

On the choice of weights for logarithmic pooling of probability distributions.

Luiz Max F. de Carvalho [lmax.procc@gmail.com], Daniel Villela, Flávio
Coelho & Leonardo S. Bastos

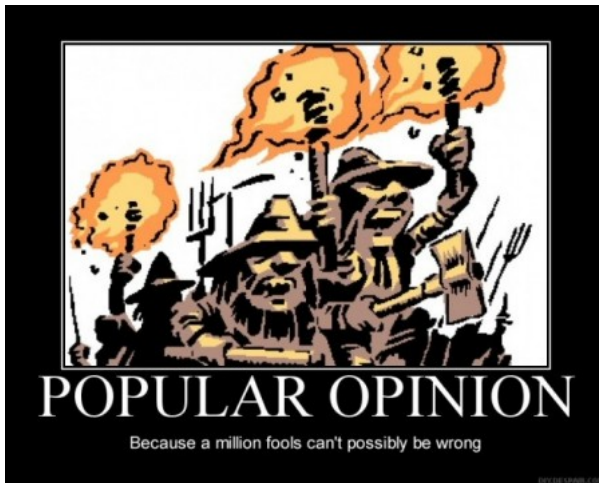
Scientific Computing Program (PROCC), Oswaldo Cruz Foundation, Fiocruz, Brazil.
Presented at the School of Applied Mathematics, Getúlio Vargas Foundation (FGV), Rio de Janeiro.

June 25, 2019

Combining (expert) opinions



Ministério da Saúde
FIOCRUZ
Fundação Oswaldo Cruz





Logarithmic pooling – Definition & Notation

Let $\mathbf{F}_\theta = \{f_0(\theta), f_1(\theta), \dots, f_K(\theta)\}$ be the set of prior distributions representing the opinions of $K + 1$ experts and let $\alpha = \{\alpha_0, \alpha_1, \dots, \alpha_K\}$ be the vector of weights, such that $\alpha_i > 0 \forall i$ and $\sum_{i=0}^K \alpha_i = 1$. Then the log-pooled prior is

$$\mathcal{LP}(\mathbf{F}_\theta, \alpha) := \pi(\theta \mid \alpha) = t(\alpha) \prod_{i=0}^K f_i(\theta)^{\alpha_i}, \quad (1)$$

where the normalising term $t(\alpha) = \int_{\Theta} \prod_{i=0}^K f_i(\theta)^{\alpha_i} d\theta$ is guaranteed to exist for all proper f_i . We simplify the proof given by [Genest et al. \(1986\)](#) by using Hölder's inequality. This operator enjoys a number of desirable properties such as external Bayesianity ([Genest et al., 1986](#)), relative propensity consistency ([Genest et al., 1984](#)) and log-concavity ([Carvalho et al., 2019](#)).



Logarithmic pooling – Properties

Property 1

External Bayesianity (**Genest et al., 1984**). Combining the set of posteriors $p_i(\theta | x) \propto l(x | \theta)f_i(\theta)$ yields the same distribution as combining the densities f_i to obtain a prior $\pi(\theta)$ and then combine it with $l(x | \theta)$ to obtain a posterior $p(\theta | x) \propto l(x | \theta)\pi(\theta)$.

Property 2

Log-concavity. Let \mathbf{F}_θ be a set of log-concave distributions, i.e., each f_i can be written as $f_i(\theta) \propto e^{\nu_i(\theta)}$, where $\nu_i(\cdot)$ is a concave function. Then $\pi(\theta | \alpha)$ is also log-concave.



Logarithmic pooling – more properties

Property 3

Relative propensity consistency (Genest et al., 1984). Taking F_X as a set of expert opinions with support on a space \mathcal{X} , define $\xi = \{F_X, a, b\}$ for arbitrary $a, b \in \mathcal{X}$. Let \mathcal{T} be a pooling operator and define two functions U and V such that

$$U(\xi) := \left(\frac{f_0(a)}{f_0(b)}, \frac{f_1(a)}{f_1(b)}, \dots, \frac{f_K(a)}{f_K(b)} \right) \text{ and} \quad (2)$$

$$V(\xi) := \frac{\mathcal{T}_{F_X}(a)}{\mathcal{T}_{F_X}(b)}. \quad (3)$$

We then say that \mathcal{T} enjoys relative propensity consistency (RPC) if and only if

$$U(\xi_1) \geq U(\xi_2) \implies V(\xi_1) \geq V(\xi_2), \quad (4)$$

for all ξ_1, ξ_2 .

