

# UNIFIED MEMORY NOTES ON GPU DATA TRANSFERS

23 April 2018 | Andreas Herten | Forschungszentrum Jülich



#### **Overview, Outline**

#### Overview

- Unified Memory enables easy access to GPU development
- But some tuning might be needed for best performance

#### **Contents**

Background on Unified Memory History of GPU Memory Unified Memory on Pascal Unified Memory on Kepler Practical Differences

Revisiting scale\_vector\_um Example

Hints for Performance

Task



# Background on Unified Memory History of GPU Memory



#### **CPU and GPU Memory**

Location, location

At the Beginning CPU and GPU memory very distinct, own addresses

CPU
CPU Memory

Scheduler Interconnect L2 DRAM

## **CPU** and **GPU** Memory Location, location, location

**CPU** 

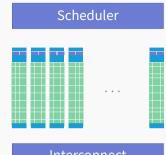
At the Beginning CPU and GPU memory very distinct, own addresses

CUDA 4.0 Unified Virtual Addressing: pointer from same address pool, but data copy manual

CUDA 6.0 Unified Memory\*: Data copy by driver, but whole data at once

CUDA 8.0 Unified Memory (truly): Data copy by driver, page faults on-demand initiate data migrations (Pascal)

Future Address Translation Service: Omit page faults



Interconnect

L<sub>2</sub>

Unified Memory

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#### **Unified Memory in Code**

#### Vojgjfe Nfnpsz

```
void sortfile(FILE *fp, int N) {
   char *data:
   char *data d;
   data = (char *)malloc(N):
   cudaMalloc(&data d, N);
   fread(data, 1, N, fp);
   cudaMemcpy(data d, data, N,
   kernel<<<....>>>(data. N):
   cudaMemcpy(data, data d, N,
   host func(data);
   cudaFree(data d): free(data): }
```

```
void sortfile(FILE *fp, int N) {
    char *data:
    cudaMallocManaged(&data, N);
    fread(data, 1, N, fp):
    kernel<<<....>>>(data. N):
    cudaDeviceSynchronize():
    host func(data);
    cudaFree(data); }
```

#### Implementation Details (on Pascal)

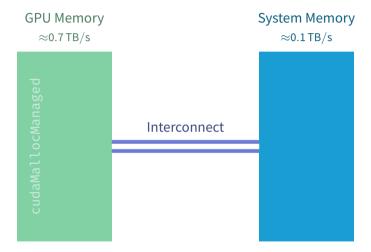
#### Under the hood

```
cudaMallocManaged(&ptr, ...);  
Empty! No pages anywhere yet (like malloc())

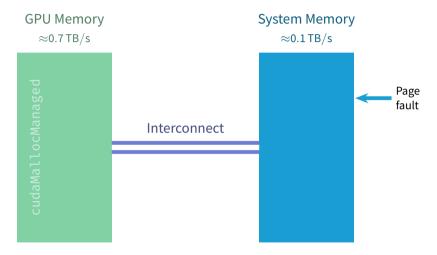
*ptr = 1;  
CPU page fault: data allocates on CPU

kernel<<<...>>(ptr);  
GPU page fault: data migrates to GPU
```

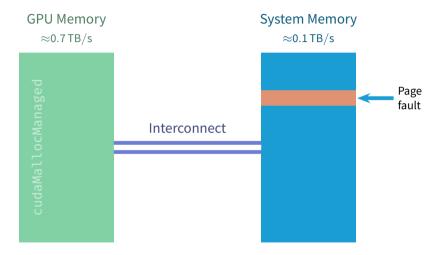
- Pages populate on first touch
- Pages migrate on-demand
- GPU memory over-subscription possible
- Concurrent access from CPU and GPU to memory (page-level)



