

**SANTA CLARA UNIVERSITY**  
**DEPARTMENT OF COMPUTER ENGINEERING**  
**DEPARTMENT OF MECHANICAL ENGINEERING**  
**DEPARTMENT OF BIOENGINEERING**

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I HEREBY RECOMMEND THAT THE THESIS PREPARED UNDER MY SUPERVISION BY

**Maxwell Abrams**  
**Cynthia Le**

ENTITLED

**3D Bioprinter for STEM Education**

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Thesis Advisor

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Thesis Advisor

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Department Chair

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Department Chair

# **3D Bioprinter for STEM Education**

by

Maxwell Abrams  
Cynthia Le

Submitted in partial fulfillment of the requirements  
for the degrees of  
Bachelor of Science in Computer Science and Engineering  
Bachelor of Science in Mechanical Engineering  
Bachelor of Science in Bioengineering  
School of Engineering  
Santa Clara University

Santa Clara, California  
December 2, 2016

# 3D Bioprinter for STEM Education

Maxwell Abrams  
Cynthia Le

Department of Computer Engineering  
Department of Mechanical Engineering  
Department of Bioengineering  
Santa Clara University  
December 2, 2016

## ABSTRACT

The 3D Bioprinter project aims to create a 3D bioprinter that can improve the capabilities of high school teachers to engage students in STEM education. In order to accomplish this goal, the team is working to expand functionality in SE3D's product line to allow for a better student and teacher user experience and the execution of more interesting experiments. The 3D Bioprinter project is split into three main goals. First, to create a modular incubating box with a variety of sensors to allow for custom environments per experiment, a clear interface to control the settings, and an automatic image capture system. Second, to conduct two feasibility studies for adding auto-calibration of the extruder head and dual- extrusion to 3D bioprinters. Last, to create a new biological experiment that uses the incubating features created in this project. As the project increases functionality, it also will keep the final deliverable as low cost as possible. These additions to the current SE3D 3D Bioprinter will increase effectiveness in the classroom and allow the target audience, high-school students, to better engage in STEM education activities.

Keywords: 3D Printing, Bioprinting, STEM, Education, Control Systems, Incubation

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# Chapter 1

## Introduction

### 1.1 Problem Statement

STEM (science, technology, engineering, and math) fields are a primary focus in education, because there is increasing need for students who have the technical skills to solve real-world problems. A major challenge that many STEM educators face is engaging students in the classroom. The education technology (ed-tech) startup, SE3D, hopes to solve this challenge by bringing 3D bioprinting technology to high school classrooms. Although SE3D has already produced a working prototype, the printer only has basic capabilities and requires further development.

The 3D bioprinter senior design team aims to create a 3D bioprinter that can improve the capabilities of high school teachers to engage students in STEM education. Implementing 3D bioprinters into high schools will generate increased understanding and interest in biology, research, and technology for the students who will soon be Americas doctors, technicians, and scientific pioneers.

In order to accomplish this goal, the team is expanding SE3Ds product line to improve student and teacher user experiences and to expand the possibilities for biological experiments. Table 1.1 shows how SE3Ds current printer can be improved to meet these goals.

Table 1.1: Current Bioprinter Problems and Senior Design Project Solutions

<b>Problem</b>	<b>Solution</b>
Printer lacks advanced features: automated camera, temperature control and humidity regulation - Limits capability of experimentation	Develop a separate, modular incubation unit (The Box) with an automated camera and humidity and temperature controls - Analysis and printing can occur in parallel since functions are not in same physical space - Automatic image capture to analyze experiment over time - Simple user interface to configure and run experiments
Printer only prints with one material - Limits print designs	Design and implement low cost dual extruder
Motion control system relies on specialized 3D printer software and feature-limited hardware - Duet Control Board only supports basic 3D printing operations - External computer necessary for control	Create custom software environment - Distributed control board system to accommodate extra control features Run on built-in computer - Keep low-cost with Raspberry Pi
Operator must manually calibrate syringe extruder - Room for human error	Implement auto-calibration software of the syringe extruder

The goals in Table 1.1 are subject to the following criteria:

1. Usable in a high school lab environment by both students and teachers
2. Safe for all users
3. Low cost

## 1.2 Background and Related Work

The current bioprinter produced by SE3D, the r3bEL, is marketed towards high school science classes. It prints using a single 5 mL syringe that has to be manually loaded by the user, put into the head of the bioprinter, and calibrated by hand to begin printing. It currently has the capability to print enzyme, alga, and bacterium 2D arrays, chocolate, and cells and scaffolds for 3D tissue engineering. The r3bEL printer can print four 3x3 array tray experiments in about 3 minutes. After it is finished, the experiment must remain on the bed of the bioprinter until it finishes culturing. The user gathers data from the experiment by constantly taking pictures of the experiment as it cultures. To capture more consistent and higher quality images, an SE3D employee created a separate box that block out external light and has its own light source. This small box has a removable ceiling, lined with LEDs, and holds a single Petri dish. A small hole in the ceiling allows a mobile phone camera to be placed over it to capture images of the experiment as it cultures, though it still requires



an individual to operate the camera and capture each image.

Table 1.2: Comparison of Existing 3D Bioprinters

	<b>Features</b>							
<b>Printers</b>	<b>UV Curing</b>	<b>Multi Material</b>	<b>Simple UI</b>	<b>Self Cleaning</b>	<b>Auto Calibration</b>	<b>Modular Incubation</b>	<b>Used for Education</b>	<b>Price</b>
<b>RegenHu</b>	X	X		X	X			250K+
<b>Bio3D</b>		X					X	*
<b>Aether 1</b>	X	X+		X	X			9K+
<b>Inkredible</b>	X	X	X					10K
<b>BioBots</b>	X	X	X					10K
<b>SE3D</b>		~	X		~	X	X	3K

**Key**

X: has feature

X+ : has advanced features

~ : project stretch goal

\* : value unknown

Although the team is enhancing the functionality of SE3Ds 3D Bioprinter, there are currently many similar products that are already available for purchase. Below are the bioprinters shown in Table 1.2 with an explanation of their key features and price ranges.

*RegenHu: 3D Discovery Printer*

RegenHu produces a professional printer priced at 250,000+ USD. It supports a wide range of functionalities and applications. It is primarily used for optimal processing of a broad biomaterial/bioactives portfolio. The device prints using cell-friendly Ink-jet and thermopolymer extrusion using a 2-component printhead. In addition, it has a high precision temperature controller for biomaterial culturing.

*Bio3D Technologies: Bio3D Explorer Series*

Three-dimensional bioprinters have also been developed internationally. Bio3D Technologies in Singapore has a series of printers in their Explorer product line. Designed for educational purposes, the Bio3D has 1 to 4 printing heads available and is lightweight and foldable with a full metal frame. The device is suitable for a wide range of applications and materials. The price was not listed online.

*Aether 1 3D Bioprinter*

Aether has a 3D bioprinter that begins with a base unit cost of 9,000 USD. The product includes 8 syringes, 2 hot ends, and 10 extruder print heads. It has the widest range of usable materials for printing, from oils to plastics. The device has many useful attachments, like a UV curing light for biomaterial prints. Its extruders are pneumatic-driven.

### *CellInk: Inkredible Printer*

In Palo Alto, California, CellInk manufactures a research grade bioprinter, Inkredible. Inkredible is priced at 10,000 USD for the base version of the printer. It focuses on assisting tissue engineers who use their custom bioink line to create hydrogel structures that allow for efficient mammalian cell culturing. It has been optimized to print skin and cartilage tissue and uses UV lighting to cure the biomaterial. The printer has a clean chamber and heated cartridges.

