

8:30 - 9:20, WAT 112  
9:30 - 10:20, KEL 303

## Section 2.4. Dimension; nullspace, rowspace and column space

Recall from last time:

If  $V$  is a vector space, a basis for  $V$  is a collection  $v_1, \dots, v_n \in V$  such that:

- $v_1, \dots, v_n$  (span  $V$ ) means: any  $v \in V$  can be written  $v = c_1v_1 + \dots + c_nv_n$  for some scalars  $c_i$ .
- $v_1, \dots, v_n$  are (linearly independent) means: if  $c_1v_1 + \dots + c_nv_n = 0$ , then  $c_1 = c_2 = \dots = c_n = 0$ .

Examples:

- $\mathbb{R}^3$  has 'standard basis'  $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ , but there are many others e.g.  $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$  or  $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$  from last lecture.
- $M_{m \times n}(\mathbb{R})$  has basis  $E_{1,1}, E_{1,2}, \dots, E_{1,n}, E_{2,1}, \dots, E_{2,n}, \dots, E_{m,1}, \dots, E_{m,n}$ . Again, there are others, e.g.  $\begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 & \dots & 1 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}$  for  $M_{2 \times 2}(\mathbb{R})$

Theorem (see 2.9 in text - not obvious!)

If  $v_1, \dots, v_n$  and  $w_1, \dots, w_m$  are both bases for the

same vector space  $V$ , then  $m=n$ .

Definition:

The dimension of a vector space is the number of elements in a basis. Notation for the dimension of  $V$ :

$$\boxed{\dim(V)}$$

Examples:

- $\dim(\mathbb{R}^3) = 3$ , and more generally  $\dim(\mathbb{R}^n) = n$
- $\dim(\mathbb{R}[x]_{\leq 2}) = 3$ , and more generally  $\dim(\mathbb{R}[x]_{\leq n}) = n+1$ .

Comments:

- Some vector spaces have bases with infinitely many vectors

*(all polynomials)*

leg. a basis for  $\mathbb{R}[x]$  is  $1, x, x^2, x^3, \dots$ )  
In this case, e.g. the dimension of  $V$  is infinite  
Notation:  $\dim(V) = \infty$ .

(In this course, you will mainly focus on finite dimensional vector spaces).

- If  $V$  is the 0 vector space, we write  $\dim(V)=0$ .

Some important properties of dimension (see 2.11 and 2.12):

Let  $V$  be a vector space with  $\dim(V) = n$ . Then:

- 1) If  $v_1, \dots, v_k \in V$  are linearly independent, then  $k \leq n$  and there are  $v_{k+1}, \dots, v_n \in V$  with  $v_1, \dots, v_k, v_{k+1}, \dots, v_n$  a basis.  
"In. Ind. collection  
cannot be too big"
- 2) If  $v_1, \dots, v_k \in V$  span  $V$ , then  $k \geq n$ , and some collection of  $n$  vectors from  $v_1, \dots, v_k$  is a basis.  
"Spanning collection  
cannot be too small"

Consequences:

- If  $v_1, \dots, v_n$  span  $V$ , they are a basis.
  - If  $v_1, \dots, v_n$  are linearly independent, they are a basis.
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Example:

Which (if any) of the following collections is a basis for  $\mathbb{R}^3$ ?

- a)  $\left\{\begin{pmatrix} 1 \\ 3 \end{pmatrix}, \begin{pmatrix} 4 \\ 6 \end{pmatrix}\right\}$
- b)  $\left\{\begin{pmatrix} 1 \\ 3 \end{pmatrix}, \begin{pmatrix} 4 \\ 8 \end{pmatrix}, \begin{pmatrix} 7 \\ 9 \end{pmatrix}\right\}$
- c)  $\left\{\begin{pmatrix} 1 \\ 3 \end{pmatrix}, \begin{pmatrix} 4 \\ 8 \end{pmatrix}, \begin{pmatrix} 7 \\ 9 \end{pmatrix}, \begin{pmatrix} 10 \\ 12 \end{pmatrix}\right\}$

