Fundamentals of Machine Learning for Predictive Data Analytics

Appendix C Differentiation Techniques for Machine Learning

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- Basic Concepts
- Derivatives of Continuous Functions
- The Chain Rule
- Partial Derivatives
- Summary

Imagine a car journey where we start out driving on a minor road at about 30mph and then move onto a highway where we drive at about 80mph before noticing an accident and braking suddenly.

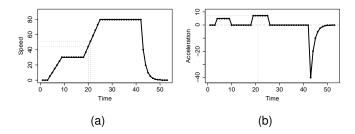


Figure: (a) the speed of a car during a journey along on the minor road before joining a motorway and finally coming to a sudden (safe) halt. (b) shows acceleration, the derivative of speed with respect to time, during this journey.

 Acceleration is a measure of the rate of change of speed over time.

The Chain Rule

- We can say more formally that acceleration is, in fact, the **derivative** of speed with respect to time.
- Differentiation is the set of techniques from calculus (the branch of mathematics that deals with how things change) that allows us to calculate derivatives.

 A continuous function, f(x), generates an output for every value of a variable x based on some expression involving x. For example:

$$f(x) = 2x + 3$$

 $f(x) = x^2$
 $f(x) = 3x^3 + 2x^2 - x - 2$

- The first function is known as a linear function as the output is a combination of only additions and multiplications
- The other two functions are known as polynomial functions as they include addition, multiplication and raising to exponents (we show a second order polynomial function, also known as a quadratic function and a third order polynomial function, also known as cubic function

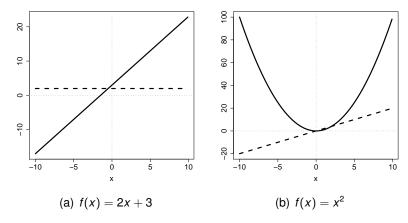


Figure: (a) - (b) Some examples of continuous functions, shown as solid lines, and their derivatives, shown as dashed lines.

Derivatives and Slopes!

• The derivative of a function f(x) with respect to x also gives us the slope of the function at that value of x.

• To actually calculate the derivative, referred to as $\frac{d}{dx}f(x)$, of a simple continuous function, f(x), we use a small number of differentiation rules:

1)
$$\frac{d}{dx}\alpha = 0$$

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2) $\frac{d}{dx}\alpha x^n = \alpha \times n \times x^{n-1}$

3)
$$\frac{d}{dx}a + b = \frac{d}{dx}a + \frac{d}{dx}b$$

4)
$$\frac{d}{dx}\alpha \times c = \alpha \times \frac{d}{dx}c$$

(where α is any constant)

(where a and b are expressions that may or may not contain x) (where α is any constant and c is an expression containing X)

• The function $f(x) = (x^2 + 1)^2$ cannot be differentiated using the rules just described because it is a **composite** function - it is a function of a function.

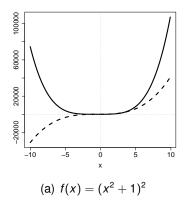


Figure: A composite function and it's derivative.

- We can rewrite f(x) as $f(x) = (g(x))^2$ where $g(x) = x^2 + 1$.
- The differentiation chain rule allows us to differentiate functions of this kind of function.

The Chain Rule

Basic Concepts

$$\frac{d}{dx}f(g(x)) = \frac{d}{dg(x)}f(g(x)) \times \frac{d}{dx}g(x) \tag{1}$$

• Applying this to the example $f(x) = (x^2 + 1)^2$ we get:

$$\frac{d}{dx}(x^2+1)^2 = \frac{d}{d(x^2+1)}(x^2+1)^2 \times \frac{d}{dx}(x^2+1)$$

$$= (2 \times (x^2+1)) \times (2x)$$

$$= 4x^3 + 4x$$

- Some functions are not defined in terms of just one variable.
- For example, $f(x, y) = x^2 y^2 + 2x + 4y xy + 2$ is a function defined in terms of two variables x and y.
- Rather than defining a curve (as was the case for all of the previous examples) this function defines a surface.

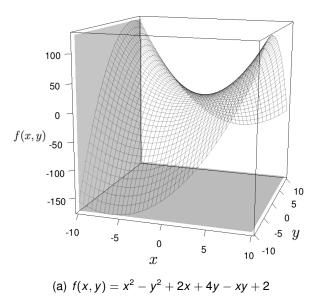


Figure: A continuous function in two variables, x and y.

Summary

- Using partial derivatives offers us an easy way to calculate the derivative of a function like this.
- A partial derivative (denoted by the symbol \(\partial \)) of a function
 of more than one variable is its derivative with respect to
 one of those variables with the other variables held
 constant.

 For the example function $f(x, y) = x^2 - y^2 + 2x + 4y - xy + 2$ we get two partial derivatives:

$$\frac{\partial}{\partial x}(x^2 - y^2 + 2x + 4y - xy + 2) = 2x + 2 - y$$

where the terms y^2 and 4y are treated as constants as they do not include x, and:

$$\frac{\partial}{\partial y}(x^2 - y^2 + 2x + 4y - xy + 2) = -2y + 4 - x$$

where the terms x^2 and 2x are treated as constants as they do not include y. Figures 5(b) [16] and 5(c) [16] show these partial derivatives.

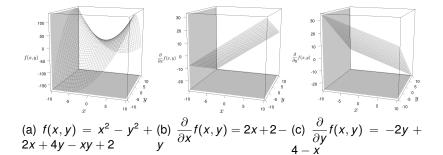


Figure: (a) a continuous function in two variables, x and y. (b) the partial derivative of this function with respect to x. (c) the partial derivative of this function with respect to y.

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