### *BioBots 3D Printer*

BioBots has a desktop 3D printer capable of printing tissues out of living cells. The base model price of BioBots 3D printer is 10,000 USD. It is small and portable to allow for ease of use. In addition, the device has a dual heated, pneumatic driven extruder system for precise printing and uses replaceable syringes for easy material changing. Blue light technology is used to safely cure the biomaterial. BioBots is based in Philadelphia; however, they ship internationally.

After reviewing these printers, it is clear that they are all capable of completing the biological experiments that SE3D desires. The one aspect that they all do not meet, however, is that they are priced much higher than the average high school laboratory budget. Furthermore, these printers require high levels of knowledge in order to operate, which is not a reasonable expectation of high school students. To improve this aspect, the UI must be simplified and easy to use for people with less than a high school education. The closest competitors are Inkredible and BioBots, which are low cost and have simple user interfaces. The 3D Bioprinter that the team is working on improves on this problem by providing the necessary functionality at a more reasonable price closer to 3,000 USD.

## **1.3 Literature Review**

The 3D Bioprinter project hopes to assist SE3D, a stem education and 3D Bioprinting company, in the development of their newest 3D bioprinter model. This project has been ongoing for several years, with the intention of improving upon the existing prototype, based on the company's needs.

### **Incubation Methods**

When dealing with biological matter, the environment in which the material is placed must be carefully controlled. For this reason, part of the project objective is to explore possible mechanisms for monitoring temperature, humidity, and lighting during an experiment. Time is an important element for running lessons, and the printer may need to be used multiple times. In order to accommodate this, this project hopes to design an external incubator. The incubation system will be

controlled using a microcontroller and must be low cost; these criteria drove primary research for the incubator.

#### *Ibrahims Low Cost Temperature Controllers*

Ibrahim used micro-controllers to develop a low cost temperature control unit. His research illustrates how the temperature in a heat exchanger can be controlled with a micro-controller that controls the amount of radiation given off by the unit. Since our projects focuses on the affordability of the Bioprinter for high schools, this method for temperature control demonstrates a way to keep the price low while still completing the temperature control criteria. This experimental procedure will be followed and further tested to determine how best to control the air surrounding the heat source, such that the entire incubation chamber temperature can be within a few degrees.

#### **Z-axis and Multiple Material Printing**

One focus of this project is to improve the systems ability to print biomaterials in the third dimension. Currently, the printer is primarily used for 2D science experiments and utilizes a single extruder syringe to print experiments. This single syringe needs to be manually replaced if it runs out or if a new material is being printed. This project aims to implement a dual extruder to streamline the printing process and to enhance the structural capabilities of the printed materials, such that printing in the z-axis direction is less restricted. Research gathered on printers with multiple extruders will assist in understanding the ideal methods for efficiently printing multiple materials and printing in the z-axis direction.

#### *Ozbolats Multi-arm Bioprinter*

The multi-arm bioprinter developed in 2014 created a method for printing two biological materials without manually replacing or exchanging the extruder source. Two fully independent robotic arms controlled the position, ejection speed, and temperature of the nozzle of each material. The single-arm multi-material test that was run by Ozbolats team required that the flow of the biological material was controlled externally from the robotic arm. Ozbolats lab ran tests using sodium alginate and calcium chloride, the same substances used for one of SE3Ds experiments; however, SE3Ds bioprinter has only one robotic arm to eject the biomaterial. The single-arm extruder method provides a base understanding of how to eject both materials from a single arm while still taking into account varying viscosity and temperature needs.

#### *Gaos Coaxial Nozzle Method*

The 3D printer developed by Gao experimented with different flow rates and material concentrations to determine the optimum high strength printable biological material. The printer used an interchangeable coaxial nozzle to print the hollow cavity of the filament. This allowed the experimenters

to control the inside diameter without significantly altering the outside diameter. SE3Ds bioprinter uses a single nozzle in the form of a syringe, which has made it difficult to print complex physical structures. Gaos research differs from the mission of the project in that method for printing multiple materials is not restricted to a coaxial nozzle. However, the experimentation and successful creation of complex 3D structures using multiple materials is vital to the understanding of how to successfully implement true 3D printing.

### **Software Redesign**

The final design requirement requested by SE3D is improving the 3D printer control software system. The open source software that the system currently uses will be replaced by a new custom software environment that will create a simple GUI for the average high school student user. However, it will also be extensible to control all of the supplementary features that will be added in the redesign. This software environment will run on a built-in computer, making the printer a stand alone device. In order to develop this system, research must be conducted to understand the general software structure of a 3D printer.

#### *Rankin and OctoPrint*

Previous processes for printing a 3D object involved generating a 3D model in STL format, converting the STL file to GCODE using a slicing software, then using a communication software, such as Pronterface, to load the GCODE and send it to the printer. What is problematic with using software like Pronterface is it needs to be run from an external computer that needs to be connected to the 3D printer at all times, which is the design SE3D currently uses. Rankin recommends a software called OctoPrint that runs the 3D printer control software on a web interface, so printing is controlled and monitored over the network and can be run off of a Raspberry Pi. Operating over the network allows for the potential to connect more control boards to the main interface, which allows more room to control the additional features planned for the printer.

## **1.4 Objectives**

The 3D bioprinting team consists of mechanical engineers, computer engineers, and bioengineers. To accomplish the project goals, the team has split the project into three parts: The Box, 3D Printing Feasibility Study, and a bioengineering experiment. The bulk of this document will focus on the software components for The Box and 3d Printing feasibility study, as that will be where the computer engineering work is applied.

- The Box:

1. Meet with Maya, SE3D CEO to define requirements for the incubating box
  2. Make design decisions for functionality included in the box and physical and structural designs
  3. Develop prototypes of box, user interface, and controls, allowing users to customize the box environment, begin and end experiments, and automatically capture a series of photos
  4. At every stage of development, run tests for proper software and hardware compatibility
  5. Share prototype with users in a classroom setting for feedback
- 3D Printer Feasibility Study:
    1. Analyze usability of the SE3D bioprinter and identify areas of improvement.
    2. Incorporate an auto-calibration mechanism for the syringe plunger through physical designs and adaptation of printer firmware.
    3. Extend printer functionality to two extruders for multi-material extrusion of biomaterial and the other PLA.
    4. At every stage of development, run tests for proper software and hardware compatibility.
    5. Share prototypes with stakeholders for feedback.

# Chapter 2

## Requirements

The requirements section defines and qualifies what our 3D printer feasibility study and the incubating box must do. We communicated with SE3D to determine the requirements.

### 2.1 Functional Requirements

Functional requirements define what the system must do.

The incubating box system will:

- Support timed image capture at a pre-specified image per time interval
- Have an interactive user interface
- Allow user to monitor and control light, temperature, and camera settings
- Allow users to download captured images
- Allow users to save settings as custom environments to be used later

The 3D printer feasibility study system will:

- Show feasibility of auto-homing of SE3D's syringe
- Show feasibility of adding a multi-material printing module to an open source printer

### 2.2 Non-Functional Requirements

Non-functional requirements define the manner in which the functional requirements need to be achieved.

The system will be:

- User friendly and intuitive

- Safe
- Secure
- Reliable

## 2.3 Design Constraints

Design Constraints are non-functional requirements that constrain the solution instead of the problem.

