0	55.601914	391.2430
26	264	15	26	0	0	84.448667	373.2410
27	264	15	27	0	0	90.626852	390.3190
28	264	15	28	0	0	19.211308	305.5760
29	264	15	29	0	0	7.412773	342.4710
30	264	15	30	0	0	50.867131	386.5955
31	264	15	31	0	0	22.183195	356.0750
32	264	15	32	0	0	5.146020	341.1475
33	264	15	33	0	0	14.648915	367.1705
34	264	15	34	0	0	64.285771	355.4715
35	264	15	35	0	0	15.752372	373.9875
36	264	15	36	0	0	34.818585	365.3500
37	264	15	37	0	0	61.748544	363.2435
38	264	15	38	0	0	102.627411	413.6665
39	264	15	39	0	0	6.460148	330.7685
40	264	15	40	0	0	45.802731	373.1850
41	264	15	41	0	0	21.008426	356.8730
42	264	15	42	0	0	9.276760	334.7805
43	264	15	43	0	0	28.316439	353.1385
44	264	15	44	0	0	36.758141	335.3380
45	264	15	45	0	0	121.996376	346.0755
46	264	15	46	0	0	69.352270	351.8705
47	264	15	47	0	0	71.266675	365.3110
48	264	15	48	0	0	81.346766	401.6110
49	264	15	49	0	0	13.311873	406.2700

par Ei

0	368.356471
1	374.965882
2	452.035882
3	437.895294
4	488.152353
5	457.685882
6	453.730000
7	412.732353
8	441.851765
9	481.564706
10	431.197059
11	430.012353
12	426.981176
13	436.524706
14	468.560588

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```
15 403.388235
16 452.331176
17 449.524706
18 414.392353
19 441.332353
20 437.038824
21 455.461176
22 360.584706
23 424.496471
24 409.491176
25 460.285882
26 439.107059
27 459.198824
28 359.501176
29 402.907059
30 454.818235
31 418.911765
32 401.350000
33 431.965294
34 418.201765
35 439.985294
36 429.823529
37 427.345294
38 486.666471
39 389.139412
40 439.041176
41 419.850588
42 393.859412
43 415.457059
44 394.515294
45 407.147647
46 413.965294
47 429.777647
48 472.483529
49 477.964706
```

Different ways to set a sky

Turtle46

This options creates a sky in a turtle of 46 directions. It is the default sky in the tool.

```
[5]: sky = "turtle46"
environment.update({"sky": sky})
```

```
[6]: lighting = LightVegeManager(lightmodel="caribu", environment=environment)
lighting.build(geometry=triangles)
lighting.run(energy=energy, hour=hour, day=day)
print(lighting.triangles_outputs)
```

	Day	Hour	Triangle	Organ	VegetationType	Area	par	Eabs	\
0	264	15	0	0	0	99.480976	313.1030		
1	264	15	1	0	0	140.415211	318.7210		
2	264	15	2	0	0	20.519232	384.2305		
3	264	15	3	0	0	23.926310	372.2110		
4	264	15	4	0	0	5.986450	414.9295		
5	264	15	5	0	0	10.845583	389.0330		
6	264	15	6	0	0	0.882299	385.6705		
7	264	15	7	0	0	32.812203	350.8225		
8	264	15	8	0	0	36.321775	375.5740		
9	264	15	9	0	0	5.071856	409.3300		
10	264	15	10	0	0	52.628089	366.5175		
11	264	15	11	0	0	103.885213	365.5105		
12	264	15	12	0	0	65.457326	362.9340		
13	264	15	13	0	0	0.567605	371.0460		
14	264	15	14	0	0	7.122030	398.2765		
15	264	15	15	0	0	5.181860	342.8800		
16	264	15	16	0	0	271.820976	384.4815		
17	264	15	17	0	0	91.585066	382.0960		
18	264	15	18	0	0	36.315518	352.2335		
19	264	15	19	0	0	31.149412	375.1325		
20	264	15	20	0	0	35.587854	371.4830		
21	264	15	21	0	0	14.172730	387.1420		
22	264	15	22	0	0	31.918145	306.4970		
23	264	15	23	0	0	76.036115	360.8220		
24	264	15	24	0	0	13.932378	348.0675		
25	264	15	25	0	0	55.601914	391.2430		
26	264	15	26	0	0	84.448667	373.2410		
27	264	15	27	0	0	90.626852	390.3190		
28	264	15	28	0	0	19.211308	305.5760		
29	264	15	29	0	0	7.412773	342.4710		
30	264	15	30	0	0	50.867131	386.5955		
31	264	15	31	0	0	22.183195	356.0750		
32	264	15	32	0	0	5.146020	341.1475		
33	264	15	33	0	0	14.648915	367.1705		
34	264	15	34	0	0	64.285771	355.4715		
35	264	15	35	0	0	15.752372	373.9875		
36	264	15	36	0	0	34.818585	365.3500		
37	264	15	37	0	0	61.748544	363.2435		
38	264	15	38	0	0	102.627411	413.6665		
39	264	15	39	0	0	6.460148	330.7685		
40	264	15	40	0	0	45.802731	373.1850		
41	264	15	41	0	0	21.008426	356.8730		
42	264	15	42	0	0	9.276760	334.7805		
43	264	15	43	0	0	28.316439	353.1385		
44	264	15	44	0	0	36.758141	335.3380		
45	264	15	45	0	0	121.996376	346.0755		
46	264	15	46	0	0	69.352270	351.8705		
47	264	15	47	0	0	71.266675	365.3110		
48	264	15	48	0	0	81.346766	401.6110		
49	264	15	49	0	0	13.311873	406.2700		
par Ei									

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0	368.356471
1	374.965882
2	452.035882
3	437.895294
4	488.152353
5	457.685882
6	453.730000
7	412.732353
8	441.851765
9	481.564706
10	431.197059
11	430.012353
12	426.981176
13	436.524706
14	468.560588
15	403.388235
16	452.331176
17	449.524706
18	414.392353
19	441.332353
20	437.038824
21	455.461176
22	360.584706
23	424.496471
24	409.491176
25	460.285882
26	439.107059
27	459.198824
28	359.501176
29	402.907059
30	454.818235
31	418.911765
32	401.350000
33	431.965294
34	418.201765
35	439.985294
36	429.823529
37	427.345294
38	486.666471
39	389.139412
40	439.041176
41	419.850588
42	393.859412
43	415.457059
44	394.515294
45	407.147647
46	413.965294
47	429.777647
48	472.483529
49	477.964706

File

You can set sky directions in a file. It needs azimuth, zenith, weight and solid angle of each direction.

```
[7]: import os
datafile = os.path.join(os.path.join(os.path.dirname(os.path.abspath("")), "data"), "sky_
↪5.data")
datafile
```

```
[7]: 'C:\\Users\\mwoussen\\cdd\\codes\\dev\\lightvegemanager\\data\\sky_5.data'
```

```
[8]: sky = datafile
environment.update({"sky": sky})
```

```
[9]: lighting = LightVegeManager(lightmodel="caribu", environment=environment)
lighting.build(geometry=triangles)
lighting.run(energy=energy, hour=hour, day=day)
print(lighting.triangles_outputs)
```

	Day	Hour	Triangle	Organ	VegetationType	Area	par	Eabs	\
0	264	15	0	0	0	99.480976	321.8920		
1	264	15	1	0	0	140.415211	410.9825		
2	264	15	2	0	0	20.519232	349.7725		
3	264	15	3	0	0	23.926310	390.1275		
4	264	15	4	0	0	5.986450	404.9985		
5	264	15	5	0	0	10.845583	405.4615		
6	264	15	6	0	0	0.882299	388.1070		
7	264	15	7	0	0	32.812203	375.9985		
8	264	15	8	0	0	36.321775	378.9715		
9	264	15	9	0	0	5.071856	393.7835		
10	264	15	10	0	0	52.628089	391.1865		
11	264	15	11	0	0	103.885213	396.1285		
12	264	15	12	0	0	65.457326	381.3970		
13	264	15	13	0	0	0.567605	382.6855		
14	264	15	14	0	0	7.122030	392.8865		
15	264	15	15	0	0	5.181860	336.5425		
16	264	15	16	0	0	271.820976	393.6545		
17	264	15	17	0	0	91.585066	357.0890		
18	264	15	18	0	0	36.315518	383.2600		
19	264	15	19	0	0	31.149412	361.9780		
20	264	15	20	0	0	35.587854	376.8490		
21	264	15	21	0	0	14.172730	380.3260		
22	264	15	22	0	0	31.918145	361.1125		
23	264	15	23	0	0	76.036115	399.0185		
24	264	15	24	0	0	13.932378	343.3480		
25	264	15	25	0	0	55.601914	411.6490		
26	264	15	26	0	0	84.448667	396.3155		
27	264	15	27	0	0	90.626852	376.1960		
28	264	15	28	0	0	19.211308	283.1020		
29	264	15	29	0	0	7.412773	384.0860		
30	264	15	30	0	0	50.867131	357.6440		
31	264	15	31	0	0	22.183195	383.9450		
32	264	15	32	0	0	5.146020	430.5005		
33	264	15	33	0	0	14.648915	416.5190		

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34	264	15	34	0	0	64.285771	414.2600
35	264	15	35	0	0	15.752372	263.4695
36	264	15	36	0	0	34.818585	389.2345
37	264	15	37	0	0	61.748544	336.5750
38	264	15	38	0	0	102.627411	402.2385
39	264	15	39	0	0	6.460148	373.0750
40	264	15	40	0	0	45.802731	397.2810
41	264	15	41	0	0	21.008426	417.2495
42	264	15	42	0	0	9.276760	404.4165
43	264	15	43	0	0	28.316439	386.4300
44	264	15	44	0	0	36.758141	411.7950
45	264	15	45	0	0	121.996376	379.8200
46	264	15	46	0	0	69.352270	327.2225
47	264	15	47	0	0	71.266675	389.3355
48	264	15	48	0	0	81.346766	381.5730
49	264	15	49	0	0	13.311873	383.4205

par Ei

0	378.696471
1	483.508824
2	411.497059
3	458.973529
4	476.468824
5	477.013529
6	456.596471
7	442.351176
8	445.848824
9	463.274706
10	460.219412
11	466.033529
12	448.702353
13	450.218235
14	462.219412
15	395.932353
16	463.122941
17	420.104706
18	450.894118
19	425.856471
20	443.351765
21	447.442353
22	424.838235
23	469.433529
24	403.938824
25	484.292941
26	466.253529
27	442.583529
28	333.061176
29	451.865882
30	420.757647
31	451.700000
32	506.471176
33	490.022353

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```

34 487.364706
35 309.964118
36 457.922941
37 395.970588
38 473.221765
39 438.911765
40 467.389412
41 490.881765
42 475.784118
43 454.623529
44 484.464706
45 446.847059
46 384.967647
47 458.041765
48 448.909412
49 451.082941

```

Custom number of directions

You can directly precise the number of directions for each spherical axis.

```

[10]: nazimuts = 5
      nzenits = 5
      skytype = "soc"
      sky = [nazimuts, nzenits, skytype]
      environment.update({"sky": sky})

[11]: lighting = LightVegeManager(lightmodel="caribu", environment=environment)
      lighting.build(geometry=triangles)
      lighting.run(energy=energy, hour=hour, day=day)
      print(lighting.triangles_outputs)

```

	Day	Hour	Triangle	Organ	VegetationType	Area	par	Eabs	\
0	264	15	0	0	0	99.480976	312.9400		
1	264	15	1	0	0	140.415211	307.4715		
2	264	15	2	0	0	20.519232	376.8230		
3	264	15	3	0	0	23.926310	380.4820		
4	264	15	4	0	0	5.986450	400.4520		
5	264	15	5	0	0	10.845583	410.6180		
6	264	15	6	0	0	0.882299	382.5890		
7	264	15	7	0	0	32.812203	342.8405		
8	264	15	8	0	0	36.321775	378.7905		
9	264	15	9	0	0	5.071856	409.1425		
10	264	15	10	0	0	52.628089	358.2720		
11	264	15	11	0	0	103.885213	370.8735		
12	264	15	12	0	0	65.457326	373.1205		
13	264	15	13	0	0	0.567605	372.0525		
14	264	15	14	0	0	7.122030	408.1645		
15	264	15	15	0	0	5.181860	320.8560		
16	264	15	16	0	0	271.820976	382.6820		
17	264	15	17	0	0	91.585066	340.6655		

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18	264	15	18	0	0	36.315518	339.7660
19	264	15	19	0	0	31.149412	385.4065
20	264	15	20	0	0	35.587854	357.5670
21	264	15	21	0	0	14.172730	393.8765
22	264	15	22	0	0	31.918145	307.1930
23	264	15	23	0	0	76.036115	352.0500
24	264	15	24	0	0	13.932378	341.7345
25	264	15	25	0	0	55.601914	387.1755
26	264	15	26	0	0	84.448667	375.2625
27	264	15	27	0	0	90.626852	391.0160
28	264	15	28	0	0	19.211308	285.6480
29	264	15	29	0	0	7.412773	359.1335
30	264	15	30	0	0	50.867131	393.6610
31	264	15	31	0	0	22.183195	343.9185
32	264	15	32	0	0	5.146020	315.2815
33	264	15	33	0	0	14.648915	357.9085
34	264	15	34	0	0	64.285771	357.0725
35	264	15	35	0	0	15.752372	371.3890
36	264	15	36	0	0	34.818585	370.8550
37	264	15	37	0	0	61.748544	349.6305
38	264	15	38	0	0	102.627411	413.2585
39	264	15	39	0	0	6.460148	317.7325
40	264	15	40	0	0	45.802731	377.5860
41	264	15	41	0	0	21.008426	335.8295
42	264	15	42	0	0	9.276760	346.0530
43	264	15	43	0	0	28.316439	370.1290
44	264	15	44	0	0	36.758141	333.0075
45	264	15	45	0	0	121.996376	362.9850
46	264	15	46	0	0	69.352270	347.6555
47	264	15	47	0	0	71.266675	371.9740
48	264	15	48	0	0	81.346766	397.0950
49	264	15	49	0	0	13.311873	406.0575

par Ei

0	368.164706
1	361.731176
2	443.321176
3	447.625882
4	471.120000
5	483.080000
6	450.104706
7	403.341765
8	445.635882
9	481.344118
10	421.496471
11	436.321765
12	438.965294
13	437.708824
14	480.193529
15	377.477647
16	450.214118
17	400.782941

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```

18 399.724706
19 453.419412
20 420.667059
21 463.384118
22 361.403529
23 414.176471
24 402.040588
25 455.500588
26 441.485294
27 460.018824
28 336.056471
29 422.510000
30 463.130588
31 404.610000
32 370.919412
33 421.068824
34 420.085294
35 436.928235
36 436.300000
37 411.330000
38 486.186471
39 373.802941
40 444.218824
41 395.093529
42 407.121176
43 435.445882
44 391.773529
45 427.041176
46 409.006471
47 437.616471
48 467.170588
49 477.714706

```

And RATP ?

All the skies defined above are available with RATP as the light model

```

[12]: lighting = LightVegeManager(lightmodel="ratp", environment=environment)
lighting.build(geometry=triangles)
lighting.run(energy=energy, hour=hour, day=day)
print(lighting.triangles_outputs)

```

	Triangle	Organ	Voxel	VegetationType	primitive_area	Day	Hour	Nx	\
0	0	0	1.0	1	99.480976	264.0	15.0	2	
7	1	0	2.0	1	140.415211	264.0	15.0	2	
14	2	0	3.0	1	20.519232	264.0	15.0	1	
25	3	0	4.0	1	23.926310	264.0	15.0	1	
26	4	0	4.0	1	5.986450	264.0	15.0	1	
15	5	0	3.0	1	10.845583	264.0	15.0	1	
16	6	0	3.0	1	0.882299	264.0	15.0	1	
29	7	0	5.0	1	32.812203	264.0	15.0	1	

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27	8	0	4.0	1	36.321775	264.0	15.0	1
1	9	0	1.0	1	5.071856	264.0	15.0	2
34	10	0	6.0	1	52.628089	264.0	15.0	2
2	11	0	1.0	1	103.885213	264.0	15.0	2
17	12	0	3.0	1	65.457326	264.0	15.0	1
18	13	0	3.0	1	0.567605	264.0	15.0	1
19	14	0	3.0	1	7.122030	264.0	15.0	1
39	15	0	7.0	1	5.181860	264.0	15.0	1
20	16	0	3.0	1	271.820976	264.0	15.0	1
21	17	0	3.0	1	91.585066	264.0	15.0	1
3	18	0	1.0	1	36.315518	264.0	15.0	2
42	19	0	8.0	1	31.149412	264.0	15.0	2
8	20	0	2.0	1	35.587854	264.0	15.0	2
22	21	0	3.0	1	14.172730	264.0	15.0	1
40	22	0	7.0	1	31.918145	264.0	15.0	1
43	23	0	8.0	1	76.036115	264.0	15.0	2
35	24	0	6.0	1	13.932378	264.0	15.0	2
44	25	0	8.0	1	55.601914	264.0	15.0	2
36	26	0	6.0	1	84.448667	264.0	15.0	2
30	27	0	5.0	1	90.626852	264.0	15.0	1
4	28	0	1.0	1	19.211308	264.0	15.0	2
45	29	0	8.0	1	7.412773	264.0	15.0	2
9	30	0	2.0	1	50.867131	264.0	15.0	2
46	31	0	8.0	1	22.183195	264.0	15.0	2
47	32	0	8.0	1	5.146020	264.0	15.0	2
31	33	0	5.0	1	14.648915	264.0	15.0	1
28	34	0	4.0	1	64.285771	264.0	15.0	1
48	35	0	8.0	1	15.752372	264.0	15.0	2
32	36	0	5.0	1	34.818585	264.0	15.0	1
10	37	0	2.0	1	61.748544	264.0	15.0	2
5	38	0	1.0	1	102.627411	264.0	15.0	2
11	39	0	2.0	1	6.460148	264.0	15.0	2
41	40	0	7.0	1	45.802731	264.0	15.0	1
6	41	0	1.0	1	21.008426	264.0	15.0	2
12	42	0	2.0	1	9.276760	264.0	15.0	2
23	43	0	3.0	1	28.316439	264.0	15.0	1
49	44	0	8.0	1	36.758141	264.0	15.0	2
24	45	0	3.0	1	121.996376	264.0	15.0	1
13	46	0	2.0	1	69.352270	264.0	15.0	2
37	47	0	6.0	1	71.266675	264.0	15.0	2
38	48	0	6.0	1	81.346766	264.0	15.0	2
33	49	0	5.0	1	13.311873	264.0	15.0	1
	Ny	Nz	ShadedPAR	SunlitPAR	ShadedArea	SunlitArea	Area \	
0	2	1	514.910706	514.910706	8.961945	378.638763	387.600708	
7	1	2	508.419556	508.419556	10.553925	363.153992	373.707916	
14	2	2	503.838837	503.838837	19.746033	613.539612	633.285645	
25	1	1	520.405823	520.405823	1.771942	128.748367	130.520309	
26	1	1	520.405823	520.405823	1.771942	128.748367	130.520309	
15	2	2	503.838837	503.838837	19.746033	613.539612	633.285645	
16	2	2	503.838837	503.838837	19.746033	613.539612	633.285645	
29	2	1	519.076111	519.076111	2.660919	183.557510	186.218430	

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27	1	1	520.405823	520.405823	1.771942	128.748367	130.520309
1	2	1	514.910706	514.910706	8.961945	378.638763	387.600708
34	1	1	516.687439	516.687439	6.621002	297.001587	303.622589
2	2	1	514.910706	514.910706	8.961945	378.638763	387.600708
17	2	2	503.838837	503.838837	19.746033	613.539612	633.285645
18	2	2	503.838837	503.838837	19.746033	613.539612	633.285645
19	2	2	503.838837	503.838837	19.746033	613.539612	633.285645
39	1	2	514.584290	514.584290	1.922020	80.980721	82.902740
20	2	2	503.838837	503.838837	19.746033	613.539612	633.285645
21	2	2	503.838837	503.838837	19.746033	613.539612	633.285645
3	2	1	514.910706	514.910706	8.961945	378.638763	387.600708
42	2	2	508.459503	508.459503	6.290421	243.749527	250.039948
8	1	2	508.419556	508.419556	10.553925	363.153992	373.707916
22	2	2	503.838837	503.838837	19.746033	613.539612	633.285645
40	1	2	514.584290	514.584290	1.922020	80.980721	82.902740
43	2	2	508.459503	508.459503	6.290421	243.749527	250.039948
35	1	1	516.687439	516.687439	6.621002	297.001587	303.622589
44	2	2	508.459503	508.459503	6.290421	243.749527	250.039948
36	1	1	516.687439	516.687439	6.621002	297.001587	303.622589
30	2	1	519.076111	519.076111	2.660919	183.557510	186.218430
4	2	1	514.910706	514.910706	8.961945	378.638763	387.600708
45	2	2	508.459503	508.459503	6.290421	243.749527	250.039948
9	1	2	508.419556	508.419556	10.553925	363.153992	373.707916
46	2	2	508.459503	508.459503	6.290421	243.749527	250.039948
47	2	2	508.459503	508.459503	6.290421	243.749527	250.039948
31	2	1	519.076111	519.076111	2.660919	183.557510	186.218430
28	1	1	520.405823	520.405823	1.771942	128.748367	130.520309
48	2	2	508.459503	508.459503	6.290421	243.749527	250.039948
32	2	1	519.076111	519.076111	2.660919	183.557510	186.218430
10	1	2	508.419556	508.419556	10.553925	363.153992	373.707916
5	2	1	514.910706	514.910706	8.961945	378.638763	387.600708
11	1	2	508.419556	508.419556	10.553925	363.153992	373.707916
41	1	2	514.584290	514.584290	1.922020	80.980721	82.902740
6	2	1	514.910706	514.910706	8.961945	378.638763	387.600708
12	1	2	508.419556	508.419556	10.553925	363.153992	373.707916
23	2	2	503.838837	503.838837	19.746033	613.539612	633.285645
49	2	2	508.459503	508.459503	6.290421	243.749527	250.039948
24	2	2	503.838837	503.838837	19.746033	613.539612	633.285645
13	1	2	508.419556	508.419556	10.553925	363.153992	373.707916
37	1	1	516.687439	516.687439	6.621002	297.001587	303.622589
38	1	1	516.687439	516.687439	6.621002	297.001587	303.622589
33	2	1	519.076111	519.076111	2.660919	183.557510	186.218430

	PARa	Intercepted	Transmitted
0	514.910706	399.159515	4677.770020
7	508.419586	380.000824	4636.436523
14	503.838837	638.147766	4564.685547
25	520.405823	135.847061	4753.783691
26	520.405823	135.847061	4753.783691
15	503.838837	638.147766	4564.685547
16	503.838837	638.147766	4564.685547
29	519.076111	193.323074	4734.602051

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27	520.405823	135.847061	4753.783691
1	514.910706	399.159515	4677.770020
34	516.687439	313.755951	4702.907227
2	514.910706	399.159515	4677.770020
17	503.838837	638.147766	4564.685547
18	503.838837	638.147766	4564.685547
19	503.838837	638.147766	4564.685547
39	514.584290	85.320900	4692.383789
20	503.838837	638.147766	4564.685547
21	503.838837	638.147766	4564.685547
3	514.910706	399.159515	4677.770020
42	508.459503	254.270370	4635.730469
8	508.419586	380.000824	4636.436523
22	503.838837	638.147766	4564.685547
40	514.584290	85.320900	4692.383789
43	508.459503	254.270370	4635.730469
35	516.687439	313.755951	4702.907227
44	508.459503	254.270370	4635.730469
36	516.687439	313.755951	4702.907227
30	519.076111	193.323074	4734.602051
4	514.910706	399.159515	4677.770020
45	508.459503	254.270370	4635.730469
9	508.419586	380.000824	4636.436523
46	508.459503	254.270370	4635.730469
47	508.459503	254.270370	4635.730469
31	519.076111	193.323074	4734.602051
28	520.405823	135.847061	4753.783691
48	508.459503	254.270370	4635.730469
32	519.076111	193.323074	4734.602051
10	508.419586	380.000824	4636.436523
5	514.910706	399.159515	4677.770020
11	508.419586	380.000824	4636.436523
41	514.584290	85.320900	4692.383789
6	514.910706	399.159515	4677.770020
12	508.419586	380.000824	4636.436523
23	503.838837	638.147766	4564.685547
49	508.459503	254.270370	4635.730469
24	503.838837	638.147766	4564.685547
13	508.419586	380.000824	4636.436523
37	516.687439	313.755951	4702.907227
38	516.687439	313.755951	4702.907227
33	519.076111	193.323074	4734.602051

2.6.3 Geometric inputs

Content

- input formats
 - Dict of triangles
 - PlantGL scene
 - VGX file
 - Voxels grid
 - MTG object from adelwheat
 - RATP inputs
 - RiRi5 inputs
- organization levels: species and organs
- stems management
- geometric transformations

Introduction

The main purpose of this tool was to merge several geometric scenes in various formats and apply a radiative modelling on it. Here, we will precise the different possibilities for manipulating geometry.

```
[1]: from lightvegemanager.LVM import LightVegeManager
     from pgljupyter import SceneWidget
```

```
[2]: # Environment parameters for this notebook
longitude = 2.
latitude = 46.
timezone = 1
coordinates = [latitude, longitude, timezone]
infinite = False
reflected = False
direct = False
diffuse = True
sky = "turtle46"

environment = {
    "coordinates": coordinates ,
    "infinite": infinite,
    "reflected": reflected,
    "direct": direct,
    "diffuse": diffuse,
    "sky": sky
}
```

Inputs Formats

In this section, we won't present single triangle and list of triangles as input geometry, as they were present in the `tool_basics.ipynb` notebook. Also, these two formats can be direct inputs of the `geometry` argument of the `build` method, unlike the following formats which needs to be included in a list, such as:

```
geometry = { "scenes": [scene1, scene2, ...] }
```

dict of triangles

A mesh of triangles can be represented as a dict, where each key is an organ ID and its value, a list of triangles belonging to the organ. A triangle is a list of a 3 vertices represented by (x,y,z)points.

In this example, we will generate random 3D triangles for 3 different organs.

```
[12]: from lightvegemanager.trianglesmesh import random_triangle_generator

spheresize = (10., 2.)
organized_triangles = {
    111: [random_triangle_generator(spheresize=spheresize, worldsize=(0,20)) for i in
    ↪ range(20)],
    222: [random_triangle_generator(spheresize=spheresize, worldsize=(20,50)) for i in
    ↪ range(30)],
    333: [random_triangle_generator(spheresize=spheresize, worldsize=(50,100)) for i in
    ↪ range(10)],
}
```

Input geometry looks like:

```
[4]: geometry = {
    "scenes": [organized_triangles]
}
```

Then, we compute lighting and run a visualization of the scene.

Note: `elements_outputs` method will return a Dataframe where results are integrated on each organ.

