# **Schwartz Inequality.**

Schwartz inequality states that, given two vectors f and g, in a vector space V and a scalar product <, > over V,  $|<f,g>|<=||f||\cdot||g||$ .

In this exercise, we apply Schwartz inequality to **Pattern recognition**.

By using  $\langle f,g \rangle / (\|f\| \cdot \|g\|)$  as a **similarity measure** you can locate a given pattern in a new (test) image. The pattern is represented as a matrix g, of odd size. Matrix f then represents a part of the image, equal in size with the pattern g.

## 1. Study the code for the MATLAB function exsim.

The MATLAB function **exsim** is included in this exercise. Exsim takes as **input parameters** an image I, and a pattern g of odd size. The **output** of the function is another image, the "**similarity map**" S. The value of each pixel in S is a measure of the similarity of the corresponding area of I to the pattern g. Similarity values are in the interval [0, 1]. You calculate S by the MATLAB command S=exsim(A,g), where A is the input image, g is the matching pattern, and S is the output "similarity map".

### Questions:

Explain how the scalar product  $\langle f,g \rangle$  is calculated (fg in the code). Explain how the norms ||f|| and ||g|| are calculated (norm\_f and norm\_g in the code). Explain, by using the properties of the scalar product  $\langle f,g \rangle$ , why the value of the similarity measure S, is in the interval [0, 1].

## 2. Pattern matching, synthetic image.

Create a 128 x 128 image. The image should have a 21 x 21 light square (intensity value 200) on a dark background (intensity value 40). Also create a matching pattern g as outlined below. Use the function exsim to calculate the similarity map.

At the MATLAB prompt, write:

```
A=ones(128,128).*40; %dark background, size 128 x 128 A(50:70,50:70)=ones(21,21).*200; %light square, size 21 x 21 %show the image in figure 1, and in gray figure(1); subplot(2,2,1); imagesc(A); colormap(gray); axis image; g=ones(21,21).*40; %pattern g g(1:10,1:21)=ones(10,21).*200;
```

S=exsim(A,g); %calculate the similarity map

## Questions:

How does the pattern g look like?

Explain the position of the white dot (=most similar position) and that of the dark dot (=least similar position) in the original image A.

Produce a new pattern which is a rotation of g by 90 degrees. Run exsim once again. Explain the result.

## 3. Pattern matching, real image.

Load the image pout.tif. As the matching pattern g take a neighbourhood of the left eye.

B=imread('pout.tif'); %load the image B=double(B); %datatype float %show the image in figure1, and in gray figure(1); colormap(gray); subplot(2,3,1); imagesc(B); axis image;

g=B(80:100,108:128); %left eye as the matching pattern 21 x 21

## D=B;

D(80:100,108:128)=ones(21,21).\*150; subplot(2,3,3); imagesc(D); axis image;%show where the pattern is located in the image

S=exsim(B,g);%calculate the similarity map

#### Questions:

Can you find the white dot (=most similar position)? Find out the coordinates of the white dot by the MATLAB command: [r,c]=find(S==max(max(S))). Is the position correct (r + 10, c + 10) = (90, 118)? Why +10, and why (90, 118)?

#### 4. Tolerance to noise.

Add gaussian noise (zero-mean, variance=0.001) to the image pout.tif. Do the pattern matching by running the MATLAB function exsim.

N=(imnoise(B/255, 'gaussian',0,0.001)).\*255; %add gaussian noise, mean=0, var=0.001 S=exsim(N,g); %calculate the similarity map

## Ouestions:

Find out if you still get a correct matching.

Increase the noise in step of 0.001 until the matching fails.

Which variance of the gaussian noise is tolerated for a correct matching?