The system must:

- Function without being connected to a desktop or laptop computer
- Be low-cost

## Chapter 3

# Use Cases

Use Case diagrams define tasks that users will perform to achieve a certain goal when using our incubating box and 3d bioprinter system.

### 3.1 The Box

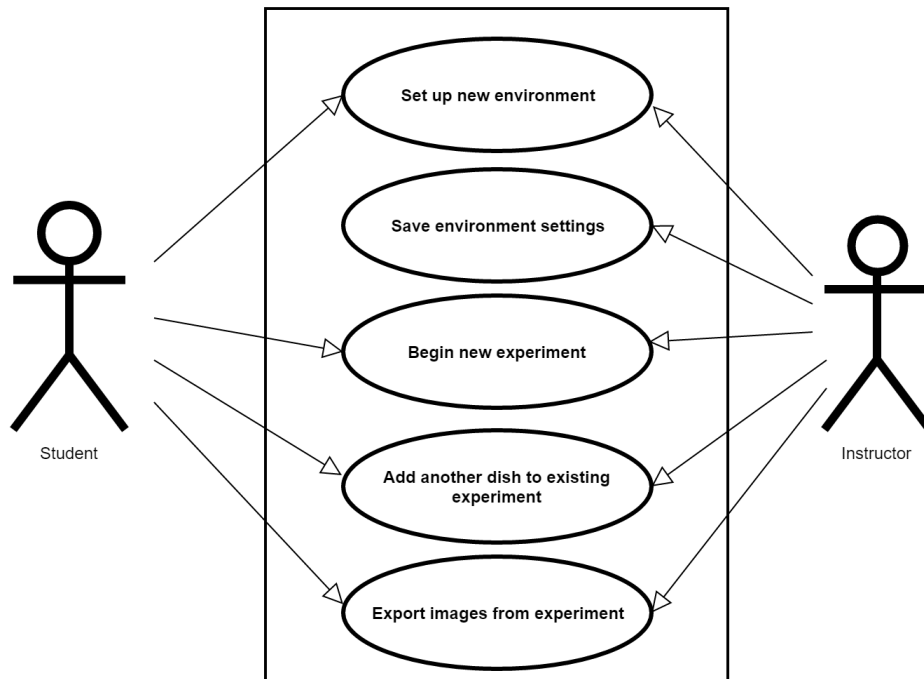


Figure 3.1: Use Case Diagram for The Box

- Name: Set up new environment  
• Goal: Prepare The Box to have the proper settings for the experiment that the user wants to run

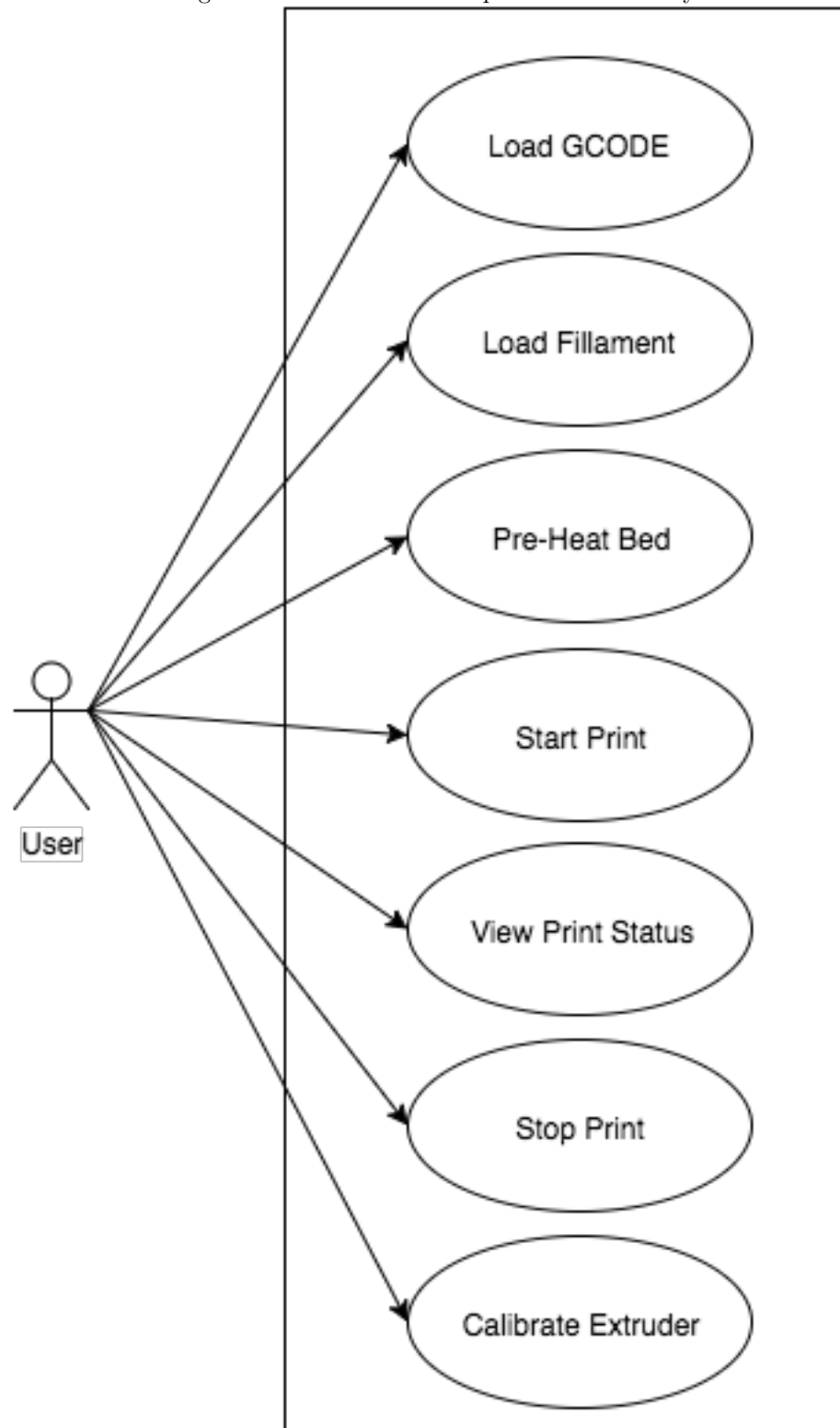


- Actors: Student, Instructor
  - Pre-conditions: No other experiment is currently running
  - Steps: Either load settings that have been previously saved, or enter custom light, temperature, and image capture settings.
  - Post-conditions: The Box is at correct environment settings for the experiment.
  - Exceptions: n/a
- 2.
- Name: Save environment settings
  - Goal: Save temperature, light, and image capture settings to prevent repetition in the future
  - Actors: Instructor
  - Pre-conditions: User has input custom temperature, light, and image capture settings
  - Steps: User clicks ‘Save Custom environment’ and enters an appropriate name
  - Post-conditions: Future users will now be able to load this environment for future experiments
  - Exceptions: n/a
- 3.
- Name: Begin new experiment
  - Goal: Begin timer and image capture on current incubated experiment
  - Actors: Student, Instructor
  - Pre-conditions: User has entered proper environment settings, selected which petri dishes are present, and has placed petri dishes in The Box. The Box has been brought to proper temperature.
  - Steps: Click ‘Begin Experiment’
  - Post-conditions: Timer and image capture begins
  - Exceptions: n/a
- 4.
- Name: Add another dish to existing experiment
  - Goal: Add another dish to a experiment that is already running
  - Actors: Student, Instructor
  - Pre-conditions: An experiment must be running in The Box