- Properties 1 and 3 are **unique** to logarithmic pooling.



Weights are crucial

The weights α are key to the shape and properties of the combined (pooled) distribution.

- In theory, the weights should reflect the *reliabilities* of the experts/information sources;



Weights are crucial

The weights α are key to the shape and properties of the combined (pooled) distribution.

- In theory, the weights should reflect the *reliabilities* of the experts/information sources;
- In practice, reliabilities are hard to determine;



Weights are crucial

The weights α are key to the shape and properties of the combined (pooled) distribution.

- In theory, the weights should reflect the *reliabilities* of the experts/information sources;
- In practice, reliabilities are hard to determine;
- As we will see, combining probability distributions in particular can lead to counterintuitive results.



Weights are crucial

The weights α are key to the shape and properties of the combined (pooled) distribution.

- In theory, the weights should reflect the *reliabilities* of the experts/information sources;
- In practice, reliabilities are hard to determine;
- As we will see, combining probability distributions in particular can lead to counterintuitive results.

Here we will consider three ways of constructing the weights “objectively”:

→ Maximise the entropy of π ;



Weights are crucial

The weights α are key to the shape and properties of the combined (pooled) distribution.

- In theory, the weights should reflect the *reliabilities* of the experts/information sources;
- In practice, reliabilities are hard to determine;
- As we will see, combining probability distributions in particular can lead to counterintuitive results.

Here we will consider three ways of constructing the weights “objectively”:

- Maximise the entropy of π ;
- Minimise the Kullback-Leibler divergence between π and each f_i ;



Weights are crucial

The weights α are key to the shape and properties of the combined (pooled) distribution.

- In theory, the weights should reflect the *reliabilities* of the experts/information sources;
- In practice, reliabilities are hard to determine;
- As we will see, combining probability distributions in particular can lead to counterintuitive results.

Here we will consider three ways of constructing the weights “objectively”:

- Maximise the entropy of π ;
- Minimise the Kullback-Leibler divergence between π and each f_i ;
- Place a probability measure over α .



Maximise the entropy of $\pi(\theta)$

- If there is no information about the reliabilities of the experts one might want to construct α so as to maximise entropy of the resulting distribution:

$$H_{\pi}(\theta) = - \int_{\Theta} \pi(\theta) \ln \pi(\theta) d\theta$$
$$H_{\pi}(\theta; \alpha) = - \sum_{i=0}^K \alpha_i E_{\pi}[\log f_i] - \log t(\alpha).$$

- Formally, we want to find $\hat{\alpha}$ such that

$$\hat{\alpha} := \arg \max H_{\pi}(\theta; \alpha)$$

- Caveats: (i) is not guaranteed to yield an unique solution; (ii) is rather prone to yield “degenerate” (trivial) solutions.



Minimise KL divergence between $\pi(\theta)$ and the f_i 's

- What if we want to minimise conflict between the consensus and each individual opinion?
- Let $d_i = \text{KL}(\pi || f_i)$ and let $L(\alpha)$ be a loss function such that

$$\begin{aligned} L(\alpha) &= \sum_{i=0}^K d_i \\ &= -(K+1) \sum_{i=0}^K \alpha_i \mathbb{E}_{\pi} [\log f_i] - \sum_{i=0}^K \mathbb{E}_{\pi} [\log f_i] - \log t(\alpha), \\ \hat{\alpha} &:= \arg \min L(\alpha) \end{aligned}$$

- Contrary to the maximum entropy problem, the loss function is convex, thus there is a unique solution (Rufo et al., 2012).



