

Math 307: Practice Midterm 1

Date of exam: November 24, in class

Instructions: You have 50 minutes. Calculators and notes are not allowed. This practice exam is slightly longer than the actual midterm.

Problem 1. State precise definitions of the following terms:

- (a) null space of A
- (b) “eigenvector” and “eigenvalue” of a matrix A

Problem 2. Determine whether the following statements are true or false. You don’t need to show your work or justify your answer.

- (a) If A is an $n \times n$ matrix of rank $n - 1$, then its nullspace is a line through the origin.
- (b) The matrix $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ is a rotation
- (c) The vectors $\begin{bmatrix} 1 \\ 1 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix}$ span a dimension 3 subspace of \mathbb{R}^4 .
- (d) If A is a 5×8 matrix with $\dim(CS(A)) = 3$, then $\dim(NS(A)) = 2$.
- (e) Let A and B be $n \times n$ matrices. If $T(v) = Av$ and $S(v) = Bv$ for all $v \in \mathbb{R}^n$, then $T \circ S(v) = ABv$.
- (f) The transformation $T(x) = x + 11$ is linear.
- (g) The matrix $A^\top A$ is symmetric.
- (h) The columns of an invertible $n \times n$ matrix form a basis of \mathbb{R}^n .
- (i) If the columns of A are linearly independent, then $Ax = b$ has exactly one solution for every b .
- (j) If v is an eigenvector of A , then it is an eigenvector of A^2
- (k) Let A be an $m \times n$ matrix, and let $T(X) = AX$ be a linear transformation. Then the domain of T is \mathbb{R}^n and the range is \mathbb{R}^m .
- (l) If A, B are $n \times n$ matrices, then $(A + B)^2 = A^2 + 2AB + B^2$.
- (m) Suppose the only solution to $Ax = 0$ (m equations, n unknowns) is $x = 0$. Then A has rank n .
- (n) Let A be an $n \times n$ matrix. If $Ax = 0$ for some nonzero vector x , then the equation $Ax = 0$ has infinitely many solutions.
- (o) The eigenvalues of a projection matrix are always 0 or 1.

5 hours: worksheet with tasks

- generate gene trees and plot the distributions etc
- focus more on interpretation and method development, biological interpretability
- 09:00-09:45 Introduction to Mendelian Randomization

Overview of MR and its applications
Key assumptions: relevance, independence, and exclusion restriction
Types of MR studies (one-sample, two-sample, bi-directional)

- 09:45-10:45 Challenges in Mendelian Randomization

Horizontal pleiotropy and methods to address it Sample overlap and measurement error Population stratification and genetic heterogeneity

- 10:45-11:00 Coffee Break

- 11:00-13:00 Hands-On Tutorial in R

Preparing exposure and outcome GWAS data Conducting basic MR analysis (TwoSampleMR R package) Robust methods: MR-Egger, weighted median, and leave-one-out analysis Interpreting and visualizing results

Problem 3. Let $A = \begin{bmatrix} 1 & 1 & 0 & 3 \\ 1 & 1 & 1 & -2 \\ 3 & 3 & 2 & -1 \end{bmatrix}$

- Find a basis for $CS(A)$.
- Find a basis for $RS(A)$.
- Find a basis for $NS(A)$.
- What is the rank of A ?
- Is A invertible?

Problem 4. [Note: there will be a problem like this on the exam.] Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the projection onto the line $y = -x$. Let $\alpha = \{e_1, e_2\}$

- Find two linearly independent eigenvectors β_1, β_2 of T and sketch them.
- What is $[T]_{\beta}^{\beta}$?
- Let P be the change-of-basis matrix from α to β . Find P and P^{-1} .
- Use your answer to the previous part to find $[T]_{\alpha}^{\alpha}$.
- What are the eigenvalues of T ?
- Verify that $[T]_{\alpha}^{\alpha}$ and $[T]_{\beta}^{\beta}$ have the same characteristic polynomial.

Problem 5. Let $A = \begin{bmatrix} 6 & -8 \\ 4 & -6 \end{bmatrix}$

- By what factor does the linear transformation of A scale area?
- Find the eigenvalues of A .
- For each eigenvalue of A , find a basis for the eigenspace.

Problem 6. Let $A = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$.

- Sketch the image of the unit square $\{(x, y) : 0 \leq x \leq 1 \text{ and } 0 \leq y \leq 1\}$ under the transformation of the matrix
- Compute the eigenvalues of A , and an eigenbasis for each eigenvalue.
- What is the inverse of A ?

Problem 7. Show that $\begin{bmatrix} 1 \\ 3 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$ form a basis for \mathbb{R}^3 .

Problem 8. Solve the following linear system:

$$\begin{aligned}2x + 3y &= 6 \\2x + y &= 2 \\x - y &= -1\end{aligned}$$

Provide a sketch and interpret your results geometrically.

Problem 9. Suppose T is a linear transformation such that $T \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 6 \end{bmatrix}$ and $T \begin{bmatrix} 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \end{bmatrix}$.

(a) Find $T \begin{bmatrix} 2 \\ 2 \end{bmatrix}$

(b) Find $T \begin{bmatrix} 5 \\ 1 \end{bmatrix}$

(c) Find $T \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

(d) Find $T \begin{bmatrix} a \\ b \end{bmatrix}$ where a, b are arbitrary real numbers.

(e) Write down a 2×2 matrix that gives the transformation T .