- Steps: User places dish in the box. Clicks on the appropriate petri dish to begin timer and image capture of new dish
  - Post-conditions: New petri dish is added into the experiment and final end time is extended to accommodate
  - Exceptions: Incubator box is full
- 5.
- Name: Export images from experiment
  - Goal: Download images captured during the experiment of a single petri dish for analysis
  - Actors: Student, Instructor
  - Pre-conditions: A USB drive has been inserted and detected
  - Steps: Click ‘download images’ button, Select the relevant dish, click ‘download’
  - Post-conditions: Images transferred onto the USB drive
  - Exceptions: No images to export

## 3.2 Feasability Study

Figure 3.2: Use Case Diagram for The Printer Components Affected by The Feasibility Study



1.
  - Name: Load GCODE
  - Goal: Load GCODE files into printer memory for printing
  - Actors: User
  - Pre-conditions: User already has GCODE from converted 3D model
  - Steps: Load media into printer controller
  - Post-conditions: Printer has access to GCODE files for printing
  - Exceptions: No valid GCODE file found
2.
  - Name: Load Filament
  - Goal: Load printer filament into extruder
  - Actors: User
  - Pre-conditions: User has printing materials ready to load
  - Steps For Biomaterials: Remove extruder syringe for biomaterial and insert new biomaterial
  - Steps For PLA Material: Remove old plastic filament spool, run script to remove old filament and prepare for new filament, then insert new filament into extruder module
  - Post-conditions: Printer has filament loaded and is ready for calibration
  - Exceptions: n/a
3.
  - Name: Preheat Bed
  - Goal: Heat print bed for printing
  - Actors: User
  - Pre-conditions: n/a
  - Steps: Select option for preheating the bed
  - Post-conditions: Bed is at optimal printing temperature
  - Exceptions: n/a
4.
  - Name: Start Print
  - Goal: Begin printing the 3D structure
  - Actors: User

- Pre-conditions: GCODE is loaded into printer memory, extruder is calibrated, and filament is loaded
  - Steps: Select 3D object to print
  - Post-conditions: Printer begins printing
  - Exceptions: User stops print
- 5.
- Name: View Print Status
  - Goal: View information about current print job
  - Actors: User
  - Pre-conditions: The printer is printing
  - Steps: Select option for viewing print status
  - Post-conditions: Print status information is shown
  - Exceptions: n/a
- 6.
- Name: Stop Print
  - Goal: Stop all printer activity
  - Actors: User
  - Pre-conditions: The printer is printing
  - Steps: Select stop option
  - Post-conditions: Printer stops all print activity
  - Exceptions: n/a
- 7.
- Name: Calibrate Extruder
  - Goal: Have extruder be automatically calibrated for printing
  - Actors: User
  - Pre-conditions: The filament is loaded
  - Steps: Select option for extruder calibration, select the extruder to calibrate
  - Post-conditions: Printer extruder is calibrated
  - Exceptions: Filament is empty

## Chapter 4

# System Sequence Diagrams

### 4.1 The Box

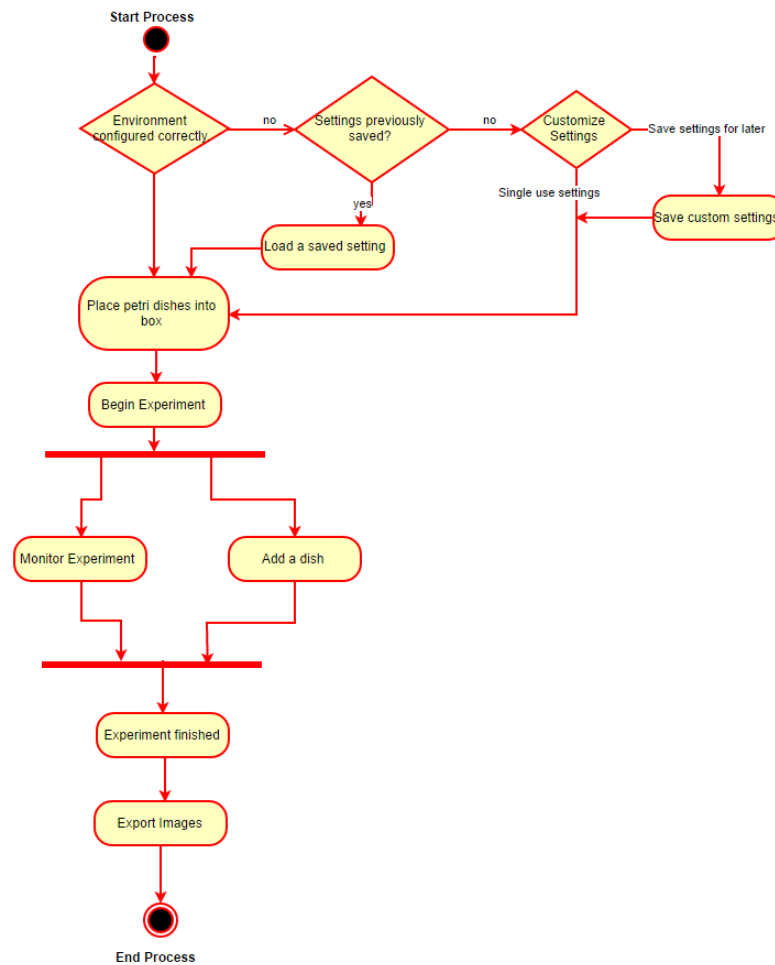


Figure 4.1: Activity diagram for user completing an experiment using the box

## 4.2 Feasability Study

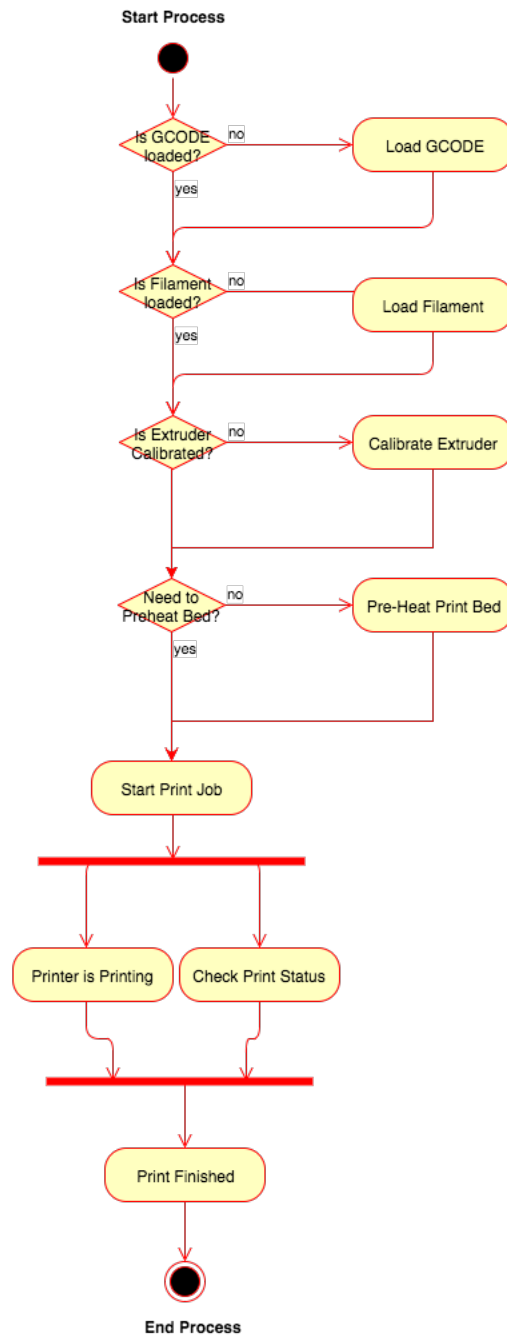


Figure 4.2: Activity diagram for user starting a print on the 3D printer

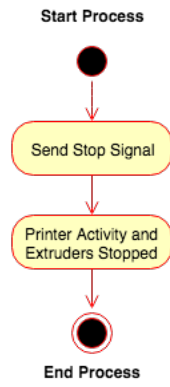


Figure 4.3: Activity diagram for user stopping a print on the 3D printer



## Chapter 5

# Architectural Design

The architectural diagram illustrates the interaction between the user interface and the device controller. Overall, the system is event based where the system transitions between states depending on input from the user interface. Both The Box and the 3D printer use this architecture.

