

On the choice of weights for logarithmic pooling of probability distributions.

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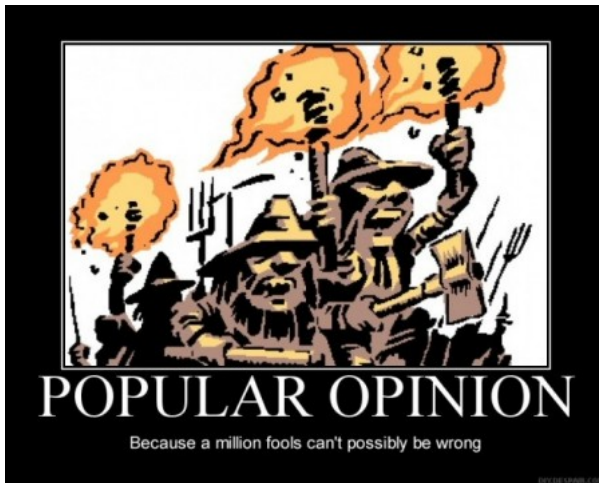
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Combining (expert) opinions



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Logarithmic pooling – Definition & Notation

Let $\mathbf{F}_\theta = \{f_0(\theta), f_1(\theta), \dots, f_K(\theta)\}$ be the set of prior distributions representing the opinions of $K + 1$ experts and let $\alpha = \{\alpha_0, \alpha_1, \dots, \alpha_K\}$ be the vector of weights, such that $\alpha_i > 0 \forall i$ and $\sum_{i=0}^K \alpha_i = 1$. Then the log-pooled prior is

$$\mathcal{LP}(\mathbf{F}_\theta, \alpha) := \pi(\theta \mid \alpha) = t(\alpha) \prod_{i=0}^K f_i(\theta)^{\alpha_i}, \quad (1)$$

where the normalising term $t(\alpha) = \int_{\Theta} \prod_{i=0}^K f_i(\theta)^{\alpha_i} d\theta$ is guaranteed to exist for all proper f_i . We simplify the proof given by [Genest et al. \(1986\)](#) by using Hölder's inequality. This operator enjoys a number of desirable properties such as external Bayesianity ([Genest et al., 1986](#)), relative propensity consistency ([Genest et al., 1984](#)) and log-concavity ([Carvalho et al., 2019](#)).



Logarithmic pooling – Properties

Property 1

External Bayesianity (**Genest et al., 1984**). Combining the set of posteriors $p_i(\theta | x) \propto l(x | \theta)f_i(\theta)$ yields the same distribution as combining the densities f_i to obtain a prior $\pi(\theta)$ and then combine it with $l(x | \theta)$ to obtain a posterior $p(\theta | x) \propto l(x | \theta)\pi(\theta)$.

Property 2

Log-concavity. Let \mathbf{F}_θ be a set of log-concave distributions, i.e., each f_i can be written as $f_i(\theta) \propto e^{\nu_i(\theta)}$, where $\nu_i(\cdot)$ is a concave function. Then $\pi(\theta | \alpha)$ is also log-concave.



Logarithmic pooling – more properties

Property 3

Relative propensity consistency (**Genest et al., 1984**). Taking F_X as a set of expert opinions with support on a space \mathcal{X} , define $\xi = \{F_X, a, b\}$ for arbitrary $a, b \in \mathcal{X}$. Let \mathcal{T} be a pooling operator and define two functions U and V such that

$$U(\xi) := \left(\frac{f_0(a)}{f_0(b)}, \frac{f_1(a)}{f_1(b)}, \dots, \frac{f_K(a)}{f_K(b)} \right) \text{ and} \quad (2)$$

$$V(\xi) := \frac{\mathcal{T}_{F_X}(a)}{\mathcal{T}_{F_X}(b)}. \quad (3)$$

We then say that \mathcal{T} enjoys relative propensity consistency (RPC) if and only if

$$U(\xi_1) \geq U(\xi_2) \implies V(\xi_1) \geq V(\xi_2), \quad (4)$$

for all ξ_1, ξ_2 .

- Properties 1 and 3 are **unique** to logarithmic pooling.



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The weights α are key to the shape and properties of the combined (pooled) distribution.

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- Maximise the entropy of π ;
- Minimise the Kullback-Leibler divergence between π and each f_i ;
- Place a probability measure over α .