Place a prior on the weights

- An appealing alternative is to place a (hyper) prior on the weights (α);
- Two approaches:
 - (a) Dirichlet prior:

$$\pi_A(\alpha \mid \mathbf{X}) = \frac{1}{\mathcal{B}(\mathbf{X})} \prod_{i=0}^K \alpha_i^{x_i-1}.$$

- (b) logistic-normal:

$$\pi_A(\alpha \mid \mu, \Sigma) = \frac{1}{|2\pi\Sigma|^{\frac{1}{2}}} \frac{1}{\prod_{i=0}^K \alpha_i} \exp\left((\eta - \mu)^T \Sigma^{-1} (\eta - \mu)\right),$$
$$\eta := \log\left(\frac{\alpha_{-K}}{\alpha_K}\right).$$

- Advantage: accomodates uncertainty in natural way, and is very flexible;
- Caveat(s): may yield inconsistent results and hardly ever allows for analytical solutions for the marginal prior $g(\theta) = \int_{\mathcal{A}} \pi(\theta \mid \alpha) d\Pi_A$.



Priors on the weights: details

- Match the first two moments of the Logistic-normal to the Dirichlet (**Aitchison and Shen, 1980**):

$$\begin{aligned}\mu_i &= \psi(x_i) - \psi(x_K), \quad i = 0, 1, \dots, K-1, \\ \Sigma_{ii} &= \psi'(x_i) + \psi'(x_K), \quad i = 0, 1, \dots, K-1, \\ \Sigma_{ij} &= \psi'(x_K),\end{aligned}$$

where $\psi(\cdot)$ is the digamma function, and $\psi'(\cdot)$ is the trigamma function.

- Exploit a non-centering trick to sample from the logistic normal *via* Cholesky decomposition of Σ ;
- We explore two sets of hyperparameters: $\mathbf{X} = \{1, 1, \dots, 1\}$ and $\mathbf{X}' = \mathbf{X}/10$ (“flexible” henceforth);



Application: survival probabilities (reliability)

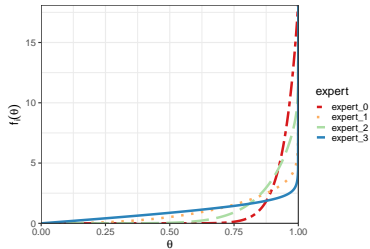
- **Savchuk and Martz (1994)** consider an example in which four experts are required supply prior information about the survival probability of a certain unit for which there have been $y = 9$ successes out of $n = 10$ trials;
- $Y \sim \text{Bernoulli}(\theta)$ and

$$f_i(\theta; a_i, b_i) = \frac{\Gamma(a_i + b_i)}{\Gamma(a_i)\Gamma(b_i)} \theta^{a_i-1} (1 - \theta)^{b_i-1}$$

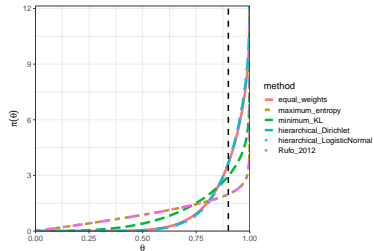
- Allows for simple expressions for the entropy and KL divergence – $\pi(\theta | \alpha)$ is also Beta – and efficient sampling from the hyperpriors;
- For this example, we can evaluate performance using integrated (marginal) likelihoods, a.k.a., prior evidence.



Survival probabilities: results



(a) Expert priors



(b) Pooled priors



Survival probabilities: results II

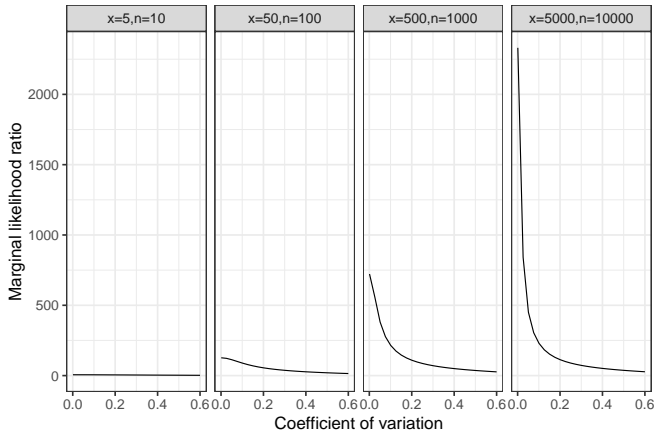
Method	α_0	α_1	α_2	α_3
Maximum entropy	0.00	0.00	0.00	1.00
Minimum KL divergence	0.04	0.96	0.00	0.00
Rufo et al. (2012)	0.00	0.00	0.00	1.00
Dirichlet prior	0.26	0.24	0.27	0.23
Logistic-normal prior	0.27	0.24	0.31	0.18