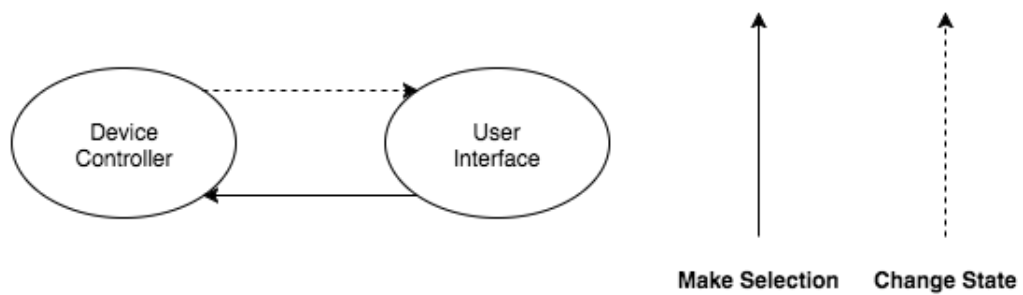


Figure 5.1: Architectural diagram for The Box and the 3D printer

## Chapter 6

# System Design- The Box

The Box is a stand alone, modular incubator that will be used to let certain SE3D experiments culture over an extended period of time. It will provide a custom lighting environment that allows consistent lighting conditions for the camera to effectively document the experiments. The box also will have temperature control capabilities to adjust temperature levels for each of the relevant SE3D experiments. The box will support nine petri dishes at one time.

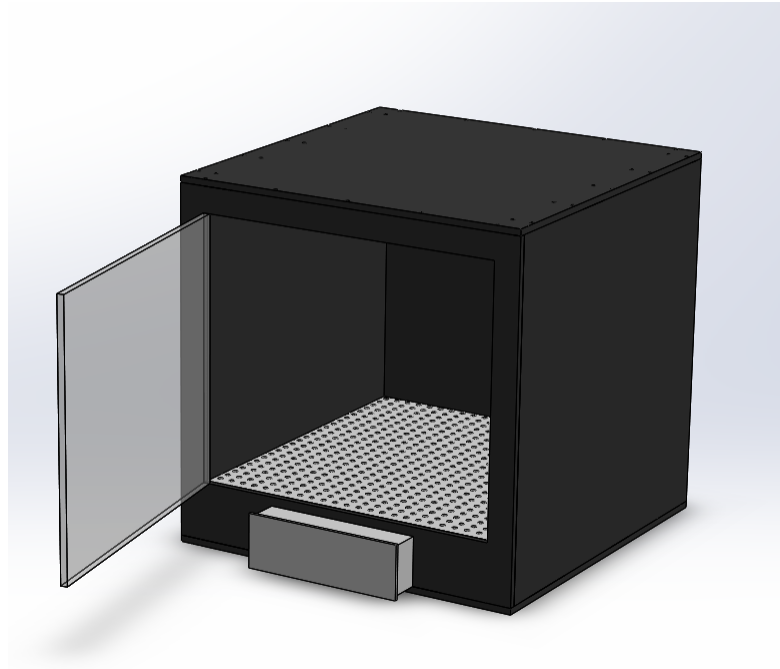


Figure 6.1: Initial Incubator Prototype

Figure 6.1 shows a initial drawing of the plans for the physical incubating box. At the top of the box, there will be a touch screen that allows users to interact with the controls of The Box.

## 6.1 Conceptual Model

The user interface for The Box consists of screens in which the user can configure the box's settings for the current experiment, begin and end experiments, and download images that are collected during the experiment. The user interface shall perform the following:

1. Run off of a microcomputer
2. Allow users to choose custom light, temperature, and image capture settings
3. Allow users to save a set of environment settings
4. Allow users to load a previously saved environment
5. Organize all images from a single experiment into a folder per petri dish so that they each can be exported to USB

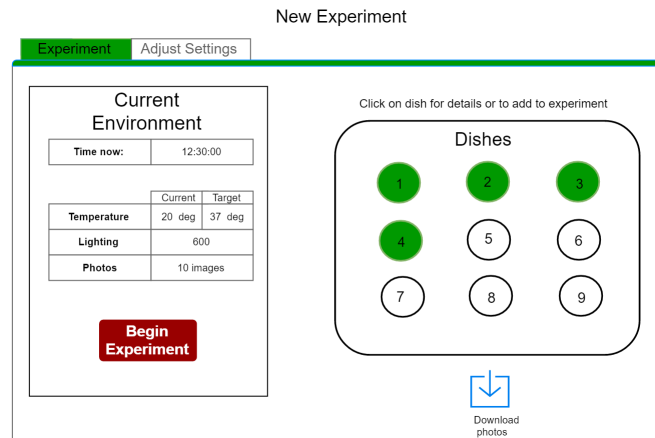
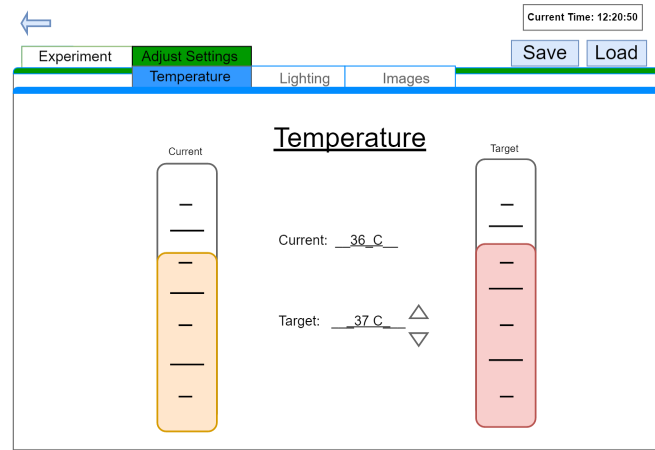


Figure 6.2: Mock up of home screen

The user interface mock-ups shown in Figures 6.2 through 6.5 step through a typical sequence of steps a user would take when using the system. The first screen shown, in Figure 6.2, is the default home screen that is shown when an experiment is not running. The home screen shows current environment status of the box. If a user would like to begin a new experiment, he would first select the dishes that will be initially placed into the incubator by clicking on each numbered circle that corresponds to a specific location inside of the physical box. Figure 6.2 shows dishes 1-4 will be present in the experiment.



