12 2025-09-22 | Week 05 | Lecture 12

This lecture is based on sections 2.1 and 2.2 in the textbook.

The nexus question of this lecture: What is a vector space?

12.1 Vector spaces

Definition 45 (Vector Space). A set V is called a **vector space** if there are operations called "vector addition" and "scalar multiplication" on V such that the following 2 "closure properties" properties hold

C1. $u + v \in V$ whenever $u, v \in V$ ("V is closed under vector addition")

C2. $cv \in V$ whenever $c \in \mathbb{R}$ and $v \in V$ ("V is closed under scalar multiplication")

and the following 8 algebraic properties hold:

A1. u + v = v + u for all $u, v \in V$ ("vector addition is commutative")

A2. u + (v + w) = (u + v) + w for all $u, v, w \in V$ ("vector addition is associative")

A3. There is a "zero vector" $\vec{0} \in V$ such that $v + \vec{0} = v$ for all $v \in V$ ("there is a zero vector")

A4. For each $v \in V$ there is an element -v such that v + (-v) = 0 ("every vector has an additive inverse")

A5. c(u+v)=cu+cv for all $c\in\mathbb{R}$ and all $u,v\in V$ ("scalar multiplication distributes over vector addition")

A6. (c+d)v = cv + dv for all $c, d \in \mathbb{R}$ and all $v \in V$ ("scalar multiplication distributes over scalar addition")

A7. c(dv) = (cd)v for all $c, d \in \mathbb{R}$ and all $v \in V$ ("scalar multiplication is associative")

A8. $1 \cdot v = v$ for all $v \in V$. ("multiplying a vector by one doesn't change it.")

These 10 properties are called the vector space axioms. The elements of V are called vectors.

Note that C1 and C2 just say that (1) the sum of two vectors is itself a vector, and (2) the act of scaling a vector returns a vector. Axioms A1-A8 say that the usual rules of algebra apply.

At heart, this is just a list of the essential properties of vectors that we are familiar with.

Example 46 (The *n*-dimensional vector space \mathbb{R}^n). We regard \mathbb{R}^n as the set of $n \times 1$ column vectors with real entries:

$$\mathbb{R}^n = \left\{ \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} : x_1, \dots, x_n \in \mathbb{R} \right\}.$$

The "vector addition" is defined as entrywise addition

$$\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} + \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} := \begin{bmatrix} x_1 + y_1 \\ \vdots \\ x_n + y_n \end{bmatrix}$$

and the "scalar multiplication" is defined for every real number c as

$$c \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} := \begin{bmatrix} cx_1 \\ \vdots \\ cx_n \end{bmatrix}$$

To check that \mathbb{R}^3 is a vector space, we have to verify each of the 8 vector space axioms.

End of Example 46. \square

12.2 Properties of Vector Spaces

Theorem 47 (Basic properties of vector spaces). Let V be a vector space. Then

- The zero vector $\vec{0} \in V$ is unique.
- If $u + v = \vec{0}$ then u = -v (i.e., the negative of v is unique.)
- For any $v \in V$, $0v = \vec{0}$.
- For any real number c, $\vec{c0} = \vec{0}$
- For any $v \in V$, (-1)v = -v.

Note about the proof of Theorem 47. The proofs of these properties are not so important, but it is worth thinking carefully about why basic properties like these need to be proved: while these properties might seem "obvious" for \mathbb{R}^n , general vector spaces may look very different from \mathbb{R}^n . See text for details.

12.3 Subspaces

Vector spaces can have smaller vector spaces sitting inside them.

Definition 48 (Subspace). A subset W of a vector space V is called a **subspace** of V if W is itself a vector space under the same operations of vector addition and scalar multiplication used by V.

We didn't really need to check all 8 axioms to verify that W is a subspace V. The important criteria to check are summarized in the following theorem

Theorem 49. Let W be a nonempty subset of a vector space V. Then W is a subspace iff the following conditions are satisfied:

- (i.) $u + v \in W$ whenever $u, v \in V$.
- (ii.) $cu \in W$ whenever $c \in \mathbb{R}$ and $u \in W$.

Proof sketch. The proof consists of checking that W satisfies the vector space axioms. Since $W \subseteq V$, most of them are satisfied automatically because they are "inherited" from V. The ones that aren't can be deduced from (i) and (ii). See text for details.

Example 50. Let W be the set

$$W := \left\{ \begin{bmatrix} x \\ y \\ 0 \end{bmatrix} : x, y \in \mathbb{R} \right\}$$

Then W is a subspace of \mathbb{R}^3 . By Theorem 49, to verify this, we first need to check that it is closed under vector addition and scalar multiplication.

End of Example 50. \square

Example 51. The set

$$A = \left\{ \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} : x, y \in \mathbb{R} \right\} \subseteq \mathbb{R}^2$$

does not form a subspace of \mathbb{R}^3 . This is because the sum of any two vectors in A has the form $\begin{bmatrix} * \\ * \\ 2 \end{bmatrix}$, which is not itself in A.

End of Example 51. \square

Example 52 (Important example). Let A be an $m \times n$ matrix. The solutions to the linear system

$$AX = 0$$

is a subspace in \mathbb{R}^n . We will check this example in the next class.

End of Example 52. \square