

Al buio non si trova:

Principled phylodynamics for pandemic preparation

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Acknowledgments



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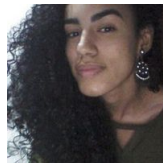
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Motivation

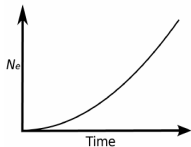
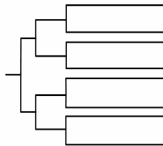
Phylogenetics of fast-evolving viruses

Inferring spatial and temporal dynamics from genomic data:

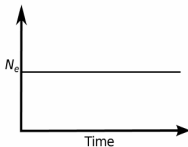
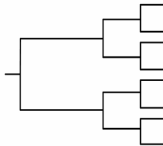
Phylogenies*!

* plus complicated models

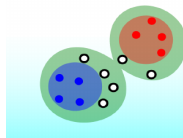
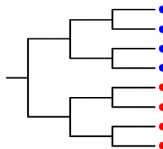
A
Exponential Growth



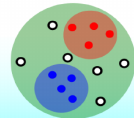
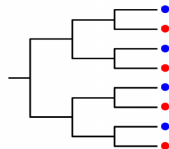
B
Constant Population Size



A
Structured Host Population



B
Unstructured Host Population



Plan for today

Statistical Problem(s)

Central object, inference, algorithms

Principled priors

Being Bayesian is great, but it ain't free

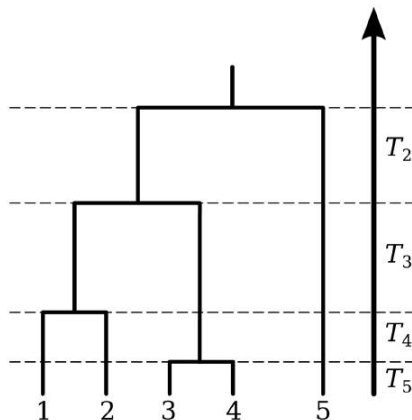
MCMC in tree space

A journey through a strange land

How to tell if phylogenetic MCMC

- A) Is correct;
- B) Works better than the state-of-the-art.

Central object: time-calibrated trees



Let T_n denote the time for n lineages to *coalesce*, i.e., merge into one ancestral lineage, in a population of size N_e . Then:

$$\Pr(T_n = t) = \lambda_n e^{-\lambda_n t}$$

$$\lambda_n = \binom{n}{2} \frac{1}{N_e} = \binom{n}{2} \frac{1}{\theta \tau}$$

where N_e is the effective population size and τ is the generation time. Let T_{mrca} denote the age of the most recent common ancestor:

$$\begin{aligned} E[T_{\text{mrca}}] &= E[T_n] + E[T_{n-1}] + \dots + E[T_2] \\ &= 1/\lambda_n + 1/\lambda_{n-1} + \dots + 1/\lambda_2 \\ &= 2N_e \left(1 - \frac{1}{n}\right) \end{aligned}$$

Figure: Figure 4 from [Volz et al. \(2013\)](#).

“Just chuck any prior”

Consider:

$$t_k \mid N_e \sim \text{Exponential} \left(\binom{n}{2} \frac{1}{N_e} \right).$$

If you pick $\pi_N(N_e) \propto 1/N_e$, i.e. the Jeffreys's-type prior, you get that the marginal prior for t_k is $\pi_T(t_k) \propto 1/t_k$.

$$P(t_k) = \exp(t_k \mathbf{Q}) = \sum_{i=0} \frac{(t_k \mathbf{Q})^i}{i!}.$$

Lemma

If \mathbf{Q} is diagonalisable, the posterior for t_k is improper¹ under a Jeffreys's prior for N_e .

¹A measure-theoretic proof of a very similar result is given in the Appendix of [Drummond et al. \(2004\)](#).