```
[5]: lighting = LightVegeManager(lightmodel="caribu", environment=environment)
lighting.build(geometry=geometry)

# compute the lighting
energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)
print(lighting.elements_outputs)
SceneWidget(lighting.plantGL_light(),
            position=(-50.0, -50.0, 0.0),
            size_display=(600, 400),
            plane=True,
            size_world = 100,
            axes_helper=True)
```


	Day	Hour	Organ	VegetationType	Area	par Eabs	par Ei
0	264	15	111	0	812.660080	254.783023	299.744733
1	264	15	222	0	906.791550	326.191765	383.755017
2	264	15	333	0	456.917637	368.655503	433.712356

```
[5]: SceneWidget(axes_helper=True, scenes=[{'id': 'BwxHSpLTosrUCKkss9pQniZu1', 'data': b'x\
↳ xda\x85\x9a\t\\U\xd5\xf6...
```

PlantGL scene

A plantGL Scene is a list of plantGL Shape which can be considered as organ. The ID of the plantGL Shape are stored as organs ID.

```
[7]: import openalea.plantgl.all as pgl
```

```
pgl_scene = pgl.Scene([pgl.Shape(pgl.Box(), pgl.Material(), 888),
                        pgl.Shape(pgl.Translated((0,0,1), pgl.Cylinder()), pgl.
↳ Material(), 999)])
```

```
[8]: geometry = {
    "scenes": [pgl_scene]
}
lighting = LightVegeManager(lightmodel="caribu", environment=environment)
lighting.build(geometry=geometry)
lighting.run(energy=energy, hour=hour, day=day)
print(lighting.elements_outputs)
SceneWidget(lighting.plantGL_light(),
            position=(0.0, 0.0, 0.0),
            size_display=(600, 400),
            plane=True,
            size_world = 5,
            axes_helper=True)
```

	Day	Hour	Organ	VegetationType	Area	par Eabs	par Ei
0	264	15	888	0	6.000000	159.643042	187.815343
1	264	15	999	0	4.475681	185.076017	217.736490

```
[8]: SceneWidget(axes_helper=True, scenes=[{'id': '8kU7diEsaj9G3BXsKdlxCbLNN', 'data': b'x\
↳ xda\x95\x99\xddn\x1bE\x1...
```

VGX file

The tool can read a VGX file as an input entry. It extracts triangles which are considered as leaves, following its colors, if Red != 42. All triangles are stored in the same organ, where its ID is set to 0.

```
[5]: import os
```

```
vgx_path = os.path.join(os.path.dirname(os.path.abspath("")), "data", "NICatObs1P2.vgx")
vgx_path
```

```
[5]: 'C:\\Users\\mwoussen\\cdd\\codes\\dev\\lightvegemanager\\data\\NICatObs1P2.vgx'
```

```
[7]: geometry = {
      "scenes": [vgx_path]
    }
    # compute the lighting
    energy = 500.
    hour = 15
    day = 264
    lighting = LightVegeManager(lightmodel="caribu", environment=environment)
    lighting.build(geometry=geometry)
    lighting.run(energy=energy, hour=hour, day=day)
    print(lighting.elements_outputs)
    SceneWidget(lighting.plantGL_light(),
                 position=(0.0, 0.0, 0.0),
                 size_display=(600, 400),
                 plane=True,
                 size_world = 100,
                 axes_helper=True)
```

	Day	Hour	Organ	VegetationType	Area	par Eabs	par Ei
0	264	15	0	0	6062.836763	193.704509	227.887658

```
[7]: SceneWidget(axes_helper=True, scenes=[{'id': 'b0BZCLMbmTxLySxt6uQ3jfKw', 'data': b'x\
↳ xda\x94\x9d\x07\x9c\x15E...
```

Grid of voxels

A voxel grid is represented as a dict of two entries: - "LA" corresponding to leaf area, is a table (`numpy.array`) of dimension $\text{number of species} \times \text{number of zlayers}$ - "dist" corresponding to leaf angled distribution, is a list of list, where is entered a leaf angled distribution for each specy

Grid dimensions and voxel size are set in the input parameters of RATP.

```
[7]: import numpy

l_scene = {"LA": numpy.ones([2, 3, 4, 4]), "distrib": [[0.5, 0.5], [0.3, 0.7]]}
```

```
[16]: geometry = {
        "scenes": [vgx_path]
    }
    ratp_parameters = {
        "voxel size" : [20.] * 3
    }
    lighting = LightVegeManager(lightmodel="ratp", environment=environment, lightmodel_
    ↪ parameters=ratp_parameters)
    lighting.build(geometry=geometry)
    lighting.run(energy=energy, hour=hour, day=day)
    print(lighting.elements_outputs)
    SceneWidget(lighting.plantGL_light(printtriangles=False, printvoxels=True),
                position=(0.0, 0.0, 0.0),
                size_display=(600, 400),
                plane=True,
```

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```
size_world = 100,
axes_helper=True)
```

	Day	Hour	Organ	VegetationType	Area	PARa	Intercepted	\
0	264.0	15.0	0	1	6062.836763	307.604456	215.922903	

	Transmitted	SunlitPAR	SunlitArea	ShadedPAR	ShadedArea
0	215.922903	307.604461	252.377915	307.604461	126.601372

```
[16]: SceneWidget(axes_helper=True, scenes=[{'id': 'OgKLbEOYkRT69libXrZkXUjuC', 'data': b'x\
↳ xda\x95XMh]E\x14\xbe4\x8...
```

MTG object from adelwheat

Finally, you can also give a MTG object with a "scene" property. The package adelwheat offers such objects.

```
[8]: from alinea.adel.adel_dynamic import AdelDyn
from alinea.adel.echap_leaf import echap_leaves
INPUTS_DIRPATH = os.path.join(os.path.dirname(os.path.abspath("")), "data")
adel_wheat = AdelDyn(seed=1, scene_unit="m", leaves=echap_leaves(xy_model="Soissons_
↳ byleafclass"))
g = adel_wheat.load(dir=INPUTS_DIRPATH)
```

```
[18]: geometry = {
    "scenes": [g]
}
lighting = LightVegeManager(lightmodel="caribu", environment=environment)
lighting.build(geometry=geometry)
lighting.run(energy=energy, hour=hour, day=day)
print(lighting.elements_outputs)
SceneWidget(lighting.plantGL_light(),
             position=(0.0, 0.0, 0.0),
             size_display=(600, 400),
             plane=True,
             size_world = 0.1,
             axes_helper=True)
```

	Day	Hour	Organ	VegetationType	Area	par Eabs	par Ei
0	264	15	19	0	0.000228	159.208612	187.304249
1	264	15	34	0	0.000013	80.953500	95.239412
2	264	15	813	0	0.000194	385.317031	453.314154
3	264	15	814	0	0.000240	367.646906	432.525772
4	264	15	51	0	0.000284	347.458387	408.774573

```
[18]: SceneWidget(axes_helper=True, scenes=[{'id': 'nOBWAHxiPOAKSumQc0CHKQkiR', 'data': b'x\
↳ xda\x95\x9a{pUW\x15\xc6/...
```

RATP inputs

All the above scenes can be geometric inputs if the lightmodel argument is set to "ratp".

```
[21]: geometry = {
    "scenes": [g]
}
lighting = LightVegeManager(lightmodel="ratp", environment=environment)
lighting.build(geometry=geometry)
lighting.run(energy=energy, hour=hour, day=day)
print(lighting.elements_outputs)
SceneWidget(lighting.plantGL_light(printvoxels=True),
             position=(0.0, 0.0, 0.0),
             size_display=(600, 400),
             plane=True,
             size_world = 0.1,
             axes_helper=True)
```

	Day	Hour	Organ	VegetationType	Area	PARa	Intercepted	\
0	264.0	15.0	19	1	0.000228	435.713379	0.000693	
1	264.0	15.0	34	1	0.000013	435.713379	0.000693	
2	264.0	15.0	813	1	0.000194	435.713379	0.000693	
3	264.0	15.0	814	1	0.000240	441.368498	0.000288	
4	264.0	15.0	51	1	0.000284	435.713379	0.000693	

	Transmitted	SunlitPAR	SunlitArea	ShadedPAR	ShadedArea
0	0.000693	435.713379	0.000776	435.713379	0.000019
1	0.000693	435.713379	0.000776	435.713379	0.000019
2	0.000693	435.713379	0.000776	435.713379	0.000019
3	0.000288	441.368498	0.000322	441.368498	0.000007
4	0.000693	435.713379	0.000776	435.713379	0.000019

```
[21]: SceneWidget(axes_helper=True, scenes=[{'id': 'wctv0d7i6YHequCnJz21Y8umG', 'data': b'x\
↳ xda\x95\x9a\x0bpT\xd5\x1...
```

RiRi5 inputs

RiRi5 can have the same inputs as RATP.

A scene grid of voxels must have exactly 9 angle classes for its leaf angle distribution, and at least one empty layer above the canopy.

Triangles mesh inputs are processed through the RATP pipeline, then is converted to RiRi5.

```
[9]: import numpy

l_scene = {"LA": numpy.ones([2, 3, 4, 4]), "distrib": [[0.1, 0.2, 0.1, 0.1, 0.05, 0.05,
↳ 0.1, 0.2, 0.1],
                                                         [0.1, 0.1, 0.1, 0.1, 0.05, 0.1,
↳ 0.2, 0.2, 0.05]]}
for i in range(4):
    for j in range(4):
        l_scene["LA"][0][0][i][j] = 0.
        l_scene["LA"][1][0][i][j] = 0.
```

```
[10]: geometry = {
      "scenes": [l_scene]
    }
    lighting = LightVegeManager(lightmodel="riri5", environment=environment)
    lighting.build(geometry=geometry)
    lighting.run(energy=energy, hour=hour, day=day)
```

```
[21]: print(lighting.riri5_intercepted_light)
```

```
[[[ 0.          0.          0.          0.          ]
  [ 0.          0.          0.          0.          ]
  [ 0.          0.          0.          0.          ]
  [ 0.          0.          0.          0.          ]]]

[[208.05400092 208.05400092 208.05400092 208.05400092]
 [208.05400092 208.05400092 208.05400092 208.05400092]
 [208.05400092 208.05400092 208.05400092 208.05400092]
 [208.05400092 208.05400092 208.05400092 208.05400092]]

[[ 33.75896074 33.75896074 33.75896074 33.75896074]
 [ 33.75896074 33.75896074 33.75896074 33.75896074]
 [ 33.75896074 33.75896074 33.75896074 33.75896074]
 [ 33.75896074 33.75896074 33.75896074 33.75896074]]]

[[[ 0.          0.          0.          0.          ]
  [ 0.          0.          0.          0.          ]
  [ 0.          0.          0.          0.          ]
  [ 0.          0.          0.          0.          ]]]

[[207.34450322 207.34450322 207.34450322 207.34450322]
 [207.34450322 207.34450322 207.34450322 207.34450322]
 [207.34450322 207.34450322 207.34450322 207.34450322]
 [207.34450322 207.34450322 207.34450322 207.34450322]]

[[ 33.2079505 33.2079505 33.2079505 33.2079505 ]
 [ 33.2079505 33.2079505 33.2079505 33.2079505 ]
 [ 33.2079505 33.2079505 33.2079505 33.2079505 ]
 [ 33.2079505 33.2079505 33.2079505 33.2079505 ]]]]
```

```
[22]: print(lighting.riri5_transmitted_light)
```

```
[[[500.          500.          500.          500.          ]
  [500.          500.          500.          500.          ]
  [500.          500.          500.          500.          ]
  [500.          500.          500.          500.          ]]]

[[ 84.60149586 84.60149586 84.60149586 84.60149586]
 [ 84.60149586 84.60149586 84.60149586 84.60149586]
 [ 84.60149586 84.60149586 84.60149586 84.60149586]
 [ 84.60149586 84.60149586 84.60149586 84.60149586]]

[[ 17.63458462 17.63458462 17.63458462 17.63458462]
```

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```
[ 17.63458462  17.63458462  17.63458462  17.63458462]
[ 17.63458462  17.63458462  17.63458462  17.63458462]
[ 17.63458462  17.63458462  17.63458462  17.63458462]]]
```

```
[12]: geometry = {
      "scenes": [organized_triangles]
    }

    lighting.build(geometry=geometry)
    lighting.run(energy=energy, hour=hour, day=day)
```

```
[13]: print(lighting.riri5_intercepted_light)
```

```
[[[0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  ...
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]]

[[0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  ...
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]]

[[0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  ...
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]]

...

[[0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  ...
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]]

[[0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  ...
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
  [0. 0. 0. ... 0. 0. 0.]
```

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```

[0. 0. 0. ... 0. 0. 0.]
[0. 0. 0. ... 0. 0. 0.]]

[[0. 0. 0. ... 0. 0. 0.]
 [0. 0. 0. ... 0. 0. 0.]
 [0. 0. 0. ... 0. 0. 0.]
 ...
 [0. 0. 0. ... 0. 0. 0.]
 [0. 0. 0. ... 0. 0. 0.]
 [0. 0. 0. ... 0. 0. 0.]]]]

```

```
[14]: print(lightning.riri5_transmitted_light)
```

```

[[[500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  ...
  [500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]]

[[[500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  ...
  [500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]]

[[[500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  ...
  [500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]]

...

[[[500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  ...
  [500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]]

[[[500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  [500. 500. 500. ... 500. 500. 500.]
  ...
  [500. 500. 500. ... 500. 500. 500.]

```

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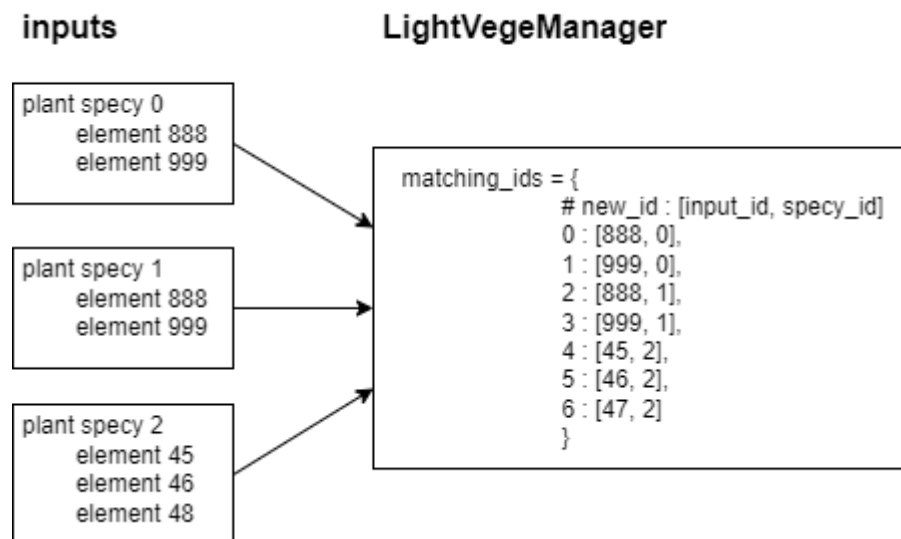
```
[500. 500. 500. ... 500. 500. 500.]
[500. 500. 500. ... 500. 500. 500.]]

[[500. 500. 500. ... 500. 500. 500.]
 [500. 500. 500. ... 500. 500. 500.]
 [500. 500. 500. ... 500. 500. 500.]
 ...
 [500. 500. 500. ... 500. 500. 500.]
 [500. 500. 500. ... 500. 500. 500.]
 [500. 500. 500. ... 500. 500. 500.]]]
```

Organizing the inputs

They are two levels of possible organization: - species - organs

Each triangle are bound to a specy ID and a organ ID. Each specy is represented as a input scene. The organs ID are set inside each scene depending on its format.



An example with several scenes with the same organs ID and CARIBU.

```
[22]: scene1 = {
    111: [random_triangle_generator(spheresize=spheresize) for i in range(20)],
    222: [random_triangle_generator(spheresize=spheresize) for i in range(30)],
    333: [random_triangle_generator(spheresize=spheresize) for i in range(10)],
}

scene2 = {
    111: [random_triangle_generator(spheresize=spheresize) for i in range(20)],
    222: [random_triangle_generator(spheresize=spheresize) for i in range(30)],
    333: [random_triangle_generator(spheresize=spheresize) for i in range(10)],
}

scene3 = {
```

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```

111: [random_triangle_generator(spheresize=spheresize) for i in range(20)],
222: [random_triangle_generator(spheresize=spheresize) for i in range(30)],
333: [random_triangle_generator(spheresize=spheresize) for i in range(10)],
}

```

We have 3 species

```

[23]: scenes = [scene1, scene2, scene3]
      geometry = { "scenes": scenes }

```

```

[24]: lighting = LightVegeManager(lightmodel="caribu")
      lighting.build(geometry=geometry)

```

```

# compute the lighting
energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)
print(lighting.elements_outputs)

```

	Day	Hour	Organ	VegetationType	Area	par Eabs	par Ei
0	264	15	111	0	865.848719	367.620782	432.495038
1	264	15	222	0	904.093391	343.903742	404.592638
2	264	15	333	0	500.476649	374.891932	441.049332
3	264	15	111	1	719.501340	330.624848	388.970410
4	264	15	222	1	1023.379192	351.641676	413.696090
5	264	15	333	1	129.105369	391.022326	460.026266
6	264	15	111	2	1047.414777	335.930702	395.212591
7	264	15	222	2	1174.044647	349.124635	410.734865
8	264	15	333	2	521.903258	361.052748	424.767939

```

[25]: SceneWidget(lighting.plantGL_light(),
                  position=(-50.0, -50.0, 0.0),
                  size_display=(600, 400),
                  plane=True,
                  size_world = 100,
                  axes_helper=True)

```

```

[25]: SceneWidget(axes_helper=True, scenes=[{'id': 'sNiVT3L9ABichdb2gAyBsVr2f', 'data': b'x\
↳ xda\x85}\x07|\x8d\xd7\xfd...

```

The two level organization are also kept with RATP

```

[27]: lighting = LightVegeManager(lightmodel="ratp")
      lighting.build(geometry=geometry)

```

```

energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)
print(lighting.elements_outputs)

```

Day	Hour	Organ	VegetationType	Area	PARa	Intercepted \
-----	------	-------	----------------	------	------	---------------

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0	264.0	15.0	111	1	865.848719	444.431609	438.050846
1	264.0	15.0	222	1	904.093391	439.138654	508.370824
2	264.0	15.0	333	1	500.476649	438.358519	466.758357
3	264.0	15.0	111	2	719.501340	441.984838	374.664274
4	264.0	15.0	222	2	1023.379192	436.324817	446.932608
5	264.0	15.0	333	2	129.105369	442.768841	373.148804
6	264.0	15.0	111	3	1047.414777	437.256257	728.403508
7	264.0	15.0	222	3	1174.044647	443.465415	536.007093
8	264.0	15.0	333	3	521.903258	432.082470	816.087594

	Transmitted	SunlitPAR	SunlitArea	ShadedPAR	ShadedArea
0	438.050846	450.722334	463.402916	356.222905	49.407779
1	508.370824	446.126727	538.617195	351.627301	58.372064
2	466.758357	446.387940	492.094716	351.888516	56.801907
3	374.664274	449.154416	395.429864	352.554837	42.809579
4	446.932608	444.042247	473.516975	347.442668	51.797538
5	373.148804	449.336097	395.819748	352.736518	45.454794
6	728.403508	444.694193	770.345275	349.806482	81.342446
7	536.007093	450.321284	565.173551	355.433568	58.993793
8	816.087594	440.468993	864.084337	345.581276	97.832614

```
c:\users\mwoussen\cdd\codes\dev\lightvegemanager\src\lightvegemanager\outputs.py:255:
↳ UserWarning: You are merging on int and float columns where the float values are not
↳ equal to their int representation.
    trianglesoutputs = pandas.merge(dftriangles, voxels_outputs)
```

Stems

If there are stems elements in the inputs, you can precise their ID and the tool will manage them, depending on the lightmodel: - with CARIBU, the optical parameters associated to the organ won't have a transmission value (rays won't cross the triangle) - with RATP, stems are separated in a new specy with its own leaf angle distribution and their leaf area is divided by 2

We reuse the wheat geometry given by adelwheat

```
[9]: geometry = {
      "scenes": [g]
    }
```

stems are stored in list where each element is a 2-tuple (organ ID, specy ID)

```
[10]: stems = [(19, 0), (34, 0)]
      geometry.update({"stems id": stems})
```

```
[11]: lighting = LightVegeManager(lightmodel="caribu")
      lighting.build(geometry=geometry)
      SceneWidget(lighting.plantGL_nolight(),
                  position=(0.0, 0.0, 0.0),
                  size_display=(600, 400),
                  plane=True,
                  size_world = 0.1,
                  axes_helper=True)
```

```
[11]: SceneWidget(axes_helper=True, scenes=[{'id': 'jZ9Zexz60T6u6TydCb9uVlZBe', 'data': b'x\
↳ xda\x95\x9a\r\x8cT\xd5\x...
```

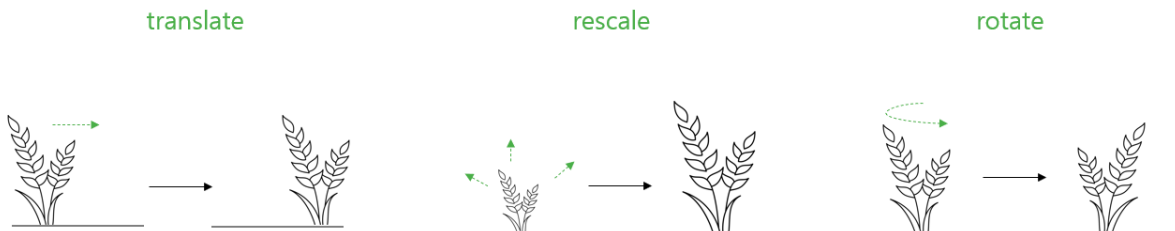
```
[32]: lighting.run(energy=energy, hour=hour, day=day)
print(lighting.elements_outputs)
SceneWidget(lighting.plantGL_light(),
             position=(0.0, 0.0, 0.0),
             size_display=(600, 400),
             plane=True,
             size_world = 0.1,
             axes_helper=True)
```

	Day	Hour	Organ	VegetationType	Area	par Eabs	par Ei
0	264	15	19	0	0.000228	194.070089	215.633432
1	264	15	34	0	0.000013	93.806573	104.229526
2	264	15	813	0	0.000194	458.967637	539.961926
3	264	15	814	0	0.000240	392.729426	462.034618
4	264	15	51	0	0.000284	350.644177	412.522561

```
[32]: SceneWidget(axes_helper=True, scenes=[{'id': 'X6MEhdoPOJgZ1bvsYLGzPEHsk', 'data': b'x\
↳ xda\x95\x9a{p\x15\xd5\x1...
```

Geometric transformations

You can apply geometric transformations on some of the inputs scenes. We have currently 3 available transformations - translation by a vector - rescale by a factor or following scenes metric unit - rotation on the xy plane



Transformations are stored in a dict, which is stored at key "transformations" in the geometry entry. Structure of transformations :

```
transformations = {
    "scenes unit": { specy ID: "metric unit", ...},
    "rescale": { specy ID: float, ...},
    "translate": { specy ID: 3-tuple (x,y,z), ...},
    "xyz orientation": { specy ID: "x+ = NEWS", ...},
}
```

Main scenes

```
[13]: spheresize = (2., 1.)
scene1 = {
    0: [random_triangle_generator(spheresize=spheresize, worldsize=(0,10)) for i in
↪range(20)]
}
scene2 = {
    0: [random_triangle_generator(spheresize=spheresize, worldsize=(10,20)) for i in
↪range(20)]
}

geometry = {"scenes": [scene1, scene2] }
```

```
[14]: lighting = LightVegeManager(lightmodel="caribu")
lighting.build(geometry=geometry)
SceneWidget(lighting.plantGL_nolight(),
            position=(0.0, 0.0, 0.0),
            size_display=(600, 400),
            plane=True,
            size_world = 50.,
            axes_helper=True)
```

```
[14]: SceneWidget(axes_helper=True, scenes=[{'id': 'DOLcNoqMANQw6VQcJjZQN4EVH', 'data': b'x\
↪xda\x85Y{TUu\x16\xbe\x80...
```

Translate

The translation vector is a 3-tuple (x,y,z). Transformations is a dict in the geometry dict.

```
[15]: tvec = (10., -10., 10.)
transformations = {
    "translate": {
        0: tvec
    }
}

geometry = {"scenes": [scene1, scene2] , "transformations": transformations}
```

```
[16]: lighting = LightVegeManager(lightmodel="caribu")
lighting.build(geometry=geometry)
SceneWidget(lighting.plantGL_nolight(),
            position=(0.0, 0.0, 0.0),
            size_display=(600, 400),
            plane=True,
            size_world = 50.,
            axes_helper=True)
```

```
[16]: SceneWidget(axes_helper=True, scenes=[{'id': 'WtsDD3lUn5IdvzQMKP8sVF7J8', 'data': b'x\
↪xda\x8d\x99\rTTe\x1a\xc7...
```

Rescale following metric unit

You can precise the metric unit of each scene from this list: "mm", "cm", "dm", "m", "dam", "hm", "km". By default the merged scene is in m but you can change its unit when you create an instance.

```
[17]: transformations = {
        "scenes unit": {
            0: "dm"
        }
    }
    geometry = {"scenes": [scene1, scene2] , "transformations": transformations}
```

```
[18]: lighting = LightVegeManager(lightmodel="caribu", main_unit="m")
    lighting.build(geometry=geometry)
    SceneWidget(lighting.plantGL_nolight(),
                position=(0.0, 0.0, 0.0),
                size_display=(600, 400),
                plane=True,
                size_world = 50.,
                axes_helper=True)
```

```
[18]: SceneWidget(axes_helper=True, scenes=[{'id': 'xZEoaWgcFvXiGSLzBxMdGtVPm', 'data': b'x\
↳ xda\x85\x98\t\\x95e\x16...
```

Rescale by a scalar factor

```
[19]: transformations = {
        "rescale": {
            0: 2.,
        }
    }
    geometry = {"scenes": [scene1, scene2] , "transformations": transformations}
```

```
[20]: lighting = LightVegeManager(lightmodel="caribu")
    lighting.build(geometry=geometry)
    SceneWidget(lighting.plantGL_nolight(),
                position=(0.0, 0.0, 0.0),
                size_display=(600, 400),
                plane=True,
                size_world = 50.,
                axes_helper=True)
```

```
[20]: SceneWidget(axes_helper=True, scenes=[{'id': '5z82zPETDhTAdHCoB1NtdJC6R', 'data': b'x\
↳ xda\x8d\x99{T\x94\xe5\x1...
```

Rotate

Finally, you can also rotate the scene around the z axis, in order to match the x+ convention for each input scene. You have the choice between: - "x+ = N" - "x+ = S" - "x+ = E" - "x+ = W"

The merged scene convention is x+ = N, which the convention in RATP and CARIBU.

```
[21]: transformations = {
    "xyz orientation": {
        0: "x+ = S",
        1: "x+ = E",
    }
}
geometry = {"scenes": [scene1, scene2] , "transformations": transformations}

[22]: lighting = LightVegeManager(lightmodel="caribu")
lighting.build(geometry=geometry)
SceneWidget(lighting.plantGL_nolight(),
    position=(0.0, 0.0, 0.0),
    size_display=(600, 400),
    plane=True,
    size_world = 50.,
    axes_helper=True)

[22]: SceneWidget(axes_helper=True, scenes=[{'id': 'vEFGxUQjZl3lco2qrN9j8zsDG', 'data': b'x\
↪xda\x8d\x99\x0bTUE\x16\x...
```

2.6.4 Light models options: how to set up the light models

Content

- CARIBU
 - Computing the sun position
 - Grid of virtual sensors
 - Other parameters
- RATP
 - Leaf angle distribution
 - Triangles tessellation in a grid
 - Other parameters

Introduction

During our use of lightvegemanager, we added special features for each known light models. This notebook gives you a small introduction to them.

The parameters of those features are stored in a dict.