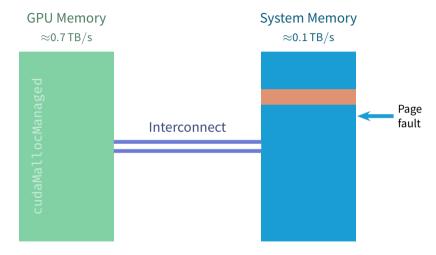




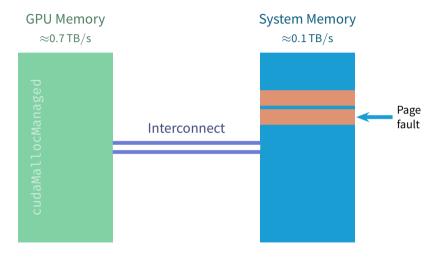




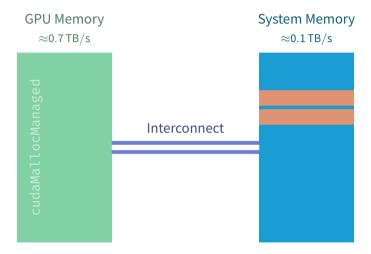






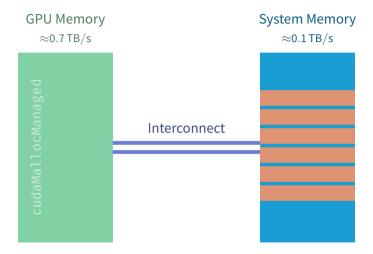




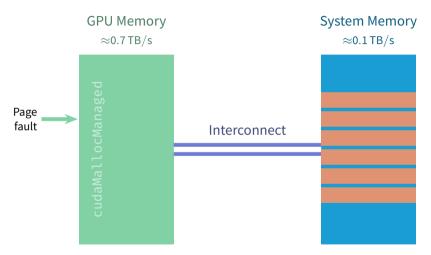


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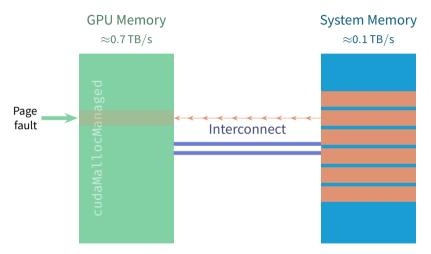




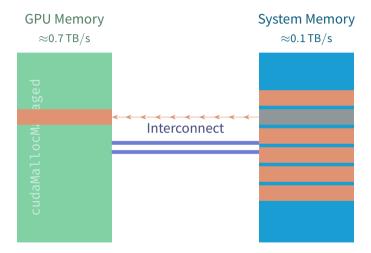




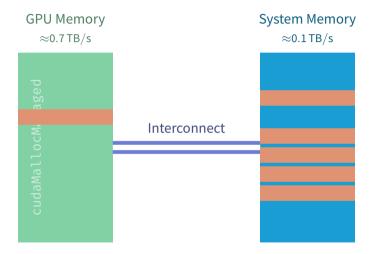






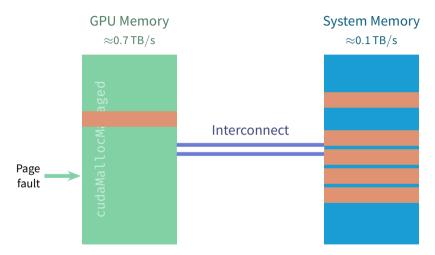




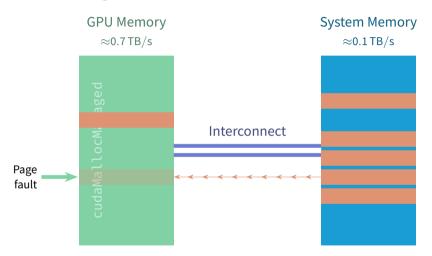


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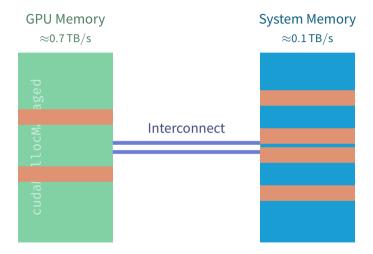




