

Fundamental of Simulation Methods

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Problem Set 8: Numerical Hydrodynamics - Part I

8.1 Advection in 1D

$$\frac{\partial q(x,t)}{\partial t} + v \frac{\partial q(x,t)}{\partial x} = 0$$

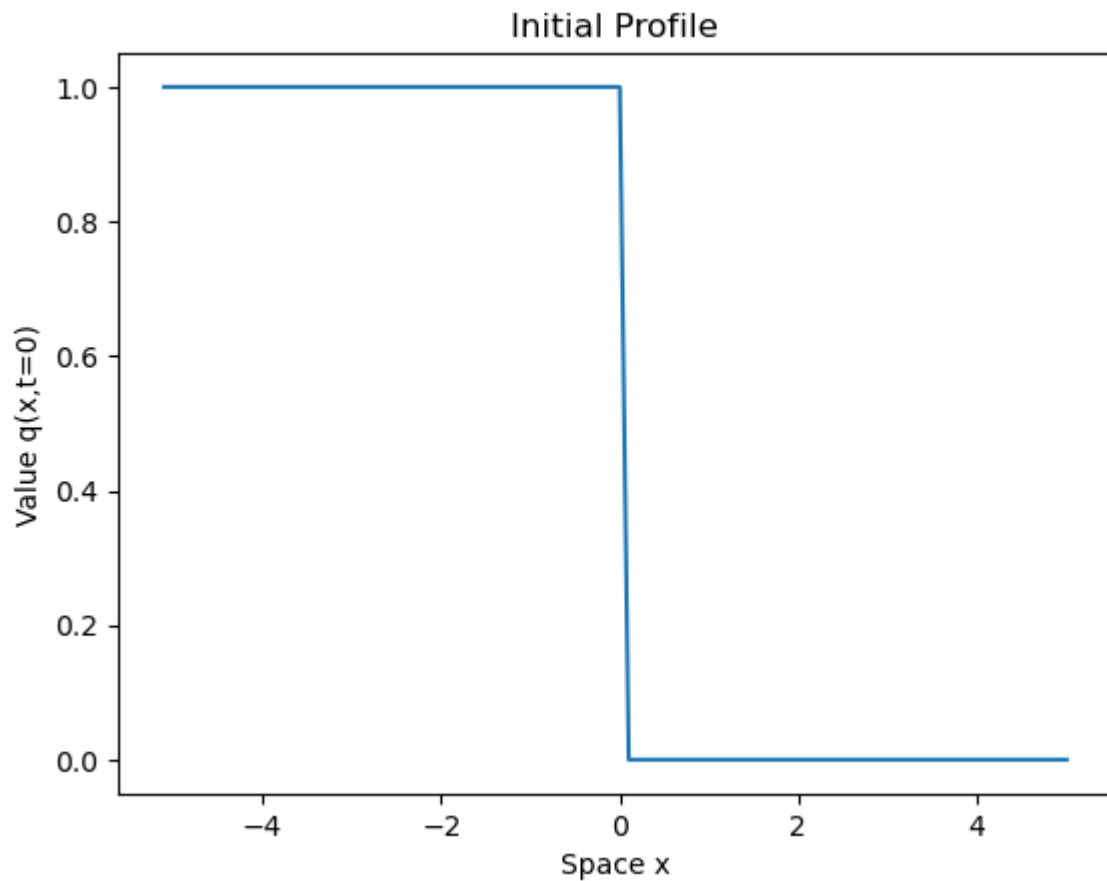
```
In [ ]: import numpy as np
import matplotlib.pyplot as plt
import cmasher
#plt.style.use("seaborn")
N = 100
L = 10
dx = L/N
x = np.arange(-L/2-dx, L/2+dx, dx)

v = 1

def q_init(x):
    q0 = np.zeros(x.shape)
    q0[np.where(x < 0)] = 1
    return q0

q0 = q_init(x)
plt.plot(x, q0)
plt.title("Initial Profile")
plt.xlabel("Space x")
plt.ylabel("Value q(x,t=0)")
```

```
Out[ ]: Text(0, 0.5, 'Value q(x,t=0)')
```



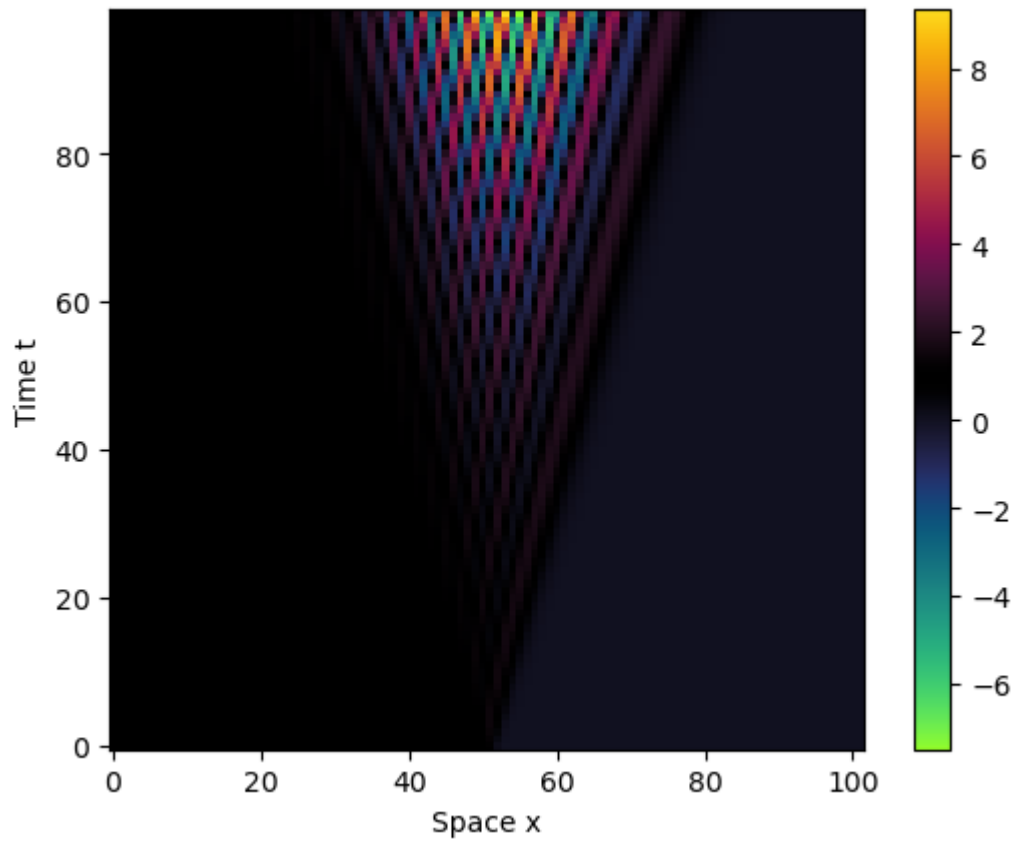
1. Numerical Integration using **Symmetric** derivative

```
In [ ]: t0 = 0
        t1 = 3
        nt = 100
        timesteps = np.linspace(0, 3, 100)
        dt = timesteps[1] - timesteps[0]

        solution = []
        for t in timesteps:
            q0 = q0 - v * dt / (2 * dx) * (np.roll(q0, -1) - np.roll(q0, 1))
            q0[0] = 1
            q0[-1] = 0
            solution.append(q0)
```

```
In [ ]: plt.imshow(solution, origin="lower", cmap="cmr.wildfire")
        plt.colorbar()
        plt.xlabel("Space x")
        plt.ylabel("Time t")
```

```
Out[ ]: Text(0, 0.5, 'Time t')
```



```
In [ ]: from maxpy.makegif import make_gif

def plot(data, name):
    plt.clf()
    plt.plot(data)
    plt.savefig(name)

make_gif(plot, solution, "./central.gif")
#plt.plot(solution[2])
```

Save Images...