```
[1]: import os
      from lightvegemanager.LVM import LightVegeManager
      from pgljupyter import SceneWidget
      from lightvegemanager.trianglesmesh import random_triangle_generator
```

CARIBU

This is the complete parameters you can provide with CARIBU:

```
caribu_args = {
    "sun algo" : "ratp",
    "sun algo" : "caribu",

    "caribu opt" : {
        band0 = (reflectance, transmittance),
        band1 = (reflectance, transmittance),
        ...
    },
    "debug" : bool,
    "soil mesh" : bool,
    "sensors" : ["grid", dxyz, nxyz, orig, vtkpath, "vtk"]
}
```

Computing the sun position

In order to compute the sun position, you can use either the algorithm from RATP or CARIBU. The (x, y, z) output is formatted in CARIBU format.

```
[2]: caribu_args = { "sun algo" : "caribu" }

lighting = LightVegeManager(lightmodel="caribu", lightmodel_parameters=caribu_args)
lighting.build(geometry=[(0., 0., 0.), (1., 0., 0.), (1., 1., 1.)])
energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)

sun_caribu = lighting.sun
print(sun_caribu)

(0.33506553253259913, -0.8798617206271511, -0.3370080733212115)
```

```
[3]: caribu_args = { "sun algo" : "ratp" }

lighting = LightVegeManager(lightmodel="caribu", lightmodel_parameters=caribu_args)
```

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```

lighting.build(geometry=[(0., 0., 0.), (1., 0., 0.), (1., 1., 1.)])
energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)

sun_ratp = lighting.sun
print(sun_ratp)

(0.33241183146897624, -0.8800565622452903, -0.3391206592769639)

```

```

[4]: dist = (sum([ (x-y)**2 for x,y in zip(sun_ratp, sun_caribu) ])) ** (1/2)
print("euclidean dist = ",dist," m")

euclidean dist = 0.003397515564596359 m

```

Grid of virtual sensors

If you can to match a grid of voxels, you can generate a set of virtual sensors following a 3D grid. You need to precise the dimension of the grid: - dxyz: [dx, dy, dz] size of one voxel - nxyz: [nx, ny, nz] number of voxels on each xyz axis - orig: [0x, 0y, 0z] origin point of the grid

Optionnaly, you can write a geometric visualisation of the sensors in VTK format. You need to provide the file path and the flag "vtk".

```

[5]: # grid dimensions
dxyz = [1.] * 3
nxyz = [5, 5, 7]
orig = [0.] * 3

```

```

[6]: # random triangles
nb_triangles = 50
spheresize = (1., 0.3) # vertices of triangles are the sphere surface
triangles = []
for i in range(nb_triangles):
    triangles.append(random_triangle_generator(worldsize=(0., 5.),
    ↪spheresize=spheresize))

```

```

[7]: caribu_args = { "sensors" : ["grid", dxyz, nxyz, orig] }

lighting = LightVegeManager(lightmodel="caribu", lightmodel_parameters=caribu_args,
    ↪environment={"infinite":True})
lighting.build(geometry=triangles)

```

You can visualize the grid of sensors with plantGL through the method plantGL_sensors

```

[8]: SceneWidget(lighting.plantGL_sensors(),
    position=(-2.5, -2.5, 0.0),
    size_display=(600, 400),
    plane=True,
    size_world = 10,
    axes_helper=True)

```



```
[8]: SceneWidget(axes_helper=True, scenes=[{'id': 'PeUbme32J7raIm5wbjhzJGRd', 'data': b'x\
↳ xda\x85\x9ai\xbf\x15G\x1...
```

The lighting results are stored in `sensors_outputs`

```
[9]: energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)

print(lighting.sensors_outputs)

{'par': {0: 0.5357183881257019, 1: 0.4686494843618967, 2: 0.43585410695767945, 3: 0.
↳ 7773054342426935, 4: 0.7653565097977126, 5: 0.8234079750501035, 6: 0.4758490954881396,
↳ 7: 0.5623902514683649, 8: 0.6648303684704121, 9: 0.7523744755517257, 10: 0.
↳ 757628513619047, 11: 0.7759095328197766, 12: 0.5042164344666725, 13: 0.
↳ 5273952940619577, 14: 0.618460535502636, 15: 0.7471856369784272, 16: 0.
↳ 7002461334186968, 17: 0.8083881379807872, 18: 0.5731391756180516, 19: 0.
↳ 6005392197593685, 20: 0.5830230691495272, 21: 0.668598834740319, 22: 0.
↳ 7491856052337844, 23: 0.7778896638896193, 24: 0.45941263771422963, 25: 0.
↳ 5231994757990336, 26: 0.5730702589058677, 27: 0.6802830730422291, 28: 0.
↳ 768563206195468, 29: 0.8783160299524551, 30: 0.4879256729568832, 31: 0.
↳ 3986838108537597, 32: 0.5107879595674222, 33: 0.7104544959233176, 34: 0.
↳ 6104289235914225, 35: 0.8335714361222757, 36: 0.49402264002060914, 37: 0.
↳ 5236661627298473, 38: 0.5559437694123442, 39: 0.7801809144392181, 40: 0.
↳ 7482355370820352, 41: 0.8703959530204384, 42: 0.4437212327094782, 43: 0.
↳ 48943914843165776, 44: 0.6265471398912993, 45: 0.6242676962673399, 46: 0.
↳ 6242541832847409, 47: 0.8029465687456536, 48: 0.4552489809791363, 49: 0.
↳ 5706269863386113, 50: 0.6707753329147661, 51: 0.6173647331272717, 52: 0.
↳ 5817093348224309, 53: 0.8761273435958801, 54: 0.39061205289281303, 55: 0.
↳ 4876144245567773, 56: 0.6081462607497906, 57: 0.6490748578167109, 58: 0.
↳ 6112989310198034, 59: 0.9081399625253275, 60: 0.4382387194995509, 61: 0.
↳ 24511969967129915, 62: 0.5564013821314899, 63: 0.6811375757235048, 64: 0.
↳ 770734538810677, 65: 0.6876474556435463, 66: 0.4333876306307797, 67: 0.
↳ 5117511864924423, 68: 0.5452643050348251, 69: 0.5855297120040052, 70: 0.
↳ 7679378169458118, 71: 0.7374054106105965, 72: 0.46718762617607673, 73: 0.
↳ 515406942360565, 74: 0.5498630958709402, 75: 0.38157016078052153, 76: 0.
↳ 6230183331063252, 77: 0.9297880197486428, 78: 0.42012696485414797, 79: 0.
↳ 43441190921900263, 80: 0.576547648435128, 81: 0.575563926783583, 82: 0.
↳ 5587431661289568, 83: 0.9428844615982549, 84: 0.40797647513225416, 85: 0.
↳ 32045180842520204, 86: 0.3860501936085704, 87: 0.6035746806015782, 88: 0.
↳ 6761415094988514, 89: 0.9147231881446279, 90: 0.35723846481058197, 91: 0.
↳ 29971902254716964, 92: 0.4617676006672053, 93: 0.6670186733643282, 94: 0.
↳ 7729889949287282, 95: 0.8223626142139061, 96: 0.43689040185742767, 97: 0.
↳ 5034266289477778, 98: 0.614485119215983, 99: 0.6753609146208617, 100: 0.
↳ 8209389374222003, 101: 0.88137358368075, 102: 0.5060744695288328, 103: 0.
↳ 5006922321596806, 104: 0.5450143532935812, 105: 0.669825913948119, 106: 0.
↳ 7948585486270389, 107: 0.9497236962858565, 108: 0.5240235293870577, 109: 0.
↳ 5291828813059647, 110: 0.5584025594129878, 111: 0.7009911880575855, 112: 0.
↳ 6644575143621863, 113: 0.896722396622886, 114: 0.48066310311501675, 115: 0.
↳ 45339172597584754, 116: 0.4928664818657807, 117: 0.6921498380364002, 118: 0.
↳ 6582322232034805, 119: 0.8062622917317241, 120: 0.4165301298570477, 121: 0.
↳ 47752211531730254, 122: 0.5422072915168136, 123: 0.7320985553256096, 124: 0.
```

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```

→760961505134305, 125: 0.8425522336315453, 126: 0.48285036844495494, 127: 0.
→4897295356464291, 128: 0.6751897497018744, 129: 0.7650357314236249, 130: 0.
→6888417962718921, 131: 0.9099594684378505, 132: 0.4801370709108044, 133: 0.
→5233846696457297, 134: 0.5942217135899492, 135: 0.7384234333722701, 136: 0.
→8064837117567087, 137: 0.955340358423788, 138: 0.5755258055313021, 139: 0.
→5351956047253674, 140: 0.5430459909905389, 141: 0.7603523762894485, 142: 0.
→8096038729562012, 143: 0.9210479253387107, 144: 0.49256349385820036, 145: 0.
→4352151194578986, 146: 0.4353486297408457, 147: 0.7458275318718196, 148: 0.
→7991276473463365, 149: 0.9117731862505419}}

```

You can also visualize the results in the plantGL scene

```

[10]: SceneWidget(lighting.plantGL_sensors(light=True),
                  position=(-2.5, -2.5, 0.0),
                  size_display=(600, 400),
                  plane=True,
                  size_world = 10,
                  axes_helper=True)

[10]: SceneWidget(axes_helper=True, scenes=[{'id': 'h4EUPTlkwcC9SjqSa9KdhgS4D', 'data': b'x\
→xda\x85\x9bk\x7fVG\x15\x...

[11]: SceneWidget(lighting.plantGL_sensors(light=True) + lighting.plantGL_nolight(),
                  position=(-2.5, -2.5, 0.0),
                  size_display=(600, 400),
                  plane=True,
                  size_world = 10,
                  axes_helper=True)

[11]: SceneWidget(axes_helper=True, scenes=[{'id': 'whSP4mA3wlgKFoL4Li9pam9AQ', 'data': b'x\
→xda\x8d\x9cy\x98\x15\xc5...

```

Other parameters

In additional features, you can activate the debug mode in CARIBU, which describe the internal steps.

```

[6]: caribu_args = { "debug" : True }

lighting = LightVegeManager(lightmodel="caribu", lightmodel_parameters=caribu_args)
lighting.build(geometry=[(0., 0., 0.), (1., 0., 0.), (1., 1., 1.)])

energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)

Prepare scene 1
done

-----
FileNotFoundError                                Traceback (most recent call last)
Cell In[6], line 9
      7 hour = 15

```

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```

8 day = 264
----> 9 lighting.run(energy=energy, hour=hour, day=day)

File c:\users\mwoussen\cdd\codes\dev\lightvegemanager\src\lightvegemanager\tool.py:533,
↳ in LightVegeManager.run(self, energy, day, hour, parunit, truesolartime, id_sensors)
531 if sun_sky_option == "mix":
532     start = time.time()
--> 533     raw_sun, aggregated_sun = run_caribu(*arg)
534     arg[0] = c_scene_sky
535     raw_sky, aggregated_sky = run_caribu(*arg)

File c:\users\mwoussen\cdd\codes\dev\lightvegemanager\src\lightvegemanager\CARIBUinputs.
↳ py:370, in run_caribu(c_scene, direct_active, infinite, sensors, energy)
329 """runs caribu depending on input options
330
331 :param c_scene: instance of CaribuScene containing geometry, light source(s),
↳ opt etc...
(...)
367 :rtype: dict of dict, dict of dict
368 """
369 if sensors is None :
--> 370     raw, aggregated = c_scene.run(direct=direct_active, infinite=infinite)
371 else :
372     raw, aggregated = c_scene.run(direct=direct_active, infinite=infinite,
373                                   sensors=sensors)

File ~\AppData\Local\miniconda3\envs\mobidivpy37\lib\site-packages\alinea.caribu-8.0.7-
↳ py3.8.egg\alinea\caribu\CaribuScene.py:568, in CaribuScene.run(self, direct, infinite,
↳ d_sphere, layers, height, screen_size, screen_resolution, sensors, split_face,
↳ simplify)
566     self.canfile = os.path.join(self.tmpdir, 'cscene.can')
567     self.optfile = os.path.join(self.tmpdir, 'band0.opt')
--> 568
↳ write_scene(triangles, materials, canfile = self.canfile, optfile = self.optfile)
570 else:
571     # self.materialvalues is a cache for the computation of the material list
572     materials = self.materialvalues

File ~\AppData\Local\miniconda3\envs\mobidivpy37\lib\site-packages\alinea.caribu-8.0.7-
↳ py3.8.egg\alinea\caribu\caribu.py:177, in write_scene(triangles, materials, canfile,
↳ optfile)
175 o_string, labels = opt_string_and_labels(materials)
176 can_string = triangles_string(triangles, labels)
--> 177 open(canfile, 'w').write(can_string)
178 open(optfile, 'w').write(o_string)

FileNotFoundError: [Errno 2] No such file or directory: './caribuscene_2672400716080\
↳ cscene.can'

```

You can also use the soilmesh option and get the lighting hitting the soil. The method soilenergy get you access to its result.

```
[12]: caribu_args = { "soil mesh" : True }

lighting = LightVegeManager(lightmodel="caribu", lightmodel_parameters=caribu_args)
lighting.build(geometry=[(0., 0., 0.), (1., 0., 0.), (1., 1., 1.)])

energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)

print(lighting.soilenergy)

{'Qi': 0.6750540873627096, 'Einc': 0.6750540873627096}
```

RATP

This is the complete parameters you can provide with CARIBU:

```
ratp_args = {
    # Grid specifications
    "voxel size" : [dx, dy, dz],
    "voxel size" : "dynamic",

    "full grid" : bool,

    "origin" : [xorigin, yorigin, zorigin],
    "origin" : [xorigin, yorigin],

    "number voxels" : [nx, ny, nz],
    "grid slicing" : "ground = 0.",
    "tessellation level" : int

    # Leaf angle distribution
    "angle distrib algo" : "compute global",
    "angle distrib algo" : "compute voxel",
    "angle distrib algo" : "file",

    "nb angle classes" : int,
    "angle distrib file" : filepath,

    # Vegetation type
    "soil reflectance" : [reflectance_band0, reflectance_band1, ...],
    "reflectance coefficients" : [reflectance_band0, reflectance_band1, ...],
    "mu" : [mu_scene0, mu_scenel, ...]
}
```

Leaf angle distribution

Leaf angle distribution can be generated in 3 ways: - from a file, one distribution per specy - global and dynamically, it generates a distribution from a triangles mesh for each specy - per voxel and dynamically, it generates a distribution from the triangles located in each voxel

```
[2]: # random triangles
nb_triangles = 50
spheresize = (1., 0.3) # vertices of triangles are the sphere surface
worldsize = (0., 5.)
triangles = [random_triangle_generator(worldsize=worldsize, spheresize=spheresize) for i_
↳ in range(nb_triangles)]
```

File

You need the flag "file" and to specify the file path.

```
[15]: filepath = os.path.join(os.path.dirname(os.path.abspath("")), "data", "luzerne_angle_
↳ distrib.data")
ratp_parameters = { "angle distrib algo" : "file", "angle distrib file" : filepath }

# initialize the instance
lighting = LightVegeManager(lightmodel="ratp", lightmodel_parameters=ratp_parameters)

# build the scene
lighting.build(geometry=triangles)

print(lighting.leafangledistribution)

{'global': [[0.1382, 0.1664, 0.1972, 0.1925, 0.1507, 0.0903, 0.0425, 0.0172, 0.005]]}
```

Global distribution

You need the flag "compute global" and to specify the number of angle classes you need.

```
[3]: ratp_parameters = { "angle distrib algo" : "compute global", "nb angle classes" : 9 }

# initialize the instance
lighting = LightVegeManager(lightmodel="ratp", lightmodel_parameters=ratp_parameters)

# build the scene
lighting.build(geometry=triangles)

print(lighting.leafangledistribution)

{'global': [[0.0, 0.01403472520994376, 0.14553389876181141, 0.13870880399511626, 0.
↳ 17786938035077418, 0.06842434118299212, 0.09608726894836216, 0.20983153542452182, 0.
↳ 14951004612647875]]}
```

Local distribution

You need the flag "compute voxel" and to specify the number of angle classes you need. You will get one distribution for each voxel of your grid and each specy.

```
[6]: ratp_parameters = {
    "voxel size" : [1., 1., 1.],
    "angle distrib algo" : "compute voxel",
    "nb angle classes" : 9
}

# initialize the instance
lighting = LightVegeManager(lightmodel="ratp", lightmodel_parameters=ratp_parameters)

# build the scene
lighting.build(geometry=triangles)

print("Global")
print(lighting.leafangledistribution["global"])
print("\n\n Local")
for a in lighting.leafangledistribution["voxel"]:
    print(a[0])

Global
[[0.009674637223767685, 0.06468549489243054, 0.10705660994810652, 0.10196105003699654, 0.
→07575759861707439, 0.3044721953841436, 0.06446975879644407, 0.14828246866341796, 0.
→12364018643761852]]

Local
[0. 0. 0. 0. 0. 0. 0. 1. 0.]
[0. 0. 0. 0. 0. 0. 0. 0. 1.]
[0. 0. 1. 0. 0. 0. 0. 0. 0.]
[0.          0.          0.55805526 0.44194474 0.          0.
 0.          0.          0.          ]
[0. 0. 0. 0. 0. 0. 0. 1. 0. 0.]
[0. 0. 0. 0. 1. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 1. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 0. 0. 0. 1. 0.]
[0. 0. 0. 0. 0. 0. 0. 0. 0. 1.]
[0. 0. 0. 0. 1. 0. 0. 0. 0. 0.]
[0. 1. 0. 0. 0. 0. 0. 0. 0. 0.]
[0. 1. 0. 0. 0. 0. 0. 0. 0. 0.]
[0. 1. 0. 0. 0. 0. 0. 0. 0. 0.]
[0. 0. 0. 1. 0. 0. 0. 0. 0. 0.]
[0. 1. 0. 0. 0. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 1. 0. 0. 0. 0. 0.]
[0.          0.          0.41000514 0.58999486 0.          0.
 0.          0.          0.          ]
[0. 0. 0. 0. 0. 1. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 0. 0. 0. 0. 1.]
[0. 0. 1. 0. 0. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 1. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 0. 0. 1. 0. 0.]
```

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```

[1. 0. 0. 0. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 1. 0. 0. 0. 0.]
[0. 0. 0. 0. 1. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 1. 0. 0. 0.]
[0.      0.      0.58893012 0.41106988 0.      0.
 0.      0.      0.      ]
[0. 0. 0. 0. 1. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 1. 0. 0. 0.]
[0.      0.30170822 0.      0.      0.      0.
 0.      0.      0.69829178]
[0.      0.      0.      0.17828753 0.      0.
 0.      0.      0.82171247]
[0. 0. 0. 1. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 1. 0. 0. 0.]
[0. 0. 0. 0. 0. 0. 0. 0. 1.]
[0. 0. 0. 1. 0. 0. 0. 0. 0.]
[0. 1. 0. 0. 0. 0. 0. 0. 0.]
[1. 0. 0. 0. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 0. 0. 1. 0.]
[0. 0. 0. 1. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 1. 0. 0. 0.]
[0. 0. 0. 0. 0. 0. 0. 0. 1.]
[0. 0. 1. 0. 0. 0. 0. 0. 0.]
[0. 0. 0. 0. 0. 0. 0. 1. 0.]
[0. 0. 0. 0. 0. 0. 0. 1. 0.]

```

For visualization of the situation

```

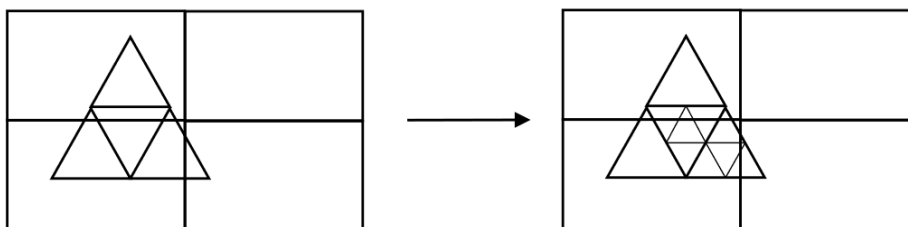
[7]: SceneWidget(lighting.plantGL_nolight(printtriangles=True, printvoxels=True),
                 position=(-2.5, -2.5, 0.0),
                 size_display=(600, 400),
                 plane=True,
                 size_world = 10,
                 axes_helper=True)

[7]: SceneWidget(axes_helper=True, scenes=[{'id': 'Rp6rgkW0hu088XZzffdSscV0V', 'data': b'x\
↳ xda\x8d\x9b{\x9c\x8d\xd5...

```

Triangles tessellation in a grid

You can reduce the error while transferring a triangle mesh to a voxel mesh by subdividing triangles across multiple voxels.



You only need to precise how many times you want to subdivide the triangles.

```
[21]: ratp_parameters = { "voxel size" : [1., 1., 1.], "tessellation level" : 7 }

# initialize the instance
lighting = LightVegeManager(lightmodel="ratp", lightmodel_parameters=ratp_parameters)

# build the scene
lighting.build(geometry=triangles)

SceneWidget(lighting.plantGL_nolight(printtriangles=True, printvoxels=True),
            position=(-2.5, -2.5, 0.0),
            size_display=(600, 400),
            plane=True,
            size_world = 10,
            axes_helper=True)

[21]: SceneWidget(axes_helper=True, scenes=[{'id': 'w9muljQPBqZrSzDk4B45B9Wav', 'data': b'x\
↪xda\x94}\x07\x9c^E\xd5~\...
```

Other parameters

By default, the number of voxels is dynamically computed following the voxel size and mesh limits, but you can force its number.

Voxel size can also be dynamically computed and is based on 3 times the longest triangle.

2.6.5 Output formats and transfer methods

Content

- Main light outputs
- transfer results to l-egume
- transfer results to CN-Wheat

Introduction

This notebook will present the different output formats given by the tool.

```
[1]: from lightvegemanager.LVM import LightVegeManager
from pgljupyter import SceneWidget
from lightvegemanager.trianglemesh import random_triangle_generator
```


Main light outputs: Pandas dataframe

Outputs are stored in at least two different scales, by triangle or voxel, and by organ. We will use a set of random triangles as an illustration.

```
[2]: # random triangles
nb_triangles = 20
spheresize = (1., 0.3) # vertices of triangles are the sphere surface
worldsize = (0., 5.)
triangles = [random_triangle_generator(worldsize=worldsize, spheresize=spheresize) for i_
↪ in range(nb_triangles)]
```

We compute one iteration with CARIBU

```
[3]: lighting = LightVegeManager(lightmodel="caribu")
lighting.build(geometry=triangles)

energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)
```

Results for each triangle

```
[4]: print(type(lighting.triangles_outputs), "\n")
print(lighting.triangles_outputs)
```

```
<class 'pandas.core.frame.DataFrame'>
```

	Day	Hour	Triangle	Organ	VegetationType	Area	par	Eabs	\
0	264	15	0	0	0	0.536966	432.528062		
1	264	15	1	0	0	0.504415	473.973825		
2	264	15	2	0	0	0.314083	466.696396		
3	264	15	3	0	0	0.057297	427.303344		
4	264	15	4	0	0	0.266138	346.795923		
5	264	15	5	0	0	0.318387	359.266951		
6	264	15	6	0	0	0.089070	480.230969		
7	264	15	7	0	0	0.436727	383.952401		
8	264	15	8	0	0	0.094307	380.840868		
9	264	15	9	0	0	0.501522	388.825138		
10	264	15	10	0	0	0.051670	382.490896		
11	264	15	11	0	0	0.193144	407.201836		
12	264	15	12	0	0	0.585857	414.603624		
13	264	15	13	0	0	0.139755	427.431809		
14	264	15	14	0	0	0.805939	317.704624		
15	264	15	15	0	0	0.104366	420.622125		
16	264	15	16	0	0	0.214229	461.347939		
17	264	15	17	0	0	0.273954	426.103905		
18	264	15	18	0	0	0.986628	376.478502		
19	264	15	19	0	0	0.303850	469.840116		
par Ei									
0	508.856544								
1	557.616265								

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```

2  549.054584
3  502.709816
4  407.995204
5  422.667001
6  564.977611
7  451.708707
8  448.048080
9  457.441339
10 449.989290
11 479.060984
12 487.768969
13 502.860951
14 373.770146
15 494.849559
16 542.762281
17 501.298712
18 442.915885
19 552.753077

```

We can try to group multiple sets of triangles

```

[5]: nb_triangles = 10
      triangles1 = [random_triangle_generator(worldsize=worldsize, spheresize=spheresize) for
                    ↪ i in range(nb_triangles)]

      nb_triangles = 9
      triangles2 = [random_triangle_generator(worldsize=worldsize, spheresize=spheresize) for
                    ↪ i in range(nb_triangles)]

      nb_triangles = 8
      triangles3 = [random_triangle_generator(worldsize=worldsize, spheresize=spheresize) for
                    ↪ i in range(nb_triangles)]

```

```

[6]: scene = {0: triangles1, 1: triangles2, 2: triangles3}

```

```

      lighting = LightVegeManager(lightmodel="caribu")
      lighting.build(geometry={"scenes": [scene] })

      energy = 500.
      hour = 15
      day = 264
      lighting.run(energy=energy, hour=hour, day=day)

```

```

[7]: print(lighting.triangles_outputs)

```

	Day	Hour	Triangle	Organ	VegetationType	Area	par Eabs	\
0	264	15	0	0	0	0.347893	466.934112	
1	264	15	1	0	0	0.230175	343.491693	
2	264	15	2	0	0	0.236752	406.441366	
3	264	15	3	0	0	0.055911	431.671508	
4	264	15	4	0	0	2.047361	349.189980	
5	264	15	5	0	0	0.132022	305.537738	

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6	264	15	6	0	0	0.179736	347.226774
7	264	15	7	0	0	0.353962	391.605479
8	264	15	8	0	0	1.065609	441.957469
9	264	15	9	0	0	0.196493	334.393347
10	264	15	10	1	0	0.014315	335.982872
11	264	15	11	1	0	0.047547	409.832578
12	264	15	12	1	0	0.932423	417.792230
13	264	15	13	1	0	0.078560	330.173348
14	264	15	14	1	0	0.037776	413.308224
15	264	15	15	1	0	1.845328	393.111328
16	264	15	16	1	0	0.212917	402.681041
17	264	15	17	1	0	0.367550	360.846221
18	264	15	18	1	0	0.104118	339.165224
19	264	15	19	2	0	0.051821	481.839430
20	264	15	20	2	0	0.172513	316.689490
21	264	15	21	2	0	0.274700	360.822712
22	264	15	22	2	0	0.150917	274.216253
23	264	15	23	2	0	0.028843	372.272165
24	264	15	24	2	0	0.643578	373.151609
25	264	15	25	2	0	0.094779	340.286767
26	264	15	26	2	0	0.069499	388.224866

par Ei

0	549.334249
1	404.107874
2	478.166313
3	507.848832
4	410.811741
5	359.456163
6	408.502087
7	460.712328
8	519.949964
9	393.403938
10	395.273967
11	482.155974
12	491.520271
13	388.439233
14	486.244970
15	462.483915
16	473.742402
17	424.524966
18	399.017911
19	566.869918
20	372.575870
21	424.497308
22	322.607357
23	437.967253
24	439.001893
25	400.337373
26	456.735136