Expert priors		Pooled priors	
Expert 0	0.237	Equal weights	0.254
Expert 1	0.211	Maximum entropy	0.163
Expert 2	0.256	Minimum KL	0.223
Expert 3	0.163	Hierarchical prior (Dirichlet/logistic-normal)	0.255



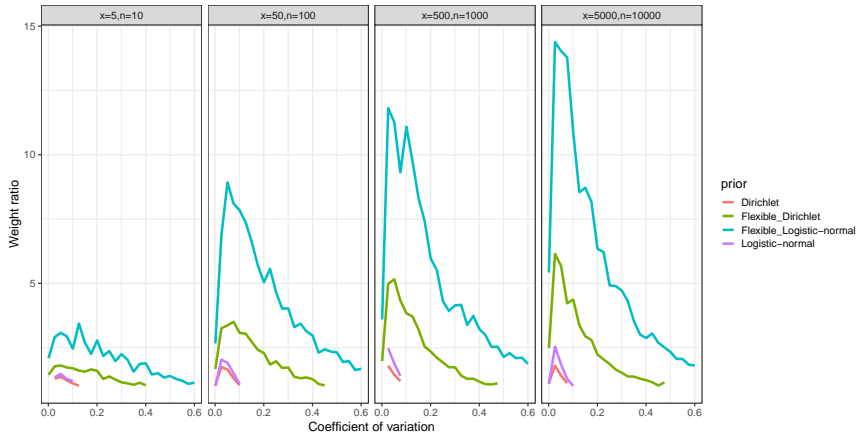
Simulated example: can we reliably learn the weights?

Setup: Five experts elicit Beta priors on a quantity p . Data will be $x/n = 5/10$. Only expert 2 (let's call her Mãe Diná) gives a reasonable prior with mean $\mu_2 = 0.50$ and coefficient of variation c_2 .





Simulated example: performance of hierarchical priors





Simulated example: explaining the weirdness

- Let $c_2 = 0.2$ and $c_j = 0.1$ for all $j \neq 2$, with $\mu = \{0.1, 0.2, \mathbf{0.5}, 0.8, 0.9\}$;



Simulated example: explaining the weirdness

- Let $c_2 = 0.2$ and $c_j = 0.1$ for all $j \neq 2$, with $\mu = \{0.1, 0.2, \mathbf{0.5}, 0.8, 0.9\}$;
- This setup leads to $\mathbf{a} = \{89.9, 79.8, \mathbf{12.0}, 19.2, 9.1\}$ and $\mathbf{b} = \{809.1, 319.2, \mathbf{12.0}, 4.8, 1.01\}$;



Simulated example: explaining the weirdness

- Let $c_2 = 0.2$ and $c_j = 0.1$ for all $j \neq 2$, with $\mu = \{0.1, 0.2, \mathbf{0.5}, 0.8, 0.9\}$;
- This setup leads to $\mathbf{a} = \{89.9, 79.8, \mathbf{12.0}, 19.2, 9.1\}$ and $\mathbf{b} = \{809.1, 319.2, \mathbf{12.0}, 4.8, 1.01\}$;
- If the data are $x = 5$ and $n = 10$, computing marginal likelihoods and normalising would lead to weights $\alpha'' = \{0.006, 0.095, \mathbf{0.710}, 0.142, 0.048\}$;