♪ Smooth operator ♪

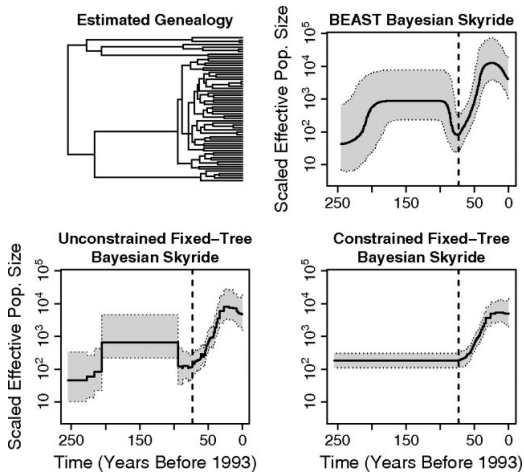


Figure: HCV in Egypt ².

²[Minin et al. \(2008\)](#). See also [Karcher et al. \(2020\)](#)

Gaussian Markov random fields to the rescue

Denote the population sizes by $\boldsymbol{\theta} = (\theta_2, \dots, \theta_n)$, the likelihood becomes

$$\Pr(\mathbf{s}|\boldsymbol{\theta}) = \prod_{k=2}^n \frac{n_{k0}(n_{k0} - 1)}{2\theta_k} \exp\left(-\sum_{j=0}^{j_k} \frac{n_{kj}(n_{kj} - 1)s_{kj}}{2\theta_k}\right),$$

$$\Pr(\boldsymbol{\gamma}|\boldsymbol{\tau}) \propto \tau^{(n-2)/2} \exp\left(-\frac{\tau}{2} \sum_{k=2}^{n-1} \frac{(\gamma_{k+1} - \gamma_k)^2}{\delta_k}\right),$$

where $\gamma_k = \log(\theta_k)$, $k = 2, \dots, n$, δ_k is the (1d) distance between intervals and τ is the precision parameter associated with the smoothing.

[Simpson et al. \(2017\)](#) propose proper priors that penalise deviations from a simple base model (“complexity”). For the GMRF precision, this prior is a Gumbel type II family:

$$\pi_2(\tau \mid a, b) = ab \cdot \tau^{-a-1} \exp(-b\tau^{-a}), \tau > 0. \quad (1)$$

We set $a = 1/2$ and b such that $\Pr(1/\sqrt{\tau} > S) = p$, where the value S and the probability p are to be chosen on substantive grounds – e.g. $S = 1$ and $p = 0.1$. We can then find $b = -\ln(p)/S$.

