view frames Result Recorded at time: 1648662231.745 odom Broadcaster: /ekf localization Average rate: $\overline{2}8.924$ Hz Most recent transform: 1648662231.781 (-0.036 sec old) Buffer length: 4.979 sec base footprint Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1648662231.745 sec old) Broadcaster: /base_footprint_to_imu_link Average rate: 10000.000 Hz Most recent transform: 0.000 (1648662231.745 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec base_link imu_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 38.229 Hz Average rate: 38.229 Hz Most recent transform: 0.000 (1648662231.745 sec old) Most recent transform: 1648662231.731 (0.014 sec old) Most recent transform: 1648662231.731 (0.014 sec old) Buffer length: 0.000 sec Buffer length: 4.970 sec Buffer length: 4.970 sec left_wheel right_wheel camera link Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (1648662231.745 sec old) Buffer length: 0.000 sec camera rgb frame Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1648662231.745 sec old) Most recent transform: 0.000 (1648662231.745 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera depth frame camera rgb optical frame Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{0}0$ Hz Most recent transform: 0.000 (1648662231.745 sec old) Buffer length: 0.000 sec

camera depth optical frame