

COMPUTER ARCHITECTURE

LECTURE 8

BY NDUMISO E. KHUMALO

ASSEMBLY LANGUAGE, RISC, SISC AND PARALLEL PROCESSING



Objective

- Assembly Language
- RISC and CISC
- Parallel Processing



- Assembly language is a low-level programming language for a computer or other programmable device specific to a particular computer architecture in contrast to most high-level programming languages, which are generally portable across multiple systems.
- Assembly language is converted into executable machine code by a utility program referred to as an assembler like NASM, MASM, etc.



- Each personal computer has a microprocessor that manages the computer's arithmetical, logical, and control activities.
- Each family of processors has its own set of instructions for handling various operations such as getting input from keyboard, displaying information on screen and performing various other jobs.
- These set of instructions are called 'machine language instructions'.



- A processor understands only machine language instructions, which are strings of 1's and 0's.
- However, machine language is too obscure and complex for using in software development.

• So, the low-level assembly language is designed for a specific family of processors that represents various instructions in symbolic code and a more understandable form.



- Having an understanding of assembly language makes one aware of:
 - How programs interface with OS, processor, and BIOS;
 - How data is represented in memory and other external devices;
 - How the processor accesses and executes instruction;
 - How instructions access and process data;
 - How a program accesses external devices.



- Other advantages of using assembly language are:
 - It requires less memory and execution time;
 - It allows hardware-specific complex jobs in an easier way;
 - It is suitable for time-critical jobs;
 - It is most suitable for writing interrupt service routines and other memory resident programs.



- An assembly program can be divided into three sections:
 - − 1. The data section
 - The data section is used for declaring initialized data or constants.
 - This data does not change at runtime.
 - You can declare various constant values, file names, or buffer size, etc., in this section.
 - The syntax for declaring data section is: section.data



- 2. The bss Section

• The bss section is used for declaring variables. The syntax for declaring bss section is:

section.bss

- -3. The text section
 - The text section is used for keeping the actual code.
 - This section must begin with the declaration global _start, which tells the kernel where the program execution begins.
 - The syntax for declaring text section is:

```
section.text
global _start
_start:
```



Comments

- Assembly language comment begins with a semicolon (;).
- It may contain any printable character including blank. It can appear on a line by itself, like:
 - ; This program displays a message on screen
- or, on the same line along with an instruction, like –
 add eax, ebx ; adds ebx to eax



- Assembly language programs consist of three types of statements:
 - 1. Executable instructions or instructions
 - They tell the processor what to do.
 - Each instruction consists of an operation code (opcode).
 - Each executable instruction generates one machine language instruction.
 - 2. Macros.
 - Macros are basically a text substitution mechanism.



- Assembly language programs consist of three types of statements:
 - 3. The assembler directives or pseudo-ops
 - tell the assembler about the various aspects of the assembly process.
 - These are non-executable and do not generate machine language instructions.



- Assembly language statements are entered one statement per line.
- Each statement follows the following format:
 - [label] mnemonic [operands] [;comment]
 - The fields in the square brackets are optional.
 - A basic instruction has two parts:
 - the first one is the name of the instruction (or the mnemonic), which is to be executed
 - the second are the operands or the parameters of the command.



• The following are some examples of typical assembly language statements

```
TNC COUNT
                ; Increment the memory variable COUNT
MOV TOTAL, 48 ; Transfer the value 48 in the
                ; memory variable TOTAL
ADD AH, BH
               ; Add the content of the
                ; BH register into the AH register
AND MASK1, 128 ; Perform AND operation on the
                : variable MASK1 and 128
ADD MARKS, 10 ; Add 10 to the variable MARKS
MOV AL, 10 ; Transfer the value 10 to the AL register
```



• The following assembly language code displays the string 'Hello World' on the screen

```
section .text
  global _start
               :must be declared for linker (ld)
                  tells linker entry point;
_start:
               ;message length
       edx,len
   mov
      ecx,msg
                  ;message to write
  mov
               ;file descriptor (stdout)
      ebx,1
  mov
      eax,4 ;system call number (sys_write)
  mov
                  :call kernel
  int
      0x80
                  ;system call number (sys_exit)
      eax,1
  mov
                  :call kernel
   int
       0x80
section .data
msg db 'Hello, world!', 0xa ;string to be printed
len equ $ - msg ;length of the string
```



- The registers are defined as:
 - EAX Accumulator Register
 - EBX Base Register
 - ECX Counter Register
 - EDX Data Register
 - ESI Source Index
 - EDI Destination Index
 - EBP Base Pointer
 - ESP Stack Pointer