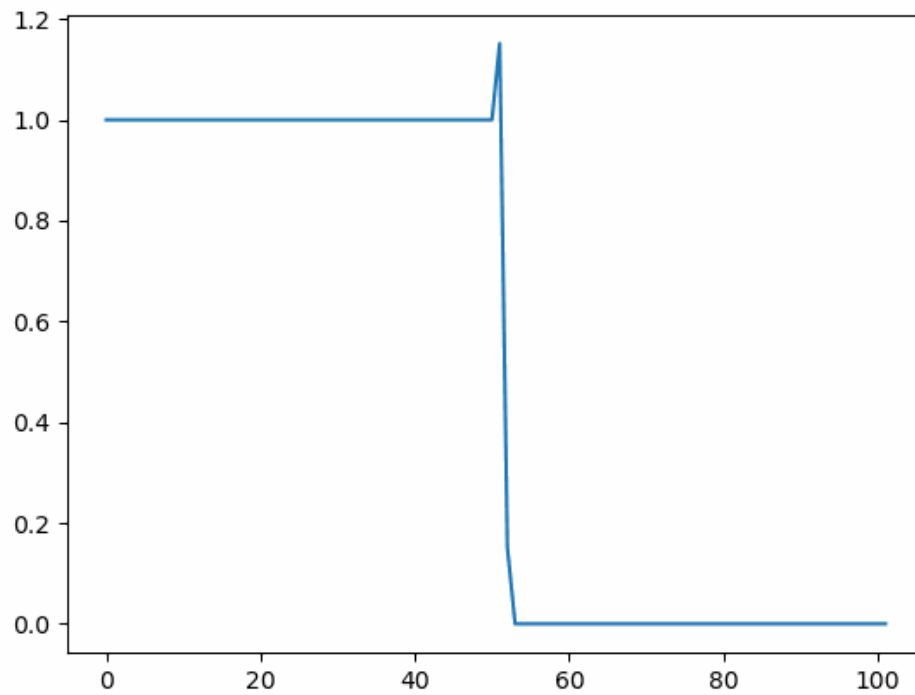
100%|██████████| 100/100 [00:02<00:00, 37.78it/s]

Done.

Make Gif...

100%|██████████| 100/100 [00:00<00:00, 138.34it/s]

Done.



2. Upwind Scheme

```
In [ ]: q0 = q_init(x)

solution = []
for t in timesteps:
    q0 = q0 - v * dt/(dx)*(q0 - np.roll(q0, 1))
    q0[0] = 1
    q0[-1] = 0
    solution.append(q0)

plt.imshow(solution, origin="lower", cmap="cmr.wildfire")
plt.colorbar()
plt.xlabel("Space x")
plt.ylabel("Time t")

make_gif(plot, solution, "./upwind.gif")
```

Save Images...

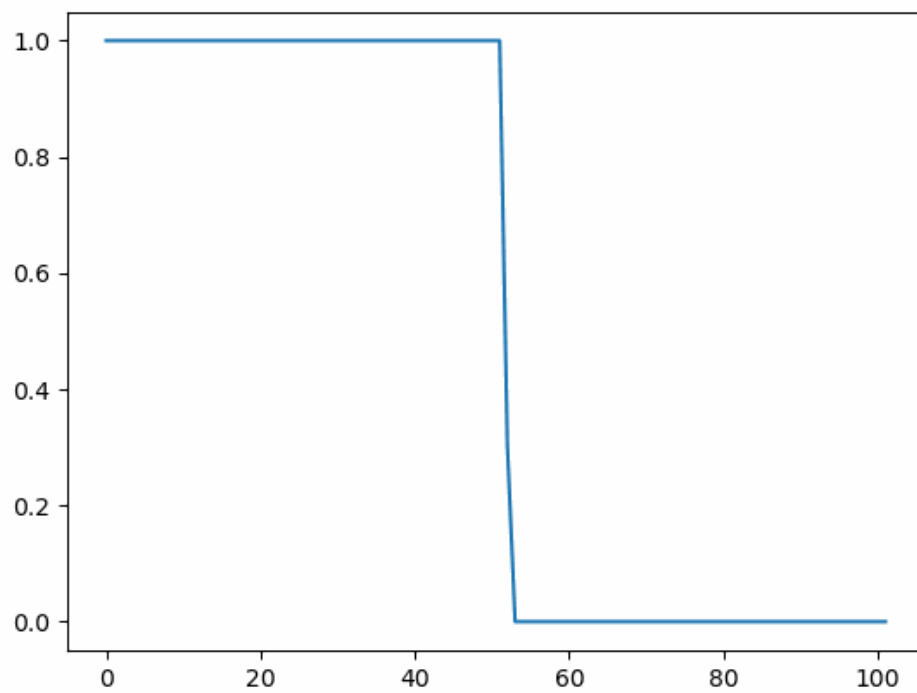
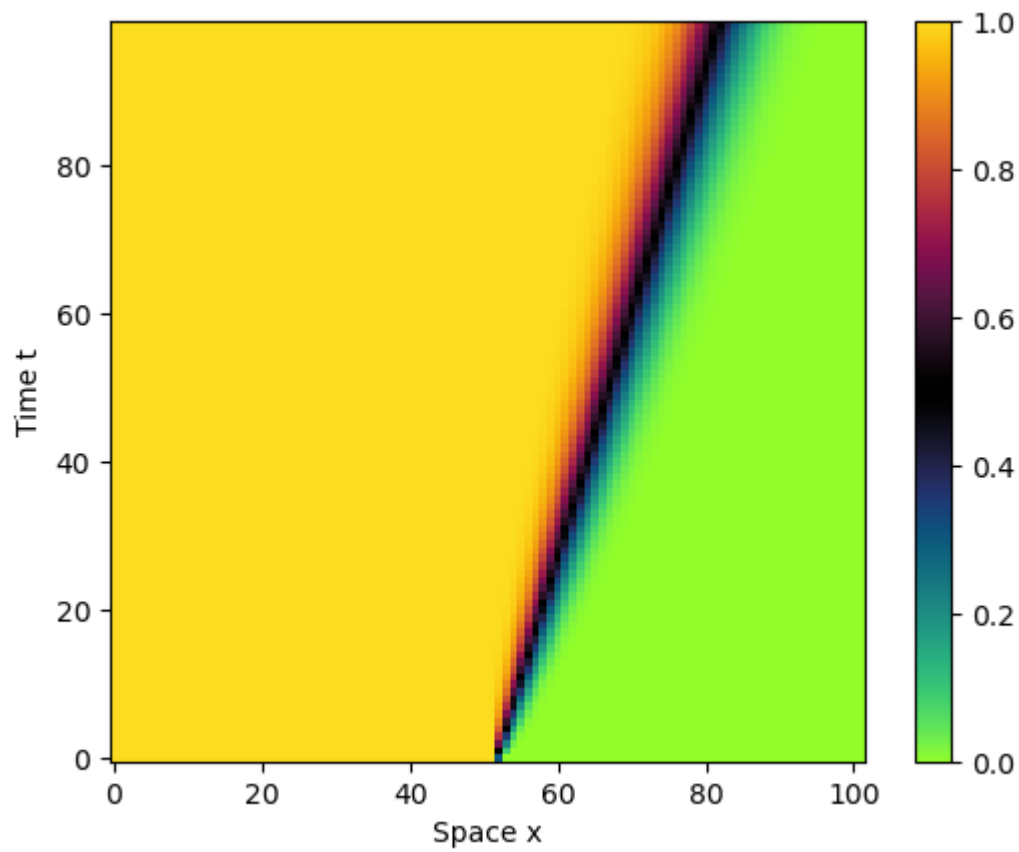
100%|██████████| 100/100 [00:02<00:00, 36.89it/s]

Done.