Some reconstructions are sensitive to the prior

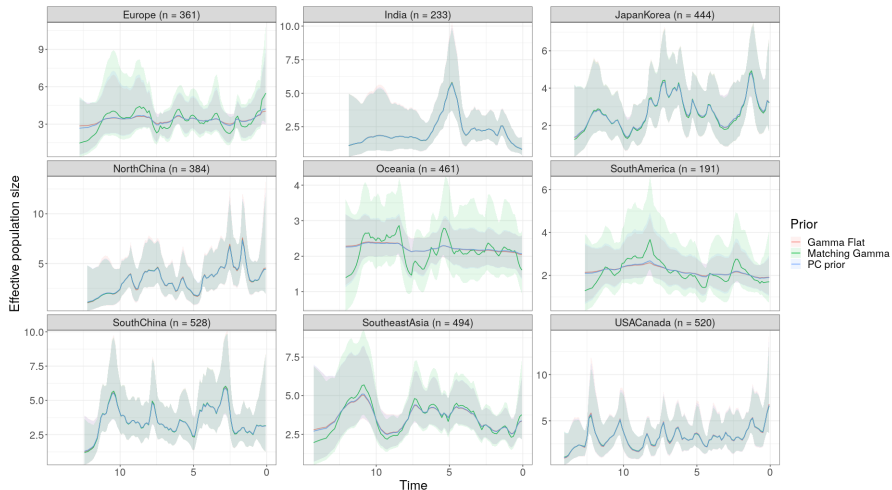


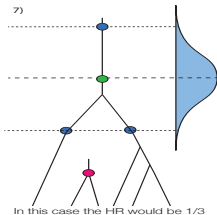
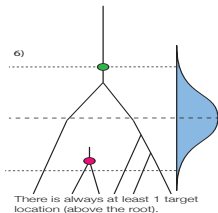
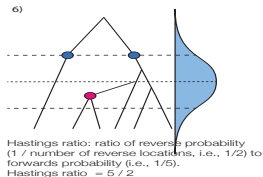
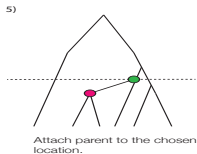
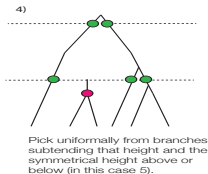
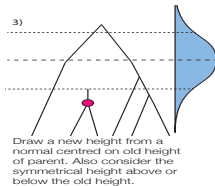
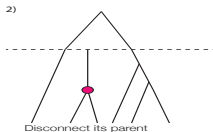
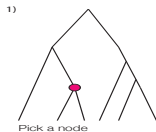
Figure: Regional Influenza

The phylogenetic target

$$p(t, \mathbf{b}, \boldsymbol{\omega} | D) = \frac{f(D | t, \mathbf{b}, \boldsymbol{\omega}) \pi(t, \mathbf{b}, \boldsymbol{\omega})}{\sum_{t_i \in T_n} \int_B \int_{\Omega} f(D | t_i, \mathbf{b}_i, \boldsymbol{\omega}) \pi(t_i, \mathbf{b}_i, \boldsymbol{\omega}) d\boldsymbol{\omega} d\mathbf{b}_i}. \quad (2)$$

- ⊙ D : observed sequence (DNA) data;
- ⊙ T_n : set of all binary ranked trees ($\mathbb{G}^{(2n-3)!!}$);
- ⊙ \mathbf{b}_k : set of branch lengths of $t_k \in T_n$ (\mathbb{R}_+^{2n-2} , kind of) ;
- ⊙ $\boldsymbol{\omega}$: set of parameters of interest such as substitution model parameters, migration rates, heritability coefficients, etc.

Traversing treespace: SubTreeLeap (STL)



Carvalho (2019), Chapter 2.

Lemma

Assume strictly positive branch lengths. Then SubTreeLeap induces an irreducible Markov chain on \mathbb{G} .

Sketch: Starting at $x \in \mathbb{G}$, notice there exists $\delta_y^\star > 0$ such that $P(x \rightarrow y \mid \delta_y^\star) > 0$ for any tree $y \in \mathbb{G}$ in the SPR neighbourhood of x .

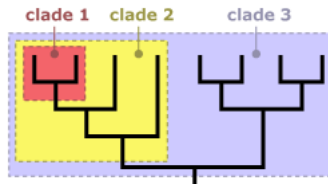
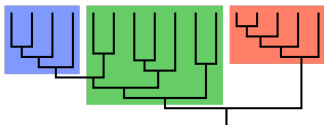
Theorem

Assume the target satisfies $p(A) > 0$ for all $A \subset \Psi$. Then, SubTreeLeap induces an ergodic Markov chain on Ψ .

Sketch: Employ the remark to get to the case where $d_{\text{SPR}}(x, y) = 0$ and then establish Harris recurrence.

A lower-dimensional projection

A clade is a partition of the set of leaves and two clades $A = A_1|A_2$ and $B = B_1|B_2$ are said to be compatible if at least one of $A_i \cap B_j$, $i, j = 1, 2$ is empty. Here's a picture³:



³Pictures taken from Wikipedia and from https://evolution.berkeley.edu/evolibrary/news/080301_elephantshrew

Why clades?

- ⊙ **Dimension!** $|\mathbb{T}_n| = (2n - 3)!!$ vs $|\mathbb{C}_n| = 2^{n-1} - 1$
- ⊙ Interpretability;
- ⊙ Under simplifying assumptions, clades are independent ([Larget, 2013](#)⁴);
- ⊙ Clade distribution is known under popular prior distributions.

⁴but see [Whidden & Matsen, 2015](#) and [Zang & Matsen, 2018](#).