And the grouped results

```
[8]: print(lighting.elements_outputs)
```

	Day	Hour	Organ	VegetationType	Area	par Eabs	par Ei
0	264	15	0	0	4.845914	382.756535	450.301806
1	264	15	1	0	3.640534	394.037183	463.573157
2	264	15	2	0	1.486650	356.659092	419.598932

With RATP, you have another output for each voxel

```
[9]: scene = {0: triangles1, 1: triangles2, 2: triangles3}
```

```
lighting = LightVegeManager(lightmodel="ratp")
lighting.build(geometry={"scenes" : [scene] })
```

```
energy = 500.
```

```
hour = 15
```

```
day = 264
```

```
lighting.run(energy=energy, hour=hour, day=day)
```

```
[10]: print(lighting.triangles_outputs)
```

	Triangle	Organ	Voxel	VegetationType	primitive_area	Day	Hour	Nx	\
0	0	0	1.0	1	0.347893	264.0	15.0	1	
1	1	0	1.0	1	0.230175	264.0	15.0	1	
2	2	0	1.0	1	0.236752	264.0	15.0	1	
3	3	0	1.0	1	0.055911	264.0	15.0	1	
4	4	0	1.0	1	2.047361	264.0	15.0	1	
5	5	0	1.0	1	0.132022	264.0	15.0	1	
6	6	0	1.0	1	0.179736	264.0	15.0	1	
7	7	0	1.0	1	0.353962	264.0	15.0	1	
8	8	0	1.0	1	1.065609	264.0	15.0	1	
9	9	0	1.0	1	0.196493	264.0	15.0	1	
10	10	1	1.0	1	0.014315	264.0	15.0	1	
11	11	1	1.0	1	0.047547	264.0	15.0	1	
12	12	1	1.0	1	0.932423	264.0	15.0	1	
13	13	1	1.0	1	0.078560	264.0	15.0	1	
14	14	1	1.0	1	0.037776	264.0	15.0	1	
15	15	1	1.0	1	1.845328	264.0	15.0	1	
16	16	1	1.0	1	0.212917	264.0	15.0	1	
17	17	1	1.0	1	0.367550	264.0	15.0	1	
18	18	1	1.0	1	0.104118	264.0	15.0	1	
19	19	2	1.0	1	0.051821	264.0	15.0	1	
20	20	2	1.0	1	0.172513	264.0	15.0	1	
21	21	2	1.0	1	0.274700	264.0	15.0	1	
22	22	2	1.0	1	0.150917	264.0	15.0	1	
23	23	2	1.0	1	0.028843	264.0	15.0	1	
24	24	2	1.0	1	0.643578	264.0	15.0	1	
25	25	2	1.0	1	0.094779	264.0	15.0	1	
26	26	2	1.0	1	0.069499	264.0	15.0	1	

	Ny	Nz	ShadedPAR	SunlitPAR	ShadedArea	SunlitArea	Area	\
0	1	1	363.182404	461.736481	0.416941	9.556157	9.973098	
1	1	1	363.182404	461.736481	0.416941	9.556157	9.973098	
2	1	1	363.182404	461.736481	0.416941	9.556157	9.973098	

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3	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
4	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
5	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
6	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
7	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
8	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
9	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
10	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
11	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
12	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
13	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
14	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
15	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
16	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
17	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
18	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
19	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
20	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
21	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
22	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
23	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
24	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
25	1	1	363.182404	461.736481	0.416941	9.556157	9.973098
26	1	1	363.182404	461.736481	0.416941	9.556157	9.973098

	PARa	Intercepted	Transmitted
0	457.616241	9.127703	44.626312
1	457.616241	9.127703	44.626312
2	457.616241	9.127703	44.626312
3	457.616241	9.127703	44.626312
4	457.616241	9.127703	44.626312
5	457.616241	9.127703	44.626312
6	457.616241	9.127703	44.626312
7	457.616241	9.127703	44.626312
8	457.616241	9.127703	44.626312
9	457.616241	9.127703	44.626312
10	457.616241	9.127703	44.626312
11	457.616241	9.127703	44.626312
12	457.616241	9.127703	44.626312
13	457.616241	9.127703	44.626312
14	457.616241	9.127703	44.626312
15	457.616241	9.127703	44.626312
16	457.616241	9.127703	44.626312
17	457.616241	9.127703	44.626312
18	457.616241	9.127703	44.626312
19	457.616241	9.127703	44.626312
20	457.616241	9.127703	44.626312
21	457.616241	9.127703	44.626312
22	457.616241	9.127703	44.626312
23	457.616241	9.127703	44.626312
24	457.616241	9.127703	44.626312
25	457.616241	9.127703	44.626312

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26	457.616241	9.127703	44.626312
----	------------	----------	-----------

```
[11]: print(lighting.voxels_outputs)
```

	VegetationType	Day	Hour	Voxel	Nx	Ny	Nz	ShadedPAR	SunlitPAR	\
0	1.0	264.0	15.0	1.0	1	1	1	363.182404	461.736481	

	ShadedArea	SunlitArea	Area	PARa	Intercepted	Transmitted
0	0.416941	9.556157	9.973098	457.616241	9.127703	44.626312

```
[12]: print(lighting.elements_outputs)
```

	Day	Hour	Organ	VegetationType	Area	PARa	Intercepted	\
0	264.0	15.0	0	1	4.845914	457.616241	9.127703	
1	264.0	15.0	1	1	3.640534	457.616241	9.127703	
2	264.0	15.0	2	1	1.486650	457.616241	9.127703	

	Transmitted	SunlitPAR	SunlitArea	ShadedPAR	ShadedArea
0	9.127703	461.736481	9.556157	363.182404	0.416941
1	9.127703	461.736481	9.556157	363.182404	0.416941
2	9.127703	461.736481	9.556157	363.182404	0.416941

I-egume results transfer

There are two possible scenarios: - with RATP, the tool reformats the data types. Grid specifications must match with l-egume internal grid instance - with CARIBU, you need to use virtual sensors following the dimensions of l-egume internal grid.

The id argument is used with you several input scenes but you need to transfer only some of them to your l-egume instance.

In both case, it will return two tables, one with intercepted lighting and another with transmitted lighting in each voxel.

```
[13]: # grid dimensions
```

```
dxyz = [1.] * 3
nxyz = [7, 7, 7]
orig = [-1., -1., 0.]
```

```
[14]: spheresize = (1., 0.3) # vertices of triangles are the sphere surface
```

```
worldsize = (0., 5.)
```

```
nb_triangles = 10
```

```
triangles1 = [random_triangle_generator(worldsize=worldsize, spheresize=spheresize) for
```

```
    ↪ i in range(nb_triangles)]
```

```
nb_triangles = 9
```

```
triangles2 = [random_triangle_generator(worldsize=worldsize, spheresize=spheresize) for
```

```
    ↪ i in range(nb_triangles)]
```

```
nb_triangles = 8
```

```
triangles3 = [random_triangle_generator(worldsize=worldsize, spheresize=spheresize) for
```

```
    ↪ i in range(nb_triangles)]
```

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```
scene = {0: triangles1, 1: triangles2, 2: triangles3}
```

RATP

Input: l-egume intern grid of leaf area

```
[15]: ratp_parameters = { "voxel size" : dxyz,
                        "origin" : orig,
                        "number voxels" : nxyz,
                        "full grid" : True}

lighting = LightVegeManager(lightmodel="ratp", lightmodel_parameters=ratp_parameters)
lighting.build(geometry={"scenes" : [scene] })

energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)
```

```
[16]: SceneWidget(lighting.plantGL_nolight(printtriangles=True, printvoxels=True),
                  position=(0., 0., 0.0),
                  size_display=(600, 400),
                  plane=True,
                  size_world = 10,
                  axes_helper=True)
```

```
[16]: SceneWidget(axes_helper=True, scenes=[{'id': 'Eo1pXjKQFbVhh6Ksf54Ry6k6D', 'data': b'x\
↵xda\x8d}\x0b\x94\xadEuf+...
```

```
[17]: import numpy

m_lais = numpy.zeros([1] + nxyz)

for row in lighting.voxels_outputs.itertuples():
    m_lais[int(row.VegetationType)-1][row.Nz-1][row.Nx-1][row.Ny-1] = row.Area
```

```
[18]: res_abs_i, res_trans = lighting.to_l_egume(m_lais=m_lais)

print("PARa intercepted")
print(res_abs_i)
print("\n")
print("PARa transmitted")
print(res_trans)

PARa intercepted
[[[1.00000000e-14 1.00000000e-14 1.00000000e-14 1.00000000e-14
    1.00000000e-14 1.00000000e-14 1.00000000e-14]
 [1.00000000e-14 1.00000000e-14 1.00000000e-14 1.00000000e-14
    1.00000000e-14 1.00000000e-14 1.00000000e-14]
 [1.00000000e-14 1.00000000e-14 1.00000000e-14 1.00000000e-14
    1.00000000e-14 1.00000000e-14 1.00000000e-14]
 [1.00000000e-14 1.00000000e-14 1.00000000e-14 1.00000000e-14
    1.00000000e-14 1.00000000e-14 1.00000000e-14]]]
```

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```

1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]]

[[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 4.89933714e-02 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 2.93938100e-01 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 2.57237822e-01
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]]

[[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 3.80286694e-01 8.93628836e-01
6.55927658e-01 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.29318118e-01 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 5.11650145e-01
3.74495775e-01 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]]

[[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 5.34315050e-01 1.000000000e-14
4.15218249e-02 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
4.28144723e-01 5.49222976e-02 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
1.000000000e-14 1.000000000e-14 2.89329551e-02]]

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```

[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]]

[[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.69486284e-01 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 8.16469371e-01 1.000000000e-14
 1.000000000e-14 6.63995743e-02 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]]

[[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 2.14309216e-01 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 2.51297981e-01 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 6.85566485e-01
 1.000000000e-14 1.11084175e+00 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]]

[[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.67224873e-02 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]
[1.000000000e-14 1.000000000e-14 1.000000000e-14 1.000000000e-14
 1.000000000e-14 1.000000000e-14 1.000000000e-14]]]

```

PARa transmitted

```

[[[1.      1.      1.      1.      1.      1.
    1.      ]

```

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```

[1.      1.      1.      1.      1.      1.
 1.      ]
[1.      1.      1.      1.      1.      1.
 1.      ]
[1.      1.      1.      1.      1.      1.
 1.      ]
[1.      1.      1.      1.      1.      1.
 1.      ]
[1.      1.      1.      1.      1.      1.
 1.      ]
[1.      1.      1.      1.      1.      1.
 1.      ]]

[[[1.      0.99966007 0.99862611 0.99862772 0.99882162 1.
 1.      ]
[0.99937242 0.99652928 0.99643964 0.99913657 0.99951363 0.99987358
 0.9998582 ]
[0.99661541 0.9750672 0.97824836 0.99296302 0.99881232 0.99979579
 0.9996115 ]
[0.9968856 0.98334223 0.88385904 0.97908282 0.99741894 0.99954569
 0.99927342]
[0.99909747 0.99502355 0.98070908 0.97873741 0.99385464 0.99878031
 1.      ]
[0.99955082 0.99661982 0.98586112 0.89782482 0.98341918 0.99853724
 0.99973792]
[1.      0.99890536 0.99653733 0.98721927 0.99558949 0.99994254
 0.99992949]]

[[[0.99485987 0.98211366 0.94685709 0.90895796 0.92835289 0.9768011
 0.99335617]
[0.98958224 0.95989323 0.78321606 0.59019464 0.68427098 0.94649696
 0.98931742]
[0.99396461 0.97352087 0.89230376 0.90797049 0.93556297 0.97943383
 0.99502289]
[0.99184281 0.98125339 0.94494903 0.93165594 0.95026821 0.98223406
 0.99335128]
[0.98969823 0.9849447 0.95014137 0.76321989 0.81169522 0.96606922
 0.98965567]
[0.99407554 0.99231446 0.976399 0.93636918 0.95371062 0.98325461
 0.99324131]
[0.99734932 0.99393582 0.9833504 0.97493804 0.9806965 0.99197996
 0.9983626 ]]

[[[0.98496985 0.96739489 0.9302929 0.89807343 0.9174937 0.95895547
 0.98020232]
[0.98125023 0.94733357 0.86565912 0.84225869 0.8774448 0.95282722
 0.98152596]
[0.97424239 0.93394589 0.72031593 0.88447887 0.90997893 0.9595657
 0.9761579 ]
[0.97994757 0.96309948 0.90736842 0.8934654 0.89512074 0.94767475
 0.97867441]
[0.98629206 0.97525859 0.95201224 0.88435513 0.7504518 0.91819239

```

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```

0.98110867]
[0.98893738 0.98108053 0.96626729 0.94061965 0.93254912 0.95972735
0.97235537]
[0.98517865 0.97681737 0.96344769 0.95575136 0.95711577 0.96942037
0.9815892 ]]

[[0.97933716 0.97092551 0.94165611 0.94100547 0.94331664 0.95525873
0.97785884]
[0.97096044 0.94943368 0.91685653 0.90953714 0.91383499 0.89041752
0.96821451]
[0.9826436 0.95704621 0.91028017 0.92085916 0.93676978 0.95857286
0.97805393]
[0.97259653 0.94509262 0.87017393 0.89592469 0.91131461 0.94362009
0.96967971]
[0.98114228 0.93692589 0.66466349 0.88666028 0.9184655 0.92707497
0.97069734]
[0.97923797 0.97428864 0.9446348 0.95074368 0.95068192 0.96627277
0.9782179 ]
[0.98016465 0.97797263 0.95464146 0.94952333 0.94629568 0.97018468
0.980313 ]]

[[0.95296037 0.95422834 0.94934404 0.93673187 0.93656844 0.93842596
0.94804531]
[0.97229284 0.96320361 0.9393397 0.92389566 0.92137164 0.87234128
0.95597047]
[0.96675485 0.94391161 0.90375632 0.92214018 0.92659348 0.92107111
0.96080649]
[0.95322537 0.92634034 0.80349278 0.84525293 0.90094328 0.86473721
0.93806767]
[0.96127474 0.93329871 0.8198998 0.64854169 0.81475776 0.55683774
0.90463072]
[0.98215431 0.96413124 0.91450155 0.88721132 0.9184497 0.89321476
0.96541333]
[0.98092657 0.96966964 0.9389317 0.95247173 0.94251043 0.95123148
0.96945715]]

[[0.94756877 0.95514208 0.94929218 0.94613492 0.92572314 0.9404825
0.93554872]
[0.97161055 0.95421797 0.92918479 0.93547511 0.92323899 0.93136919
0.94081557]
[0.94040775 0.94937837 0.93365628 0.92724371 0.91473806 0.9428041
0.93166846]
[0.94083965 0.92754972 0.9003523 0.89309627 0.89577699 0.90264505
0.92660093]
[0.94083911 0.92529798 0.88156152 0.84460795 0.84956956 0.85377795
0.90978062]
[0.93541592 0.93342227 0.9089222 0.90135753 0.88972384 0.89331508
0.92612672]
[0.96249211 0.96975094 0.94652379 0.9468134 0.93272442 0.94823855
0.95390475]]]

```

CARIBU

Input: l-egume intern grid of leaf area

```
[19]: caribu_args = { "sensors" : ["grid", dxyz, nxyz, orig] }

lighting = LightVegeManager(lightmodel="caribu", lightmodel_parameters=caribu_args,
↪environment={"infinite":True})
lighting.build(geometry={"scenes" : [scene] })

energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)

[20]: SceneWidget(lighting.plantGL_sensors(light=True) + lighting.plantGL_nolight(),
                position=(-0., -0., 0.0),
                size_display=(600, 400),
                plane=True,
                size_world = 10,
                axes_helper=True)

[20]: SceneWidget(axes_helper=True, scenes=[{'id': 'wJZ83l0BmoFl6R5sdBeyGBiUB', 'data': b'x\
↪xda\x8d\x9d\r\xbcUE\xb9\...

[21]: # plant parameters, those variables are part of l-egume, here is a simplified version.
↪for our example
list_invar = [{"Hplante": [0.0] * 2}]
list_lstring = [
    {
        0: [0, 0, 0, 0, 0, 0, 0, 0, 0, 0, "dev"],
        1: [0, 0, 0, 0, 0, 0, 0, 0, 0, 0, "sen"],
        2: [1, 0, 0, 0, 0, 0, 0, 0, 0, 0, "dev"],
    }
]
list_dicFeuilBilanR = [
    {"surf": [0.5, 1e-8]},
]

import numpy

m_lais = numpy.zeros([1] + nxyz)

[22]: res_trans = lighting.to_l_egume(m_lais=m_lais,
                                    list_lstring=list_lstring,
                                    list_dicFeuilBilanR=list_dicFeuilBilanR,
                                    list_invar=list_invar)

print("PARa transmitted")
print(res_trans)

print("\n")
print("PARa absorbed per plant")
print(list_invar)
```


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```

0.91514608]
[0.93257741 0.86079298 0.8449184 0.8523624 0.87150218 0.91578729
0.9013189 ]
[0.96779888 0.93102995 0.91071792 0.92115358 0.933688 0.94220112
0.93189039]
[0.97735824 0.96935045 0.93242933 0.91134405 0.94099756 0.959761
0.95889625]]

[[0.92296813 0.90516463 0.90284731 0.91447234 0.87371474 0.88073977
0.93560093]
[0.88270877 0.88940347 0.85396849 0.85397283 0.84917024 0.87384279
0.91539319]
[0.87898549 0.8856543 0.83203816 0.82884733 0.86532201 0.89502837
0.90832493]
[0.88237416 0.84629472 0.83386876 0.83964468 0.85864715 0.90311898
0.92454761]
[0.89126296 0.83400359 0.8388134 0.86334547 0.86850161 0.9055682
0.93470077]
[0.92007599 0.8866167 0.88060342 0.90901959 0.91319735 0.91664405
0.93776939]
[0.93967084 0.9347306 0.92625581 0.93690253 0.94524498 0.94220458
0.9435016 ]]

[[0.85841022 0.74993594 0.76130349 0.85284938 0.86431234 0.87480163
0.90179267]
[0.86526185 0.74226062 0.75591914 0.85134443 0.83492443 0.83171408
0.88010129]
[0.86923228 0.77258171 0.7676997 0.8318704 0.83804378 0.85347289
0.87805225]
[0.87857998 0.816706 0.79000755 0.82842821 0.8698445 0.89948354
0.90035524]
[0.89811456 0.86396829 0.85201001 0.87253328 0.90782969 0.91597453
0.9044806 ]
[0.92190268 0.89046769 0.8868083 0.91020047 0.92585094 0.88768819
0.87828466]
[0.89487078 0.8693884 0.85757664 0.86653003 0.90359564 0.88007679
0.87716112]]

[[0.85301056 0.8414348 0.8673805 0.88293181 0.85568144 0.8688417
0.88986585]
[0.84806958 0.8108317 0.82544714 0.84720828 0.86359825 0.88581908
0.90040623]
[0.85604356 0.81045805 0.8047335 0.83012291 0.86524461 0.89470453
0.87592102]
[0.85554426 0.81356764 0.79736908 0.80259271 0.83525448 0.8843983
0.85818303]
[0.86421433 0.81436691 0.80029539 0.79579841 0.819411 0.86965378
0.88410009]
[0.88160032 0.85434114 0.81889592 0.80924773 0.85369548 0.88390842
0.9028424 ]
[0.89895522 0.86912624 0.83433478 0.82886494 0.87638531 0.8954713
0.89080121]]]

```

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```

PARa absorbed per plant
[{'Hplante': [0.0, 0.0], 'parap': array([122.57339982, 154.20674688]), 'parip':
↪array([235.25554024, 154.20674688])}]

```

CN-Wheat results transfer

The method `to_MTG` is used to transfer results to Cn-Wheat through a MTG object with the properties "PARa" and "Erel". The `id` argument is used with you several input scenes but you need to transfer only some of them to your MTG instance.

```

[23]: # load a MTG instance
import os
from alineaa.adel.adel_dynamic import AdelDyn
from alineaa.adel.echap_leaf import echap_leaves

INPUTS_DIRPATH = os.path.join(os.path.dirname(os.path.abspath("")), "data")
adel_wheat = AdelDyn(seed=1, scene_unit="m", leaves=echap_leaves(xy_model="Soissons_
↪byleafclass"))
g = adel_wheat.load(dir=INPUTS_DIRPATH)

```

```

[24]: lighting = LightVegeManager(lightmodel="caribu")
lighting.build(geometry={"scenes" : [g] })

energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)

```

```

[25]: lighting.to_MTG(mtg=g)
print(g.property("PARa"))
print(g.property("Erel"))

{19: 183.28839878423275, 34: 88.59510772768847, 813: 458.96763725505764, 814: 392.
↪72942554102866, 51: 350.64417693430573}
{19: 0.3665767975684655, 34: 0.17719021545537694, 813: 0.9179352745101153, 814: 0.
↪7854588510820574, 51: 0.7012883538686114}

```

```

[26]: lighting = LightVegeManager(lightmodel="ratp")
lighting.build(geometry={"scenes" : [g] })

energy = 500.
hour = 15
day = 264
lighting.run(energy=energy, hour=hour, day=day)

```

```

[27]: lighting.to_MTG(mtg=g)
print(g.property("PARa"))
print(g.property("Erel"))

```

```
{19: 468.0222778320313, 34: 468.02227783203136, 813: 468.0222778320312, 814: 473.  
↪66244791932104, 51: 468.02227783203125}  
{19: 0.0007445579394698143, 34: 0.0007445579394698143, 813: 0.0007445579394698141, 814: 0.  
↪0.00030915768207336026, 51: 0.0007445579394698143}
```

2.6.6 Example of use

Here is an example with a more “realistic” canopy. We start from a single fescue and alfafa stored in .bgeom files, then we will generate copies in random positions, in order to make a canopy.

```
[1]: import os  
from lightvegemanager.LVM import LightVegeManager  
from pglljupyter import SceneWidget  
from openalea.plantgl.all import Scene
```

Canopy generation

Load the .bgeom files

```
[2]: fet_fgeom = os.path.join(os.path.dirname(os.path.abspath("")), "data", "Fet-LD-F2.bgeom")  
luz_fgeom = os.path.join(os.path.dirname(os.path.abspath("")), "data", "LD-F1.bgeom")  
bgeom_files = [fet_fgeom, luz_fgeom]  
bgeom_files  
[2]: ['C:\\Users\\mwoussen\\cdd\\codes\\dev\\lightvegemanager\\data\\Fet-LD-F2.bgeom',  
'C:\\Users\\mwoussen\\cdd\\codes\\dev\\lightvegemanager\\data\\LD-F1.bgeom']
```

Generate copies in random position

```
[3]: from lightvegemanager.trianglemesh import create_heterogeneous_canopy  
  
# scene generation parameters  
nplants = 50  
plant_density=130  
var_plant_position=110  
  
# generate random canopy from plant examples  
if not isinstance(bgeom_files, list): bgeom_files = [bgeom_files]  
scenes = []  
for f in bgeom_files :  
    plant_scene = Scene()  
    plant_scene.read(f, 'BGEOM')  
  
    # multiply a plant with variations  
    canopy, domain = create_heterogeneous_canopy(plant_scene,  
                                                    nplants=nplants,  
                                                    plant_density=plant_density,  
                                                    var_plant_position=var_plant_position)  
  
    scenes.append(canopy)
```


Lighting simulation

Set simulation parameters

```
[4]: # setup environment
environment = {}
environment["coordinates"] = [48.8 ,2.3 ,1] # latitude, longitude, timezone

# we compute only sun light in an infinite scene
environment["diffus"] = False
environment["direct"] = True
environment["reflected"] = False
environment["infinite"] = True

# CARIBU parameters
caribu_parameters = {
    "sun algo": "caribu",
    "caribu opt" : { "par": (0.10, 0.05) }
}

# inputs values for lighting
energy=500
day=264
hour=15
```

Run the simulation

```
[5]: # Initializing the tool
lighting = LightVegeManager(lightmodel="caribu",
                             environment=environment,
                             lightmodel_parameters=caribu_parameters)

# build the scene
geometry = {"scenes" : scenes }

lighting.build(geometry)

# compute lighting
lighting.run(energy=energy, hour=hour, day=day)

# print results gathered by elements (Shapes in the plantGL Scene)
print(lighting.elements_outputs)
```

	Day	Hour	Organ	VegetationType	Area	par	Eabs	par	Ei
0	264	15	825510368	0	83.332180	76.246899	89.702234		
1	264	15	825501440	0	75.958035	212.034963	249.452897		
2	264	15	825503168	0	4.520565	108.134153	127.216650		
3	264	15	825503824	0	57.771363	79.214402	93.193414		
4	264	15	825498448	0	5.711880	97.236152	114.395473		
..
321	264	15	825485200	1	2.625990	287.633701	338.392589		

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322	264	15	825485904	1	18.000312	82.696127	97.289562
323	264	15	825486976	1	12.152513	78.609077	92.481268
324	264	15	825488784	1	9.200676	519.140172	610.753143
325	264	15	825489120	1	9.200676	424.977325	499.973324

[326 rows x 7 columns]

```
[6]: # visualisation
SceneWidget(lighting.plantGL_light(printtriangles=True, printvoxels=False),
            position=(0.0, 0.0, 0.0),
            size_display=(600, 400),
            plane=True,
            size_world = 100,
            axes_helper=True)

[6]: SceneWidget(axes_helper=True, scenes=[{'id': 'iscrYkj7jZcxvvYDWDY2BWysh', 'data': b'x\
↪ xda\x94\x9d\t|e\x95\xff...
```

2.6.7 Misc fonctionnalités

Content

- Subdivision of all triangles in the scene
- Visualisation with VTK
- External tools for analysing leaf angle distribution from a mesh

Introduction

We provide more useful tools to help the lighting management

```
[1]: import os
from lightvegemanager.LVM import LightVegeManager
from pgljupyter import SceneWidget
from lightvegemanager.trianglemesh import random_triangle_generator
```

Simple mesh subdivision

If you want to refine the shadowing process in your mesh, you can subdivide all triangles.

```
[2]: # random triangles
nb_triangles = 50
spheresize = (1., 0.3) # vertices of triangles are the sphere surface
worldsize = (0., 5.)
triangles = [random_triangle_generator(worldsize=worldsize, spheresize=spheresize) for i_
↪ in range(nb_triangles)]
```

```
[3]: lighting = LightVegeManager(lightmodel="caribu")
lighting.build(geometry=triangles)
SceneWidget(lighting.plantGL_nolight(),
            position=(-2.5, -2.5, 0.0),
            size_display=(600, 400),
            plane=True,
            size_world = 10,
            axes_helper=True)

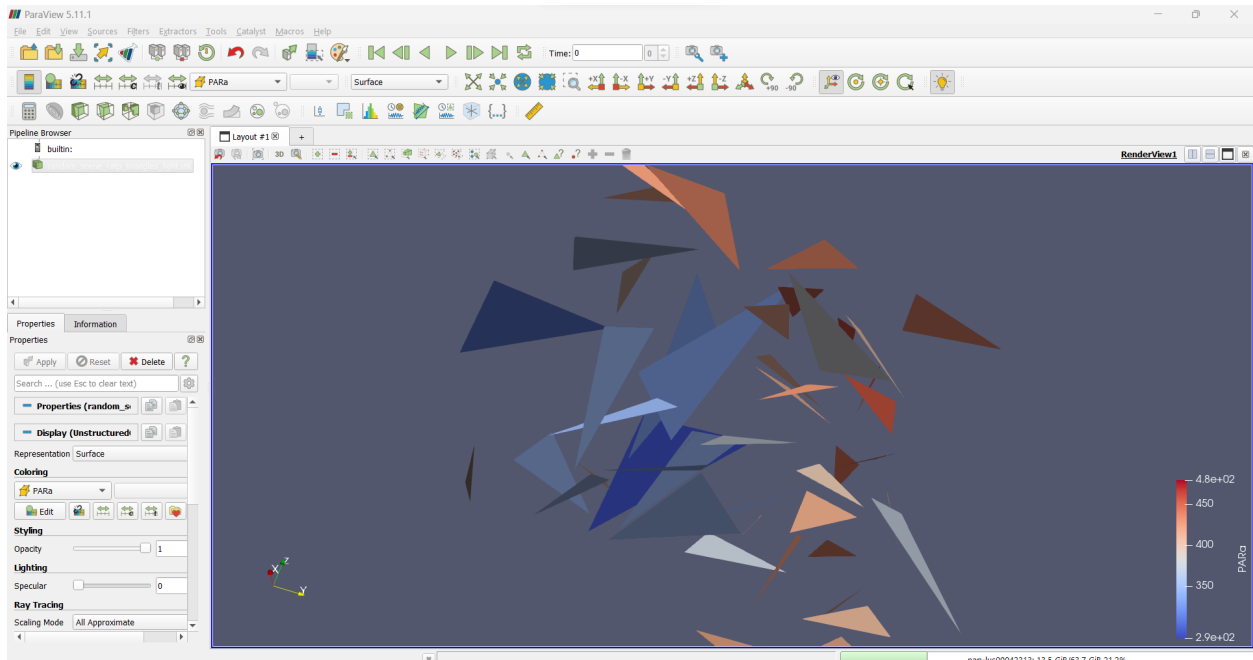
[3]: SceneWidget(axes_helper=True, scenes=[{'id': '09xJcnvhQDpm2yuSozG1BZUoe', 'data': b'x\
↳ xda\x8d\x99yXUU\x17\xc6/...
```

```
[4]: global_scene_tessellate_level = 5
lighting.build(geometry=triangles, global_scene_tessellate_level=global_scene_tessellate_
↳ level)
SceneWidget(lighting.plantGL_nolight(),
            position=(-2.5, -2.5, 0.0),
            size_display=(600, 400),
            plane=True,
            size_world = 10,
            axes_helper=True)

[4]: SceneWidget(axes_helper=True, scenes=[{'id': 'LgksLWwDW2DzGMUPPzSXEO0nw', 'data': b'x\
↳ xda\x94]\x07x]\xc5\xb16/...
```

Visualisation with VTK

PlantGL offers a good first approach to visualizing scene geometry, but software such as Paraview can take this visualization even further. LightVegeManager lets you export the scene in VTK format for further processing in ParaView.