Make Gif...

100%|██████████| 100/100 [00:00<00:00, 172.00it/s]

Done.



3. Downwind

```
In [ ]: q0 = q_init(x)

solution = []
for t in timesteps:
```

```
q0 = q0 - v * dt/(dx)*(np.roll(q0, -1) - q0)
q0[0] = 1
q0[-1] = 0
solution.append(q0)

plt.imshow(solution, origin="lower", cmap="cmr.wildfire")
plt.colorbar()
plt.xlabel("Space x")
plt.ylabel("Time t")

make_gif(plot, solution, "./downwind.gif")
```

Save Images...

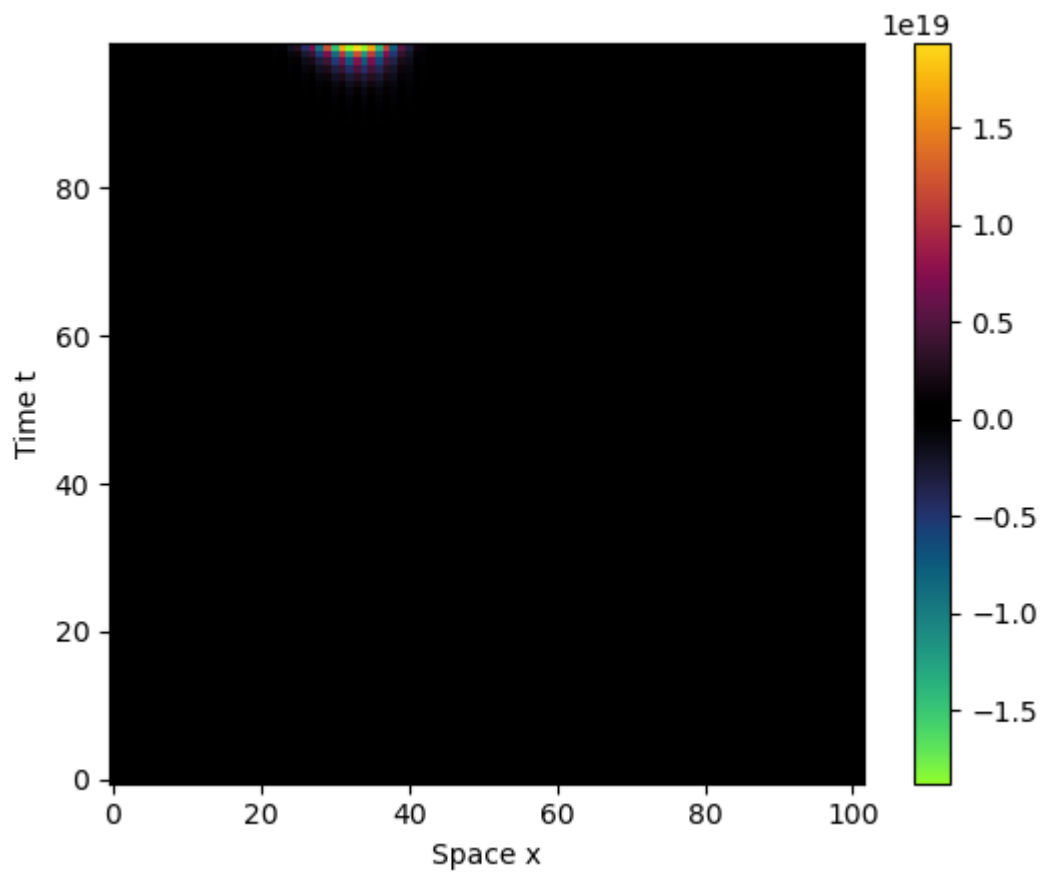
0%| | 0/100 [00:00<?, ?it/s]100%|██████████| 100/100 [00:02<00:00, 41.53it/s]

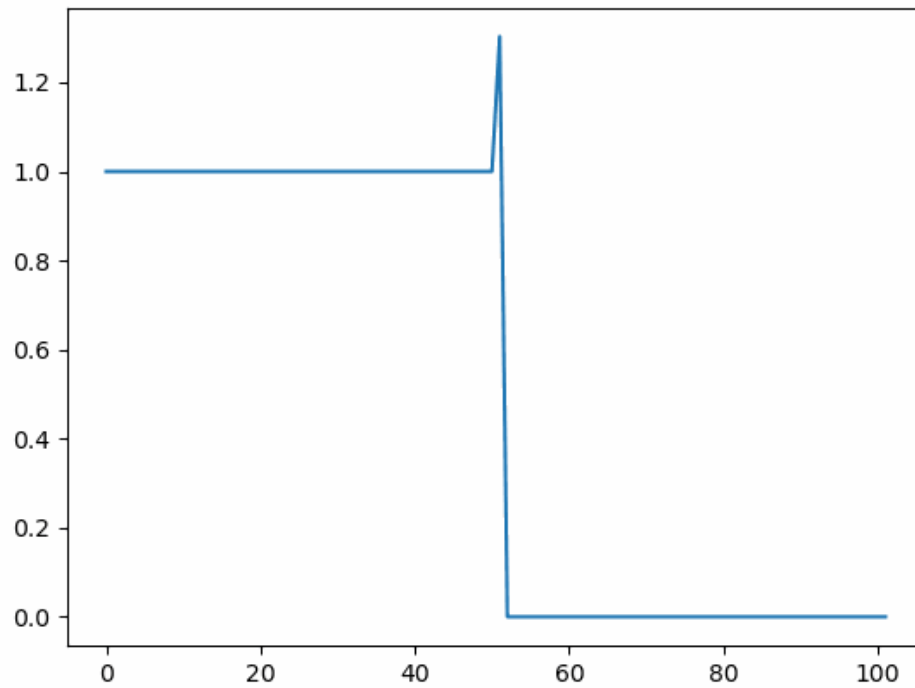
Done.

Make Gif...

100%|██████████| 100/100 [00:00<00:00, 174.83it/s]

Done.





4. Left boundary condition to $q(-L/2, t) = 0.5$

```
In [ ]: q0 = q_init(x)

solution = []
for t in timesteps:
    q0 = q0 - v * dt/(dx)*(q0 - np.roll(q0, 1))
    q0[0] = 0.5
    q0[-1] = 0
    solution.append(q0)

plt.imshow(solution, origin="lower", cmap="cmr.wildfire")
plt.colorbar()
plt.xlabel("Space x")
plt.ylabel("Time t")

make_gif(plot, solution, "./boundary-1.gif")
```

Save Images...