- To set up your environment for assembly language on Windows:
 - 1. Open command prompt (cmd) as an Administrator
 - 2. Type *wsl --install* and press Enter
 - 3. Enter your new Linux username and password when prompted to do so and press Enter
 - 4. Restart your machine
 - 5. Open command prompt (cmd) as an administrator and type wsl and press Enter



- To set up your environment for assembly language on Windows:
 - − 6. Type cd /mnt/c then press Enter to go to drive C:
 - 7. Create a folder named nasm by typing *mkdir nasm* and press Enter

− 8. Type *cd nasm*



- 9. To install nasm, follow these steps:
 - i. First check if it is already installed, by typing *whereis nasm* and press Enter. It should show the path where nasm is installed. If not continue to ii below.
 - ii. Type *sudo apt-get update* and press Enter. Supply your password if prompted to do so. Wait until it's done.
 - iii. Type *sudo apt-get -y install nasm* and press Enter. Supply your password if prompted to do so. Wait until it's done
- Type whereis nasm and press enter to check if it has been installed
 - It should show the path where nasm is installed



- Compiling and Linking an Assembly Program in NASM
 - Make sure you have set the path of nasm and ld binaries in your PATH environment variable. Now, take the following steps for compiling and linking the above program –
 - 1. Type the code using a text editor and save it as *hello.asm*
 - 2. Make sure that you are in the same directory as where you saved hello.asm
 - 1. Preferably, save it in the nasm folder created earlier



- 4. To assemble the program, type nasm -f elf hello.asm
- 5. If there is any error, you will be prompted about that at this stage. Otherwise, an object file of your program named *hello.o* will be created.
- 6. To link the object file and create an executable file named hello, type *ld -m elf_i386 -s -o hello hello.o*
- 7. Execute the program by typing ./hello



 Download the functions.asm file from https://classroom.google.com/c/NTkwNjIxNzg4OD
 c5/m/NjQ0OTgxNzI5NDI4/details to help you with the next two problems

Copy it to the nasm folder



Assembly Language; Addition

• Type the following program. Assembly it and run it.

```
%include 'functions.asm'
SECTION .text
global _start
_start:
        eax, 30; move our first number into eax
  mov
  mov ebx, 9; move our second number into ebx
  add eax, ebx; add ebx to eax
        iprintLF; call our integer print with linefeed function
  call
  call
        quit
```



Assembly Language: Subtraction

• Type the following program. Assembly it and run it.

```
%include 'functions.asm'
SECTION .text
global _start
_start:
        eax, 30; move our first number into eax
  mov
      ebx, 9; move our second number into ebx
  mov
        eax, ebx; subtract ebx from eax
  sub
        iprintLF; call our integer print with linefeed function
  call
  call
        quit
```



Assembly Language: Multiplication

• Type the following program. Assembly it and run it.

```
%include 'functions.asm'
SECTION .text
global _start
_start:
        eax, 30; move our first number into eax
  mov
  mov ebx, 9; move our second number into ebx
       ebx; multiply ebx by eax
  mul
        iprintLF; call our integer print with linefeed function
  call
  call
        quit
```



Assembly Language: User input

Type the following program. Assembly it and run it.

```
%include
                 'functions.asm'
SECTION .data
msg1
                     'Please enter your name: ', Oh
                                                         ; message string asking user for input
            db
                     'Hello, ', Oh
                                                          ; message string to use after user has entered their name
msg2
SECTION .bss
sinput:
                    255
                                                          ; reserve a 255 byte space in memory for the users input string
            resb
SECTION .text
global _start
start:
    mov
            eax, msg1
    call
            sprint
                            ; number of bytes to read
            edx, 255
            ecx, sinput
                             ; reserved space to store our input (known as a buffer)
    mov
            ebx, 0
                             ; read from the STDIN file
    mov
                             ; invoke SYS READ (kernel opcode 3)
            eax, 3
    mov
    int
            80h
    mov
            eax, msg2
    call
            sprint
                             ; move our buffer into eax (Note: input contains a linefeed)
            eax, sinput
    mov
    call
            sprint
                             ; call our print function
    call
            quit
```



- What are RISCs and why do we need them?
 - RISC architectures represent an important innovation in the area of computer organization.
 - The RISC architecture is an attempt to produce more CPU power by simplifying the instruction set of the CPU.

• The opposed trend to RISC is that of complex instruction set computers (CISC).



- Both RISC and CISC architectures have been developed as an attempt to cover the semantic gap
- The Main Characteristics of RISC Architectures
 - The instruction set is limited and includes only simple instructions.
 - The goal is to create an instruction set containing instructions that execute quickly; most of the RISC instructions are executed in a single machine cycle (after fetched and decoded).