Maximise the entropy of $\pi(\theta)$

- If there is no information about the reliabilities of the experts one might want to construct α so as to maximise entropy of the resulting distribution:

$$H_{\pi}(\theta) = - \int_{\Theta} \pi(\theta) \ln \pi(\theta) d\theta$$
$$H_{\pi}(\theta; \alpha) = - \sum_{i=0}^K \alpha_i E_{\pi}[\log f_i] - \log t(\alpha).$$

- Formally, we want to find $\hat{\alpha}$ such that

$$\hat{\alpha} := \arg \max H_{\pi}(\theta; \alpha)$$

- Caveats: (i) is not guaranteed to yield an unique solution; (ii) is rather prone to yield “degenerate” (trivial) solutions.



Minimise KL divergence between $\pi(\theta)$ and the f_i 's

- What if we want to minimise conflict between the consensus and each individual opinion?
- Let $d_i = \text{KL}(\pi || f_i)$ and let $L(\alpha)$ be a loss function such that

$$\begin{aligned} L(\alpha) &= \sum_{i=0}^K d_i \\ &= -(K+1) \sum_{i=0}^K \alpha_i \mathbb{E}_{\pi} [\log f_i] - \sum_{i=0}^K \mathbb{E}_{\pi} [\log f_i] - \log t(\alpha), \\ \hat{\alpha} &:= \arg \min L(\alpha) \end{aligned}$$

- Contrary to the maximum entropy problem, the loss function is convex, thus there is a unique solution (Rufo et al., 2012).



Place a prior on the weights

- An appealing alternative is to place a (hyper) prior on the weights (α);
- Two approaches:
 - (a) Dirichlet prior:

$$\pi_A(\alpha \mid \mathbf{X}) = \frac{1}{\mathcal{B}(\mathbf{X})} \prod_{i=0}^K \alpha_i^{x_i-1}.$$

- (b) logistic-normal:

$$\pi_A(\alpha \mid \mu, \Sigma) = \frac{1}{|2\pi\Sigma|^{\frac{1}{2}}} \frac{1}{\prod_{i=0}^K \alpha_i} \exp\left((\eta - \mu)^T \Sigma^{-1} (\eta - \mu)\right),$$
$$\eta := \log\left(\frac{\alpha_{-K}}{\alpha_K}\right).$$

- Advantage: accomodates uncertainty in natural way, and is very flexible;
- Caveat(s): may yield inconsistent results and hardly ever allows for analytical solutions for the marginal prior $g(\theta) = \int_{\mathcal{A}} \pi(\theta \mid \alpha) d\Pi_A$.



Priors on the weights: details

- Match the first two moments of the Logistic-normal to the Dirichlet (**Aitchison and Shen, 1980**):

$$\begin{aligned}\mu_i &= \psi(x_i) - \psi(x_K), \quad i = 0, 1, \dots, K-1, \\ \Sigma_{ii} &= \psi'(x_i) + \psi'(x_K), \quad i = 0, 1, \dots, K-1, \\ \Sigma_{ij} &= \psi'(x_K),\end{aligned}$$

where $\psi(\cdot)$ is the digamma function, and $\psi'(\cdot)$ is the trigamma function.

- Exploit a non-centering trick to sample from the logistic normal *via* Cholesky decomposition of Σ ;
- We explore two sets of hyperparameters: $\mathbf{X} = \{1, 1, \dots, 1\}$ and $\mathbf{X}' = \mathbf{X}/10$;



Application: survival probabilities (reliability)

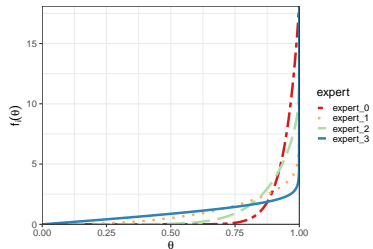
- **Savchuk and Martz (1994)** consider an example in which four experts are required supply prior information about the survival probability of a certain unit for which there have been $y = 9$ successes out of $n = 10$ trials;
- $Y \sim \text{Bernoulli}(\theta)$ and

$$f_i(\theta; a_i, b_i) = \frac{\Gamma(a_i + b_i)}{\Gamma(a_i)\Gamma(b_i)} \theta^{a_i-1} (1 - \theta)^{b_i-1}$$

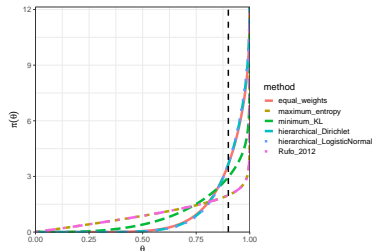
- Allows for simple expressions for the entropy and KL divergence [$\pi(\theta; \alpha)$ is also Beta], and efficient sampling from the hyperpriors;
- For this example, we can evaluate performance using integrated (marginal) likelihoods, a.k.a., prior evidence.