Current Time: 12:20:50

Experiment Adjust Settings Save Load

Temperature Lighting Images

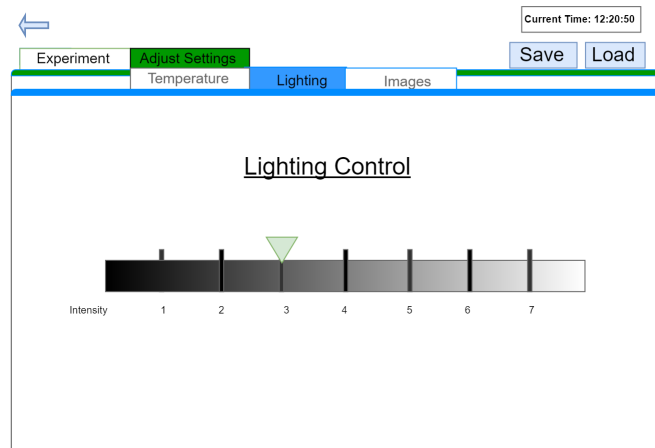
### Temperature

Current: 36 C

Target: 37 C

The interface shows a 'Temperature' control panel. It has a 'Current' section with a vertical bar and a 'Target' section with a vertical bar. The 'Current' bar is orange and the 'Target' bar is red. Both bars have a scale from 0 to 10. The 'Current' value is 36 C and the 'Target' value is 37 C. There are up and down arrow buttons next to the target value.

Figure 6.3: Mock up of temperature setting



Current Time: 12:20:50

Experiment Adjust Settings Save Load

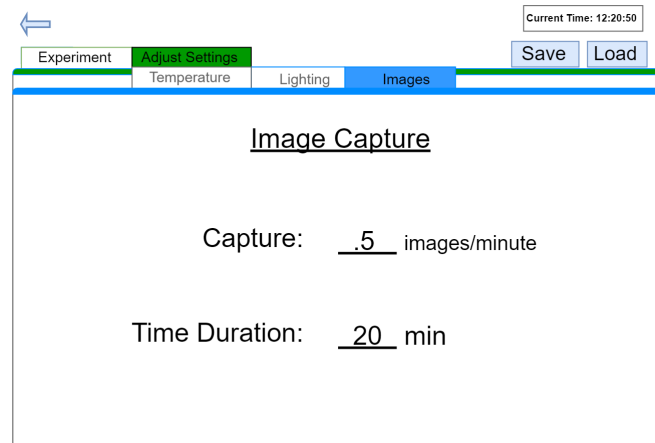
Temperature Lighting Images

### Lighting Control

Intensity 1 2 3 4 5 6 7

The interface shows a 'Lighting Control' panel. It features a horizontal bar with a gradient from black to white, representing light intensity. The bar is divided into seven segments, numbered 1 to 7. A green triangle points to the third segment, indicating the current setting.

Figure 6.4: Mock up of light intensity setting



Current Time: 12:20:50

Experiment Adjust Settings Save Load

Temperature Lighting Images

### Image Capture

Capture: .5 images/minute

Time Duration: 20 min

The interface shows an 'Image Capture' panel. It has two input fields: 'Capture' and 'Time Duration'. The 'Capture' field is set to '.5' images/minute and the 'Time Duration' field is set to '20' min.

Figure 6.5: Mock up of image capture setting

Next, to customize the environment, the user would click adjust settings to be taken to the settings panel, shown in Figures 6.3 through 6.5. The user can choose to load a previously saved set of environment settings or provide a new set of environment settings. In each of these panels, the user can choose the appropriate temperature, light, and image capture settings for the system. After, he can choose to save the set of settings to be used in the future.

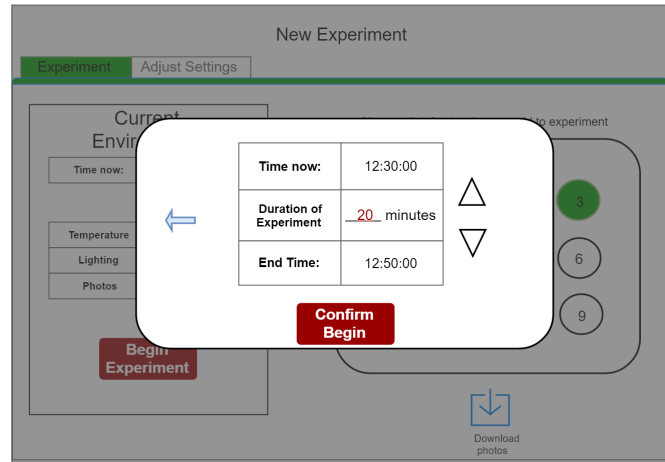


Figure 6.6: Mock up confirming experiment begin

Once the settings are appropriately chosen, the user navigates back to the home page to begin the experiment. The user clicks the 'Begin Experiment' button and a confirmation screen will pop up to allow users to specify how long the incubating box will maintain the environment. This is shown in Figure 6.6.

