

VIT

Vellore Institute of Technology

(Deemed to be University under section 3 of UGC Act, 1956)

B.Tech. Winter Semester 2023-24 School Of Computer Science and Engineering (SCOPE)

Digital Assignment - I Embedded Systems

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Prepare a detailed analysis on the Automatic Garden Watering System in the following aspects (Digital or Hand written).

- Purpose and significance of the project.
- Requirement Analysis,
- Functional Diagram,
- Block Diagram, UML Diagrams (Use Case Diagram and/or/Sequence Diagram)

1.1 Answer

Purpose

The primary purpose of an Automatic Garden Watering System is to automate the process of watering plants in a garden or any designated area. It aims to deliver the right amount of water to plants at the right time, without manual intervention.

Significance

- Water Conservation: Optimizes water usage, reducing waste.
- Time Savings: Automates a time-consuming chore.
- Convenience: Provides consistent watering, even when the user is away.
- Plant Health: Promotes healthier plant growth through consistent moisture.

Requirement Analysis

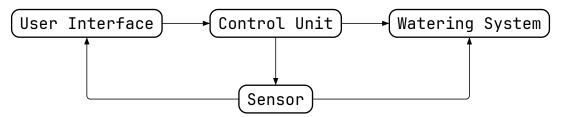
Functional Requirements:

- Soil Moisture Sensing: Detect soil moisture levels.
- Automated Watering: Trigger water flow when moisture is low.
- Adjustable Thresholds: Allow users to set moisture trigger points.
- Programmable Schedules: Enable watering at set times/intervals.
- Manual Override: Provide a manual on/off switch.

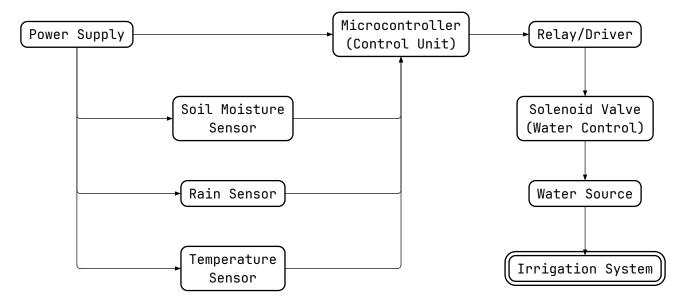
Non-Functional Requirements:

- Reliability: Consistent operation.
- Durability: Weather-resistant components.
- Power Efficiency: Minimize energy consumption.
- Ease of Use: Simple user interface.
- Safety: No electrical or water hazards.

Functional Diagram



Block Diagram



Describe the special purpose register used for interrupt configuration. Assume that two switches are connected to pin p3.2 p3.3 write a program to monitor the switch and perform the following using external hardware interrupt. if SW1=0, FLASH port0 with (FF to 00) if SW2 =0 , FLASH port2 with (55 to AA)

2.1 Answer

```
Ans 2:
Interrupt Enable (IE) is the special purpose register used to manage and configure interrupts.
 IE Register But Dotail.
            Description
  BIT
              alabal Internet 0/1
    7
             Reserved
             Times 2 Interryt Enable 0/1
    6
    5
             Serial Port Interryt Enable 0/1
    4
             Timer | Interryt Enable 0/1
             External Interrupt | Enable 0/1
             Times O Interrupt Enable 0/1
             External Interrept O Enable 0/1
Here Bito is controlled by P3.2 and Bit 2 is controlled by
 P3.3.
 Brogram to Monidor Switches and Flach.
 ORG OOM
LJMP MAIN
ORG O3H
LJMP INTO-ISR
ORG 01311
LJMP INTILISR
MAIN:
  MOV IE, # 100001018.
  SETB P3.2
  SETB P3.3
   LOOP:
      SJMP LOOP
```

```
INTO_ISR
   JB P3 2, INTO. EXIT
   MOV A, #OFFH
   LOOPI:
     MOV PO, A
     ACALL DELAY
     CLRC
     RLC A
    JC JNTO-EXIT
    JMP 200P1
   INTO_EXIT
     RETI
INTILISR
   JB P3.3
   MOV A, #55H
                           of allowing out yourse
   LOOP2:
                              and the day of
     MOV PZ, A
     ACALL DELAY
                          and a section of the section of the section of
     CPL A
     CINE A, # OAAH, LOOP2
     MOV P2, A
                            The same of the second
     ACALL DELAY
   INTI-EXIT:
      RETI
DELAY:
   MOV R7,# 255
   LOOP3:
     DJNZ R7, LOOP3
      RET
END
```

The 8051 microcontroller is configured for serial communication at a baud rate of 9600 using a crystal frequency of 11.0592 MHz. The UART is set in Mode 1 (8-bit data, variable baud rate), and Timer 1 is used in Mode 2 (8-bit auto-reload mode) to generate the baud rate. What value should be loaded into the Timer 1 TH1 register to achieve the desired baud rate?

3.1 Answer

```
Ans 3-
We know: -
Band Rate = Oscillator Frequency
32 ×12 × (256 - TMI)
Then,
 TMI = 256 - Oscillator Frequency
32×12× Band Rate
 Given : -
   · Oscillator Frequency = 11.0592 MMz.
   · Band Rate = 9600
 Then
 TMI = 256 - 11.0592 x106
                   32×12 × 9600
        = 253
        = OxFD
Then FD should be loaded to Timer 1 THI
 Code: -
 MOV TMOD, # 20H
        THI, #OFOM
 MOV
  MOV SCON, # 50H
```

Draw the following in A3.

- 1. architecture of 8051 microcontroller
- 2. PIn diagram
- 3. RAM (4 register banks with its address, bit addressable field)
- 4. SPR with address
- 5. TCON
- 6. TMOD
- 7. SCON
- 8. PCON
- 9. DPTR

4.1 Answer

