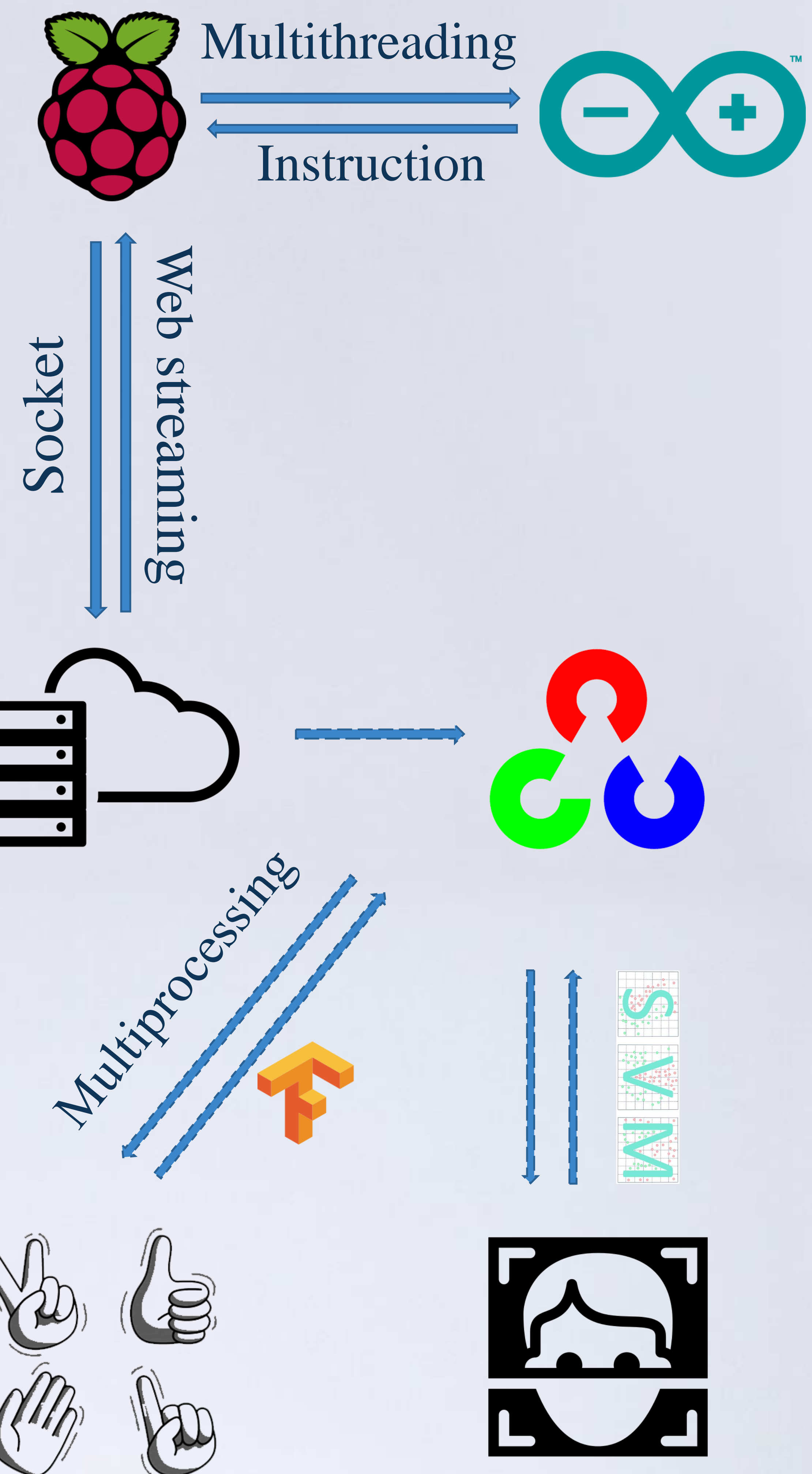# Fancy Robot

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SWS3009: Deep Learning + Tele-Robotic
School of Computing Summer Workshop 2019
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Deployment Diagram

Implementation

(Key problems → Solutions used)

Model delay → Multi-processing

Information transfer blocking → Multi-threading

Functionality

The robot can perform face recognition , identifying who is his master. When he identifies his master , he will act according to the different gestures of his master.