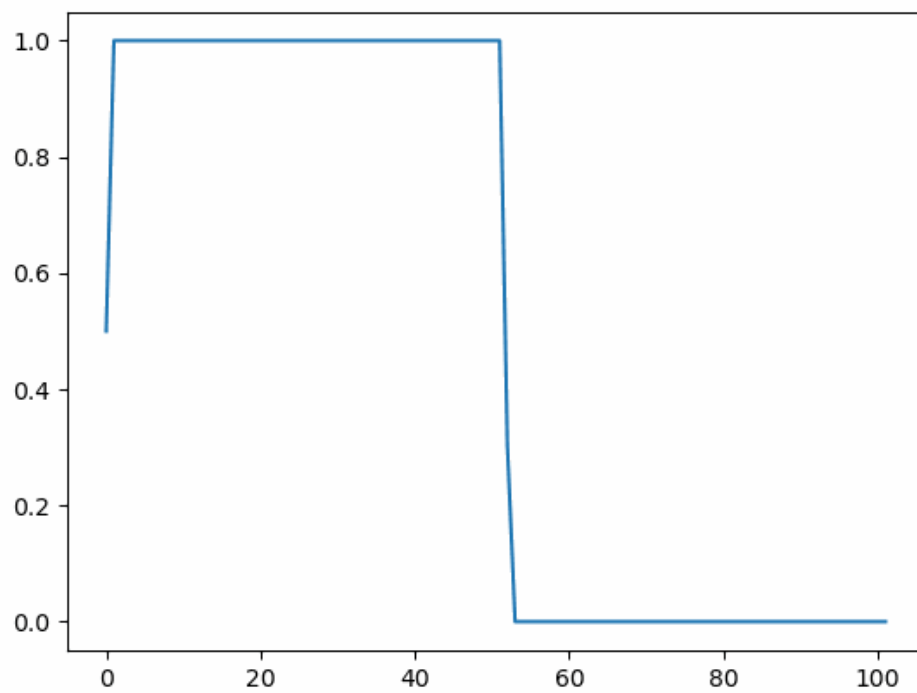
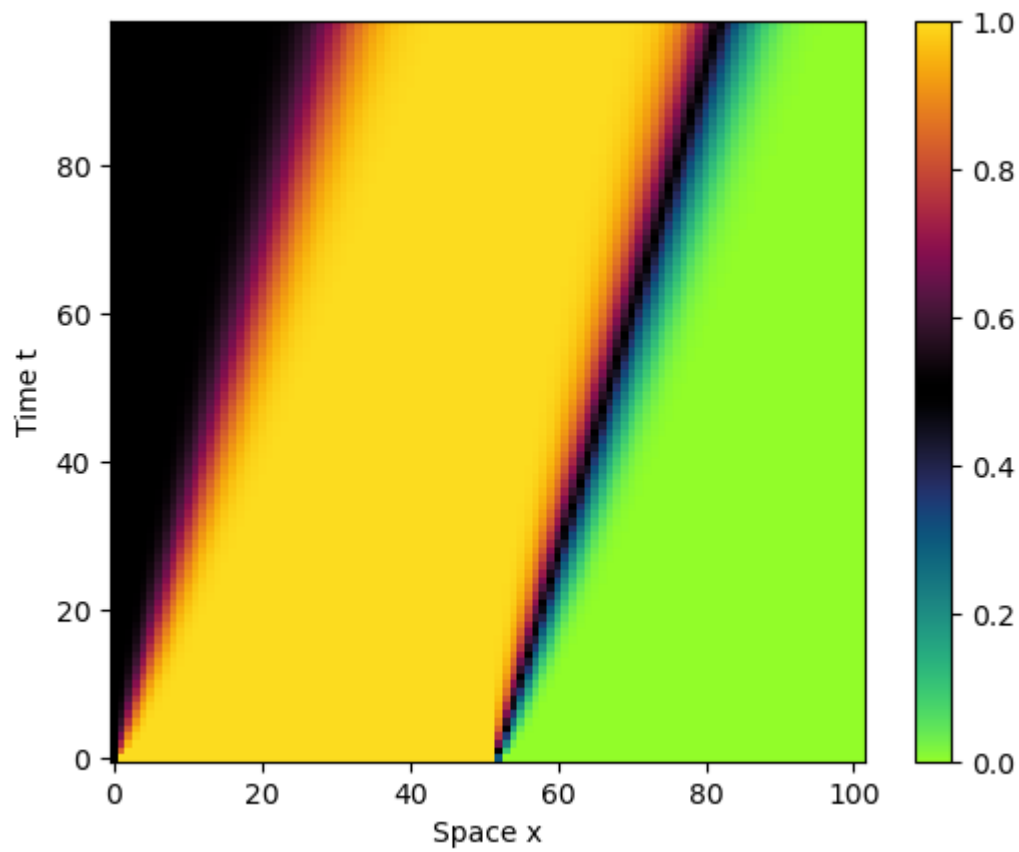
0%| | 0/100 [00:00<?, ?it/s]100%| | 100/100 [00:02<00:00, 41.24it/s]

Done.

Make Gif...

100%| | 100/100 [00:00<00:00, 159.18it/s]

Done.



The new boundary value can propagate according to upwind from left to right

5. Right boundary condition to $q(+L/2, t) = 0.5$

```
In [ ]: q0 = q_init(x)
```



```
solution = []
for t in timesteps:
    q0 = q0 - v * dt/(dx)*(q0 - np.roll(q0, 1))
    q0[0] = 1
    q0[-1] = 0.5
    solution.append(q0)

plt.imshow(solution, origin="lower", cmap="cmr.wildfire")
plt.colorbar()
plt.xlabel("Space x")
plt.ylabel("Time t")

make_gif(plot, solution, "./boundary-2.gif")
```

Save Images...

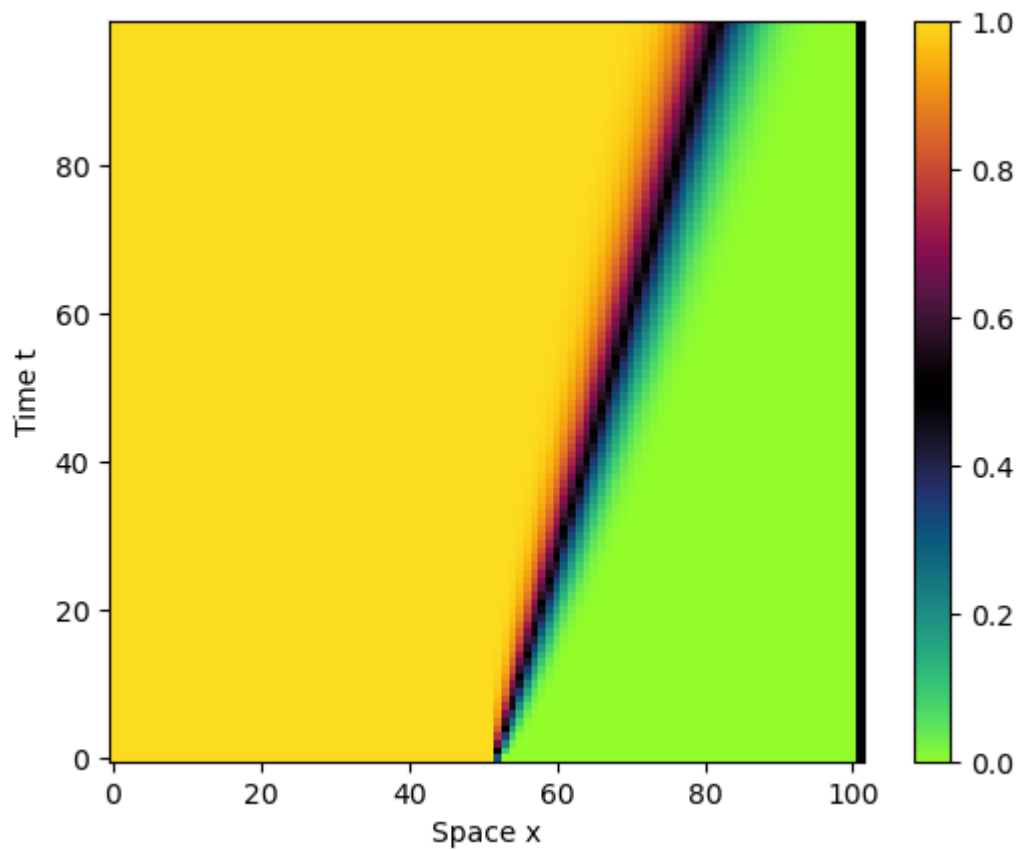
0%| | 0/100 [00:00<?, ?it/s]100%|██████████| 100/100 [00:02<00:00, 43.66it/s]