There are three methods to export VTK files: - VTK_nolight: exports only the geometric information, organ ID and specy ID - VTK_light: adds all the information about the scene's sunlight - VTK_sun: exports sun direction of the

current iteration

Triangles exportation

```
[10]: lighting = LightVegeManager(lightmodel="caribu")  
      lighting.build(geometry=triangles)
```

```
[11]: pathfile = "random_scene"
```

```
[12]: lighting.VTK_nolight(pathfile)
```

```
[13]: energy = 500.  
      hour = 15  
      day = 264  
      lighting.run(energy=energy, hour=hour, day=day)
```

```
[14]: lighting.VTK_light(pathfile)
```

Voxels exportation

If you use voxels grid, you exports them too. In our example, it will exports the triangles mesh and the voxels mesh specified in the inputs.

```
[15]: ratp_parameters = {"voxel size" : [1., 1., 1.] }  
      lighting = LightVegeManager(lightmodel="ratp", lightmodel_parameters=ratp_parameters)  
      lighting.build(geometry=triangles)
```

```
[16]: pathfile = "random_scene_ratp"
```

```
[17]: lighting.VTK_nolight(pathfile, printtriangles=True, printvoxels=True)
```

```
[18]: energy = 500.  
      hour = 15  
      day = 264  
      lighting.run(energy=energy, hour=hour, day=day)
```

```
[19]: lighting.VTK_light(pathfile, printtriangles=True, printvoxels=True)
```

Analyze with s2v and s5

We added the possibility to call s2v and s5, two analysis tools which returns informations in order to convert the triangle mesh in a RATP grid format. Depending on the grid dimensions you specify, it will return leaf area in each voxel (depending on the barycenter position of each triangle in the grid) and leaf angle distribution.

```
[6]: # random triangles  
      nb_triangles = 5  
      spheresize = (1., 0.3) # vertices of triangles are the sphere surface
```

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```
worldsize = (0., 5.)
triangles = [random_triangle_generator(worldsize=worldsize, spheresize=spheresize) for i_
↳ in range(nb_triangles)]
```

s5 (fortran)

```
[7]: ratp_parameters = {"voxel size" : [1., 1., 1.] }
lighting = LightVegeManager(lightmodel="ratp", lightmodel_parameters=ratp_parameters)
lighting.build(geometry=triangles)
```

```
[8]: lighting.s5()
```

```
--- Fin de s5.f
```

Description of fort.60

- xy dimension of the scene
- statistics per specy
 - Total leaf area
 - Leaf area index
 - Global zenith angle distribution
 - Global azimuth angle distribution
- statistics per voxel
 - #specy #ix #iy ~iz leaf area density
 - zenith angle distribution
 - azimuth angle distribution

```
[9]: outfile = os.path.join(os.path.dirname(os.path.abspath("")), "s5", "fort.60")
with open(outfile, "r") as fichier:
    for ligne in fichier:
        print(ligne, end="")
```

```
dimensions de la maquette (x,y):    5.000    3.000
nombre de repetitions du motif:    1.0
```

STATISTIQUES GLOBALES DE CHAQUE ESPECE

```
espece: 1    surface foliaire: .411D+01    lai : 0.2738
distribution en zenith: 0.0000 0.3407 0.0000 0.1688 0.0000 0.0000 0.3105 0.0000 0.1800
distribution en azimuth: 0.0189 0.0000 0.3407 0.0000 0.3105 0.0000 0.0000 0.3299 0.0000
```

STATISTIQUES PAR CELLULE

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```

1 1 1 1 0.041
0.0000 0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000 0.0000
1.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
1 1 3 1 0.008
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000 0.0000 0.0000
0.0000 0.0000 0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000
1 2 3 1 0.011
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000 0.0000 0.0000
0.0000 0.0000 0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000
1 3 1 1 0.014
0.0000 0.0000 0.0000 0.1847 0.0000 0.0000 0.0000 0.0000 0.8153
0.1847 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.8153 0.0000
1 3 2 1 0.180
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000 0.0000
2 1 1 1 0.032
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000 0.0000
2 1 2 1 0.718
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.4841 0.0000 0.5159
0.0000 0.0000 0.0000 0.0000 0.4841 0.0000 0.0000 0.5159 0.0000
2 1 3 1 0.027
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.9534 0.0000 0.0466
0.0000 0.0000 0.0000 0.0000 0.9534 0.0000 0.0000 0.0466 0.0000
2 2 3 1 0.005
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000 0.0000 0.0000
0.0000 0.0000 0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000
2 3 1 1 0.039
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000 0.0000
2 3 2 1 0.104
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000 0.0000
3 1 1 1 0.058
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000 0.0000 0.0000
0.0000 0.0000 0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000
3 1 2 1 0.696
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000 0.0000 0.0000
0.0000 0.0000 0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000
3 2 3 1 0.007
0.0000 1.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
3 3 3 1 0.183
0.0000 1.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
4 1 2 1 0.288
0.0000 0.0000 0.0000 0.5694 0.0000 0.0000 0.4306 0.0000 0.0000
0.0000 0.0000 0.0000 0.0000 0.4306 0.0000 0.0000 0.5694 0.0000
4 1 3 1 0.204
0.0000 0.4558 0.0000 0.5442 0.0000 0.0000 0.0000 0.0000 0.0000
0.0000 0.0000 0.4558 0.0000 0.0000 0.0000 0.0000 0.5442 0.0000
4 2 2 1 0.157

```

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```

0.0000 0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000 0.0000
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000 0.0000
 4  2  3  1      0.357
0.0000 0.6117 0.0000 0.3883 0.0000 0.0000 0.0000 0.0000 0.0000
0.0000 0.0000 0.6117 0.0000 0.0000 0.0000 0.0000 0.3883 0.0000
 4  3  3  1      0.897
0.0000 1.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
 5  1  1  1      0.034
0.0000 0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000 0.0000
1.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
 5  1  2  1      0.026
0.0000 0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000 0.0000
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000 0.0000
 5  1  3  1      0.001
0.0000 1.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000
 5  2  2  1      0.019
0.0000 0.0000 0.0000 1.0000 0.0000 0.0000 0.0000 0.0000 0.0000
0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000 1.0000 0.0000

```

Description of leafarea

- for each specy
 - for each voxel
 - * ix | iy | iz | #specy | LAD | zenith angle distribution | azimuth angle distribution

```

[10]: outfile = os.path.join(os.path.dirname(os.path.abspath("")), "s5", "leafarea")
with open(outfile, "r") as fichier:
    for ligne in fichier:
        print(ligne, end="")

```

```

 1  1  1  1      0.041 0.000 0.000 0.000 1.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000
→1.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000
 1  1  3  1      0.008 0.000 0.000 0.000 0.000 0.000 0.000 1.000 0.000 0.000 0.000
→0.000 0.000 0.000 0.000 1.000 0.000 0.000 0.000 0.000 0.000
 1  2  3  1      0.011 0.000 0.000 0.000 0.000 0.000 0.000 1.000 0.000 0.000 0.000
→0.000 0.000 0.000 0.000 1.000 0.000 0.000 0.000 0.000 0.000
 1  3  1  1      0.014 0.000 0.000 0.000 0.185 0.000 0.000 0.000 0.000 0.815 0.000
→0.185 0.000 0.000 0.000 0.000 0.000 0.000 0.815 0.000
 1  3  2  1      0.180 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 1.000
→0.000 0.000 0.000 0.000 0.000 0.000 0.000 1.000 0.000
 2  1  1  1      0.032 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.000 1.000
→0.000 0.000 0.000 0.000 0.000 0.000 0.000 1.000 0.000
 2  1  2  1      0.718 0.000 0.000 0.000 0.000 0.000 0.000 0.484 0.000 0.516 0.000
→0.000 0.000 0.000 0.000 0.484 0.000 0.000 0.516 0.000
 2  1  3  1      0.027 0.000 0.000 0.000 0.000 0.000 0.000 0.953 0.000 0.047 0.000
→0.000 0.000 0.000 0.000 0.953 0.000 0.000 0.047 0.000
 2  2  3  1      0.005 0.000 0.000 0.000 0.000 0.000 0.000 1.000 0.000 0.000 0.000
→0.000 0.000 0.000 0.000 1.000 0.000 0.000 0.000 0.000

```

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2	3	1	1	0.039	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	1.000	└
↪0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	1.000	0.000					
2	3	2	1	0.104	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	1.000	└
↪0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	1.000	0.000					
3	1	1	1	0.058	0.000	0.000	0.000	0.000	0.000	0.000	1.000	0.000	0.000	└
↪0.000	0.000	0.000	0.000	0.000	1.000	0.000	0.000	0.000	0.000					
3	1	2	1	0.696	0.000	0.000	0.000	0.000	0.000	0.000	1.000	0.000	0.000	└
↪0.000	0.000	0.000	0.000	0.000	1.000	0.000	0.000	0.000	0.000					
3	2	3	1	0.007	0.000	1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	└
↪0.000	0.000	1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000					
3	3	3	1	0.183	0.000	1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	└
↪0.000	0.000	1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000					
4	1	2	1	0.288	0.000	0.000	0.000	0.569	0.000	0.000	0.431	0.000	0.000	└
↪0.000	0.000	0.000	0.000	0.000	0.431	0.000	0.000	0.569	0.000					
4	1	3	1	0.204	0.000	0.456	0.000	0.544	0.000	0.000	0.000	0.000	0.000	└
↪0.000	0.000	0.456	0.000	0.000	0.000	0.000	0.000	0.544	0.000					
4	2	2	1	0.157	0.000	0.000	0.000	1.000	0.000	0.000	0.000	0.000	0.000	└
↪0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	1.000	0.000					
4	2	3	1	0.357	0.000	0.612	0.000	0.388	0.000	0.000	0.000	0.000	0.000	└
↪0.000	0.000	0.612	0.000	0.000	0.000	0.000	0.000	0.388	0.000					
4	3	3	1	0.897	0.000	1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	└
↪0.000	0.000	1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000					
5	1	1	1	0.034	0.000	0.000	0.000	1.000	0.000	0.000	0.000	0.000	0.000	└
↪1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000					
5	1	2	1	0.026	0.000	0.000	0.000	1.000	0.000	0.000	0.000	0.000	0.000	└
↪0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	1.000	0.000					
5	1	3	1	0.001	0.000	1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	└
↪0.000	0.000	1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000					
5	2	2	1	0.019	0.000	0.000	0.000	1.000	0.000	0.000	0.000	0.000	0.000	└
↪0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	1.000	0.000					

s2v (c++)**[11]:** lighting.s2v()

--- Fin de s2v.cpp

Description of s2v.log

- Program logs
- global statistic for each specy
 - total leaf area
 - leaf area index
 - global zenith angle distribution

[12]: outfile = os.path.join(os.path.dirname(os.path.abspath("")), "s2v", "s2v.log")
 with open(outfile, "r") as fichier:

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```

for ligne in fichier:
    print(ligne, end="")

.\s2v++.exe
Lecture du fichier parametre dans fichier :
nji=9, nja=9, njz=4
bz[0]=4
5, 5, 1, 3, 3, 1, 1
s2v.cpp:530 -> Fin de lecture de fichier
=> Calcul des distributions
==> nje rel = 1
=> Ecriture des resultats : (c|std)err, leafarea, out.dang
Il y a eu 640 depassement en z+
xl=5, yl=3, xymaille=1

STATISTIQUES GLOBALES DE CHAQUE ESPECE
esp 1 : surfT=4.10686 - Stot=4.10686, LAI=0.27379 dist d'inclinaison :0 0.340694 0 0.
↪168815 0 0 0.310531 0 0.179961
0.018865800.34069400.310531000.329910
genere le fichier out.dang => entree de sailm pour calculer la BRDF
      : xx= 0 ; Uz= 1e-009
ferrlog stream close() called.

```

Description of s2v.can

Copy of each triangle with the z layer in which the triangle belongs

```

[13]: outfile = os.path.join(os.path.dirname(os.path.abspath("")), "s2v", "s2v.can")
with open(outfile, "r") as fichier:
    for ligne in fichier:
        print(ligne, end="")

p 2 100001001000 2 3 2.985657 4.113371 1.842963 2.750814 2.983446 1.871450 3.732794 3.
↪462100 2.480996
p 2 100001001000 2 3 3.433085 1.126134 1.322910 3.511158 2.888248 1.501685 1.933951 1.
↪618254 1.795654
p 2 100001001000 2 3 1.039979 3.215031 1.956095 0.182558 1.870699 2.746943 0.636121 2.
↪520374 3.280594
p 2 100001001000 2 3 2.120032 3.026543 3.191847 0.226976 3.530282 1.788605 2.980323 3.
↪379190 2.619068
p 2 100001001000 0 3 4.355116 3.219292 4.362386 4.516341 3.181239 4.363903 4.653955 2.
↪345981 3.852559

```

Description of s2v.area

each line contains: triangle id | z layer | triangle area

```
[14]: outfile = os.path.join(os.path.dirname(os.path.abspath("")), "s2v", "s2v.area")
with open(outfile, "r") as fichier:
    for ligne in fichier:
        print(ligne, end="")
```

```
100001001000      2      0.615819
100001001000      2      1.39918
100001001000      2      0.739072
100001001000      2      1.27531
100001001000      0      0.0774794
```

Description of out.dang

File for SAIL model - line 1: global leaf area index for specy 1 - line 2: global zenith angle distribution for specy 1

```
[15]: outfile = os.path.join(os.path.dirname(os.path.abspath("")), "s2v", "out.dang")
with open(outfile, "r") as fichier:
    for ligne in fichier:
        print(ligne, end="")
```

```
0.273790
0.000000 0.340694 0.000000 0.168815 0.000000 0.000000 0.310531 0.000000 0.179961
```

Description of leafarea

File for SAIL model each line: - 0 idz “Leaf area index by layer inclination class” 0 0 “total leaf area density on the z layer”

```
[16]: outfile = os.path.join(os.path.dirname(os.path.abspath("")), "s2v", "leafarea")
with open(outfile, "r") as fichier:
    for ligne in fichier:
        print(ligne, end="")
```

```
0 1 0.000000 0.000000 0.000000 0.353762 0.000000 0.000000 0.267263 0.000000 0.378975
↪ 0 0.219015
0 2 0.000000 0.000000 0.000000 0.167022 0.000000 0.000000 0.533621 0.000000 0.299357
↪ 0 0.2189191
0 3 0.000000 0.823702 0.000000 0.147280 0.000000 0.000000 0.028594 0.000000 0.000425
↪ 0 0.1698650
0 4 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000
↪ 0 0.000000
```

2.6.8 More examples

```
[1]: import openalea.plantgl.all as pgl_all
      from lightvegemanager.LVM import LightVegeManager
      from pgljupyter import SceneWidget
```

Sun positions

The `print_sun` function allows you to compare the sun position differences between RATP and CARIBU internal computation.

```
[38]: from lightvegemanager.sun import print_sun
```

```
print(print_sun.__doc__)
```

Prints sun position outputs from RATP and CARIBU algorithm with the same inputs

```
:param day: input day
:type day: int
:param hour: input hour
:type hour: int
:param coordinates: [latitude, longitude, timezone]
:type coordinates: list
:param truesolartime: activates true solar time or local time to compute sun position
:type truesolartime: bool
```

```
[11]: print_sun(201, 12, [0.0, 0.0, 0.0], True)
      print_sun(201, 12, [40.0, 0.0, 0.0], True)
      print_sun(201, 16, [40.0, 12.0, 2.0], True)
      print_sun(201, 16, [40.0, 12.0, 2.0], False)
      print_sun(347, 16, [46.0, 0.0, 0.0], True)
```

```
---      SUN COORDONATES      ---
--- Convention x+ = North, vector from sky to floor
--- azimuth: south clockwise E = -90° W = 90°      zenith:
↪zenith = 0° horizon = 90°
--- day: 201      hour: 12      latitude: 0.00 °
--- true solar time
--- RATP ---
      azimuth: 180.000      zenith: 69.227
      x: -0.354671      y: -0.000000      z: -0.934991
--- CARIBU ---
      azimuth: 180.000      zenith: 68.944
      x: -0.359285      y: -0.000000      z: -0.933228

---      SUN COORDONATES      ---
--- Convention x+ = North, vector from sky to floor
--- azimuth: south clockwise E = -90° W = 90°      zenith:
↪zenith = 0° horizon = 90°
--- day: 201      hour: 12      latitude: 40.00 °
--- true solar time
```

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```

--- RATP ---
      azimuth: 0.000    zenith: 70.773
      x: 0.329307      y: -0.000000      z: -0.944223
--- CARIBU ---
      azimuth: 0.000    zenith: 71.148
      x: 0.323132      y: -0.000000      z: -0.946354

---      SUN COORDONATES      ---
--- Convention x+ = North, vector from sky to floor
--- azimuth: south clockwise E = -90° W = 90°      zenith:
↪zenith = 0° horizon = 90°
--- day: 201      hour: 16      latitude: 40.00 °
--- true solar time
--- RATP ---
      azimuth: 87.963      zenith: 35.881
      x: 0.028807      y: -0.809726      z: -0.586100
--- CARIBU ---
      azimuth: 88.295      zenith: 36.115
      x: 0.024030      y: -0.807482      z: -0.589402

---      SUN COORDONATES      ---
--- Convention x+ = North, vector from sky to floor
--- azimuth: south clockwise E = -90° W = 90°      zenith:
↪zenith = 0° horizon = 90°
--- day: 201      hour: 16      latitude: 40.00 °
--- local time, true solar time is 18.70
--- RATP ---
      azimuth: 112.480      zenith: 5.641
      x: -0.380514      y: -0.919537      z: -0.098291
--- CARIBU ---
      azimuth: 112.736      zenith: 5.895
      x: -0.384436      y: -0.917420      z: -0.102706

---      SUN COORDONATES      ---
--- Convention x+ = North, vector from sky to floor
--- azimuth: south clockwise E = -90° W = 90°      zenith:
↪zenith = 0° horizon = 90°
--- day: 347      hour: 16      latitude: 46.00 °
--- true solar time
--- RATP ---
      azimuth: 52.853      zenith: 2.129
      x: 0.603439      y: -0.796543      z: -0.037150
--- CARIBU ---
      azimuth: 53.169      zenith: 2.592
      x: 0.598849      y: -0.799584      z: -0.045228

```

Two planes

A small example with two horizontal planes, in order to check if the xy orientation according to North-East-South-West.

```
[2]: geom1 = pgl_all.FaceSet([(0,0,0),(2,0,0), (2,2,0),(0,2,0)], [range(4)]) # plaque dessous
geom2 = pgl_all.FaceSet([(0,1,1),(2,1,1), (2,3,1),(0,3,1)], [range(4)]) # plaque dessus,
↳ décalée en y (axe est-ouest) vers l'ouest
s = pgl_all.Scene([pgl_all.Shape(geom1, pgl_all.Material((250,0,0),1), 888),
                  pgl_all.Shape(geom2, pgl_all.Material((0,250,0),1), 999)])
```

```
[3]: # input dict
geometry = {}
environment = {}
caribu_parameters = {}

# Paramètres pré-simulation
geometry["scenes"] = [s]

environment["coordinates"] = [0. ,0. ,0.] # latitude, longitude, timezone
environment["direct"] = True
environment["diffus"] = False
environment["reflected"] = False
environment["caribu opt"] = {}
environment["caribu opt"]["par"] = (0.10, ) # plaques opaques
environment["infinite"] = False

## Paramètres CARIBU ##
caribu_parameters["sun algo"] = "caribu"
caribu_parameters["caribu opt"] = {}
caribu_parameters["caribu opt"]["par"] = (0.10, ) # plaques opaques

# Déclaration de l'objet
lghtcaribu = LightVegeManager(environment=environment,
                              lightmodel="caribu",
                              lightmodel_parameters=caribu_parameters)

# création de la scène dans l'objet
lghtcaribu.build(geometry, global_scene_tessellate_level=5)
```

```
[39]: # forçage arbitraire en  $\mu\text{mol.m}^{-2}.\text{s}^{-1}$ 
PARi = 500
# jour arbitraire (21 septembre)
day = 264

# heure matin, soleil arrive de l'est, les 2 plaques reçoivent tout le rayonnement
hour = 16
print("--- day %i, hour %i"%(day, hour))

# Calcul du rayonnement
lghtcaribu.run(energy=PARi, day=day, hour=hour, parunit="micromol.m-2.s-1",
↳ truesolartime=True)

--- day 264, hour 16
```

```
[10]: # visualisation
SceneWidget(lghtcaribu.plantGL_light(),
            position=(0.0, 0.0, 0.0),
            size_display=(600, 400),
            plane=False,
            size_world = 10,
            axes_helper=True)

[10]: SceneWidget(axes_helper=True, plane=False, scenes=[{'id': 'PidZp3tokVAgJYlb04DHRXebB',
→ 'data': b'x\xda\x9c\xbd...
```

Examples with RATP and stem elements

Stems processing checking

Scene for verification is a set of horizontal planes in one voxel as so:

We compare the PAR mean on all the planes between CARIBU and RATP

Stems processing

* CARIBU

Computing of incident PAR is done with no transmittance, triangles are opaques

* RATP

triangles area are divided by 2

```
[34]: geom1 = pgl_all.FaceSet([(0.1,0.1,0.96),(0.1,0.6,0.96), (0.6,0.6,0.96),(0.6,0.1,0.96)],
    → [range(4)])
geom2 = pgl_all.FaceSet([(0.1,0.5,0.806),(0.1,0.9,0.806), (0.6,0.9,0.806),(0.6,0.5,0.
    → 806)], [range(4)])
geom3 = pgl_all.FaceSet([(0.5,0.1,0.646),(0.5,0.7,0.646), (0.9,0.7,0.646),(0.9,0.1,0.
    → 646)], [range(4)])
geom4 = pgl_all.FaceSet([(0.3,0.5,0.486),(0.3,0.9,0.486), (0.8,0.9,0.486),(0.8,0.5,0.
    → 486)], [range(4)])
geom5 = pgl_all.FaceSet([(0.3,0.1,0.32),(0.3,0.5,0.32), (0.8,0.5,0.32),(0.8,0.1,0.32)],
    → [range(4)])
geom6 = pgl_all.FaceSet([(0.2,0.4,0.16),(0.2,0.9,0.16), (0.6,0.9,0.16),(0.6,0.4,0.16)],
    → [range(4)])
s = pgl_all.Scene([pgl_all.Shape(geom1, pgl_all.Material((250,0,0),1), 888),
    pgl_all.Shape(geom2, pgl_all.Material((250,0,0),1), 888),
    pgl_all.Shape(geom3, pgl_all.Material((250,0,0),1), 888),
    pgl_all.Shape(geom4, pgl_all.Material((250,0,0),1), 888),
    pgl_all.Shape(geom5, pgl_all.Material((250,0,0),1), 888),
    pgl_all.Shape(geom6, pgl_all.Material((250,0,0),1), 888)])
```

```
[35]: geometry = {}
environment = {}
ratp_parameters = {}
caribu_parameters = {}

# Paramètres pré-simulation
geometry["scenes"] = [s]
geometry["stems id"] = [(888, 0)]

environment["coordinates"] = [0., 0., 0.] # latitude, longitude, timezone
environment["sky"] = "turtle46" # turtle à 46 directions par défaut
environment["diffus"] = False
environment["direct"] = True
environment["reflected"] = False
environment["infinite"] = False

## Paramètres CARIBU ##
caribu_parameters["sun algo"] = "caribu"
caribu_parameters["caribu opt"] = {}
caribu_parameters["caribu opt"]["par"] = (0.10, 0.05)
lghtcaribu = LightVegeManager(environment=environment,
                              lightmodel="caribu",
                              lightmodel_parameters=caribu_parameters)

lghtcaribu.build(geometry)
```

```
[36]: ## Paramètres RATP ##
dv = 1. # m
dx, dy, dz = dv, dv, dv # m
ratp_parameters["voxel size"] = [dx, dy, dz]
ratp_parameters["soil reflectance"] = [0., 0.]
ratp_parameters["mu"] = [1.]
ratp_parameters["tessellation level"] = 0
ratp_parameters["angle distrib algo"] = "compute global"
ratp_parameters["nb angle classes"] = 30
ratp_parameters["reflectance coefficients"] = [[0.1, 0.05]]
lghttratp = LightVegeManager(environment=environment,
                              lightmodel="ratp",
                              lightmodel_parameters=ratp_parameters)

lghttratp.build(geometry)
```

```
[28]: # visualisation
SceneWidget(lghtratp.plantGL_nolight(printvoxels=True),
            position=(0.0, 0.0, 0.0),
            size_display=(600, 400),
            plane=False,
            size_world = 2,
            axes_helper=True)
```

```
[28]: SceneWidget(axes_helper=True, plane=False, scenes=[{'id': '31qAWA8Lxo9Ajw1YbU2IJwjFk',
↪ 'data': b'x\xda\x85\x95...
```

```
[29]: PARi=500
```

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```
day=100.
hour=12
```

```
[ ]: PARI=500
     day=100.
     hour=17.5
```

```
[31]: lghtcaribu.run(energy=PARI, day=day, hour=hour, parunit="micromol.m-2.s-1",
    ↪ truesolartime=True)
print("=== CARIBU ===")
print(lghtcaribu.elements_outputs)
# visualisation
SceneWidget(lghtcaribu.plantGL_light(),
             position=(0.0, 0.0, 0.0),
             size_display=(600, 400),
             plane=False,
             size_world = 2,
             axes_helper=True)
```

```
=== CARIBU ===
   Day Hour Organ VegetationType Area   par Eabs   par Ei
0  100.0  12   888                0  1.29  226.615845  251.795383
```

```
[31]: SceneWidget(axes_helper=True, plane=False, scenes=[{'id': 'euPE10Vd7GkTxzNRtZPTE36Dx',
    ↪ 'data': b'x\xda\x85\xd5...
```

```
[33]: lghtratp.run(energy=PARI, day=day, hour=hour, parunit="micromol.m-2.s-1",
    ↪ truesolartime=True)
print("=== RATP ===")
print(lghtratp.elements_outputs)
# visualisation
SceneWidget(lghtratp.plantGL_light(printvoxels=True),
             position=(0.0, 0.0, 0.0),
             size_display=(600, 400),
             plane=False,
             size_world = 2,
             axes_helper=True)
```

```
=== RATP ===
   Day Hour Organ VegetationType Area   PARa Intercepted \
0  100.0 12.0   888                2  1.29  377.546967   0.487036

   Transmitted   SunlitPAR   SunlitArea   ShadedPAR   ShadedArea
0     0.487036  499.828644    0.487203         0.0     0.157797
```

```
[33]: SceneWidget(axes_helper=True, plane=False, scenes=[{'id': 'GNw9osvivwBapMiJRL2W1wlXa',
    ↪ 'data': b'x\xda\x85\xd6...
```


2.7 Reference Guide

This manual details, for each module of *lightvegemanager*, the functions and objects included in *lightvegemanager*, describing what they are and what they do.