- Pipeline operation (without memory reference):
- RISC instructions, being simple, are hard-wired, while CISC architectures have to use microprogramming in order to implement complex instructions.
- Having only simple instructions results in reduced complexity of the control unit and the data path; as a consequence, the processor can work at a high clock frequency.



- The instruction set is limited and includes only simple instructions.
- The goal is to create an instruction set containing instructions that execute quickly; most of the RISC instructions are executed in a single machine cycle (after fetched and decoded).
- The pipelines are used efficiently if instructions are simple and of similar execution time.



 Complex operations on RISCs are executed as a sequence of simple RISC instructions. In the case of CISCs they are executed as one single or a few complex instruction.



- Are RISCs Really Better than CISCs?
 - RISC architectures have several advantages
 - However, a definitive answer to the above question is difficult to give.
 - A lot of performance comparisons have shown that benchmark programs are really running faster on RISC processors than on processors with CISC characteristics.



- Are RISCs Really Better than CISCs?
 - However, it is difficult to identify which feature of a processor produces the higher performance. Some "CISC fans" argue that the higher speed is not produced by the typical RISC features but because of technology, better compilers, etc.
 - An argument in favor of the CISC: the simpler instruction set of RISC processors results in a larger memory requirement compared to the similar program compiled for a CISC architecture



- Are RISCs Really Better than CISCs?
 - Most of the current processors are not typical RISCs or CISCs but try to combine advantages of both approaches



Why Parallel Computation?

The need for high performance!

- Two main factors contribute to high performance of modern processors:
 - 1. Fast circuit technology
 - -2. Architectural features:
 - large caches, multiple fast buses, pipelining, superscalar architectures (multiple funct. units)



- However: Computers running with a single CPU, often are not able to meet performance needs in certain areas:
 - -1. Fluid flow analysis and aerodynamics;
 - −2. Simulation of large complex systems, for example in physics, economy, biology, technic;
 - -3. Computer aided design
 - -4. Multimedia.



• Applications in those domains are characterized by a very high amount of numerical computation and/or a high quantity of input data.



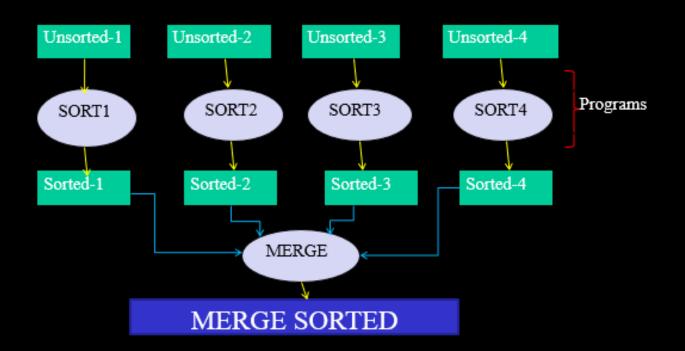
- A Solution: Parallel Computers
 - One solution to the need for high performance: architectures in which several CPUs are running in order to solve a certain application.
 - -Such computers have been organized in very different ways.



- -Some key features:
 - number and complexity of individual CPUs
 - availability of common (shared memory)
 - interconnection topology
 - performance of interconnection network
 - I/O devices



• Parallel Programs : Parallel sorting





HIGH PERFOMANCE COMPUTING

- There are different ways to classify parallel computers.
 One of the more widely used classifications, in use since 1966, is called Flynn's Taxonomy.
- Flynn's taxonomy distinguishes multi-processor computer architectures according to how they can be classified along the two independent dimensions of Instruction and Data.
- Each of these dimensions can have only one of two possible states: Single or Multiple.



HIGH PERFOMANCE COMPUTING

 The matrix below defines the 4 possible classifications according to Flynn

SISD	SIMD
MISD	MIMD

 Flynn's Classification of Computer Architectures is based on the nature of the instruction flow executed by the computer and that of the data flow on which the instructions operate.



HIGH PERFOMANCE COMPUTING

- 1. Single Instruction stream, Single Data stream (SISD)
- 2. Single Instruction stream, Multiple Data stream (SIMD)



- SIMD (Single-Instruction Multi-Data)
 - All processors in a parallel computer execute the same instructions but operate on different data at the same time.
 - Only one program can be run at a time.
 - Processors run in synchronous, lockstep function
 - Shared or distributed memory
 - Less flexible in expressing parallel algorithms, usually exploiting parallelism on array operations, e.g. F90



- MIMD (Multi-Instruction Multi-data)
 - All processors in a parallel computer can execute different instructions and operate on different data at the same time.
 - Parallelism achieved by connecting multiple processors together
 - Shared or distributed memory
 - Different programs can be run simultaneously
 - Each processor can perform any operation regardless of what other processors are doing.



THE END

BITCA3111