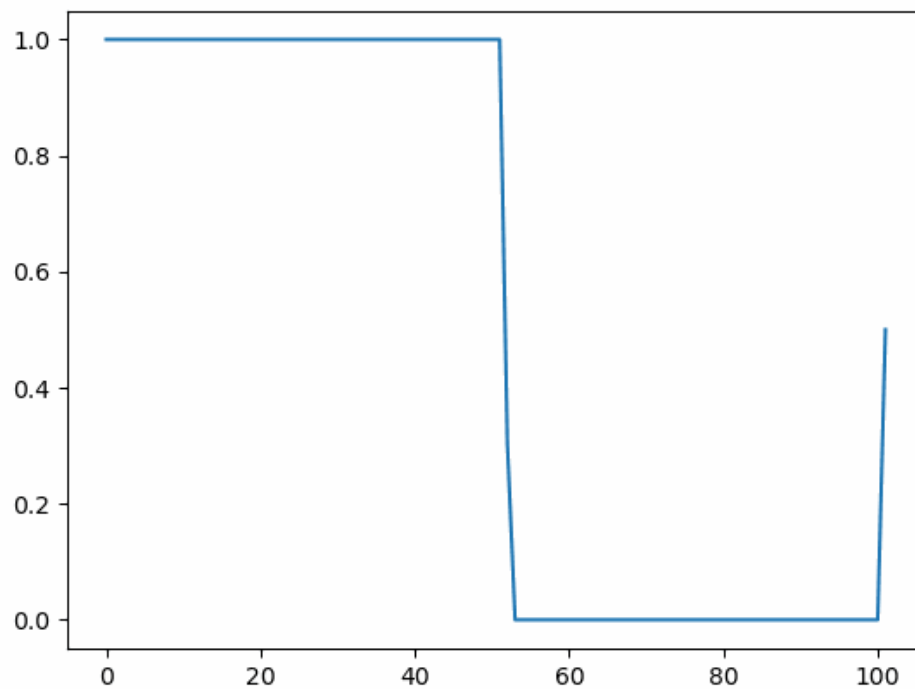
Done.

Make Gif...

100%|██████████| 100/100 [00:00<00:00, 176.30it/s]

Done.





The information on the right side can not propagate any further because the upwind scheme takes information from left to right. With periodic boundary conditions it could also travel but would reappear on the left side.

6. Smaller Step Size

```
In [ ]: q0 = q_init(x)

t0 = 0
t1 = 3
nt = 1000
timesteps = np.linspace(t0, t1, nt)
dt = timesteps[1] - timesteps[0]

solution = []
for t in timesteps:
    q0 = q0 - v * dt / (dx) * (q0 - np.roll(q0, 1))
    q0[0] = 1
    q0[-1] = 0.5
    solution.append(q0)

plt.imshow(solution, origin="lower", aspect="auto", cmap="cmr.wildfire")
plt.colorbar()
plt.xlabel("Space x")
plt.ylabel("Time t")

make_gif(plot, solution, "./boundary-3.gif")
```

Save Images...

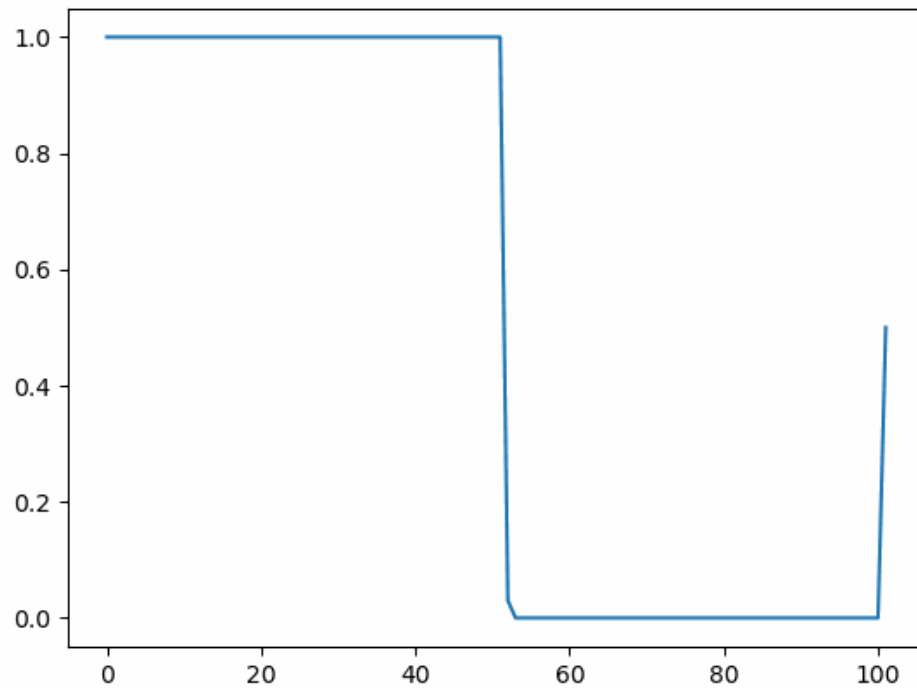
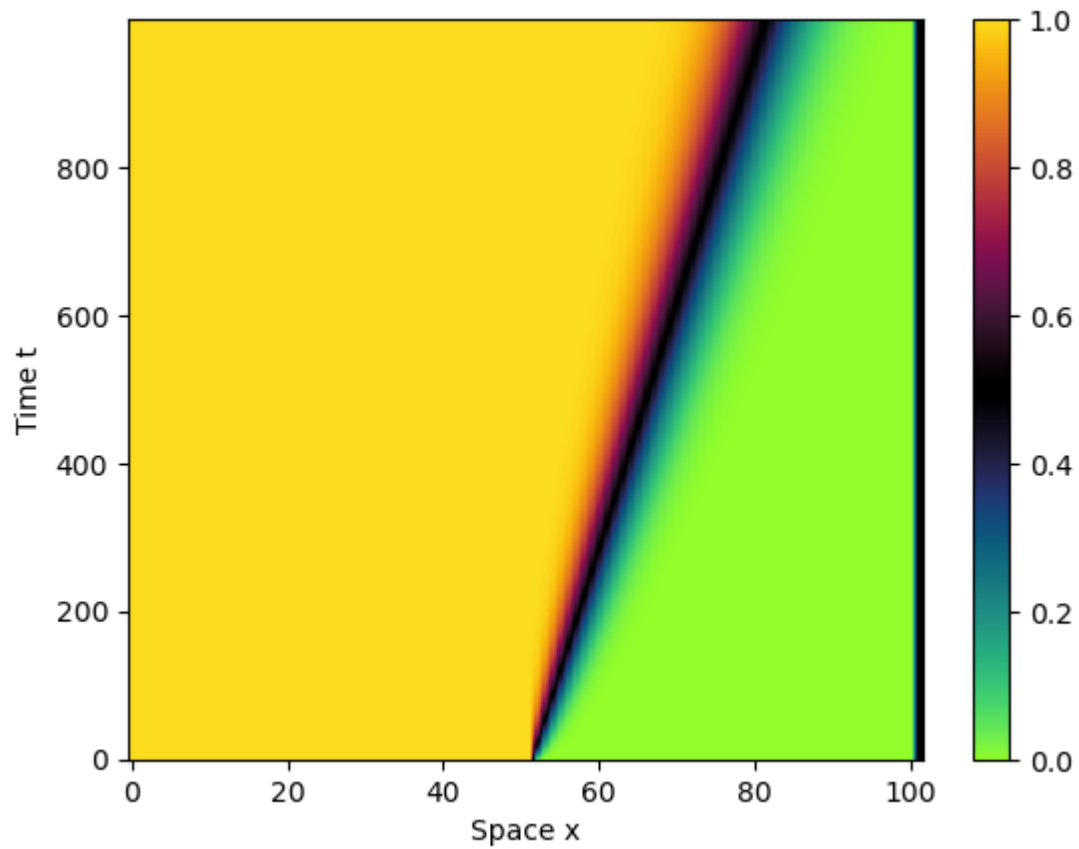
0% | 0/1000 [00:00<?, ?it/s] 100% | 1000/1000 [00:56<00:00, 17.59it/s]

Done.