Simulated example: explaining the weirdness

- Let $c_2 = 0.2$ and $c_j = 0.1$ for all $j \neq 2$, with $\mu = \{0.1, 0.2, \mathbf{0.5}, 0.8, 0.9\}$;
- This setup leads to $\mathbf{a} = \{89.9, 79.8, \mathbf{12.0}, 19.2, 9.1\}$ and $\mathbf{b} = \{809.1, 319.2, \mathbf{12.0}, 4.8, 1.01\}$;
- If the data are $x = 5$ and $n = 10$, computing marginal likelihoods and normalising would lead to weights $\alpha'' = \{0.006, 0.095, \mathbf{0.710}, 0.142, 0.048\}$;
- However, by calculating $a^{**} = \sum_{i=0}^K \alpha_i'' a_i = 19.75$ and $b^{**} = \sum_{i=0}^K \alpha_i'' b_i = 44.00$, we obtain a pooled prior with $\mathbb{E}_\pi[p] = 0.31$, far off the “optimal” $1/2$;



Simulated example: explaining the weirdness

- Let $c_2 = 0.2$ and $c_j = 0.1$ for all $j \neq 2$, with $\mu = \{0.1, 0.2, \mathbf{0.5}, 0.8, 0.9\}$;
- This setup leads to $\mathbf{a} = \{89.9, 79.8, \mathbf{12.0}, 19.2, 9.1\}$ and $\mathbf{b} = \{809.1, 319.2, \mathbf{12.0}, 4.8, 1.01\}$;
- If the data are $x = 5$ and $n = 10$, computing marginal likelihoods and normalising would lead to weights $\alpha'' = \{0.006, 0.095, \mathbf{0.710}, 0.142, 0.048\}$;
- However, by calculating $a^{**} = \sum_{i=0}^K \alpha_i'' a_i = 19.75$ and $b^{**} = \sum_{i=0}^K \alpha_i'' b_i = 44.00$, we obtain a pooled prior with $\mathbb{E}_\pi[p] = 0.31$, far off the “optimal” $1/2$;
- If the data were, say, $x = 50$, $n = 100$, then one would obtain a pooled prior for which $\mathbb{E}_\pi[p] = 0.51$.



Simulated example: explaining the weirdness

- Let $c_2 = 0.2$ and $c_j = 0.1$ for all $j \neq 2$, with $\mu = \{0.1, 0.2, \mathbf{0.5}, 0.8, 0.9\}$;
- This setup leads to $\mathbf{a} = \{89.9, 79.8, \mathbf{12.0}, 19.2, 9.1\}$ and $\mathbf{b} = \{809.1, 319.2, \mathbf{12.0}, 4.8, 1.01\}$;
- If the data are $x = 5$ and $n = 10$, computing marginal likelihoods and normalising would lead to weights $\alpha'' = \{0.006, 0.095, \mathbf{0.710}, 0.142, 0.048\}$;
- However, by calculating $a^{**} = \sum_{i=0}^K \alpha_i'' a_i = 19.75$ and $b^{**} = \sum_{i=0}^K \alpha_i'' b_i = 44.00$, we obtain a pooled prior with $\mathbb{E}_\pi[p] = 0.31$, far off the “optimal” $1/2$;
- If the data were, say, $x = 50$, $n = 100$, then one would obtain a pooled prior for which $\mathbb{E}_\pi[p] = 0.51$.
- Now let $c_2 = 0.001$. Then $a_2 = b_2 = 499999.5$. Can you see the problem?



Bayesian melding

Suppose we have deterministic model M with inputs $\theta \in \Theta \subseteq \mathbb{R}^p$ and outputs $\phi \in \Phi \subseteq \mathbb{R}^q$, such that $\phi = M(\theta)$. We have the combined prior on the outputs:

$$\tilde{q}_\Phi(\phi) \propto q_1^*(\phi)^\alpha q_2(\phi)^{1-\alpha}, \quad (5)$$

where $q_1^*(\cdot)$ is the **induced** and q_2 is “natural” prior on ϕ . The prior in (5) can then be inverted to obtain a *coherised* prior on θ , $\tilde{q}_\Theta(\theta)$. Standard Bayesian inference may then follow, leading to the posterior

$$p_\Theta(\theta \mid \mathbf{y}, \alpha) \propto \tilde{q}_\Theta(\theta) L_1(\theta) L_2(M(\theta)) \pi_A(\alpha). \quad (6)$$