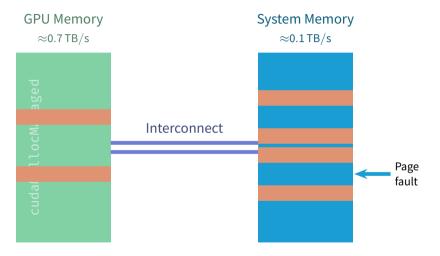




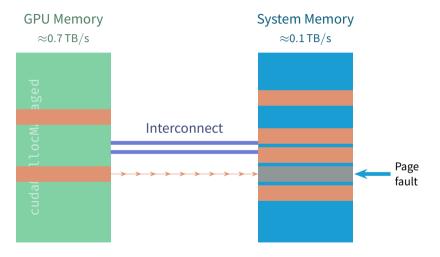






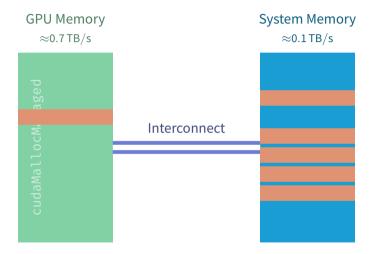






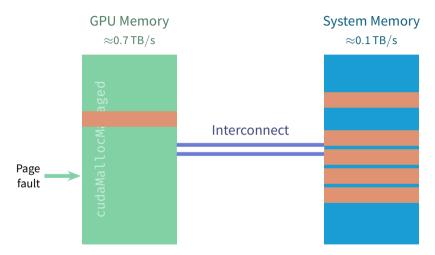
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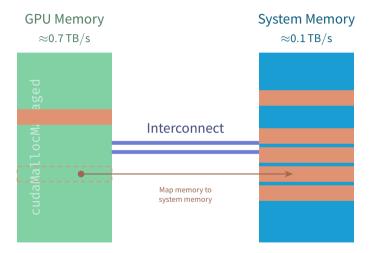


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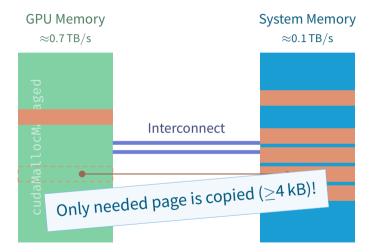






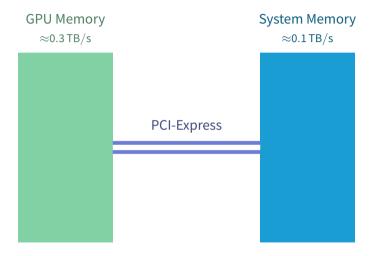




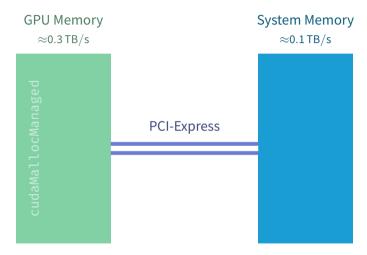


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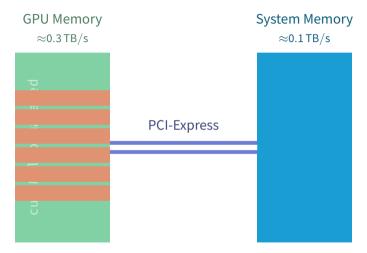




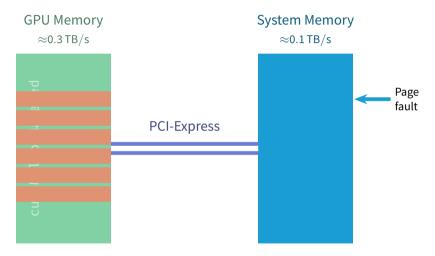


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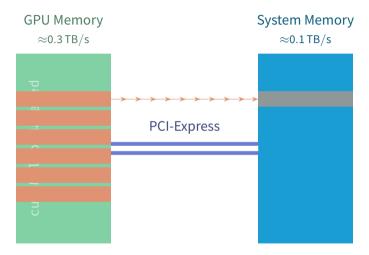