Survival probabilities: results



(a) Expert priors



(b) Pooled priors



Survival probabilities: results II

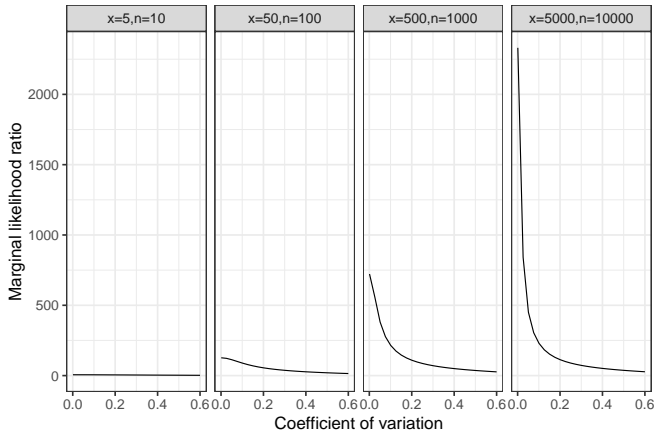
Method	α_0	α_1	α_2	α_3
Maximum entropy	0.00	0.00	0.00	1.00
Minimum KL divergence	0.04	0.96	0.00	0.00
Rufo et al. (2012)	0.00	0.00	0.00	1.00
Dirichlet prior	0.26	0.24	0.27	0.23
Logistic-normal prior	0.27	0.24	0.31	0.18

Expert priors		Pooled priors	
Expert 0	0.237	Equal weights	0.254
Expert 1	0.211	Maximum entropy	0.163
Expert 2	0.256	Minimum KL	0.223
Expert 3	0.163	Hierarchical prior (Dirichlet/logistic-normal)	0.255



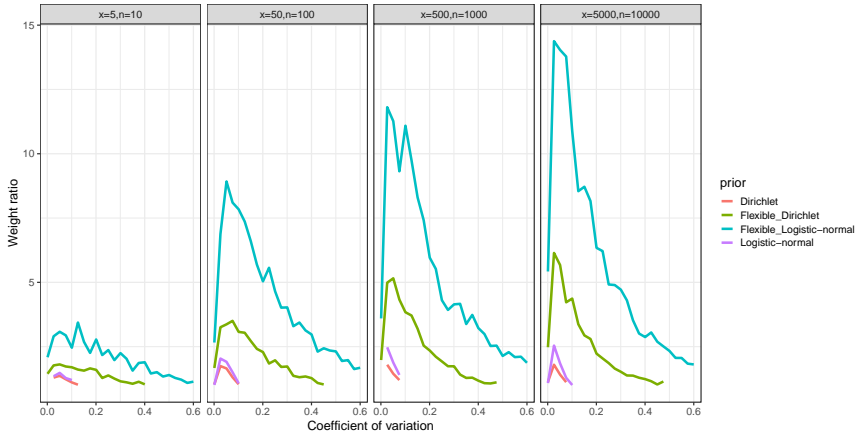
Simulated example: can we reliably learn the weights?

Setup: Five experts elicit Beta priors on a quantity p . Data will be $x/n = 5/10$. Only expert 2 (let's call her Mãe Diná) gives a reasonable prior with mean $\mu_2 = 0.50$ and coefficient of variation c_2 .





Simulated example: performance of hierarchical priors





Simulated example: explaining the weirdness

- Let $c_2 = 0.2$ and $c_j = 0.1$ for all $j \neq 2$, with $\mu = \{0.1, 0.2, \mathbf{0.5}, 0.8, 0.9\}$;



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- However, by calculating $a^{**} = \sum_{i=0}^K \alpha_i'' a_i = 19.75$ and $b^{**} = \sum_{i=0}^K \alpha_i'' b_i = 44.00$, we obtain a pooled prior with $\mathbb{E}_\pi[p] = 0.31$, far off the “optimal” $1/2$;



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- If the data were, say, $x = 50$, $n = 100$, then one would obtain a pooled prior for which $\mathbb{E}_\pi[p] = 0.51$.