Make Gif...

100%|██████████| 1000/1000 [00:06<00:00, 159.78it/s]

Done.



It stays more or less exactly the same as before. Even with higher resolution, the information can not travel from right to left with the upwind scheme and positive

velocities

```
In [ ]: q0 = q_init(x)

t0 = 0
t1 = 3
nt = 10
timesteps = np.linspace(t0, t1, nt)
dt = timesteps[1] - timesteps[0]

solution = []
for t in timesteps:
    q0 = q0 - v * dt / (dx) * (q0 - np.roll(q0, 1))
    q0[0] = 1
    q0[-1] = 0.5
    solution.append(q0)

plt.imshow(solution, origin="lower", aspect="auto", cmap="cmr.wildfire")
plt.colorbar()
plt.xlabel("Space x")
plt.ylabel("Time t")

make_gif(plot, solution, "./boundary-4.gif")
```

Save Images...

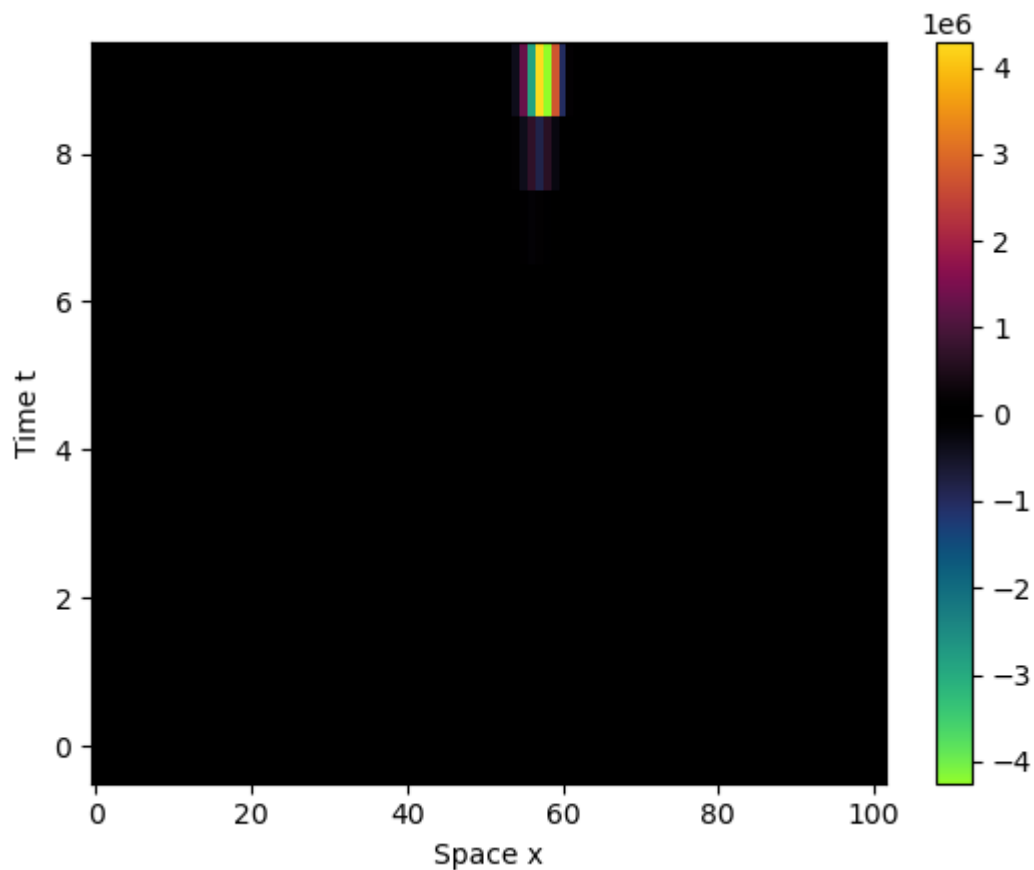
100%|██████████| 10/10 [00:00<00:00, 4153.60it/s]

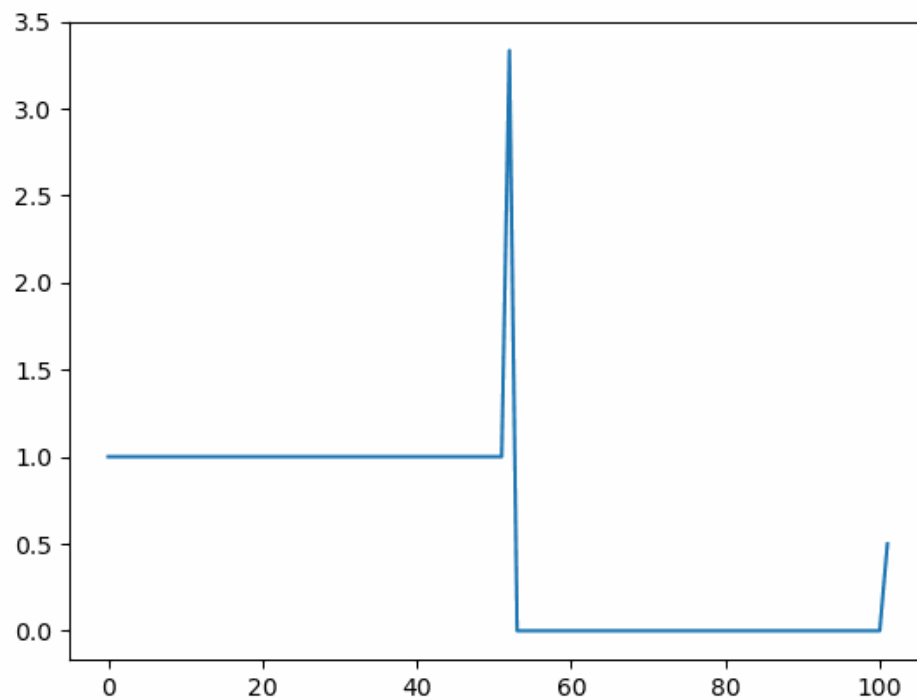
Done.

Make Gif...

100%|██████████| 10/10 [00:00<00:00, 169.19it/s]

Done.





Now the step size is too large. Too large means that the information travels more than one cell per time step, which leads to instability. This can be avoided by considering the CFL limit on the time stepping.