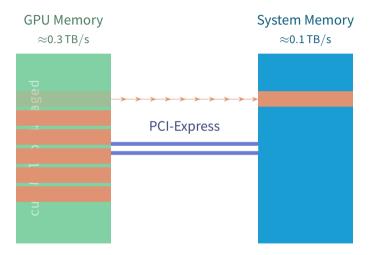




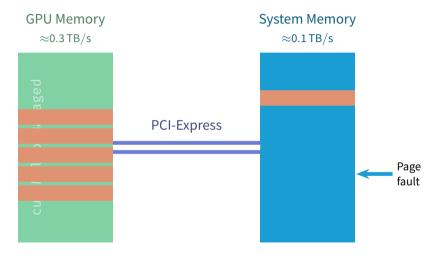




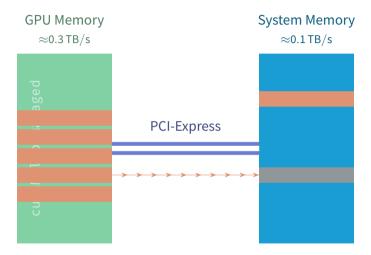




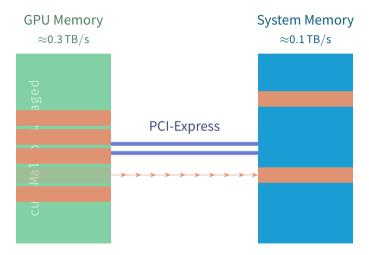




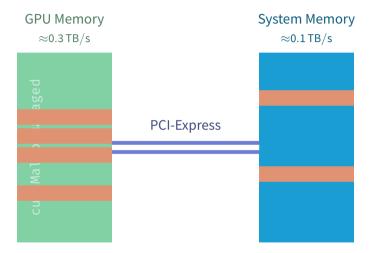




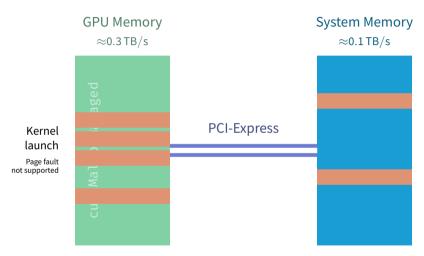






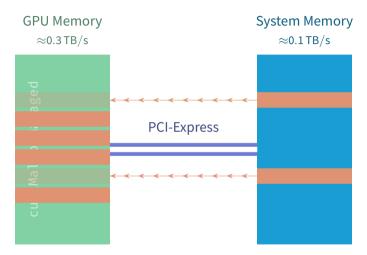






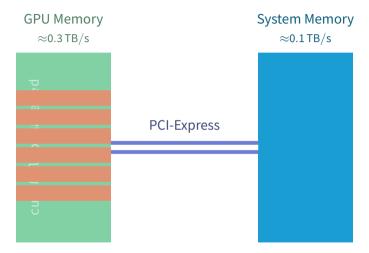
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## Implementation before Pascal

Kepler (JURECA), Maxwell, ...

- Pages populate on GPU with cudaMallocManaged()
- $\rightarrow$  Might migrate to CPU if touched there first
  - Pages migrate in bulk to GPU on kernel launch
  - No over-subscription possible



#### **Practical Differences**

Revisiting scale\_vector\_um Example



# **Comparing UM on Pascal & Kepler**

Different scales

Comparing scale\_vector\_um on JURON and JURECA

```
JURON
```

#### Why?!

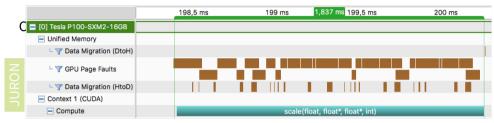
Shouldn't P100 be about  $4 \times$  faster than K80?

```
JUREC/
```



# **Comparing UM on Pascal & Kepler**

#### Different scales



	324 ms	324 <mark>1,447 ms</mark>	325 ms		
■ [0] Tesla K80					
<ul> <li>Unified Memory</li> </ul>					
└ 🍸 Data Migration (DtoH)					I
└ 🍸 Data Migration (HtoD)	Data Migration	Data Migration Data Migration	Data Migra		
Context 1 (CUDA)					
<ul><li>Compute</li></ul>				scale	
└ 🍸 100,0% scale(flo				scale	



## **Comparing UM on Pascal & Kepler**

What happens?