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- If the data were, say, $x = 50$, $n = 100$, then one would obtain a pooled prior for which $\mathbb{E}_\pi[p] = 0.51$.
- Let $c_2 = 0.001$. Then $a_2 = b_2 = 499999.5$. Can you see the problem?



Bayesian melding

Suppose we have deterministic model M with inputs $\theta \in \Theta \subseteq \mathbb{R}^p$ and outputs $\phi \in \Phi \subseteq \mathbb{R}^q$, such that $\phi = M(\theta)$. We have the combined prior on the outputs:

$$\tilde{q}_{\Phi}(\phi) \propto q_1^*(\phi)^{\alpha} q_2(\phi)^{1-\alpha}, \quad (5)$$

where $q_1^*(\cdot)$ is the **induced** and q_2 is “natural” prior on ϕ . The prior in (5) can then be inverted to obtain a *coherised* prior on θ , $\tilde{q}_{\Theta}(\theta)$. Standard Bayesian inference may then follow, leading to the posterior

$$p_{\Theta}(\theta \mid \mathbf{y}, \alpha) \propto \tilde{q}_{\Theta}(\theta) L_1(\theta) L_2(M(\theta)) \pi_A(\alpha). \quad (6)$$



Application: Influenza in a boarding school

In 1978, 512 out of 763 lads got came down with the flu. We model the spread using a standard SIR model

$$\begin{aligned}\frac{dS}{dt} &= -\beta SI, \\ \frac{dI}{dt} &= \beta SI - \gamma I, \\ \frac{dR}{dt} &= \gamma I,\end{aligned}$$

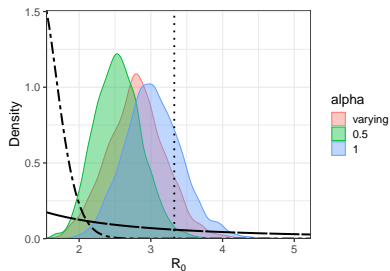
where $S(t) + I(t) + R(t) = N \forall t$, β is the transmission (infection) rate and γ is the recovery rate. The basic reproductive number is

$$R_0 = \frac{\beta N}{\gamma}. \quad (7)$$

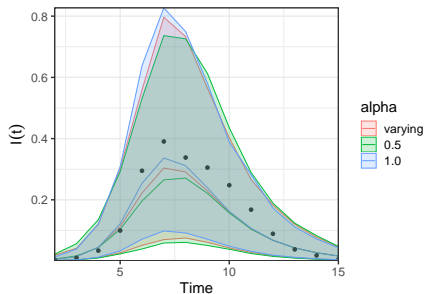
We choose $\beta, \gamma \sim \text{log-normal}(0, 1)$ (q_1) and $R_0 \sim \text{log-normal}(\mu_2, \sigma_2)$ such that R_0 has a mean of 1.5 and a standard deviation of 0.25 (q_2) which is informed by seasonal flu.



SIR model: results



(c) R_0



(d) Predictions

Posterior for α : **0.77** (0.18–0.99).



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- Interpretation of the weights is not always straightforward;
- In Bayesian melding, letting the pooling weight α vary leads to more robust inferences.



Induce-then-pool or pool-then-induce?

Question: what to do when $M : \Theta \rightarrow \Phi$ is non-invertible? We may want to gain insight about ϕ , even though we only have expert opinions on θ .

→ If we apply $M(\cdot)$ to each component of \mathbf{F}_θ , we get a set induced distributions \mathbf{G}_ϕ , which are then pooled to get $\pi_P(\phi)$ [**induce-then-pool**];



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- When M is non-invertible, things get complicated, as we shall see.



SIR model (again)

Recall that $\theta = \{\beta, \gamma\}$ and $M(\theta) = R_0$. Suppose $p(\beta, \gamma) = p(\beta)p(\gamma)$.

Useful result:

If $\beta \sim \text{Gamma}(k_\beta, t_\beta)$ and $\gamma \sim \text{Gamma}(k_\gamma, t_\gamma)$, then

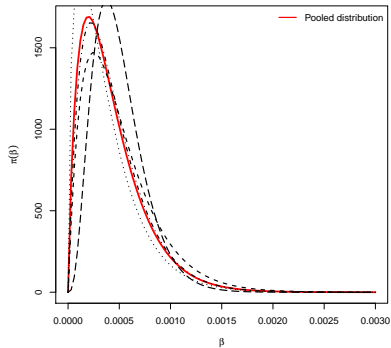
$$f_{R_0}(r \mid k_\beta, t_\beta, k_\gamma, t_\gamma, N) = \frac{(Nt_\beta t_\gamma)^{k_1+k_2}}{\mathcal{B}(k_\beta, k_\gamma)(Nt_\beta)^{k_\beta} t_\gamma^{k_\gamma}} R_0^{k_\beta-1} (t_\gamma R_0 + Nt_\beta)^{-(k_\beta+k_\gamma)}$$

where $\mathcal{B}(a, b) = \Gamma(a+b)/\Gamma(a)\Gamma(b)$ is the Beta function.