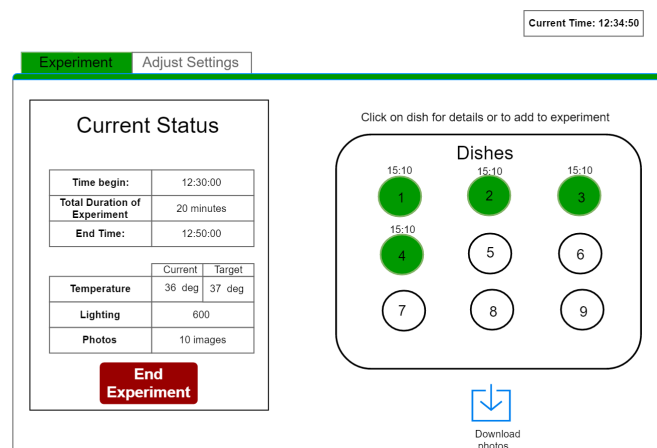


Figure 6.7: Mock up of status screen during an experiment

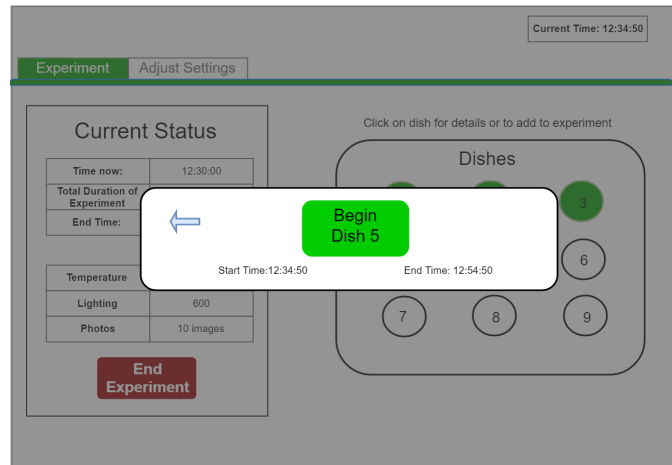


Figure 6.8: Mock up of how a dish is added in the middle of an experiment

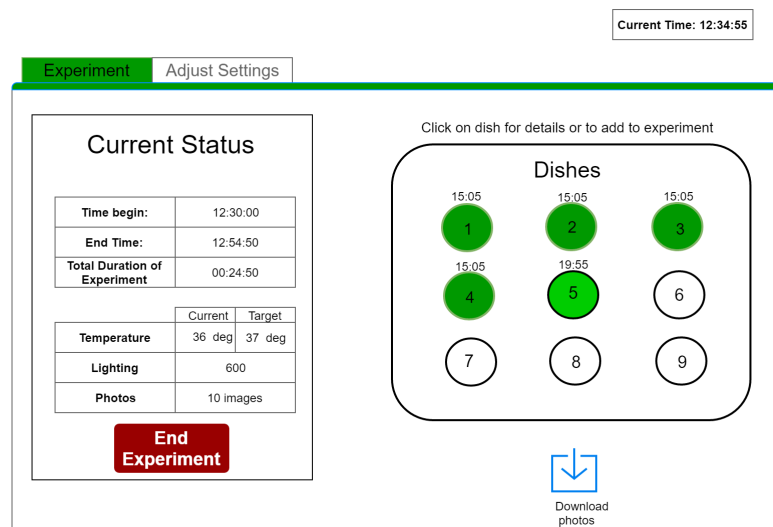


Figure 6.9: Mock up of how current status screen reflects addition of a dish

As seen in Figure 6.7, users will be able to monitor the experiment in real time and see how much time is left in the experiment as well as the current incubator conditions. If another dish needs to be added into the incubator in the middle of a running experiment, the user will add the dish into the box, then click on the corresponding circle on the screen. Figure 6.8 shows Dish 5 being added into the experiment. After the dish is added, the current status screen is updated appropriately to reflect the change- specifically in the duration of experiment and end time sections as well as in the 'Dishes' graphic. This is shown in Figure 6.9.

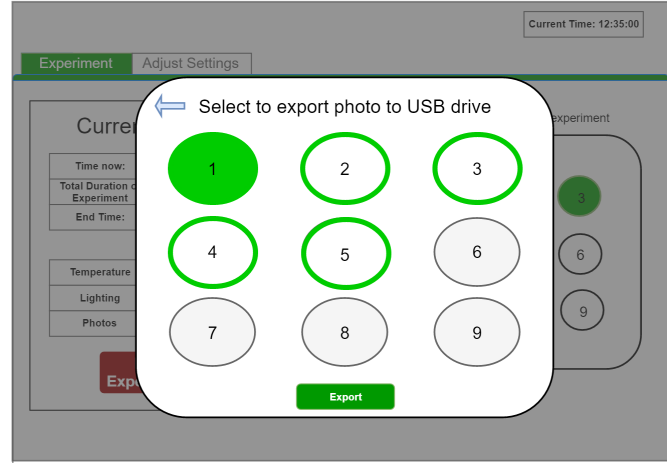


Figure 6.10: Mock up of export images to a USB drive

After an experiment is finished, users will export the images captured by USB. After a USB drive is inserted and recognized by the system, the user can click ‘Download Photos’ on the status screen. A pop-up will allow the user to choose which dish’s images the user would like to export. In Figure 6.10, the images of Dish 1 will be exported to the USB drive.

## 6.2 Technologies Used

- Git: A commonly used version control system. Git allows distributed work flow with high data integrity.
- Raspberry PI: A small, commonly used open-source computer with large community support. The Raspberry PI has General Purpose Input/Output (GPIO) pins for interfacing with other devices as well as built in WIFI, Bluetooth, GPU with HDMI output, and USB support.
- Java: A class based, object oriented computer programming language that is used for general purpose computing. Java is commonly found in projects around the world.

## 6.3 Design Rationale

### 6.3.1 Justification of User Experience

We decided a touch screen interface was the most effective solution for the most enjoyable user experience for both high school students and instructors. A touch screen interface provides better image quality and intuitive interaction for users. Users are familiar with touch screens because of the popularity of touch screen smart phones and other screens.

The user interface is optimized for a touch screen experience. Since users will be using fingertips to navigate the interface, instead of a mouse cursor or stylus, all functions are tied to simple and prominent buttons. We kept the interface as simple as possible, only showing options and information that are necessary. Since we anticipate that we will have about a 5 in. screen, a simpler interface allows users to more easily navigate the system. In addition, since our users will be high school students, limiting the options they have on each screen reduces confusion on what to do next and lowers the chance of error due to unintentional clicks of other buttons.

There is minimal direct user input of values to reduce the need for on-screen keyboards that can be hard to navigate on a small screen. Instead, numbers are increased or decreased with up and down arrows, images, text, and color highlighting are used for signaling if certain dishes are selected or in use, and sliders are used in configuration. Reducing direct user input reduces the likelihood of human error.

We chose not to include preloaded experiment settings that users can choose from after speaking with Maya from SE3D. Allowing users to input their own settings provides more flexibility for the user to customize experiments and create their own experiments. Since there are only a few criteria to set- light, temperature, image capture, and duration of experiment- it does not add too much overhead in set-up time. Users will have the option to save a certain combination of environment settings to use in the future. Thus, the ‘preloaded experiment’ feature is emulated here- an instructor could set up a desired environment before class begins and save it to the system. Students can then load the environment that was set up by their instructor.

### **6.3.2 Justification of Technologies Used**

- Git: Git was chosen because of its ability to store nearly any type of electronic materials such as images, source code, and documentation. It is commonly used in industry and is well supported. It allows the developers to work concurrently on various parts of the project which results in much faster completion times. Finally, because it is a version control system we can easily reference old code and track changes.
- Raspberry Pi: The Pi was selected for the box because it incorporates sensor control and built in compatibility for cameras at an extremely low price point of \$35. It has a large community of developers that allow for support of external devices. Because it is a full computer with a dedicated Graphical Processing Unit (GPU) it has integrated support for high resolution monitors with touch screens. It also has a filesystem for saving photos and onboard USB interfaces to exporting.



- Java: The Java programming language was chosen because it is natively supported on the Raspberry Pi and has built in library support for filesystem manipulation, camera use, and GPIO. In addition, Java has many integrated graphical libraries which is necessary for GUI design. Because it is an object-oriented language, functionality can be abstracted into specific classes.

## Chapter 7

# System Design- Feasibility Study

The feasibility Study consists primarily of adding a second extruder for PLA materials and an auto-calibration system for the biomaterial extruder.

### 7.1 Conceptual Model

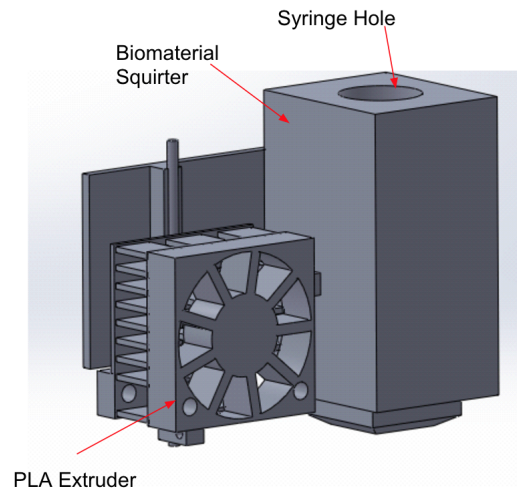


Figure 7.1: Rendering of additional PLA extruder module

By having a second extruder, the printer can print with both biomaterial and PLA plastic. The module in Figure 7.1 demonstrates how the PLA extruder will be positioned next to the biological extruder. This allows for quick transitions between print materials.