Clade indicators during MCMC

Let $X_j^{(i)} \in \{0, 1\}$ be the indicator of whether clade j in the tree sampled at the i -th iteration and $\hat{p}_j = M^{-1} \sum_{i=1}^M X_j^{(i)}$ be a simple MCMC estimator of its marginal success probability.



Playing pretend

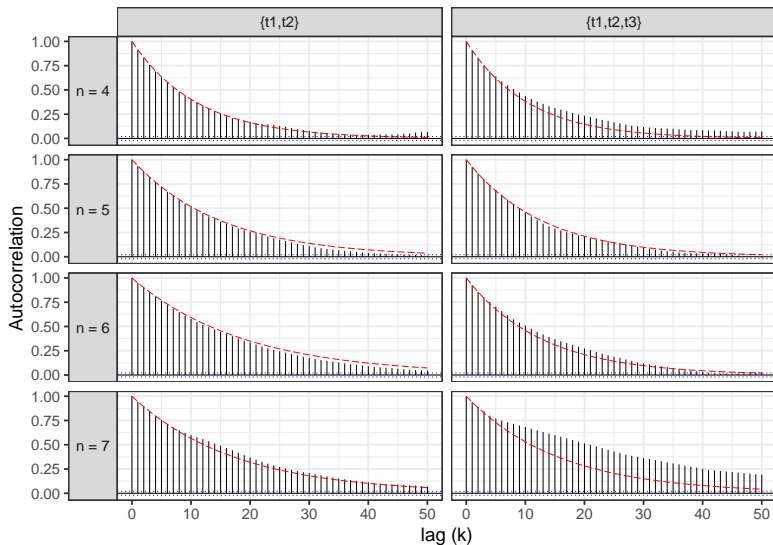
Pretend for a second $(X_j^{(i)})_{i \geq 0}$ is Markov on $\mathcal{X} = \{0, 1\}$ and reparametrise the usual two-state model as

$$\tilde{P}_x := \begin{bmatrix} 1 - \alpha & \alpha \\ \alpha \frac{1-p}{p} & \frac{p - \alpha(1-p)}{p} \end{bmatrix}, \quad (3)$$

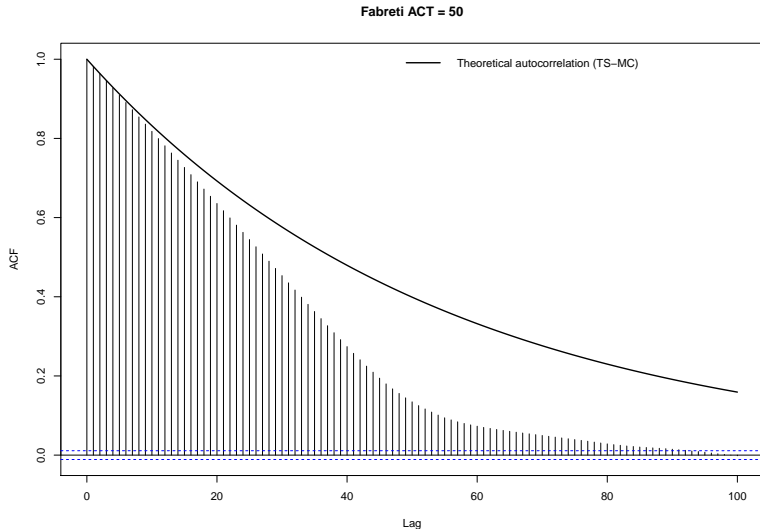
where p is the marginal success probability and a α controls the “flipping rate” of the chain. Then

$$\begin{aligned} \text{ESS} &= \frac{M}{1 + 2 \sum_{t=1}^{\infty} \rho_t}, \\ &= \frac{M}{1 + 2 \frac{p - \alpha}{\alpha}}, \\ &= \frac{\alpha}{2p - \alpha} M. \end{aligned}$$

Lumpability in clade space



Doesn't always work



$$\rho_n(A, B) = \frac{p_n(A, B) - p_n(A)p_n(B)}{\sqrt{p_n(A)[1 - p_n(A)]p_n(B)[1 - p_n(B)]}}.$$

Theorem (Minimum and maximum correlation)