Contents

- *Reference Guide*
 - *LVM module*
 - * *LightVegeManager*
 - *CARIBUinputs module*
 - * *CARIBUinputs*
 - *RATPinputs module*
 - * *RATPinputs*
 - *VTK module*
 - * *VTK*
 - *basicgeometry module*
 - * *basicgeometry*
 - *buildRATPscene module*
 - * *buildRATPscene*
 - *defaultvalues module*
 - * *defaultvalues*
 - *leafangles module*
 - * *leafangles*
 - *outputs module*
 - * *outputs*
 - *plantGL module*
 - * *plantGL*
 - *sky module*
 - * *sky*
 - *stems module*
 - * *stems*
 - *sun module*
 - * *sun*
 - *tesselator module*
 - * *tesselator*
 - *transfer module*

```

    * transfer
- trianglesmesh module
    * trianglesmesh
- voxelsmesh module
    * voxelsmesh

```

2.7.1 LVM module

LightVegeManager

Main class of the tool. Calls all the other modules in src.

3 inputs dict for setting all parameters:

```

geometry = {
    "scenes" : [scene0, scene1, scene2, ...] ,
    "domain" : ((xmin, ymin), (xmax, ymax)),
    "stems id" : [(id_element, id_scene), ...],
    "transformations" : {
        "scenes unit" : kwarg ,
        "rescale" : kwarg ,
        "translate" : kwarg ,
        "xyz orientation" : kwarg
    }
}

```

```

environment = {
    "coordinates" : [latitude, longitude, timezone] ,

    "sky" : "turtle46" ,
    "sky" : ["file", filepath] ,
    "sky" : [nb_azimut, nb_zenith, "soc" or "uoc"] ,

    "direct" : bool, # sun radiations
    "diffus" : bool, # sky radiations
    "reflected" : bool, # reflected radiation in the canopy
    "infinite" : bool, # infinitisation of the scene
}

```

Currently LightVegeManager handles the light models RATP and CARIBU:

```

caribu_args = {
    "sun algo" : "ratp",
    "sun algo" : "caribu",

    "caribu opt" : {
        band0 = (reflectance, transmittance),
        band1 = (reflectance, transmittance),
        ...
    },
}

```

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```

        "debug" : bool,
        "soil mesh" : bool,
        "sensors" : ["grid", dxyz, nxyz, orig, vtkpath, "vtk"]
    }

```

```

ratp_args = {
    # Grid specifications
    "voxel size" : [dx, dy, dz],
    "voxel size" : "dynamic",

    "origin" : [xorigin, yorigin, zorigin],
    "origin" : [xorigin, yorigin],

    "number voxels" : [nx, ny, nz],
    "grid slicing" : "ground = 0."
    "tessellation level" : int

    # Leaf angle distribution
    "angle distrib algo" : "compute global",
    "angle distrib algo" : "compute voxel",
    "angle distrib algo" : "file",

    "nb angle classes" : int,
    "angle distrib file" : filepath,

    # Vegetation type
    "soil reflectance" : [reflectance_band0, reflectance_band1, ...],
    "reflectance coefficients" : [reflectance_band0, reflectance_band1, ...],
    "mu" : [mu_scene0, mu_scenel, ...]
}

```

See also:

For more details *Inputs description*

class LVM.**LightVegeManager**(environment={}, lightmodel="", lightmodel_parameters={}, main_unit='m')

Bases: object

Main class for the tool LightVegeManager

Common simulation order:

input geometries -> build and prepare data -> call light model -> transfer results to plant models

It includes:

Main methods:

- `__init__`: initializes and builds static object for the rest of simulation
- `build()`: builds and prepare all geometric meshes
- `run()`: calls a light model and manages its inputs and outputs

Transfer methods:

- `to_MTG()`: transfers lighting results to a MTG table

- `to_l_egume()`: transfers lighting results to l-egume by creating two arrays as inputs for the plant model

Analysis tools: analyses a set of triangles and formats them as a turbid medium inputs

- `s5()`: fortran tool
- `s2v()`: c++ tool

Visualisation tools:

- `plantGL_nolight()`: return a plantGL scene from the geometry
- `plantGL_light()`: return a plantGL scene from the geometry with lighting results
- `plantGL_sensors()`: return a plantGL scene from virtual sensors if created
- `VTK_nolight()`: write VTK file with only geometric informations
- `VTK_light()`: write VTK file with geometric informations and associated light results
- `VTK_sun()`: write VTK file representing the sun as a line

Getters: to use light results with external routines

- `riri5_transmitted_light()`
- `riri5_intercepted_light()`
- `elements_outputs()`
- `triangles_outputs()`
- `voxels_outputs()`
- `sensors_outputs()`
- `sun()`
- `soilenergy()`
- `maxtrianglearea()`
- `legume_empty_layers()`
- `tesselationtime()`
- `modelruntime()`
- `leafangledistribution()`

Parameters

- **environment** (*dict*, *optional*) – Environment parameters, defaults to {}
- **lightmodel** (*str*, *optional*) – either "ratp" or "caribu", defaults to ""
- **lightmodel_parameters** (*dict*, *optional*) – light model parameters, defaults to {}
- **main_unit** (*str*, *optional*) – measure unit for the global scene where the light will be computed, defaults to "m"

Raises

ValueError – lightmodel entry not valid, either 'ratp' or 'caribu'

build(*geometry={}*, *global_scene_tessellate_level=0*)

Builds a mesh of the simulation scene in the right light model format

Parameters

- **geometry** (*dict*, *optional*) – geometric parameters, contains geometric scenes, defaults to {}
- **global_scene_tessellate_level** (*int*, *optional*) – option to subdivide all triangles of the mesh a certain number of times (to fine tuning the mesh), defaults to 0

Raises

ValueError – Currently, converting voxels mesh to triangles mesh is not possible

run(*energy=0.0*, *day=0*, *hour=0*, *parunit='micromol.m-2.s-1'*, *true солartime=False*, *id_sensors=None*)

Calls the light model and formats lighting results

Parameters

- **energy** (*float*, *optional*) – input radiation energy, defaults to 0
- **day** (*int*, *optional*) – simulation day, defaults to 0
- **hour** (*int*, *optional*) – simulation hour, defaults to 0
- **parunit** (*str*, *optional*) – input energy unit, light models manages radiations in different unit, you can precise input unit and LightVegeManager will convert it in the right unit, defaults to “micromol.m-2.s-1”
- **true солartime** (*bool*, *optional*) – simulation hour is a true solar time or local time (depending on simulation coordinates), defaults to False
- **id_sensors** (*list*, *optional*) – if you use CARIBU with a grid of virtual sensors, you have to precise which input scenes the grid must match, defaults to None

Raises

- **ValueError** – with CARIBU you can precise the sun algorithm to calculate sun position, can be either "caribu" or "ratp"
- **ValueError** – valid radiations are "direct", "diffuse", "reflected"

to_MTG(*energy=1.0*, *mtg=None*, *id=None*)

Transfers lighting results to a MTG table.

Warning: The *run()* must have been called before to have results dataframes.

Results are `pandas.DataFrame` stored in the `self`

Parameters

- **energy** (*float*, *optional*) – input energy, defaults to 1
- **mtg** (*MTG*, *optional*) – MTG table with "PARa" and "Erel" entries in its properties, defaults to None
- **id** (*list or tuple*, *optional*) – you can precise to which input scenes the MTG table corresponds, defaults to None

Raises

AttributeError – you need to call `:func:run` first

to_l_egume(*energy=1.0, m_lais=[], list_lstring=[], list_dicFeuilBilanR=[], list_invar=[], id=None*)

Transfers lighting results to l-egume

Warning: The `run()` must have been called before to have results dataframes.

Warning: l-egume needs transmitted energy informations located in a grid of voxels. You need to have the same dimensions in the lighting results.

- With RATP, RATP grid must have the same dimensions as l-egume intern grid.
- With CARIBU, you must create a grid of virtual sensors in the same dimensions as l-egume intern grid.

Results are `pandas.DataFrame` stored in the `self`

Parameters

- **energy** (*float, optional*) – input energy, defaults to 1
- **m_lais** (*numpy.array, optional*) – leaf area represented in a `numpy.array` of dimension [number of species, number of z layers, number of y layers, number of x layers], defaults to []
- **list_lstring** (*list of dict, optional*) – from l-egume, each element corresponds to an input specy of l-egume. Each element is a dict lstring stores the l-system of each plant, defaults to []
- **list_dicFeuilBilanR** (*list of dict, optional*) – from l-egume, each element corresponds to an input specy of l-egume. Each element is a dict dicFeuiBilanR stores correspondances between voxels grid and each plant, defaults to []
- **list_invar** (*list of dict, optional*) – from l-egume, each element corresponds to an input specy of l-egume. Each element is a dict invar stores instant intern variables of l-egume., defaults to []
- **id** (*list, optional*) – list of indices from input scenes which corresponds to current l-egume instance. If you have several plantmodel among the input scenes, you need to precise which results you want to transfer to which instance of l-egume. defaults to None

Raises

- **AttributeError** – you need to call `run()` first
- **ValueError** – unknown light model

Returns

if light model is RATP `transfer_ratp_legume()` :

- **res_abs_i**: absorbed energy in each voxels of a grid matching the dimensions of l-egume intern grid of voxels. One value for each specy.
- **res_trans**: transmitted energy in each voxels of a grid matching the dimensions of l-egume intern grid of voxels

if light model is CARIBU :`func:transfer_caribu_legume` :

- update of `list_invar`: updates the keys "parap" and "parip" for each specy. Cumulative energy per plant

- `res_trans`: transmitted energy in each voxels of a grid matching the dimensions of l-egume intern grid of voxels

Return type

numpy.array

s5()

Creates inputs files for s5 and runs it s5 is an external tool made to analyse a set of triangles in order to use a grid of voxels. It also computes leaf angle distribution from the triangulation

Note: All files are located in s5 folder

Input files created

- `fort.51`: contains triangulation. Possibility to precise stem elements it is registered in the instance of LightVegeManager
- `s5.par`: stores grid of voxels informations and number of entities

Output files created

- `fort.60`
 - dimensions xy of the grid
 - stats by specy
 - total leaf area
 - leaf area index
 - global zenital leaf angle distribution
 - global azimuthal leaf angle distribution
 - stats by voxels
 - `#specy | #ix | #iy | #iz` (coordinate xyz of the voxel) | eaf area density
 - local zenital leaf angle distribution
 - local azimuthal leaf angle distribution
- `leafarea`: for each specy, for each voxel
 - `ix | iy | iz | #specy | LAD | zenital-distribution | azimuthal-distribution`

example

```
>>> myscene # a plantgl Scene
>>> testofs5 = LightVegeManager() # create a instance
>>> testofs5.build( geometry={ "scenes" : [myscene] } ) # build the geometry
>>> testofs5.s5() # run of s5, creates input and output files
```

s2v()

Creates inputs files for s2v and runs it s5 is an external tool made to analyse a set of triangles in order to use a grid of voxels. It also computes leaf angle distribution from the triangulation

Note: All files are located in s2v folder

Input files created

- `fort.51`: stores triangulation. Possibility to precise stem elements it is registered in the instance of `LightVegeManager`
- `s2v.par`: stores grid of voxels informations and number of entities

Output files created

- `s2v.log`
 - logs about processing
 - global statistics
 - total leaf area per specy
 - total leaf area
 - leaf area index
 - global zenital leaf angle distribution
- `s2v.can`
 - z layer where each triangle is located (and copy its vertices)
- `s2v.area`
 - triangle id | z layer | triangle area
- `out.dang`: SAIL file
 - line 1: global leaf area index for specy 1 line 2: global zenital leaf angle distribution for specy 1
- `leafarea`: SAIL file
 - each line: 0 | idz | leaf area index for each slope class in current z layer | 0 | 0 | leaf area density on the layer

example

```
>>> myscene # a plantgl Scene
>>> testofs2v = LightVegeManager() # create a instance
>>> testofs2v.build( geometry={ "scenes" : [myscene] } ) # build the geometry
>>> testofs2v.s2v() # run of s2v, creates input and output files
```

VTK_nolight(*path*, *i=None*, *printriangles=True*, *printvoxels=True*)

Writes a VTK from mesh(es) in `self`, with only geometric informations

Parameters

- **path** (*string*) – file and path name
- **i** (*int*, *optional*) – associate the created file with an indice in its filename, defaults to `None`
- **printriangles** (*bool*, *optional*) – write triangulation if one has been created in `:func:build`, defaults to `True`
- **printvoxels** (*bool*, *optional*) – write grid of voxels if one has been created in `:func:build`, defaults to `True`

VTK_light(*path*, *i=None*, *printriangles=True*, *printvoxels=True*)

Writes a VTK from mesh(es) in `self`, with geometric informations and lighting results

Warning: The `run()` must have been called before to have results dataframes.

Parameters

- **path** (*string*) – file and path name
- **i** (*int*, *optional*) – associate the created file with an indice in its filename, defaults to None
- **printtriangles** (*bool*, *optional*) – write triangulation if one has been created in `build()`, defaults to True
- **printvoxels** (*bool*, *optional*) – write grid of voxels if one has been created in `build()`, defaults to True

Raises

AttributeError – you need to call `run()` first

VTK_sun(*path*, *scale*=2, *orig*=(0, 0, 0), *center*=True, *i*=None)

Write a VTK file representing the sun by a simple line

Warning: The `run()` must have been called before to have results dataframes.

if `center` is False, `orig` is the starting point the line and it ends at `orig + scale*sun.position`

if `center` is True, `orig` is the middle point of the line.

Parameters

- **path** (*string*) – file and path name
- **scale** (*int*, *optional*) – size of the line, defaults to 2
- **orig** (*tuple*, *optional*) – starting or middle point of the line, defaults to (0,0,0)
- **center** (*bool*, *optional*) – if True `orig` is the middle of the line, otherwise it is the starting point, defaults to True
- **i** (*int*, *optional*) – associate the created file with an indice in its filename, defaults to None

Raises

AttributeError – you need to call `run()` first

plantGL_sensors(*light*=False)

plantGL_nolight(*printtriangles*=True, *printvoxels*=False)

Return a plantGL Scene from mesh(es) in `self`, with geometric informations

Parameters

- **printtriangles** (*bool*, *optional*) – write triangulation if one has been created in `build()`, defaults to True
- **printvoxels** (*bool*, *optional*) – write grid of voxels if one has been created in `build()`, defaults to True

plantGL_light(*printtriangles=True, printvoxels=False*)

Return a plantGL Scene from mesh(es) in **self**, with geometric informations and lighting results

Warning: The *run()* must have been called before to have results dataframes.

Parameters

- **printtriangles** (*bool, optional*) – write triangulation if one has been created in *build()*, defaults to True
- **printvoxels** (*bool, optional*) – write grid of voxels if one has been created in *build()*, defaults to True

Raises

AttributeError – you need to call *run()* first

property riri5_transmitted_light

transmitted results if light model is RiRi light

Returns

transmitted energy following a grid of voxels

Return type

numpy.array

property riri5_intercepted_light

Intercepted results if light model is RiRi light,

Returns

intercepted energy following a grid of voxels, for each specy

Return type

numpy.array

property elements_outputs

Lighting results aggregate by element

Returns

Column names can change depending on the light model. Commonly, there is element indice, its area and intercepted energy

Return type

pandas.DataFrame

property triangles_outputs

Lighting results aggregate by triangle, if it has a triangulation in its inputs

Returns

See also:

outputs for column names

Return type

pandas.DataFrame

property voxels_outputs

Lighting results aggregate by voxels, only with RATP as the selected light model

Returns**See also:**

outputs for column names

Return type

pandas.DataFrame

property sensors_outputs

Lighting results aggregate by sensors. Only with CARIBU if you activated the virtual sensors option

Returns

The output format is the same as CARIBU output format. Dict with Eabs key for absorbed energy and Ei for incoming energy

Return type

dict

property sun

Return sun position of the last :func:run call

Returns

vector (x, y, z)

Return type

tuple

property soilenergy

Return soil energy, only with CARIBU if soilmesh option is activated

Returns

The output format is the same as CARIBU output format. Dict with Eabs key for absorbed energy and Ei for incoming energy

Return type

dict

property maxtrianglearea

Returns the largest triangle of triangles mesh Computed in *build()*

Returns

area the triangle

Return type

float

property legume_empty_layers

Returns number of empty layers between top of the canopy and number of z layers expected by l-egume

Returns

result of *fill_ratpgrid_from_legumescene()*

Return type

int

property tessellationtime

summary

Returns

description

Return type`_type_`**property modelruntime**

Returns running time of the light model

Returns

time in s

Return type

float

property leafangledistribution**property domain**Returns the largest triangle of triangles mesh Computed in *build()***Returns**

area the triangle

Return type

float

2.7.2 CARIBUinputs module

CARIBUinputs

Manages and prepares input information for CARIBU.

In this module we use two of the LightVegeManager's inputs dict.

- parameters corresponding to CARIBU parameters and contains

```
caribu_args = {
    "sun algo" : "ratp",
    "sun algo" : "caribu",

    "caribu opt" : {
        band0 = (reflectance, transmittance),
        band1 = (reflectance, transmittance),
        ...
    },
    "debug" : bool,
    "soil mesh" : bool,
    "sensors" : ["grid", dxyz, nxyz, orig, vtkpath, "vtk"]
}
```

- geometry corresponding to the geometric information with the scenes inputs

```
geometry = {
    "scenes" : [scene0, scene1, scene2, ...] ,
    "domain" : ((xmin, ymin), (xmax, ymax)),
    "stems id" : [(id_element, id_scene), ...],
    "transformations" : {
        "scenes unit" : kwarg ,
        "rescale" : kwarg ,
    }
}
```

(continues on next page)

(continued from previous page)

```

        "translate" : kwarg ,
        "xyz orientation" : kwarg
    }
}

```

See also:

For more details *Inputs description*

CARIBUinputs.**Prepare_CARIBU**(*trimesh, geometry, matching_ids, minmax, parameters, infinite, idsensors*)

Format optical parameters and prepare virtual sensors and debug if activated

Parameters

- **trimesh** (*dict*) – triangles mesh aggregated by indice elements

```
{ id : [triangle1, triangle2, ...]}
```

- **geometry** (*dict*) – geometric parameters from inputs of LightVegeManager
- **matching_ids** (*dict*) – dict that matches new element indices in trimesh with specy indice and input element indice,

```
matching_ids = { new_element_id : (input_element_id, specy_id)}
```

- **minmax** (*[3-tuple, 3-tuple]*) – list of minimum point and maximum point in a triangles mesh
- **parameters** (*dict*) – RATP parameters from inputs of LightVegeManager
- **infinite** (*bool*) – if the user wishes to activate infinitisation of the grid
- **idsensors** (*list of int*) – Sets which input scenes the grid of virtual sensors will match. Elements of this list refers to indices in the list `geometry["scenes"]`. If no input indices are given, the grid will match the global scene `trimesh`. Otherwise, you can match the grid to a specific set of input scenes

Returns

- **opt:** optical parameters formatted for CARIBU. It takes the form of dict, where each key is a bandlength (PAR, NIR etc...) and values are transmittance and reflectance (or only reflectance for stems elements)
- **sensors_caribu:** geometric data of the virtual sensors in CARIBU scene format.

Sensors
are horizontal square made of two triangles

```
sensors_caribu = { sensor_id : [triangle1, triangle2], ...}
```

- **debug:** boolean if user wants to activate the debug option in CARIBU

Return type

dict, dict, bool

CARIBUinputs.**CARIBU_opticals**(*matching_ids, parameters, stems_id=None*)

Sets optical parameters for CARIBU from LightVegeManager inputs. It removes transmittance for stems elements if precised

Parameters

- **matching_ids** (*dict*) – dict that matches new element indices in trimesh with specy indice and input element indice, `matching_ids = { new_element_id : (input_element_id, specy_id)}`
- **parameters** (*dict*) – RATP parameters from inputs of LightVegeManager
- **stems_id** (*list of 2-tuple, optional*) – list of potential stems element in the input scenes, defaults to None

Returns

optical parameters formatted for CARIBU. It takes the form of dict, where each key is a bandlength (PAR, NIR etc...) and values are transmittance and reflectance (or only reflectance for stems elements)

Return type

dict

`CARIBUinputs.create_caribu_legume_sensors(dxzy, nxyz, orig, pmax, trimesh, matching_ids, id_sensors, infinite)`

Creates a set of virtual sensors following a voxels grid each sensor is a square made by two triangles and takes place on the bottom face of a voxel The grid follow the xyz axis (and so the voxels)

Parameters

- **dxzy** (*list*) – [dx, dy, dz] size of a voxel in each direction
- **nxyz** (*list*) – [nx, ny, nz] number of voxels on each axis
- **orig** (*list (or tuple)*) – [x_origin, y_origin, z_origin], origin of the grid, cartesian coordinates
- **pmax** (*list (or tuple)*) – [x, y, z] maximum point of trimesh in the xyz space
- **trimesh** (*dict*) – triangles mesh aggregated by indice elements

```
{ id : [triangle1, triangle2, ...]}
```

- **matching_ids** (*dict*) – dict that matches new element indices in trimesh with specy indice and input element indice, `matching_ids = { new_element_id : (input_element_id, specy_id)}`
- **idsensors** (*list of int*) – Sets which input scenes the grid of virtual sensors will match. Elements of this list refers to indices in the list `geometry["scenes"]`. If no input indices are given, the grid will match the global scene `trimesh`. Otherwise, you can match the grid to a specific set of input scenes
- **infinite** (*bool*) – if the user wishes to activate infinitisation of the grid

Returns

it returns 3 objects:

- **sensors_caribu**, geometric data of the virtual sensors in CARIBU scene format.

Sensors

are horizontal square made of two triangles `sensors_caribu = { sensor_id : [triangle1, triangle2], ...}`

- **s_capt**, PlantGL scene of the virtual sensors
- **sensors_maxcenter**, [x, y, z] representing point on the highest sensors layer and middle of xy plane in the grid

Return type

dict, PlantGL scene, list

CARIBUinputs.**run_caribu**(*c_scene*, *direct_active*, *infinite*, *sensors*, *energy=1.0*)

runs caribu depending on input options

Parameters

- **c_scene** (*CaribuScene*) – instance of CaribuScene containing geometry, light source(s), opt etc...
- **direct_active** (*bool*) – Whether only first order interception is to be computed, default is True (no rediffusions)
- **infinite** (*bool*) – if the user wishes to activate infinitisation of the grid
- **sensors** (*dict*) – geometric data of the virtual sensors in CARIBU scene format. Sensors are horizontal square made of two triangles

```
sensors_caribu = { sensor_id : [triangle1, triangle2], ...}
```

- **energy** (*float*, *optional default is 1.*) – input energy value

Returns

results are stored in two dict

- **raw (dict of dict) a {band_name: {result_name: property}} dict of dict.**
Except for result_name='sensors', each property is a {primitive_id: [values,]} dict containing results for individual triangles of the primitive
- **aggregated (dict of dict)**
[a {band_name: {result_name: property}}] Except for result_name='sensors', each property is a {primitive_id: value} dict containing aggregated results for each primitive

result_name are :

- **area** (*float*): the individual areas (m2)
- **Eabs** (*float*): the surfacic density of energy absorbed (m-2)
- **Ei** (*float*): the surfacic density of energy incoming (m-2) additionally, if split_face is True
- **Ei_inf** (*float*): the surfacic density of energy incoming on the inferior face (m-2)
- **Ei_sup** (*float*): the surfacic density of energy incoming on the superior face (m-2)
- **sensors** (*dict of dict*): area, surfacic density of incoming direct energy and surfacic density of incoming total energy of sensors grouped by id, if any

Return type

dict of dict, dict of dict

2.7.3 RATPinputs module

RATPinputs

Manage vegetation and meteo input informations for RATP

The argument *parameters* refers to one the three inputs dict of LightVegeManager. It is structured as so:

```
ratp_args = {
    # Grid specifications
    "voxel size" : [dx, dy, dz],
    "voxel size" : "dynamic",

    "origin" : [xorigin, yorigin, zorigin],
    "origin" : [xorigin, yorigin],

    "number voxels" : [nx, ny, nz],
    "grid slicing" : "ground = 0.",
    "tessellation level" : int,

    "full grid" : bool,

    # Leaf angle distribution
    "angle distrib algo" : "compute global",
    "angle distrib algo" : "compute voxel",
    "angle distrib algo" : "file",