Application: Influenza in a boarding school

In 1978, 512 out of 763 lads got came down with the flu. We model the spread using a standard SIR model

$$\begin{aligned}\frac{dS}{dt} &= -\beta SI, \\ \frac{dI}{dt} &= \beta SI - \gamma I, \\ \frac{dR}{dt} &= \gamma I,\end{aligned}$$

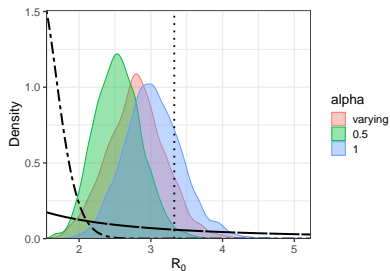
where $S(t) + I(t) + R(t) = N \forall t$, β is the transmission (infection) rate and γ is the recovery rate. The basic reproductive number is

$$R_0 = \frac{\beta N}{\gamma}. \quad (7)$$

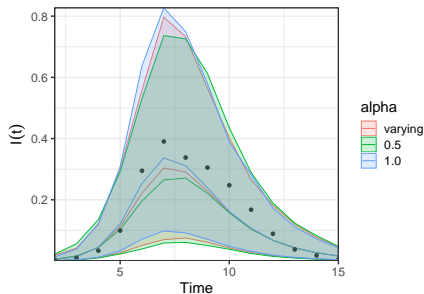
We choose $\beta, \gamma \sim \text{log-normal}(0, 1)$ (q_1) and $R_0 \sim \text{log-normal}(\mu_2, \sigma_2)$ (q_2) such that R_0 has a mean of 1.5 and a standard deviation of 0.25 (q_2) which is informed by seasonal flu.



SIR model: results



(c) R_0



(d) Predictions

Posterior for α : **0.77** (0.18–0.99).



Partial Sum up

- Optimality criteria often give weird results;



Partial Sum up

- Optimality criteria often give weird results;
- It is possible to learn about the weights from data, for some configurations of the opinions \mathbf{F}_X (and the data \mathbf{y});



Partial Sum up

- Optimality criteria often give weird results;
- It is possible to learn about the weights from data, for some configurations of the opinions \mathbf{F}_X (and the data \mathbf{y});
- Interpretation of the weights is not always straightforward;



- Optimality criteria often give weird results;
- It is possible to learn about the weights from data, for some configurations of the opinions \mathbf{F}_X (and the data \mathbf{y});
- Interpretation of the weights is not always straightforward;
- In Bayesian melding, letting the pooling weight α vary can protect against prior misspecification.



Induce-then-pool or pool-then-induce?

Question: what to do when $M : \Theta \rightarrow \Phi$ is non-invertible? We may want to gain insight about ϕ , even though we only have expert opinions on θ .

→ If we apply $M(\cdot)$ to each component of \mathbf{F}_θ , we get a set induced distributions \mathbf{G}_ϕ , which are then pooled to get $\pi_P(\phi)$ [**induce-then-pool**];



Induce-then-pool or pool-then-induce?

Question: what to do when $M : \Theta \rightarrow \Phi$ is non-invertible? We may want to gain insight about ϕ , even though we only have expert opinions on θ .

- If we apply $M(\cdot)$ to each component of \mathbf{F}_θ , we get a set induced distributions \mathbf{G}_ϕ , which are then pooled to get $\pi_P(\phi)$ [**induce-then-pool**];
- Alternatively, we can combine the $f_i(\theta)$ to obtain $\pi_T(\theta)$ and then transform to get a distribution $\pi'_P(\phi)$ [**pool-then-induce**];



Induce-then-pool or pool-then-induce?

Question: what to do when $M : \Theta \rightarrow \Phi$ is non-invertible? We may want to gain insight about ϕ , even though we only have expert opinions on θ .