JURON Kernel is launched, data is needed by kernel, data migrates host→device

⇒ Run time of kernel **incorporates** time for data transfers

JURECA Data will be needed by kernel – so data migrates host→device **before** kernel launch

⇒ Run time of **kernel** without any transfers

- Implementation on Pascal is the more convenient one
- Total run time of whole program does not principally change Except it gets shorter because of faster architecture
- But data transfers sometimes sorted to kernel launch
- $\Rightarrow$  What can we do about this?



### **Performance Hints for UM**

**General hints** 

- Keep data local
   Prevent migrations at all if data is processed by close processor
- Minimize thrashing
   Constant migrations hurt performance
- Minimize page fault overhead Fault handling costs  $\mathcal{O}$  (10  $\mu$ s), stalls execution

### **Performance Hints for UM**

#### **New API routines**

API calls to augment data location knowledge of runtime

- cudaMemPrefetchAsync(data, length, device, stream)
   Prefetches data to device (on stream) asynchronously
- cudaMemAdvise(data, length, advice, device) Advise about usage of given data, advice:
  - cudaMemAdviseSetReadMostly: Data is mostly read and occasionally written to
  - cudaMemAdviseSetPreferredLocation: Set preferred location to avoid migrations; first access will establish mapping
  - cudaMemAdviseSetAccessedBy: Data is accessed by this device; will pre-map data to avoid page fault
- Use cudaCpuDeviceId for device CPU, or use cudaGetDevice() as usual to retrieve current GPU device id (default: 0)



#### **Hints in Code**

```
void sortfile(FILE *fp, int N) {
    char *data:
   // ...
    cudaMallocManaged(&data, N);
    fread(data. 1. N. fp):
    cudaMemAdvise(data, N, cudaMemAdviseSetReadMostly, device);
    cudaMemPrefetchAsync(data, N, device);
    kernel<<<....>>>(data. N):
    cudaDeviceSynchronize():
    host func(data);
    cudaFree(data); }
```

Read-only copy of data is created on GPU during prefetch

→ CPU and GPU reads will not fault

Prefetch data to avoid expensive GPU page faults



## Tuning scale\_vector\_um



#### **Express data movement**

- Location of code: Unified Memory/exercises/tasks/scale/
- Look at Instructions.md for instructions
  - 1 Show runtime that data should be migrated to GPU before kernel call
  - 2 Build with make
  - 3 Run with make run
    Orbsub -I -R "rusage[ngpus shared=1]" ./scale vector um
  - 4 Generate profile to study your progress see make profile
- See also CUDA C programming guide for details on data usage

Finished early? There's one more task in the appendix!



### **Conclusions**

What we've learned

- Unified Memory is productive feature for GPU programming
- Unified Memory is implemented differently on Pascal (JURON) and Kepler (JURECA)
- With CUDA 8.0, there are new API calls to express data locality





Appendix Jacobi Task Glossary



### Jacobi Task



#### One more time...

- Location of code: Unified\_Memory/exercises/tasks/jacobi/
- See Jiri Kraus' slides on Unified Memory from 2016 at Unified\_Memory/exercises/slides/jkraus-unified\_memory-2016.pdf
- Short instructions
  - Avoid data migrations in while loop of Jacobi solver: apply boundary conditions with provided GPU kernel; try to avoid remaining migrations
  - Build with make (CUDA needs to be loaded!)
  - Run with make run
  - Look at profile see make profile



# Glossary I

CUDA Computing platform for GPUs from NVIDIA. Provides, among others, CUDA C/C++. 4, 5, 49, 50

JSC Jülich Supercomputing Centre, the supercomputing institute of Forschungszentrum Jülich, Germany. 53

JURECA A multi-purpose supercomputer with 1800 nodes at JSC. 45, 50

JURON One of the two HBP pilot system in Jülich; name derived from Juelich and Neuron. 45, 50

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NVIDIA US technology company creating GPUs. 53

Pascal GPU architecture from NVIDIA (announced 2016). 4, 5, 45



# **Glossary II**

CPU Central Processing Unit. 4, 5, 7, 41, 47, 48

GPU Graphics Processing Unit. 2, 3, 4, 5, 7, 41, 47, 48, 49, 50, 52, 53

HBP Human Brain Project. 53



# References: Images, Graphics I

[1] Martin Oslic. Bug. Freely available at Unsplash. URL: https://unsplash.com/photos/Qi93Pl5vDRw.

