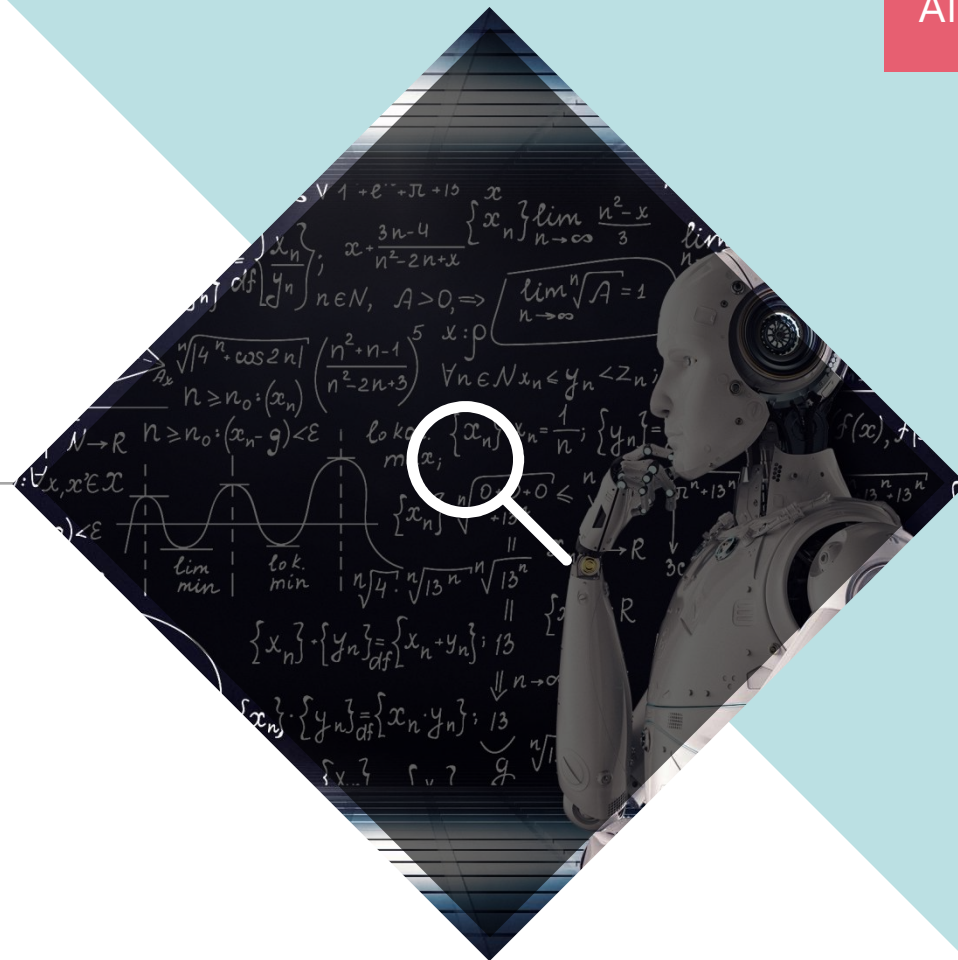
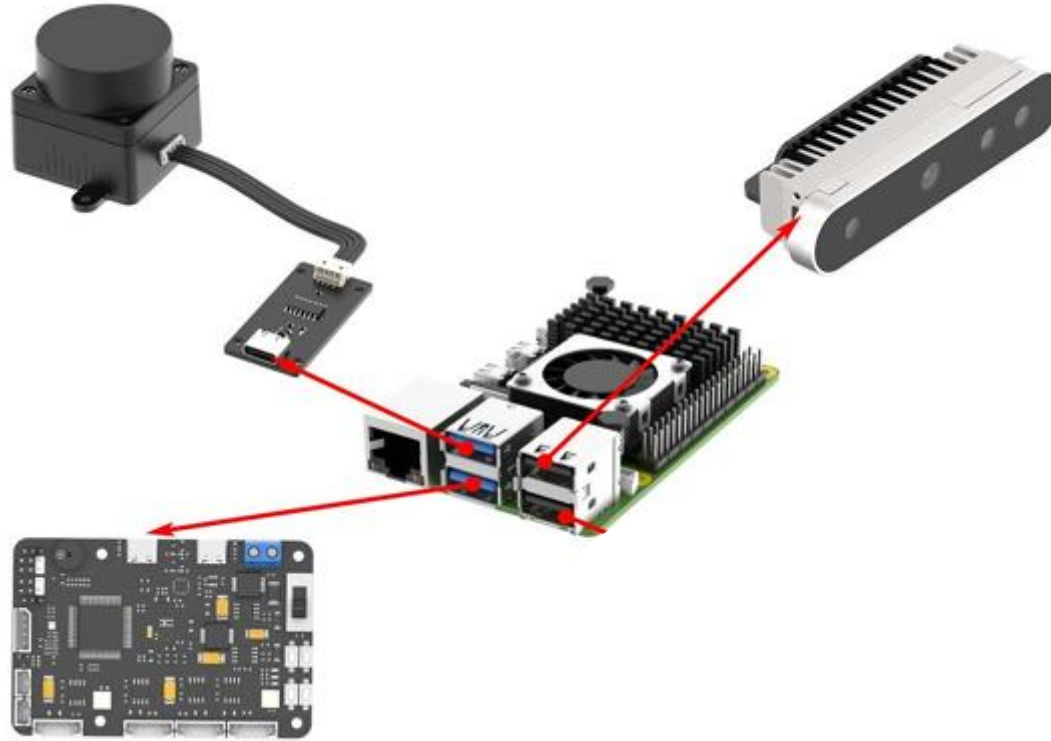