    "nb angle classes" : int,
    "angle distrib file" : filepath,

    # Vegetation type
    "soil reflectance" : [reflectance_band0, reflectance_band1, ...],
    "reflectance coefficients" : [reflectance_band0, reflectance_band1, ...],
    "mu" : [mu_scene0, mu_scene1, ...]
}
```

See also:

Inputs description

`RATPinputs.RATP_vegetation(parameters, angle_distrib, reflected)`

Initialise a RATP Vegetation object from LightVegeManager input datas

Parameters

- **parameters** (*dict*) – RATP parameters from inputs of LightVegeManager
- **angle_distrib** (*dict*) – leaf angle distribution
- **reflected** (*bool*) – if the user wishes to activate reflected radiations

Returns

Vegetation types contains clumoing effect ratio, leaf angle distribution and reflectance/transmittance of leaves for each specy

Return type

PyRATP.pyratp.vegetation.Vegetation

`RATPinputs.RATP_meteo(energy, day, hour, coordinates, parunit, truesolartime, direct, diffus)`

Initialise a RATP MicroMeteo object from LightVegeManager input parameters

Parameters

- **energy** (*float*) – input ray energy
- **day** (*int*) – input day
- **hour** (*int*) – input hour
- **coordinates** (*list*) – [latitude, longitude, timezone]
- **parunit** (*string*) – unit of energy argument, “micromol.m-2.s-1” or else
- **truesolartime** (*bool*) – activates true solar time or local time to compute sun position
- **direct** (*bool*) – if direct rays are activated
- **diffus** (*bool*) – if diffuse rays are activated

Returns

input meteorological data at current time step

Return type

PyRATP.pyratp.micrometeo.MicroMeteo

`RATPinputs.RdRSH(Rg, DOY, heureTU, latitude)`

fraction diffus/Global en fonction du rapport Global(Sgd)/Extraterrestre(Sod)- pas de temps horaire

2.7.4 VTK module

VTK

Writes VTK files from LightVegeManager geometry and lighting data. Used for visualisation We recommend the software Paraview for visualisation

`VTK.VTKtriangles(trimesh, var=[], varname=[], filename=)`

Writes VTK files from a triangulation mesh. Possibility to associate physical values to the triangles

Parameters

- **trimesh** (*dict of list*) – triangles mesh aggregated by indice elements

```
{ id : [triangle1, triangle2, ...]}
```

- **var** (*list of list*) – list of physical values associated to each triangle. Each element of var is a physical value for each triangle. Then, for n triangles and m values, var looks like:

```
var = [[var1_1, ..., var1_n], ..., [varm_1, ..., varm_n]]
```

- **varname** (*list of string*) – list of variable names
- **filename** (*string*) – name and path for the output file

`VTK.VTKline(start, end, filename)`

Writes a VTK file representing a line

Parameters

- **start** (*list*) – starting point [x, y, z] of the line

- **end** (*list*) – ending point [*x*, *y*, *z*] of the line
- **filename** (*string*) – name and path for the output file

VTK.**ratp_prepareVTK**(*ratpgrid*, *filename*, *columns*=[], *df_values*=None)

Sets and prepare data to write a voxel grid in VTK format from a RATP grid

Possibility to sets physical values to each voxel. Otherwise, it will assign leaf area density for each voxel.

Then, it runs :func:VTKvoxels to write a VTK file with the grid of voxels.

Parameters

- **ratpgrid** (*pyratp.grid*) – RAPT grid of voxels
- **filename** (*string*) – name and path for the output file
- **columns** (*list*, *optional*) – list of columns name of *df_values* to associate to each voxel, defaults to []
- **df_values** (*pandas.DataFrame*, *optional*) – dataframe with a "Voxel" and a "VegetationType" columns, matching *ratpgrid*. It stores physical values associated to each voxel that you want to print, defaults to None

VTK.**VTKvoxels**(*grid*, *datafields*, *varnames*, *nomfich*)

Writes a VTK file with a grid of voxels and associated physical values.

Display Voxels colored by variable with Paraview

RATP Grid is written in VTK Format as a structured grid

Parameters

- **grid** (*pyratp.grid*) – the RATP grid
- **datafields** (*list of list*) – a list of 3 arrays composed of the a RATP variable to be plotted, corresponding entities, and Voxel ID
 - [0] : kxyz (numpy.array)
 - [1] : entities (numpy.array)
 - [2, ..., n] : variable_0, ... variable_n-2 (numpy.array)
- **varnames** (*list of string*) – name of the variable to be plotted
- **nomfich** (*string*) – the VTK filename and path

VTK.**PlantGL_to_VTK**(*scenes*, *path*, *i*=0, *in_unit*='m', *out_unit*='m')

Directly converts a list plantGL scenes to a single VTK file The routine aggregates all the scenes in one global triangulation and then calls :func:VTKtriangles Possibility to rescale measure unit scenes

Parameters

- **scenes** (*lists of plantgl.Scene*) – list of scenes to be written
- **path** (*string*) – path of the file. File name is set by default with "triangles_plantgl_ "+str(*i*)+".vtk"
- **i** (*int*, *optional*) – id of the file. Used if you want to batch a large number of scenes, defaults to 0
- **in_unit** (*str*, *optional*) – input measure unit, defaults to "m"
- **out_unit** (*str*, *optional*) – output measure unit, defaults to "m"

Raises

ValueError – in_unit or out_unit not a valid entry upon the listed measure units

2.7.5 basicgeometry module

basicgeometry

Provides basic geometric operations in 3D used by LightVegeManager. Vectors are represented by their cartesian coordinates in a 3-tuple of floats such as $v = (x, y, z)$ Triangles are a list of 3 vectors representing its vertices

`basicgeometry.crossproduct(v1, v2)`

Crossproduct between two vectors $v1 \wedge v2$

Parameters

- **v1** (3-tuple) – vector 1
- **v2** (3-tuple) – vector 2

Returns

crossproduct

Return type

3-tuple

`basicgeometry.middle(v1, v2)`

Middle point between v1 and v2

Parameters

- **v1** (3-tuple) – vector 1
- **v2** (3-tuple) – vector 2

Returns

middle point $p = (v1 + v2)/2$

Return type

3-tuple

`basicgeometry.triangle_normal(triangle)`

Computes normal of an oriented triangle (3D)

Note: a triangle is $[(x1, y1, z1), (x2, y2, z2), (x3, y3, z3)]$

Parameters

triangle (list) – triangle represented by its 3 vertices

Returns

normalized vector

Return type

3-tuple

basicgeometry.**triangle_elevation**(*triangle*)

Computes normal elevation of triangle

Note: a triangle is $[(x_1, y_1, z_1), (x_2, y_2, z_2), (x_3, y_3, z_3)]$

Parameters

triangle (*list*) – triangle represented by its 3 vertices

Returns

angle in degree elevation starts from ground to normal vector must be between 0 and 90°

Return type

float

basicgeometry.**triangle_area**(*triangle*)

triangle area

Note: a triangle is $[(x_1, y_1, z_1), (x_2, y_2, z_2), (x_3, y_3, z_3)]$

Parameters

triangle (*list*) – triangle represented by its 3 vertices

Returns

area

Note: algorithm is a copy of `_surf` in `alinea.caribu.caributriangle`set

Return type

float

basicgeometry.**triangle_barycenter**(*triangle*)

triangle barycenter

Note: a triangle is $[(x_1, y_1, z_1), (x_2, y_2, z_2), (x_3, y_3, z_3)]$

Parameters

triangle (*list*) – triangle represented by its 3 vertices

Returns

isobarycenter $(s_1 + s_2 + s_3)/3$

Return type

float

basicgeometry.**rescale**(*triangles, h*)

Multiplies all triangle vertices by a ratio h

Note: a triangle is $[(x_1, y_1, z_1), (x_2, y_2, z_2), (x_3, y_3, z_3)]$

Parameters

- **triangles** (*list of list*) – list of triangles in the same format as below
- **h** (*float*) – ratio

Returns

list of triangles with each triangle from input rescaled by h

Return type

list of list

example

```
>>> triangles = [[(0,0,0), (0,1,0), (0,1,1)], [(0,0,1), (0,0,0), (1,0,1)]]
>>> rescale(triangles, 3)
[[ (0,0,0), (0,3,0), (0,3,3)], [(0,0,3), (0,0,0), (3,0,3)]]
```

`basicgeometry.translate(triangles, tvec)`

Moves a list of triangles with a translation of vector tvec

Note: a triangle is [(x1,y1,z1), (x2,y2,z2), (x3,y3,z3)]

Parameters

- **triangles** (*list of list*) – list of triangles in the same format as below
- **tvec** (*3-tuple*) – vector

Returns

list of triangles with each triangle from input translated by tvec

Return type

list of list

example

```
>>> triangles = [[(0,0,0), (0,1,0), (0,1,1)], [(0,0,1), (0,0,0), (1,0,1)]]
>>> tvec = (3,0,1)
>>> translate(triangles, tvec )
[[ (3,0,1), (3,1,1), (3,1,2)], [(3,0,2), (3,0,1), (4,0,2)]]
```

`basicgeometry.zrotate(triangles, omegadeg)`

Rotates a list of triangles in the xy plane from an angle

Note: a triangle is [(x1,y1,z1), (x2,y2,z2), (x3,y3,z3)]

Parameters

- **triangles** (*list of list*) – list of triangles in the same format as below
- **omegadeg** (*float*) – angle in degree

Returns

list of triangles with each triangle from input rotated around z axis by ω_{deg}

Return type

list of list

example

```
>>> triangles = [[(0,0,0), (0,1,0), (0,1,1)], [(0,0,1), (0,0,0), (1,0,1)]]
>>> zrotate(triangles, 90 )
[[ (0,0,0), (-1,0,0), (-1,0,1)], [(0,0,1), (0,0,0), (0,1,1)]]
```

2.7.6 buildRATPscene module

buildRATPscene

Creation of a PyRATP.grid from inputs. The following functions create and initialize a grid from either a triangles mesh, a l-egume grid or an empty geometric input

The argument parameters refers to one the three inputs dict of LightVegeManager. It is structured as so:

```
ratp_args = {
    # Grid specifications
    "voxel size" : [dx, dy, dz],
    "voxel size" : "dynamic",

    "origin" : [xorigin, yorigin, zorigin],
    "origin" : [xorigin, yorigin],

    "number voxels" : [nx, ny, nz],
    "grid slicing" : "ground = 0.",
    "tessellation level" : int

    # Leaf angle distribution
    "angle distrib algo" : "compute global",
    "angle distrib algo" : "compute voxel",
    "angle distrib algo" : "file",

    "nb angle classes" : int,
    "angle distrib file" : filepath,

    # Vegetation type
    "soil reflectance" : [reflectance_band0, reflectance_band1, ...],
    "reflectance coefficients" : [reflectance_band0, reflectance_band1, ...],
    "mu" : [mu_scene0, mu_scene1, ...]
}
```

See also:

For more details *Inputs description*

`buildRATPscene.extract_grid_origin(parameters, minmax)`

Create grid origin from either input parameters or from the scene

Parameters

- **parameters** (*dict*) – RATP parameters from inputs of LightVegeManager
- **minmax** (*[3-tuple, 3-tuple]*) – list of minimum point and maximum point in a triangles mesh

Returns

origin of the grid depending of input parameters and size of the mesh

Return type

3-tuple

```
buildRATPscene.build_RATPscene_from_trimesh(trimesh, minmax, triLmax, matching_ids, parameters,
                                             coordinates, reflected, infinite, stems_id=None,
                                             nb_input_scenes=0, fullgrid=False)
```

Build a RATP grid from a triangles mesh.

Parameters

- **trimesh** (*dict*) – triangles mesh aggregated by indice elements .. code-block:: { id : [triangle1, triangle2, ...]}
- **minmax** (*[3-tuple, 3-tuple]*) – list of minimum point and maximum point in a triangles mesh
- **triLmax** (*float*) – longest side of all the triangles in trimesh
- **matching_ids** (*dict*) – dict that matches new element indices in trimesh with specy indice and input element indice .. code:: matching_ids = { new_element_id : (input_element_id, specy_id)}
- **parameters** (*dict*) – RATP parameters from inputs of LightVegeManager
- **coordinates** (*list*) – [latitude, longitude, timezone]
- **reflected** (*bool*) – if the user wishes to activate reflected radiations
- **infinite** (*bool*) – if the user wishes to activate infinitisation of the grid
- **stems_id** (*list of 2-tuple, optional*) – list of potential stems element in the input scenes, defaults to None
- **nb_input_scenes** (*int, optional*) – number of input scenes in the geometry dict, defaults to 0

Returns

It returns 3 objects:

- **ratpgrid**
pyratp.grid filled with areas of triangles in trimesh and input parameters
- **matching_tri_vox**
dict where key is a triangle indice and value the matching voxel indice where the barycenter of the triangle is located
- **distrib**
dict with a "global" key and if ["angle distrib algo"] = "compute voxel" a second entry where key is "voxel"

value for "voxel" is a `numpy.array` of dimension (numberofvoxels, numberofentities, numberofclasses)

value for "global" is a list of numberofentities list of numberofclasses elements

Return type

pyratp.grid, dict, dict

`buildRATPscene.build_RATPscene_empty(parameters, minmax, coordinates, infinite)`

Build a RATP grid from an empty geometric input

Parameters

- **parameters** (*dict*) – RATP parameters from inputs of LightVegeManager
- **minmax** (*[3-tuple, 3-tuple]*) – list of minimum point and maximum point in a triangles mesh
- **coordinates** (*list*) – [latitude, longitude, timezone]
- **infinite** (*bool*) – if the user wishes to activate infinitisation of the grid

Returns

- **ratpgrid**: pyratp.grid sets with input parameters
- **distrib**: dict with one entry "global" : [1.]

Return type

pyratp.grid, dict

`buildRATPscene.legumescene_to_RATPscene(legumescene, parameters, coordinates, reflected, infinite)`

Creates a RATP grid of voxels from a l-egume grid format

Parameters

- **legumescene** (*dict*) – l-egume grid represented by a dict with two entries:
 - "LA": equivalent to m_lais in l-egume, a numpy.array of dimension (nent, nz, ny, nx) which represents leaf area in each voxel for each specy
 - "distrib": equivalent to ls_dif in l-egume, a numpy.array of dimension (nent, nclasses) which represents the global leaf angle distribution for each input specy

Note: legumescene is the only input geometric scene which can handle several species

- **parameters** (*dict*) – RATP parameters from inputs of LightVegeManager
- **coordinates** (*list*) – [latitude, longitude, timezone]
- **reflected** (*bool*) – if the user wishes to activate reflected radiations
- **infinite** (*bool*) – if the user wishes to activate infinitisation of the grid

Returns

It returns 3 objects

- **ratpgrid**: pyratp.grid filled with areas of triangles in trimesh and input parameters
- **distrib**: dict with only a "global" key, value for "global" is a list of numberofentities list of numberofclasses elements
- **nb0**: number of empty layers between top canopy and maximum layer in legumescene

Return type

pyratp.grid, dict, int

2.7.7 defaultvalues module

defaultvalues

Default for simulation fixed parameters These parameters are sets in LightVegeManager if the user did not precise thoses inputs

`defaultvalues.default_LightVegeManager_inputs()`

returns default parameters for LightVegeManager constructor `__init__`

Returns

environment and light model parameters

Return type

dict, dict

2.7.8 leafangles module

leafangles

Handles leaf angle distribution, both in its dynamic computing or reading a file

An angle distribution is a list of n elements, where n is the number of angle class between 0 and 90°. Each element of this list is a percentage for leaves to be oriented from 0 to 90/ n degree. The sum of all the list entries must equal 1.

`leafangles.read_distrib_file(path, numberofentities)`

Reads global leaf angle distribution in a file the file must matches the format : one specy distribution per line each percentage separated by a coma ','

example