For $n \geq 4$, the minimum and maximum values for $\rho_n(A, B)$ are, respectively

$$\rho_{\min}(n) = -\frac{2}{3n-5},$$

$$\rho_{\max}(n) = \frac{2u(n)k(n) - 4n^2(n-1)}{2n(n-1)\sqrt{\left[\lfloor \frac{n}{2} \rfloor (\lfloor \frac{n}{2} \rfloor + 1) k(n) - 2n\right] \left[\lceil \frac{n}{2} \rceil (\lceil \frac{n}{2} \rceil + 1) k(n) - 2n\right]}},$$

Measuring efficiency

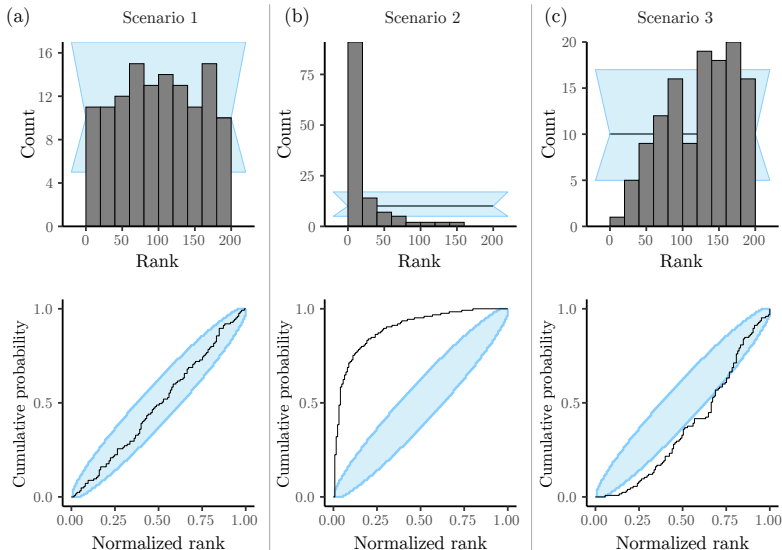
Thus, we can employ the idea from [Vats, Flegal & Jones \(2019\)](#):
[Magee et al, 2021](#) point out that trees are fundamentally multivariate objects.

$$\text{mESS} = M \left(\frac{\det(\Lambda)}{\det(\Sigma)} \right)^{1/p}.$$

```
> ( evals.naive <- eigen(cov.dep, only.values = TRUE)$values )  
[1] 2.460008e-01 2.357391e-01 2.161817e-01 1.374673e-01 8.833706e-02 7.734214e-02  
[7] 5.809434e-02 3.283007e-02 1.535663e-02 8.976874e-03 3.982149e-03 2.242468e-03  
[13] 1.437667e-03 6.836824e-04 4.688762e-04 3.356731e-04 1.117728e-17 4.321235e-18  
[19] 1.419069e-18 5.143897e-20 -1.708911e-19 -1.086942e-18 -8.299469e-18 -3.081920e-17  
> ( evals.robust <- eigen(robust.cov.dep, only.values = TRUE)$values )  
[1] 2.459980e-01 2.357382e-01 2.161232e-01 1.374668e-01 8.833950e-02 7.738005e-02  
[7] 5.809705e-02 3.281389e-02 1.535756e-02 8.976479e-03 3.981357e-03 2.244039e-03  
[13] 1.442280e-03 6.864393e-04 4.714446e-04 3.383832e-04 4.970055e-06 4.970055e-06  
[19] 4.970055e-06 2.988021e-06 9.980030e-07 9.980030e-07 9.980030e-07 9.980030e-07
```

Figure: Eigenvalues can be numerically unstable.

Simulation-based calibration



Principled priors

Prior calibration, proper priors for generative modelling.

Principled simulation methods

Ascertaining correctness and efficiency

Major methodological challenges (as I see them)

- A) Thinking carefully about priors, especially as regularisers;
- B) Efficient (preferably on-line) methods for phylogeny reconstruction;
- C) Incorporate mathematical models to link to other data (model-driven data integration).

THE
END