# Day 07

실습



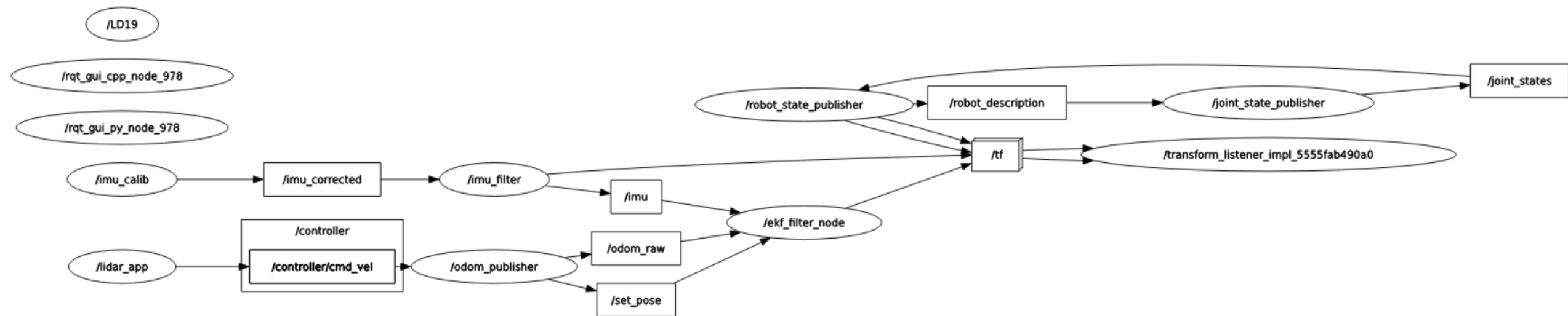
# HW 연결상태 확인



# 장애물 감지 회피기동 실습

LiDAR 실습을 위한 node 들을 launch

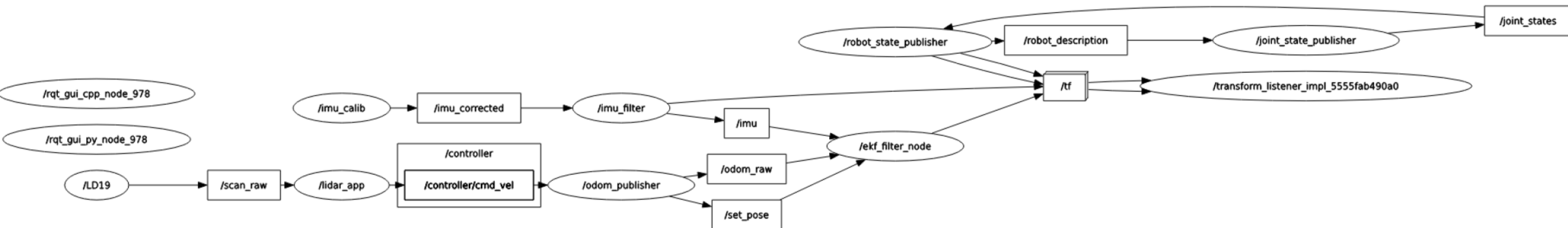
```
ros2 launch app lidar_node.launch.py debug:=true
```



# 장애물 감지 회피기동 실습

## LiDAR 실습을 위한 node 들을 launch (cont.)

```
ros2 service call /lidar_app/enter std_srvs/srv/Trigger {}
```



### 회피기동 시작

```
ros2 service call /lidar_app/set_running interfaces/srv/SetInt64 "{data: 1}"
```

### 회피기동 시작

```
ros2 service call /lidar_app/set_running interfaces/srv/SetInt64 "{data: 0}"
```



**THANK YOU**