view frames Result Recorded at time: 1645975730.351 map Broadcaster: /slam gmapping Average rate: 20.202 Hz

Most recent transform: 1645975730.361 (-0.010 sec old) Buffer length: 4.950 sec odom Broadcaster: /vacumm hw main Average rate: $100.\overline{206}$ Hz Most recent transform: 1645975730.289 (0.062 sec old) Buffer length: 4.860 sec base_footprint Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1645975730.351 sec old) Buffer length: 0.000 sec base link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 29.608 Hz Average rate: 29.608 Hz Most recent transform: 0.000 (1645975730.351 sec old) Most recent transform: 1645975730.149 (0.202 sec old) Most recent transform: 1645975730.149 (0.202 sec old) Buffer length: 4.830 sec Buffer length: 0.000 sec Buffer length: 4.830 sec camera link left wheel right wheel Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Broadcaster: /camera base link Average rate: 10000.000 Hz Most recent transform: 0.000 (1645975730.351 sec old) Most recent transform: 0.000 (1645975730.351 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera depth frame camera_rgb_frame Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{0}0$ Hz Most recent transform: 0.000 (1645975730.351 sec old) Most recent transform: 0.000 (1645975730.351 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera depth optical frame camera rgb optical frame