- If we apply $M(\cdot)$ to each component of \mathbf{F}_θ , we get a set induced distributions \mathbf{G}_ϕ , which are then pooled to get $\pi_P(\phi)$ [**induce-then-pool**];
- Alternatively, we can combine the $f_i(\theta)$ to obtain $\pi_T(\theta)$ and then transform to get a distribution $\pi'_P(\phi)$ [**pool-then-induce**];
- **Remark:** if $M(\cdot)$ is invertible, $\pi_P(\phi) \equiv \pi'_P(\phi)$.



Induce-then-pool or pool-then-induce?

Question: what to do when $M : \Theta \rightarrow \Phi$ is non-invertible? We may want to gain insight about ϕ , even though we only have expert opinions on θ .

- If we apply $M(\cdot)$ to each component of \mathbf{F}_θ , we get a set induced distributions \mathbf{G}_ϕ , which are then pooled to get $\pi_P(\phi)$ [**induce-then-pool**];
- Alternatively, we can combine the $f_i(\theta)$ to obtain $\pi_T(\theta)$ and then transform to get a distribution $\pi'_P(\phi)$ [**pool-then-induce**];
- **Remark:** if $M(\cdot)$ is invertible, $\pi_P(\phi) \equiv \pi'_P(\phi)$.
- When M is non-invertible, things get complicated, as we shall see.



SIR model (again)

Recall that $\theta = \{\beta, \gamma\}$ and $M(\theta) = R_0$. Suppose $p(\beta, \gamma) = p(\beta)p(\gamma)$.

Useful result:

If $\beta \sim \text{Gamma}(k_\beta, t_\beta)$ and $\gamma \sim \text{Gamma}(k_\gamma, t_\gamma)$, then

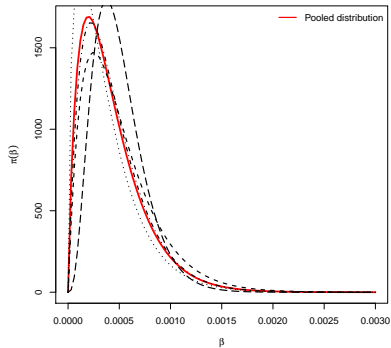
$$f_{R_0}(r \mid k_\beta, t_\beta, k_\gamma, t_\gamma, N) = \frac{(Nt_\beta t_\gamma)^{k_1+k_2}}{\mathcal{B}(k_\beta, k_\gamma)(Nt_\beta)^{k_\beta} t_\gamma^{k_\gamma}} R_0^{k_\beta-1} (t_\gamma R_0 + Nt_\beta)^{-(k_\beta+k_\gamma)}$$

where $\mathcal{B}(a, b) = \Gamma(a+b)/\Gamma(a)\Gamma(b)$ is the Beta function.



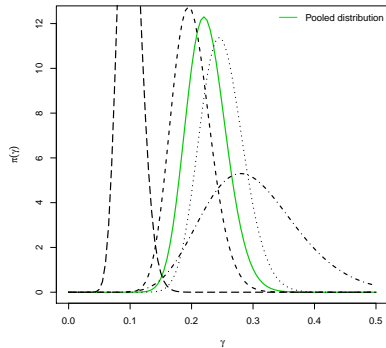
SIR model – Priors

Pooled distribution for the transmission rate



(e)

Pooled distribution for the recovery/removal rate



(f)



Pool-then-induce

- Pool:

$$\pi(\beta) = \text{Gamma}(t_1^*, k_1^*)$$

$$\pi(\gamma) = \text{Gamma}(t_2^*, k_2^*)$$

where $t^* = \sum_{i=0}^K \alpha_i t_i$ and $k^* = \sum_{i=0}^K \alpha_i k_i$. Then

- Induce:

$$\pi(R_0) \propto R_0^{k_1^*-1} (t_2^* R_0 + N t_1^*)^{-(k_1^*+k_2^*)}$$

- Nice!