8.2 General-purpose 1D Advection Function

```
In [ ]: def advect(qold, vold, dx, dt):
    """General purpose 1D advection function.
    Vectorized with numpy arrays.

    Parameters
    -----
    qold : Old value profile
           Old value profile
    vold : np.array
           Old velocity profile
    dx : float
           Spatial resolution
    dt : float
           temporal resolution

    Returns
    -----
    np.array
           New value profile one time step later
    """
    qnew = np.zeros(qold.shape)

    # Find positive/negative velocities to decide upwind/downwind
    v_mask = np.argwhere(vold > 0)
    v_mask_not = np.argwhere(vold <= 0)
```

```

# Upwind
qnew[v_mask] = qold[v_mask] - vold[v_mask]*dt/dx*(qold - np.roll(qold, 1))
# Downwind
qnew[v_mask_not] = qold[v_mask_not] - vold[v_mask_not]*dt/dx*(np.roll(qold, -1) - qold[v_mask_not])
return qnew

```

8. Apply function to exercise 8.1

```

In [ ]: q0 = q_init(x)

t0 = 0
t1 = 3
nt = 100
timesteps = np.linspace(t0, t1, nt)
dt = timesteps[1] - timesteps[0]

v = np.ones(q0.shape)

solution = []
for t in timesteps:
    q0 = advect(q0, v, dx, dt)
    q0[0] = 1
    q0[-1] = 0
    solution.append(q0.copy())

plt.imshow(solution, origin="lower", aspect="auto", cmap="cmr.wildfire")
plt.colorbar()
plt.xlabel("Space x")
plt.ylabel("Time t")

make_gif(plot, solution, "./general-advection-1.gif")

```

Save Images...

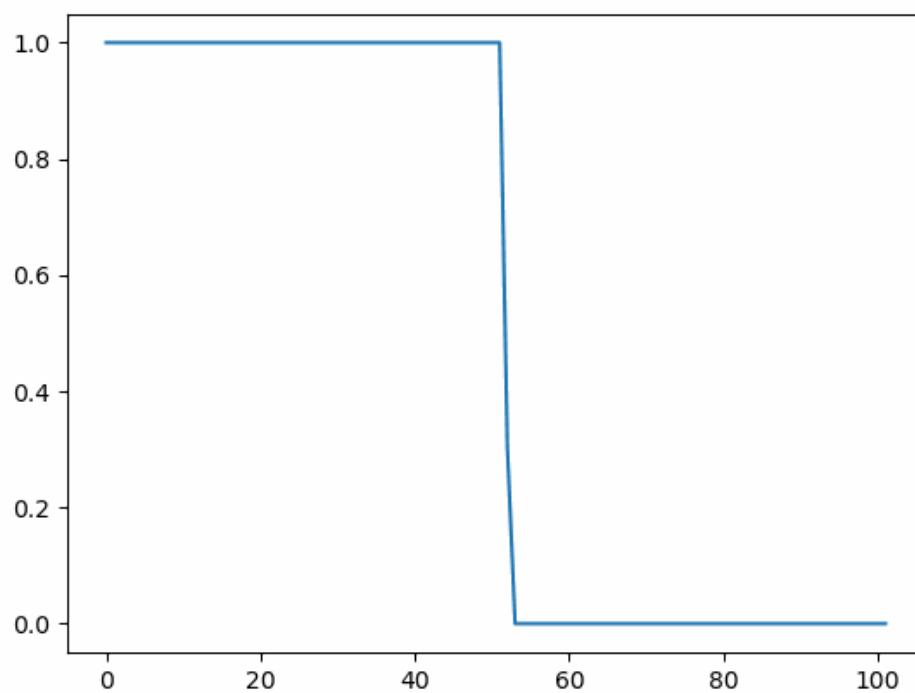
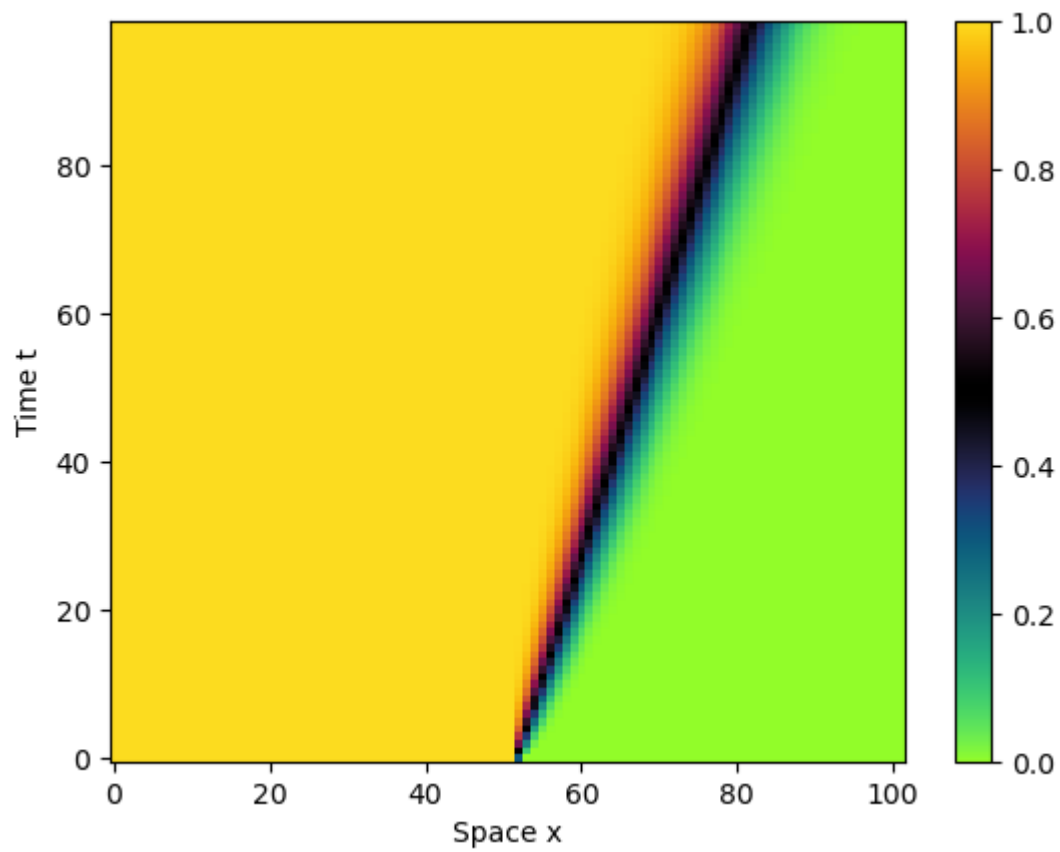
100%|██████████| 100/100 [00:02<00:00, 44.87it/s]

Done.

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Done.