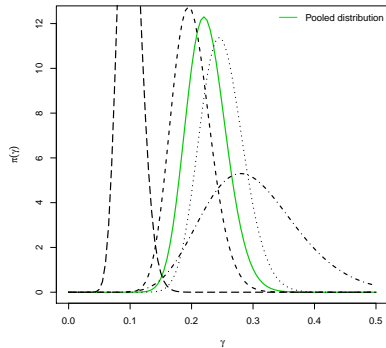
SIR model – Priors

Pooled distribution for the transmission rate



(e)

Pooled distribution for the recovery/removal rate



(f)



Pool-then-induce

- Pool:

$$\pi(\beta) = \text{Gamma}(t_1^*, k_1^*)$$

$$\pi(\gamma) = \text{Gamma}(t_2^*, k_2^*)$$

where $t^* = \sum_{i=0}^K \alpha_i t_i$ and $k^* = \sum_{i=0}^K \alpha_i k_i$. Then

- Induce:

$$\pi(R_0) \propto R_0^{k_1^*-1} (t_2^* R_0 + N t_1^*)^{-(k_1^*+k_2^*)}$$

- Nice!



Induce-then-pool

- Induce (transform) each distribution (Gamma ratio):

$$g_i(R_0) \propto R_0^{k_1-1} (t_2 R_0 + N t_1)^{-(k_1+k_2)}$$

then

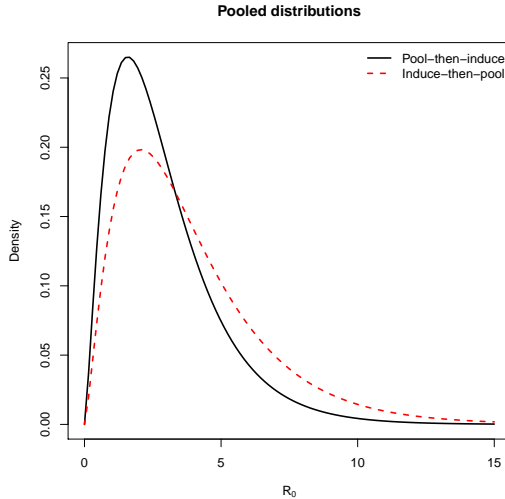
- Pool:

$$\pi'(R_0) \propto \prod_{i=0}^K g_i(R_0)^{\alpha_i}$$

- Ugly!



Pool-then-induce vs Induce-then-pool





A final result

Remark 1

It is possible to have $\pi_\phi \equiv \pi'_\phi$ even when M is not invertible.

Proof.

By an explicit example. Let $\theta \sim \text{normal}(0, \sigma^2)$ and let $M(\theta) = \theta^2$. If we define $\Omega(\phi) := \{x : M(x) = \phi\}$ then clearly $\Omega(\phi) = \{\omega_0, \omega_1\} = \{-\sqrt{\phi}, \sqrt{\phi}\}$ and hence

$$\begin{aligned} g_i(\phi) &= \frac{f_i(\omega_0)}{|2\omega_0|} + \frac{f_i(\omega_1)}{|2\omega_1|}, \\ &= \frac{f_i(\sqrt{\phi})}{\sqrt{\phi}} = \frac{1}{\sqrt{2\pi v_i \phi}} \exp\left(-\frac{\phi}{2v_i}\right), \end{aligned}$$

where the second line follows by using the symmetry of f_i around zero. Rest of the proof follows analogously to the arguments in [Carvalho et al. \(2019\)](#) for the pool of Gaussians. □



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- τ_h Letting the weights vary can lead to more flexible prior modelling and better posterior inferences;
- τ_h Further work is needed in order to make logarithmic pooling widely applicable in Statistics.



Thank you!

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- All the necessary code and data are publicly available at https://github.com/maxbiostat/opinion_pooling



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