Induce-then-pool

- Induce (transform) each distribution (Gamma ratio):

$$g_i(R_0) \propto R_0^{k_1-1} (t_2 R_0 + N t_1)^{-(k_1+k_2)}$$

then

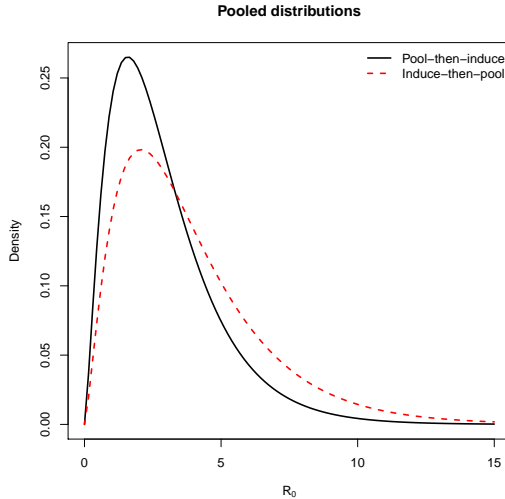
- Pool:

$$\pi'(R_0) \propto \prod_{i=0}^K g_i(R_0)^{\alpha_i}$$

- Ugly!



Pool-then-induce vs Induce-then-pool





A final result

Remark 1

It is possible to have $\pi_\phi \equiv \pi'_\phi$ even when M is not invertible.

Proof.

By an explicit example. Let $\theta \sim \text{normal}(0, \sigma^2)$ and let $M(\theta) = \theta^2$. If we define $\Omega(\phi) := \{x : M(x) = \phi\}$ then clearly $\Omega(\phi) = \{\omega_0, \omega_1\} = \{-\sqrt{\phi}, \sqrt{\phi}\}$ and hence

$$\begin{aligned} g_i(\phi) &= \frac{f_i(\omega_0)}{|2\omega_0|} + \frac{f_i(\omega_1)}{|2\omega_1|}, \\ &= \frac{f_i(\sqrt{\phi})}{\sqrt{\phi}} = \frac{1}{\sqrt{2\pi v_i \phi}} \exp\left(-\frac{\phi}{2v_i}\right), \end{aligned}$$

where the second line follows by using the symmetry of f_i around zero. Rest of the proof follows analogously to the arguments in [Carvalho et al. \(2019\)](#) for the pool of Gaussians. □



τ_h Log-linear mixtures have many desirable properties;



τ_h Log-linear mixtures have many desirable properties;

τ_h It is possible to learn the weights from data, under certain constraints;



Take home

- τ_h Log-linear mixtures have many desirable properties;
- τ_h It is possible to learn the weights from data, under certain constraints;
- τ_h Letting the weights vary can lead to more flexible prior modelling and better posterior inferences;



Take home

- τ_h Log-linear mixtures have many desirable properties;
- τ_h It is possible to learn the weights from data, under certain constraints;
- τ_h Letting the weights vary can lead to more flexible prior modelling and better posterior inferences;
- τ_h Further work is needed in order to make logarithmic pooling widely applicable in Statistics.



Thank you!

- Thank you very much for your attention!
- The authors would like to thank Professor Adrian Raftery (University of Washington) for helpful suggestions. DAMV was supported in part by Capes under Capes/Cofecub project (N. 833/15). FCC is grateful to Fundação Getulio Vargas for funding during this project.
- All the necessary code and data are publicly available at https://github.com/maxbiostat/opinion_pooling



References

- Aitchison, J. and Shen, S. M. (1980). Logistic-normal distributions: Some properties and uses. *Biometrika*, 67(2):261–272.
- Carvalho, L. M., Villela, D. V., Coelho, F. C., and Bastos, L. S. (2019). On the choice of weights for the logarithmic pooling of probability distributions. *In preparation*.
- Genest, C., McConway, K. J., and Schervish, M. J. (1986). Characterization of externally bayesian pooling operators. *The Annals of Statistics*, pages 487–501.
- Genest, C., Weerahandi, S., and Zidek, J. V. (1984). Aggregating opinions through logarithmic pooling. *Theory and Decision*, 17(1):61–70.
- Rufo, M., Martin, J., Pérez, C., et al. (2012). Log-linear pool to combine prior distributions: A suggestion for a calibration-based approach. *Bayesian Analysis*, 7(2):411–438.
- Savchuk, V. P. and Martz, H. F. (1994). Bayes reliability estimation using multiple sources of prior information: binomial sampling. *Reliability, IEEE Transactions on*, 43(1):138–144.