Solutions:

- a) No: has too few vectors (so cannot span).
- c) No: has too many vectors (so cannot be linearly independent).  
*not all of  $c_1, c_2, c_3$  zero*
- b) Need to check if  $c_1 \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} + c_2 \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix} + c_3 \begin{pmatrix} 7 \\ 9 \\ 9 \end{pmatrix} = \begin{pmatrix} 8 \\ 8 \\ 8 \end{pmatrix}$  has non-trivial solutions,  
i.e. if  $\begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 9 \\ 2 & 6 & 9 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 8 \\ 8 \\ 8 \end{pmatrix}$  has non-trivial solutions.

Check linear independence by row reducing:

$$\begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 9 \\ 2 & 6 & 9 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 7 \\ 0 & -3 & -6 \\ 0 & -6 & -12 \end{bmatrix} \begin{array}{l} R_2 - 2R_1 \\ R_3 - 3R_1 \end{array}$$

$$\rightarrow \begin{bmatrix} 1 & 4 & 7 \\ 0 & -3 & -6 \\ 0 & 0 & 0 \end{bmatrix} \quad R_3 - 2R_2$$

As we have a row of zeros, there are no conditions on  $c_3$ , and we see that there are infinitely many solutions.

Conclude: the collection is not a basis (as not linearly independent)

### Null space, row space, column space

Let  $A \in M_{m \times n}(\mathbb{R})$

number rows  $\nwarrow$  number columns

There are three important vector spaces associated with  $A$ :

- The column space, which is the subspace of  $M_{n \times 1}(\mathbb{R})$  spanned by the columns of  $A$ .

Notation:  $\boxed{CS(A)}$

- The row space, which is the subspace of  $M_{1 \times n}(\mathbb{R})$  spanned by the rows of  $A$

Notation:  $\boxed{RS(A)}$

- The null space which is the subspace of  $\mathbb{R}^n$  of vectors  $x$  such that  $Ax = 0$ .

Notation:  $\boxed{NS(A)}$

Example:

Let  $A = \begin{bmatrix} 1 & 0 & -1 & 3 \\ 2 & 1 & 4 & -1 \\ 4 & 1 & 2 & 5 \end{bmatrix} \in M_{3 \times 4}(\mathbb{R})$

Find basis for:

- a)  $\text{RS}(A)$
- b)  $\text{NS}(A)$

Solutions:

(a) WRONG:  $\{1 \ 0 \ -1 \ 3\}$ ,  $\{2 \ 1 \ 4 \ -1\}$ ,  $\{4 \ 1 \ 2 \ 5\}$

(Idea: row reduction does not change row space, so  
row reduce until we get a linearly independent set)

The reduced row echelon form is:  $\begin{bmatrix} 1 & 0 & -1 & 3 \\ 0 & 1 & 6 & -7 \\ 0 & 0 & 0 & 0 \end{bmatrix} (*)$

So: a basis is  $\boxed{\{1 \ 0 \ -1 \ 3\}, \{0 \ 1 \ 6 \ -7\}}$

b) Can read off solutions from (\*):

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} x_3 - 3x_4 \\ -6x_3 + 7x_4 \\ x_3 \\ 2x_4 \end{pmatrix} = x_3 \begin{pmatrix} 1 \\ -6 \\ 0 \\ 1 \end{pmatrix} + x_4 \begin{pmatrix} -3 \\ 7 \\ 0 \\ 1 \end{pmatrix}$$

So: a basis is

$$\boxed{\begin{pmatrix} 1 \\ -6 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} -3 \\ 7 \\ 0 \\ 1 \end{pmatrix}}$$

Notes:

- To find  $CS(A)$ , take transpose, or reduce to find basis for  $RS(A^T)$ , then transpose back.
- For  $A \in M_{m,n}(A)$ , the dimensions satisfy these relations:

$$\boxed{\dim(RS(A)) = \dim(CS(A))}$$

$$\boxed{\dim(CS(A)) + \dim(NS(A)) = n}$$

(see pages 102-3 in text).