```
0.1382,0.1664,0.1972,0.1925,0.1507,0.0903,0.0425,0.0172,0.005
0.3,0.1,0.15,0.2,0.05,0.2
```

Parameters

- **path** (*string*) – path to the file
- **numberofentities** (*int*) – number of species, aka nombre of lines in the file

Returns

distribution for each specy, number of entries on one line

Return type

list of list

`leafangles.compute_distrib_globale(trimesh, matching_ids, numberofclasses)`

Calculation of a global leaf angle distribution from a triangle mesh

Parameters

- **trimesh** (*dict*) – triangles mesh aggregated by indice elements { **id** : [triangle1, triangle2, ...]}
- **matching_ids** (*dict*) – dict that matches new element indices in trimesh with specy indice and input element indice, `matching_ids = { new_element_id : (input_element_id, specy_id)}`

this dict allows us to look how species there is the inputs geometric data

- **numberofclasses** (*int*) – number angle class wanted between 0 and 90 degree

Returns

a leaf angle distribution for each specy. Each distribution is a length `numberofclasses` the distribution is computed on all trimesh

Return type

list of list

`leafangles.compute_distrib_voxel(trimesh, matching_ids, numberofclasses, numberofvoxels, matching_tri_vox)`

Calculation of a local leaf angle distribution from a triangle mesh on each voxel of a grid

Parameters

- **trimesh** (*dict*) – triangles mesh aggregated by indice elements { `id` : [`triangle1`, `triangle2`, ...]}
- **matching_ids** (*dict*) – dict that matches new element indices in trimesh with specy indice and input element indice, `matching_ids` = { `new_element_id` : (`input_element_id`, `specy_id`)} this dict allows us to look how species there is the inputs geometric data
- **numberofclasses** (*int*) – number angle class wanted between 0 and 90 degree
- **numberofclasses** – number of non empty voxels in the grid
- **matching_tri_vox** (*dict*) – dict where key is a triangle indice and value the matching voxel indice where the barycenter of the triangle is located

Returns

array of dimension [number of voxels][number of species][number of angle classes] i.e. it returns for each voxel a leaf angle distribution for each specy

Return type

numpy.array

2.7.9 outputs module

outputs

Manages and reformat output results from the light models in `pandas.DataFrame` with similar columns names.

Light models managed in this module:

- RATP
- CARIBU

Column names for voxels:

- **'VegetationType'**: id of the specy
- **'Iteration'**: RATP can handle multiple iterations in inputs, but it is not properly exploited in LightVegeManager yet
- **'Day'**: input day if LightVegeManager
- **'Hour'**: input hour if LightVegeManager
- **'Voxel'**: index of current voxel
- **'Nx'**: index in grid following x axis, corresponds to `pyrapt.grid.numx`

- 'Ny': index in grid following y axis, corresponds to `pyrapt.grid.numy`
- 'Nz': index in grid following z axis, corresponds to `pyrapt.grid.numz`
- 'ShadedPAR': shaded energy in the current voxel, 0 if no direct light in the input
- 'SunlitPAR': sunlit energy
- 'ShadedArea': leaf area in voxel which is shaded
- 'SunlitArea': leaf area in voxel which is sunlit
- 'Area': total leaf area in the voxel
- 'PARa': $(\text{ShadedPAR} * \text{ShadedArea} + \text{SunlitPAR} * \text{SunlitArea}) / (\text{ShadedArea} + \text{SunlitArea})$
- 'Intercepted': relative portion of input rays intercepted by the voxel
- 'Transmitted': relative portion of input rays leaving out the voxel

Column names for triangles:

- 'VegetationType': id of the specy
- 'Day': input day if LightVegeManager
- 'Hour': input hour if LightVegeManager
- 'Triangle': indice of the triangle
- 'Organ': element where the triangle belongs

if ligh model is CARIBU:

- 'Area': area of the triangles

for each bandwidth in the inputs you have two entries:

- `band + " Eabs"`: energy absorbed by the triangle
- `band + " Ei"`: energy intercepted by the triangle

If light model is RATP:

- 'Area': area of total leaf area in the voxel where the triangle is located
- 'primitive_area': area of the triangle
- 'Voxel': index of the voxel where the triangle is located
- 'Nx': index in grid following x axis, corresponds to `pyrapt.grid.numx`
- 'Ny': index in grid following y axis, corresponds to `pyrapt.grid.numy`
- 'Nz': index in grid following z axis, corresponds to `pyrapt.grid.numz`
- 'ShadedPAR': shaded energy in the current voxel
- 'SunlitPAR': sunlit energy, 0 if no direct light in the input
- 'ShadedArea': leaf area in voxel which is shaded
- 'SunlitArea': leaf area in voxel which is sunlit
- 'PARa': $(\text{ShadedPAR} * \text{ShadedArea} + \text{SunlitPAR} * \text{SunlitArea}) / (\text{ShadedArea} + \text{SunlitArea})$
- 'Intercepted': relative portion of input rays intercepted by the voxel
- 'Transmitted': relative portion of input rays leaving out the voxel

Column names for elements:

- 'Day': input day if LightVegeManager
- 'Hour': input hour if LightVegeManager
- 'Organ': id of current element
- "VegetationType": id of the specy
- "Area": area of the element (sum of all triangles belonging to current element)

if light model is CARIBU, for each bandwidth in the optical inputs you have two entries:

- band + " Eabs": energy absorbed by the element, integrated on all triangles belonging to current element
- band + " Ei": energy intercepted by the triangle, integrated on all triangles belonging to current element

if light model is RATP, the following entries are integrated on all triangles belonging to current element with E, current element, t triangles in E and V an entry: $\frac{\sum_{t \in E} area_t * V_t}{area_E}$

- "PARa"
- "Intercepted"
- "Transmitted"
- "SunlitPAR"
- "SunlitArea"
- "ShadedPAR"
- "ShadedArea"

`outputs.out_ratp_empty_grid(day, hour)`

Returns an empty dataframe results for RATP

Parameters

- **day** (*int*) – day of simulation
- **hour** (*int*) – hour of simulation

Returns

returns a dataframe with all the keys expected with a RATP simulation but results are empty used if input geometry is empty

Return type

pandas.DataFrame

`outputs.out_ratp_voxels(ratpgrid, res, parunit)`

Converts RATP results to pandas dataframe compared to the voxels

Parameters

- **ratpgrid** (*pyratp.grid*) – RATP grid with voxels informations
- **res** (*pyratp.ratp.out_rayt*) – output table of RATP
- **parunit** (*string*) – energy unit of input

RATP expects W.m-2 in input and return results in $\mu\text{mol.s-1.m-2}$. if `parunit="W.m-2"` the outputs is converted to W.m-2, otherwise results are in $\mu\text{mol.s-1.m-2}$

Returns

res.T converted in a pandas Dataframe with voxels relative columns. The soil is not part of the results

Return type

pandas.DataFrame

`outputs.out_ratp_triangles(trimesh, matching_ele_ent, matching_tr_vox, voxels_outputs)`

Converts RATP results to pandas dataframe compared to the triangles (and voxels)

Parameters

- **trimesh** (*dict*) – triangles mesh aggregated by indice elements .. code-block:: { id : [triangle1, triangle2, ...]}
- **matching_ele_ent** (*dict*) – dict that matches new element indices in trimesh with specy indice and input element indice, .. code:: matching_ids = { new_element_id : (input_element_id, specy_id)}
- **matching_tr_vox** (*dict*) – dict where key is a triangle indice and value the matching voxel indice where the barycenter of the triangle is located
- **voxels_outputs** (*pandas.DataFrame*) – output of :func:out_ratp_voxels

Returns

output of :func:out_ratp_voxels merged with associated triangles

Return type

pandas.DataFrame

`outputs.out_ratp_elements(matching_ele_ent, reflected, reflectance_coef, trianglesoutputs)`

If trimesh is not empty, aggregates RATP results by element (keys in dict trimesh)

Parameters

- **matching_ele_ent** (*dict*) – dict that matches new element indices in trimesh with specy indice and input element indice, .. code:: matching_ids = { new_element_id : (input_element_id, specy_id)}
- **reflected** (*bool*) – if the user wishes to activate reflected radiations
- **reflectance_coef** (*list of list*) – coefficient for each specy and each input bandwidth
- **trianglesoutputs** (*pandas.DataFrame*) – output of :func:out_ratp_triangles

Returns

dataframe integrated on element informations

Return type

pandas.DataFrame

`outputs.out_caribu_mix(rdrs, c_scene_sun, c_scene_sky, raw_sun, aggregated_sun, raw_sky, aggregated_sky, issensors, issoilmesh)`

Mix diffuse and direct rays results according to a ratio rdrs

Parameters

- **rdrs** (*float*) – Spitters's model estimating for the diffuse:direct ratio
- **c_scene_sun** (*CaribuScene*) – CaribuScene with direct lighting computed (from a sun)
- **c_scene_sky** (*CaribuScene*) – CaribuScene with diffuse lighting computed (from a sky)
- **raw_sun** (*dict of dict*) – results of c_scene_sun for triangles

- **aggregated_sun** (*dict of dict*) – results of `c_scene_sun` aggregated by element
- **raw_sky** (*dict of dict*) – results of `c_scene_sky` for triangles
- **aggregated_sky** (*dict of dict*) – results of `c_scene_sky` aggregated by element
- **issensors** (*bool*) – if option virtual sensors is activated
- **issoilmesh** (*bool*) – if option soil mesh is activated

Returns

if sensors is activated, it extracts its results from `aggregated_sun` and `aggregated_sky`

if soilmesh is activated, it extracts its results from `c_scene_sun` and `c_scene_sky`

then it mixes raw, aggregated, virtual sensors and soil energy results such as

`result = rdrs * diffuse_result + (1 - rdrs) * direct_result`

Return type

dict of dict, dict of dict, dict of list, dict of float

`outputs.out_caribu_nomix(c_scene, aggregated, issensors, issoilmesh)`

Extracts only sensors and soilmesh results if activated

Parameters

- **c_scene** (*CaribuScene*) – instance of `CaribuScene` containing geometry, light source(s), opt etc...
- **aggregated** (*dict of dict*) – result of `CaribuScene.run`
- **issensors** (*bool*) – if option virtual sensors is activated
- **issoilmesh** (*bool*) – if option soil mesh is activated

Returns

extracts sensors results from `aggregated` and soil energy from `c_scene`

Return type

dict, dict

`outputs.out_caribu_elements(day, hour, trimesh, matching_ids, aggregated, sun_up, caribu_triangles={})`

Converts aggregated in a `pandas.DataFrame` following indices in `LightVegeManager`

Parameters

- **day** (*int*) – day of simulation
- **hour** (*int*) – hour of simulation
- **trimesh** (*dict*) – triangles mesh aggregated by indice elements .. code-block:: { id : [triangle1, triangle2, ...]}
- **matching_ele_ent** (*dict*) – dict that matches new element indices in `trimesh` with specy indice and input element indice, .. code:: matching_ids = { new_element_id : (input_element_id, specy_id)}
- **aggregated** (*dict of dict*) – result of `CaribuScene.run`
- **sun_up** (*bool*) – if sun elevation is $> 2^\circ$ and direct rays are $> 0 \text{ W.m}^2$

Returns

aggregated results rearrange in a `Dataframe` with element correspondance in `LightVegeManager`

Return type

pandas.DataFrame

`outputs.out_caribu_triangles(day, hour, trimesh, matching_ids, raw, sun_up)`

Converts raw in a pandas.DataFrame following simulation datas

Parameters

- **day** (*int*) – day of simulation
- **hour** (*int*) – hour of simulation
- **trimesh** (*dict*) – triangles mesh aggregated by indice elements .. code-block:: { id : [triangle1, triangle2, ...]}
- **matching_ele_ent** (*dict*) – dict that matches new element indices in trimesh with specy indice and input element indice, .. code:: matching_ids = { new_element_id : (input_element_id, specy_id)}
- **raw** (*dict of dict*) – triangles results from CaribuScene.run
- **sun_up** (*bool*) – if sun elevation is $> 2^\circ$ and direct rays are $> 0 \text{ W.m}^2$

Returns

triangle results rearrange in a DataFrame

Return type

pandas.DataFrame

2.7.10 plantGL module

plantGL

visualisation plantGL

`plantGL.cscene_to_plantGLScene_stems(cscene, stems_id=None, matching_ids={})`

Transform a triangles mesh to a plantGL scene, with a color difference between leaves and stems

Parameters

- **cscene** (*dict of list*) – LightVegeManager triangulations mesh
- **stems_id** (*list of tuple, optional*) – list of tuple (element_id, specy_id), defaults to None
- **matching_ids** (*dict of tuple, optional*) – dict that matches new element indices in trimesh with specy indice and input element indice, defaults to {} matching_ids = { new_element_id : (input_element_id, specy_id)}

Returns

cscene in plantGL scene format with leaves in green and stems in brown

Return type

plantGL Scene

`plantGL.cscene_to_plantGLScene_light(cscene, outputs={}, column_name='par Ei')`

Transform a triangles mesh to a plantGL scene, colors represent lightint results from blue to red

Parameters

- **cscene** (*dict of list*) – LightVegeManager triangulations mesh

- **outputs** (*Pandas.DataFrame, optional*) – outputs results from LightVegeManager, defaults to {}
- **column_name** (*str, optional*) – name of the value to plot, defaults to “par Ei”

Returns

cscene in plantGL scene format with a color from blue to red

Return type

plantGL Scene

`plantGL.ratpgrid_to_plantGLScene(ratpgrid, transparency=0.0, plt_cmap='Greens', outputs={})`

Transform a RATP grid mesh to a plantGL scene Colors can either follows leaf area or lighting values

Parameters

- **ratpgrid** (*pyratp.grid*) – grid of voxels in RATP format
- **transparency** (*float, optional*) – transparency value of the voxels from 0 to 1, defaults to 0.
- **plt_cmap** (*str, optional*) – name of the colormap to color the voxels, defaults to “Greens”
- **outputs** (*pandas.DataFrame, optional*) – lighting results from LightVegeManager, defaults to {}

Returns

ratpgrid in plantGL scene

Return type

plantGL Scene

2.7.11 sky module

sky

Build a sky from LightVegeManager input informations

Possible sky options:

- "turtle46" : soc sky composed by 46 directions in a turtle shape
- `filepath` : string indicating a file path
- [`nb_azimut`, `nb_zenith`, "soc" or "uoc"] : build a sky with a custom number of directions

output :

- with RATP : `pyratp.skyvault`
- with CARIBU : [(`weight`, (`dir[0]`, `dir[1]`, `dir[2]`)), ...]

Sky file is in RATP format

`sky.ratpformat_to_caribuformat(az, h, pc, rad=True)`

Converts sky informations from RATP format to CARIBU format

Parameters

- **az** (*list*) – azimuths of each sky direction (degree)
- **h** (*list*) – elevation of each sky direction (degree)

- **pc** (*list*) – perez weight of each sky direction

Returns

direction vectors and weights for each sky direction list of (weight, (x, y, z)) vector is from sky to ground

Return type

list of tuple

`sky.caribuformat_to_ratpformat(directions)`

Converts CARIBU format to RATP sky format

Parameters

directions (*list of tuples*) – list of all each sky directions, such as one direction is (perez coeff, (x, y, z)) where vector looks from sky to floor

Returns

- **pc** : perez coefficients for each direction
- **az** : azimuth of each direction, $x+ = 0$.
- **h** : elevation of each direction

:rtype: list, list, list

`sky.RATPSky(skytype)`

Creates a pyratp.skyvault

Parameters

skytype (*string or list*) – the environment[“sky”] from the LightVegeManager inputs. It is either: * “turtle46” * a filepath * [nb_azimut, nb_elevation, “soc” or “uoc”], nb_azimut is the number of azimuth directions and nb_elevation the number of zenital directions for cutting out the sky

Raises

ValueError – if skytype is not one of the curretn 3 possibilities

Returns

a sky in RATP format

Return type

pyratp.skyvault

`sky.CARIBUSky(skytype)`

Build a sky in CARIBU format

Parameters

skytype (*string or list*) – the environment[“sky”] from the LightVegeManager inputs. It is either:

- “turtle46”
- a filepath
- [nb_azimut, nb_elevation, “soc” or “uoc”], nb_azimut is the number of azimuth directions and nb_zenith the number of zenital directions for cutting out the sky

Raises

ValueError – if skytype is not one of the curretn 3 possibilities

Returns

a list of the directions representing the sky. each entry of the list is a tuple (weight, vector), where

weight is a float for the weight the direction and vector, a tuple (x, y, z), representing the position of the sky direction, from sky to the ground

Return type

list of tuple

`sky.discrete_sky(n_azimuts, n_zeniths, sky_type)`

Cuts out a sky following input number of directions

Parameters

- **n_azimuts** (*int*) – number of azimuth directions of the sky
- **n_zeniths** (*int*) – number of elevations directions of the sky
- **sky_type** (*string*) – "soc" or "uoc"

Returns

4 output lists of length `n_azimuts * n_zeniths * ele`: elevations in degrees (angle soil to sky) * `azi`: azimuths in degrees * `omega`: solid angle of directions * `pc`: relative contribution of directions to incident diffuse radiation

Return type

list, list, list, list

2.7.12 stems module

stems

Manages stems element (opaque)

`stems.extract_stems_from_MTG(MTG, entity_id)`

Extracts stems element from a MTG table

Parameters

- **MTG** (*openalea.mtg.mtg.MTG*) – MTG table describing plant elements
- **entity_id** (*int*) – indice of the corresponding geometric scene of the MTG table scene in the LightVegeManager inputs

Returns

stems is a list where each entry is a tuple (element indice, entity_id)

Return type

list of tuple

`stems.manage_stems_for_ratp(stems_id, matching_ids, ratp_parameters)`

Adds a specy to separate stems from leaves in vegetation parameters

Parameters

- **stems_id** (*list of tuple*) – list of tuple (element_id, specy_id)
- **matching_ids** (*dict*) – dict that matches new element indices in trimesh with specy indice and input element indice `matching_ids = { new_element_id : (input_element_id, specy_id)}`
- **ratp_parameters** (*dict*) – RATP parameters from inputs of LightVegeManager

Raises

ValueError – if too many stems elements are identified comparing to the total number of elements cumulated over all species

2.7.13 sun module**sun**

Build a sun respecting each light model format

For computing the sun position you can either use CARIBU or RATP algorithm, which slightly change in the process

`sun.ratp_sun(day, hour, coordinates, truesolartime)`

Converts output RATP sundirection routine to CARIBU light format

Parameters

- **day** (*int*) – input day
- **hour** (*int*) – input hour
- **coordinates** (*list*) – [latitude, longitude, timezone]
- **truesolartime** (*bool*) – activates true solar time or local time to compute sun position

Returns

sun direction in a tuple with cartesian coordinates (x,y,z), vector is oriented from sky to ground

Return type

tuple

`sun.caribu_sun(day, hour, coordinates, truesolartime)`

Compute sun direction from CARIBU algorithm

Parameters

- **day** (*int*) – input day
- **hour** (*int*) – input hour
- **coordinates** (*list*) – [latitude, longitude, timezone]
- **truesolartime** (*bool*) – activates true solar time or local time to compute sun position

Returns

sun direction in a tuple with cartesian coordinates (x,y,z), vector is oriented from sky to ground

Return type

tuple

`sun.print_sun(day, hour, coordinates, truesolartime)`

Prints sun position outputs from RATP and CARIBU algorithm with the same inputs

Parameters

- **day** (*int*) – input day
- **hour** (*int*) – input hour
- **coordinates** (*list*) – [latitude, longitude, timezone]
- **truesolartime** (*bool*) – activates true solar time or local time to compute sun position

2.7.14 tesselator module

tesselator

Handles tessellation of a triangulation, the subdivision of triangulation. The tessellation was initially made to have a better matching of a triangle mesh in a grid of voxels and avoid triangle to be located in several voxels

Tessellation operates as a recursive function until a certain level is reached

`tesselator.whichvoxel(p, mygrid)`

Returns in which voxel *p* is located

Parameters

- **p** (*list or tuple*) – 3D vector located in the grid
- **mygrid** (*pyratp.grid*) – RATP grid

Returns

returns the voxels where *p* is located in a list [*kx*, *ky*, *kz*] where *ki* is the indice voxel on each axis, [0, 0, 0] is origin voxel

Return type

list

`tesselator.samevoxel(voxels)`

Check if all voxels in list *voxels* are the same

Parameters

voxels (*list*) – list of voxels in format [*kx*, *ky*, *kz*]

Returns

if all elements of voxels are the same

Return type

bool

`tesselator.tessellate(mygrid, triangle)`

Check if the triangle is strictly inside a voxel or between several voxels. If so, it cuts out triangle in 4 smaller triangles.

Parameters

- **mygrid** (*pyratp.grid*) – RATP voxels grid
- **triangle** (*list of tuple*) – triangle represented by its 3 vertices `triangle = [(x1, y1, z1), (x2, y2, z2), (x3, y3, z3)]`

Returns

- if the triangle is inside a voxel, it returns the input triangle in a 1-list
- else if the triangle is between several voxels, it cuts out triangle in four smaller triangles from its vertices and barycenter

Return type

list of triangle

`tesselator.tessellate2(triangle)`

Same as :func:tessellate but without the grid matching

Parameters

triangle (*list of tuple*) – triangle represented by its 3 vertices `triangle = [(x1, y1, z1), (x2, y2, z2), (x3, y3, z3)]`

Returns

it cuts out triangle in four smaller triangles from its vertices and barycenter

Return type

list of triangle

`tesselator.iterate_trianglesingrid(triangle, mygrid, level, levelmax, triangles_shape)`

Recursion on a triangle, while its subdivision doesn't match an RATP grid or exceed a certain level of tessellation

Parameters

- **triangle** (*list of tuple*) – triangle represented by its 3 vertices `triangle = [(x1, y1, z1), (x2, y2, z2), (x3, y3, z3)]`
- **mygrid** (*pyratp.grid*) – RATP voxels grid
- **level** (*int*) – current level of tessellation, i.e. how many times we cut out the initial triangle
- **levelmax** (*int*) – final level of tessellation to not be exceeded
- **triangles_shape** (*list of triangles*) – list of triangles used to stock new triangles or input `triangle` if no tessellation is computed

Returns

`triangles_shape` updates with input `triangle` or new triangles if tessellation was activated

Return type

list of triangles

`tesselator.iterate_triangles(triangle, level, levelmax, triangles_shape)`

Subdivide a triangle until its tessellation reaches levelmax. It stocks the new triangles in `triangle_shape`
Recursive function

Parameters

- **triangle** (*list of tuple*) – triangle represented by its 3 vertices `triangle = [(x1, y1, z1), (x2, y2, z2), (x3, y3, z3)]`
- **level** (*int*) – current level of tessellation, i.e. how many times we cut out the initial triangle
- **levelmax** (*int*) – final level of tessellation to not be exceeded
- **triangles_shape** (*list of triangles*) – list of triangles used to stock new triangles or input `triangle` if no tessellation is computed

Returns

`triangles_shape` updates with new triangles from tessellation

Return type

list of triangles

2.7.15 transfer module

transfer

Handles transfer of LightVegeManager results to plant Models.

Currently, it manages CN-Wheat and l-egume. Only l-egume needs additionnal processes to converts Dataframe results in a compatible format.

l-egume expects the absorb PAR either per plant or locally following a grid of voxels, and the transmitted PAR locally following a grid of voxels. Here, we will convert and transform results for CARIBU and RATP to those l-egume format.

`transfer.transfer_ratp_legume(m_lais, energy, ratp_grid, voxels_outputs, nb0, epsilon=1e-08)`

Transfers LightVegeManager outputs from RATP to l-egume Absorb and transmitted PAR will follow a RATP grid of voxels, matching the dimensions of intern l-egume grid of voxels.

Parameters

- **m_lais** (*numpy.array*) – leaf area represented in a numpy.array of dimension [number of species, number of z layers, number of y layers, number of x layers]
- **energy** (*float*) – input energy
- **ratp_grid** (*pyratp.grid*) – RATP grid of voxels
- **voxels_outputs** (*pandas.DataFrame*) – results from LightVegeManager
- **nb0** (*int*) – number of empty layers from top of the canopy and maximum z layers in m_lais
- **epsilon** (*float*) – criteria of minimum intercepted portion of PAR in a non empty voxel

Returns

two array with lighting informations

- **res_abs_i**: absorb PAR in each voxel for RATP grid of voxels. It has the same dimensions as m_lais
- **res_trans**: transmitted PAR in each voxel, i.e. the energy leaving the voxels from input rays. This value is not dependent on specy

dimensions are (number of z layers, number of y layers, number of x layers)

Return type

numpy.array, numpy.array

`transfer.transfer_caribu_legume(energy, skylayer, id, elements_outputs, sensors_outputs, sensors_dxyz, sensors_nxyz, m_lais, list_invar, list_lstring, list_dicFeuilBilanR, infinite, epsilon)`

Transfers LightVegeManager outputs from CARIBU to l-egume We will update list_invar which stores the total intercepted energy for each plant, and return an array storing transmitted energy following the intern grid of voxels in l-egume. To do so, we used virtual sensors in CARIBU to get incoming radiations in selected locations.

Parameters

- **energy** (*float*) – input energy
- **skylayer** (*int*) – number of empty layers from top of the canopy and maximum z layers in m_lais
- **id** (*list of int*) – list of indices of input scenes associated with l-egume

- **elements_outputs** (*pandas.DataFrame*) – Dataframe results of elements formatted by :func:outputs.out_caribu_elements
- **sensors_outputs** (*dict of list*) – lighting results of virtual sensors form CARIBU in the format for each bandwidth computed,

```
sensors_outputs[band+" Eabs"] = {sensor_id : energy}
sensors_outputs[band+" Ei"] = {sensor_id : energy}
```

- **sensors_dxyz** (*list*) – size of sides of a voxel in the grid of virtual sensors [dx, dy, dz]
- **sensors_nxyz** (*list*) – number of sensors in each direction in the grid [nx, ny, nz]
- **m_lais** (*numpy.array*) – leaf area represented in a numpy.array of dimension [number of species, number of z layers, number of y layers, number of x layers]
- **list_invar** (*list of dict*) – from l-egume, each element corresponds to an input specy of l-egume. Each element is a dict invar stores instant intern variables of l-egume.
- **list_lstring** (*list of dict*) – from l-egume, each element corresponds to an input specy of l-egume. Each element is a dict lstring stores the l-system of each plant
- **list_dicFeuilBilanR** (*list of dict*) – from l-egume, each element corresponds to an input specy of l-egume. Each element is a dict dicFeuilBilanR stores correspondances between voxels grid and each plant
- **infinite** (*bool*) – if the user wishes to activate infinitisation of the grid
- **epsilon** (*float*) – criteria of minimum intercepted portion of PAR in a voxel (if res_abs_i is zero, l-egume will crash)

Raises

ValueError – Virtual sensors and finite scene doesn't work yet with CARIBU

Returns

- it updates **list_invar** and its key entries "parap" and "parip", each element if the scipy.array is the sum of all intercepted energy for each plant. This process is a rewrite of calc_paraF in ShootMorpho.py module of l-egume, adapted to LightVegeManager numerotation of triangles
- **res_trans** an array of transmitted energy for each voxel in a grid of dimensions **sensors_dxyz * sensors_nxyz**

Return type

numpy.array

2.7.16 trianglesmesh module

trianglesmesh

It builds and handles triangulation mesh.

The main triangulation format in LightVegeManager is the CARIBU format: scene (dict): a {*primitive_id*: [*triangle*,]} dict. A triangle is a list of 3-tuples points coordinates. example:

```
scene = {    # element 0
    0 : [
        [(1,1,1), (0,0,0), (1,2,2)], # triangle 0 of element 0
```

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```
        [(10,10,10), (0,0,0), (10,20,20)] # triangle 1 of element 0
    ] ,

    # element 1
    1 : [
        [(12,12,12), (10,20,30), (21,22,22)],
        [(10,10,10), (10,20,30), (20,20,20)]
    ]
}
```

See also:

For more details *Inputs description*

`trianglesmesh.triangles_entity(cscene, entity_id, matching_ids)`

Return a list of triangles belonging to the specy `entity_id`

Parameters

- **cscene** (*dict of list*) – LightVegeManager triangulations mesh
- **entity_id** (*int*) – specy indice in `matching_ids`
- **matching_ids** (*dict*) – dict that matches new element indices in `cscene` with specy indice and input element indice, .. code:: `matching_ids = { new_element_id : (input_element_id, specy_id)}`

this dict allows us to look how species there is the inputs geometric data

Returns

list of triangles belonging to `entity_id` in `cscene`, a triangle is `[(x1, y1, z1), (x2, y2, z2), (x3, y3, z3)]`

Return type

list

`trianglesmesh.globalid_to_elementid(cscene, triangleid)`

Return the element index in `cscene` from a global triangle indice, as if triangles were in a list without a sorting by element.

Parameters

- **cscene** (*dict of list*) – LightVegeManager triangulations mesh
- **triangleid** (*int*) – indice from 0 to total number of triangles in `cscene`

Raises

IndexError – if `triangleid > total number of triangles in cscene`

Returns

element indice where `triangleid` belongs in `cscene`

Return type

int

`trianglesmesh.globalid_to_triangle(cscene, triangleid)`

Return the corresponding triangle in `cscene` from a global triangle indice, as if triangles were in a list without a sorting by element.

Parameters

- **cscene** (*dict of list*) – LightVegeManager triangulations mesh
- **triangleid** (*int*) – indice from 0 to total number of triangles in cscene

Raises

IndexError – if triangleid > total number of triangles in cscene

Returns

Corresponding triangle in cscene

Return type

list of tuple

`trianglesmesh.compute_area_max(cscene)`

Maximum triangle area in a triangulation

Parameters

cscene (*dict of list*) – LightVegeManager triangulations mesh

Returns

maximum triangle area in cscene

Return type

float

`trianglesmesh.compute_minmax_coord(cscene)`

Maximum and minimum point in all triangulation mesh

Parameters

cscene (*dict of list*) – LightVegeManager triangulations mesh

Returns

minimum point, maximum point

Return type

list, list

`trianglesmesh.compute_trilenght_max(cscene)`

Search for maximum side of an axis oriented voxel where all triangles could fit in

Parameters

cscene (*dict of list*) – LightVegeManager triangulations mesh

Returns

maximum side of an axis oriented voxel where all triangles in cscene could fit in

Return type

float

`trianglesmesh.isatriangle(t)`

`trianglesmesh.chain_triangulations(scenes)`

Aggregates all input geometric scenes in one global triangulation

Current known formats:

- plantGL scene
- VGX file
- CARIBU triangulation format (which is used in LightVegeManager for the global scene)
- MTG table with "geometry" identifier

- l-egume grid: dict of two entries, leaf area through a voxels grid and leaf angle distribution, for each specy

Only l-egume grid can stores multiple species, otherwise each entry scene must represent one specy

Parameters

scenes (*list*) – geometric["scenes"] from LightVegeManager inputs, list of geometric scenes. Scenes can be in different format in the list.

Returns

it returns 4 objects

- **complete_trimesh**: global triangulation which aggregates all input scenes. It is in CARIBU format
- **matching_ids**: dict which stores correspondances between new element indice, element indice in the input and specy indice
- **legume_grid**: boolean specifying if at least one l-egume grid is among the input scenes
- **id_legume_scene**: indice in the input scenes of a l-egume grid

Return type

dict of list, dict of list, bool, int

`trianglesmesh.vgx_to_caribu(file, id_element)`

Reads VGX file and converts them in CARIBU scene format line is a leaf triangle if R column != 42 :param file: path name of the file :type file: string :param id_element: element indice where the triangulation will be stored :type id_element: int :return: triangulation in CARIBU format {id_element : [triangle,]} :rtype: dict of list

`trianglesmesh.apply_transformations(cscene, matching_ids, transformations, cscene_unit)`

Applies geometric transformations on some part of the triangulation set in input datas Each transformation applies on all triangles from the same input scene.

Parameters

- **cscene** (*dict of list*) – LightVegeManager triangulations mesh
- **matching_ids** (*dict*) – dict that matches new element indices in cscene with specy indice and input element indice,

```
matching_ids = { new_element_id : (input_element_id, specy_id)}
```

this dict allows us to look how species there is the inputs geometric data

- **transformations** – dict containing which geometric to apply on which element

Possible transformations:

- ["scenes unit"] = {id_scene: unit}
- ["rescale"] = {id_scene: h}
- ["translate"] = {id_scene: vector}
- ["xyz orientation"] = {id_scene: orientation}

id_scene is the index in the input geometric scenes list

Parameters

cscene_unit (*string*) – measure unit of cscene

Raises

- **ValueError** – unit is not in the list ['mm', 'cm', 'dm', 'm', 'dam', 'hm', 'km']
- **ValueError** – unit is not in the list ['mm', 'cm', 'dm', 'm', 'dam', 'hm', 'km']
- **ValueError** – xyz orientation is not one of "x+ = S", "x+ = E", "x+ = W", "x+ = N"

Returns

cscene with transformations applied to inputs scene parts in the global mesh

Return type

dict of list

```
trianglesmesh.create_heterogeneous_canopy(geometrical_model, mtg=None, nplants=50,
                                          var_plant_position=0.03, var_leaf_inclination=0.157,
                                          var_leaf_azimut=1.57, var_stem_azimut=0.157,
                                          plant_density=250, inter_row=0.15, id_type=None,
                                          seed=None)
```

Duplicate a plant in order to obtain a heterogeneous canopy.

Parameters

- **nplants** (*int*) – the desired number of duplicated plants
- **var_plant_position** (*float*) – variability for plant position (m)
- **var_leaf_inclination** (*float*) – variability for leaf inclination (rad)
- **var_leaf_azimut** (*float*) – variability for leaf azimut (rad)
- **var_stem_azimut** (*float*) – variability for stem azimut (rad)
- **id_type** (*string*) – precise how to set the shape id of the elements : None, plant or organ

Returns

duplicated heterogenous scene and its domain

Return type

openalea.plantgl.all.Scene, (float)

```
trianglesmesh.random_triangle_generator(worldsize=(0, 100), spheresize=(1.0, 1.0),
                                       sigma_angle=(3.141592653589793, 3.141592653589793),
                                       theta_angle=(0.7853981633974483, 0.6283185307179586))
```

Generate a random based on parameters

Vertices are generated on a surface of a sphere

Args:

worldsize (tuple, optional): min and max where sphere center can be generated. Defaults to (0,100). sphere-size (tuple, optional): mean and std of the sphere size. Defaults to (1.,1.). sigma_angle (tuple, optional): mean and std of the spherical angle on xy plane. Defaults to (math.pi, math.pi). theta_angle (tuple, optional): mean and std of the zenithal angle. Defaults to (math.pi/4, math.pi/5).

Returns:

list of 3 3-tuples: triangles defined by 3 xyz points

2.7.17 voxelsmesh module

voxelsmesh

Builds and handles axis oriented voxels mesh

`voxelsmesh.compute_grid_size_from_trimesh(pmin, pmax, dv, grid_slicing=None)`

Dynamically compute number of voxels for each axis in the grid The grid is ajusted to be the smallest box containing another mesh

Parameters

- **pmin** (*list*) – Minimum point of a mesh [*x*, *y*, *z*]
- **pmax** (*list*) – Maximum point of a mesh [*x*, *y*, *z*]
- **dv** (*list*) – size a voxel in each direction [*dx*, *dy*, *dz*]
- **grid_slicing** (*string*, *optional*) – possibility to force the ground to be at *z*=0, defaults to None

Returns

number of voxels in each direction *x*, *y* and *z*

Return type

int, int, int

`voxelsmesh.tessellate_trimesh_on_grid(trimesh, ratpgrid, levelmax)`

Loop on all triangles of a triangulation to tessellate them for better matching a grid of voxels Triangles will subdivide on sides of voxels respecting a certain maximum level

Parameters

- **trimesh** (*dict of list*) – triangles mesh aggregated by indice elements
- ```
{ id : [triangle1, triangle2, ...]}
```
- **ratpgrid** (*pyratp.grid*) – RATP grid of voxels
  - **levelmax** (*int*) – maximum level for subdividing triangles

#### Returns

a copy of trimesh with subdivided triangles

#### Return type

dict of list

`voxelsmesh.fill_ratpgrid_from_trimesh(trimesh, matching_ids, ratpgrid, stems_id=None, nb_input_scenes=0)`

Fills a RATP grid from a triangulation. It gives barycenters and areas of triangles to update the leaf area density in the corresponding voxel.

#### Parameters

- **trimesh** (*dict of list*) – triangles mesh aggregated by indice elements
- ```
{ id : [triangle1, triangle2, ...]}
```
- **matching_ids** (*dict*) – dict that matches new element indices in cscene with specy indice and input element indice,

```
matching_ids = { new_element_id : (input_element_id, specy_id)}
```

this dict allows us to look how species there is the inputs geometric data

- **ratpgrid** (*pyratp.grid*) – RATP grid of voxels
- **stems_id** (*list of 2-tuple, optional*) – list of potential stems element in the input scenes, defaults to None
- **nb_input_scenes** (*int, optional*) – number of input geometrical scenes. It can be different with number of species if there is a l-egume grid in the input with several species in it, defaults to 0

Returns

copy of ratpgrid with leaf area density values from barycenters and areas of the input triangles

Return type

pyratp.grid

`voxelsmesh.fill_ratpgrid_from_legumescene(legumescene, ratpgrid, nb0)`

Fills a RATP grid from a l-egume grid It updates ratpgrid.

Parameters

- **legumescene** (*dict*) – l-egume grid represented by a dict with two entries:
 - "LA": equivalent to m_lais in l-egume, a numpy.array of dimension (nent, nz, ny, nx) which represents leaf area in each voxel for each specy. nz=0 is the top layer
 - "distrib": equivalent to ls_dif in l-egume, a numpy.array of dimension (nent, nclasses) which represents the global leaf angle distribution for each input specy

Note: legumescene is the only input geometric scene which can handle several species

- **ratpgrid** (*pyratp.grid*) – RATP grid of voxels. nz=0 is the top layer
- **nb0** (*int*) – number of empty layers from top of the canopy and maximum z layers in m_lais

`voxelsmesh.reduce_layers_from_trimesh(trimesh, pmax, dxyz, nxyz, matching_ids, ids=None)`

Number of empty layers in a grid of voxels, from the top of the canopy to the last expected layer. It computes this number from a triangles mesh

Parameters

- **trimesh** (*dict of list*) – triangles mesh aggregated by indice elements
- **pmax** (*list*) – Maximum point of a mesh [x, y, z]
- **dxyz** (*list*) – size of sides of a voxel [dx, dy, dz]
- **nxyz** (*list*) – number of voxels in each direction [nx, ny, nz], nz is the expected number of layers
- **matching_ids** (*dict*) – dict that matches new element indices in cscene with specy indice and input element indice,

```
matching_ids = { new_element_id : (input_element_id, specy_id)}
```

this dict allows us to look how species there is the inputs geometric data

- **ids** (*list of int, optional*) – list of specy indices considered not empty, defaults to None

Returns

number of empty layers between top of the canopy (represented by `trimesh`) and `nxyz[2]`

Return type

int

CONTACT

For any question, please submit to <https://github.com/mwoussen/lightvegemanager/issues>.

AUTHORS

- Maurane Woussen
- Romain Barillot
- Didier Combes
- Gaëtan Louarn

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FUNDING

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