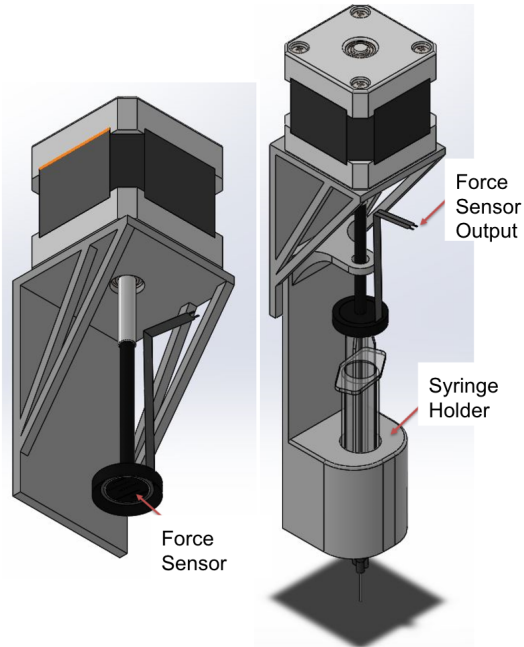


Figure 7.2: Rendering of auto-calibration plunger

By using a force sensor as shown in Figure 7.2 will be able to detect the amount of force required to drive the plunger. Through testing, we can observe the change in force between various biomaterials and air. Then, we can use the servo motor to drive the plunger until it has been sensed that all of the air has been expelled.

## 7.2 Technologies Used

- Git: A commonly used version control system. Git allows distributed workflow with high data integrity.
- Arduino Microprocessor: A small, widely used open-source microprocessor commonly used for electronic projects. Arduinos have many controllable input and output pins used to interact with other devices.

## 7.3 Design Rationale

### 7.3.1 Justification for PLA Extruder

One of the main features missing from the SE3D printer when compared to other printers in the market is the ability to print with additional materials. By adding a second extruder, the usability of the printer is increased. With the PLA extruder, structural scaffolding can be printed. By using both PLA and biomaterials, more complex structures can be created.

### 7.3.2 Justification for Auto-calibration of Extruder

Users of the SE3D printer have given feedback that one of the most difficult aspects for students is proper calibration of the printer. Without proper calibration, prints may fail. By adding auto-calibration to the extruder, we can improve the user experience and decrease the number of failed prints.

### 7.3.3 Justification of Technologies Used

- **Git:** Git was chosen because of its ability to store nearly any type of electronic materials such as images, source code, and documentation. It is commonly used in industry and is well supported. It allows the developers to work concurrently on various parts of the project which results in much faster completion times. Finally, because it is a version control system we can easily reference old code and track changes.
- **Arduino Microprocessor:** The Arduino board is commonly used for 3D printers because of its modularity, cheap price, and well supported community. There are many available open-source printer firmwares available that are designed specifically for the Arduino Platform. The Duet board SE3D uses actually switched to Arduino firmware because of the development community around the Arduino Mega. The Arduino can also easily interface with other technologies, such as media readers and LCD screens. Finally, its processor allows for accurate and fast control of stepper motors, which is required for the success of 3D prints.

## 7.4 Development Timeline

We use Gantt Charts as graphical representations of all the tasks that are needed for the completion of the project. The Gantt Chart proves to be an efficient visual method of tracking the different tasks of the project and helps staying on schedule. For this report, we have only included tasks to which the computer engineers are specifically assigned.

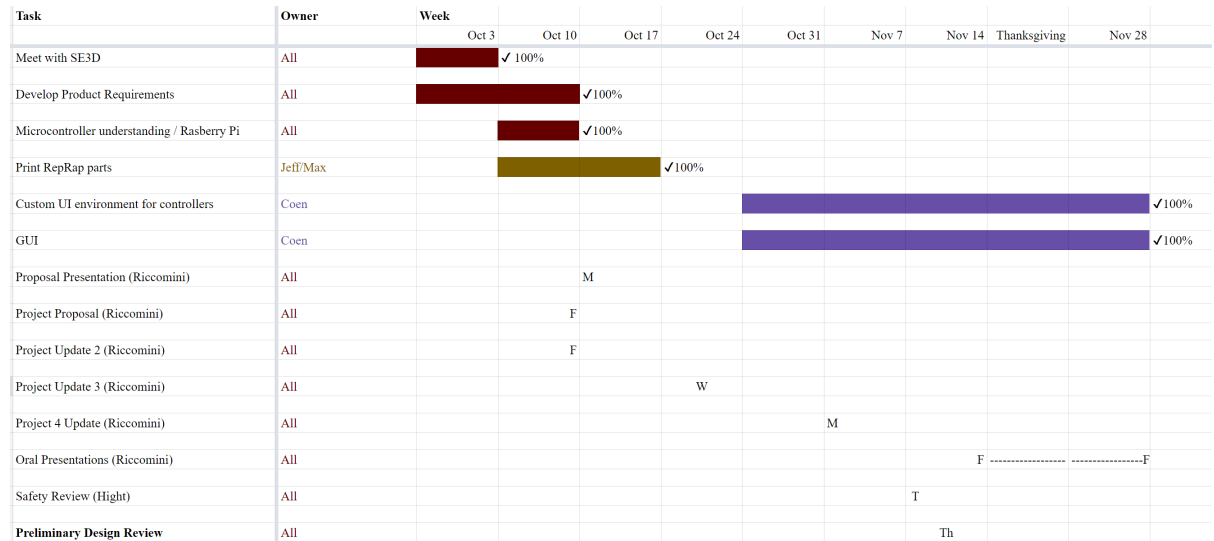


Figure 7.3: Fall Gantt Chart

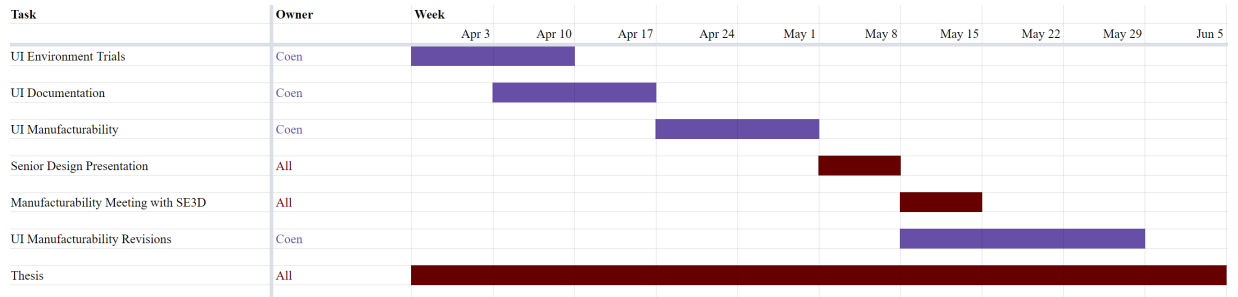


Figure 7.4: Winter Gantt Chart

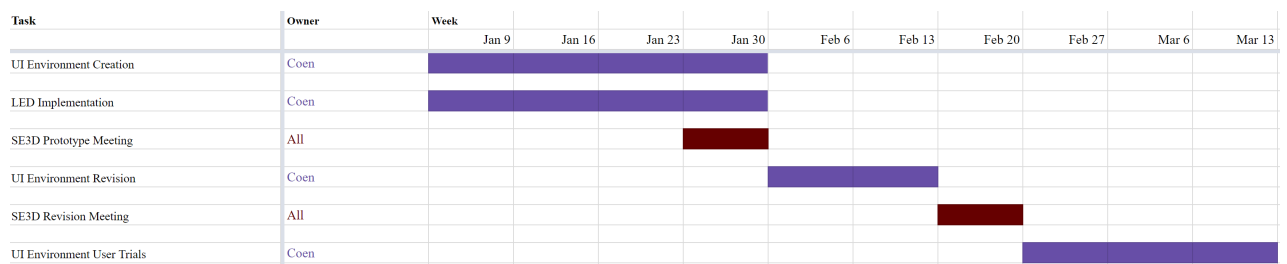


Figure 7.5: Spring Gantt Chart

## Chapter 8

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