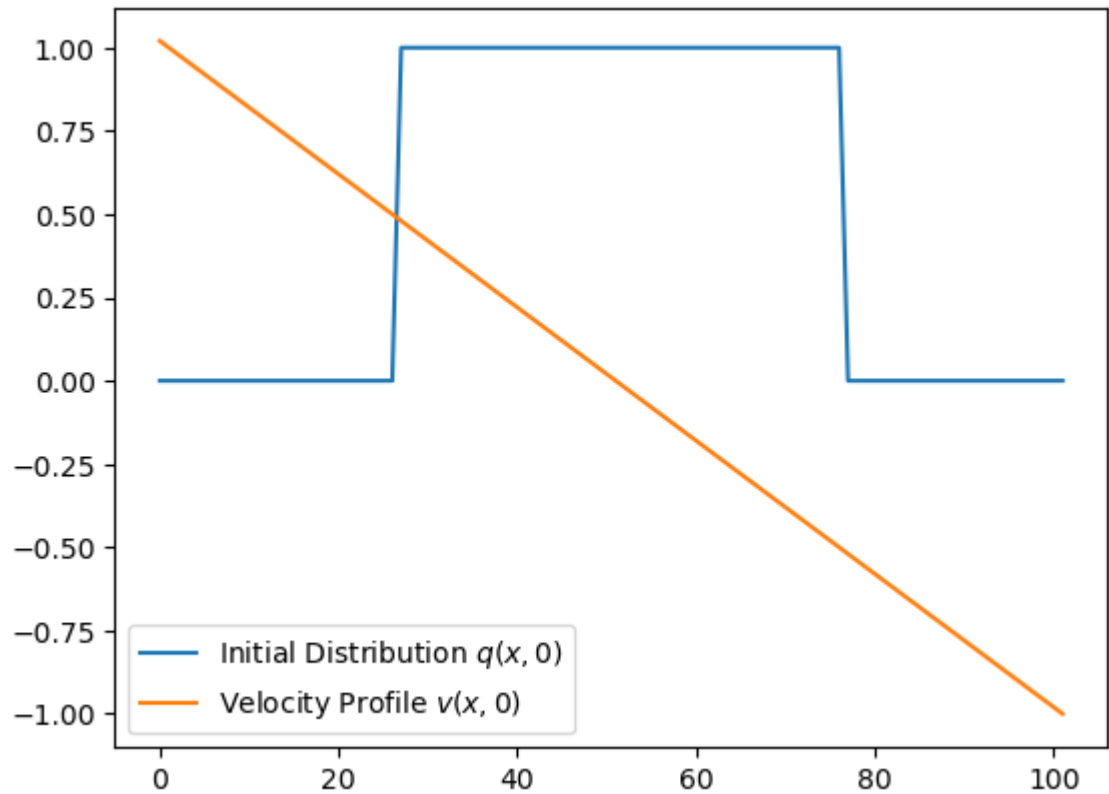
9. Converging velocity field

```
In [ ]: q0 = np.zeros(x.shape)
        q0[np.where(np.abs(x) <= L/4)] = 1

        v = -2*x/L
```

```
plt.plot(q0, label="Initial Distribution $q(x,0)$")
plt.plot(v, label="Velocity Profile $v(x,0)$")
plt.legend()
```

Out[]: <matplotlib.legend.Legend at 0x7fa8e4058f90>



```
In [ ]: solution = []
for t in timesteps:
    q0 = advect(q0, v, dx, dt)
    q0[0] = 0
    q0[-1] = 0
    solution.append(q0.copy())

plt.imshow(solution, origin="lower", aspect="auto", cmap="cmr.wildfire")
plt.colorbar()
plt.xlabel("Space x")
plt.ylabel("Time t")

make_gif(plot, solution, "./general-advection-2.gif")
```

Save Images...

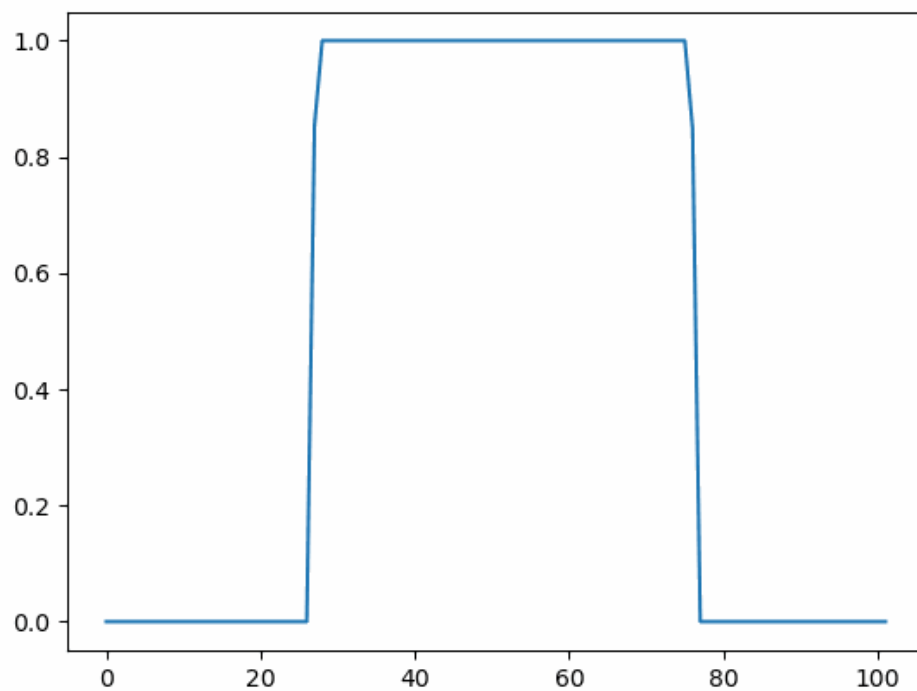
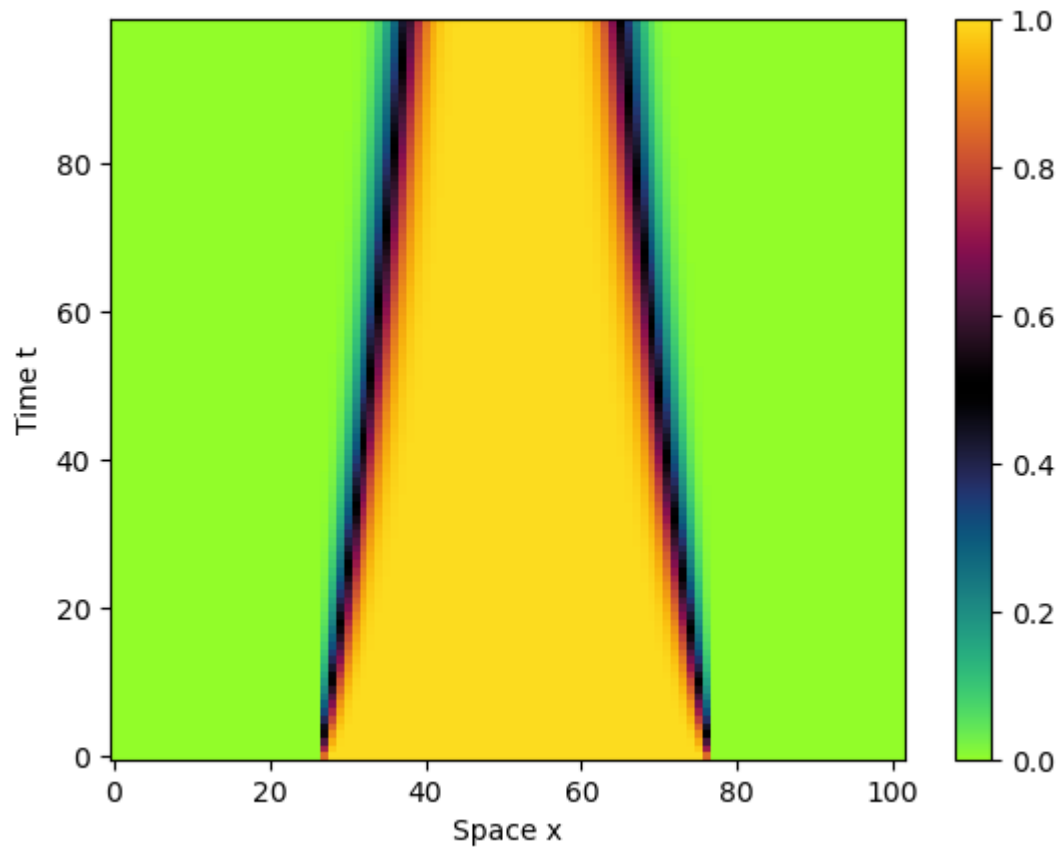
100%|██████████| 100/100 [00:02<00:00, 35.58it/s]

Done.

Make Gif...

100%|██████████| 100/100 [00:00<00:00, 159.30it/s]

Done.



Now the box shaped initial profile gets shrunk into a smaller width by the converging velocity profile. This is because on the left the velocity is positive and on the right it is negative, so the right wave travels to the left and the left wave travels to the right.