

TLEN 30012 MID-TEST 2018

(1) $n = -2$: $h[0] + 1.5h[-1] + 0.5h[-2] = \delta[-2]$
 $\Rightarrow h[0] = 0$ (1)

(a) $n = -1$: $h[1] + 1.5h[0] + 0.5h[-1] = \delta[-1]$
 $\Rightarrow h[1] = 0$ (1)

$n = 0$: $h[2] + 1.5h[1] + 0.5h[0] = \delta[0]$
 $\Rightarrow h[2] = 1$ (1)

$n = 1$: $h[3] + 1.5h[2] + 0.5h[1] = \delta[1]$
 $\Rightarrow h[3] = -1.5h[2]$
 $= -1.5$ (1)

(b) $\cos(2t)$ has $\omega_1 = 2 \Rightarrow T_1 = \frac{2\pi}{\omega_1} = \pi$ (1)
 $\cos(\frac{5t}{2})$ has $\omega_2 = \frac{5}{2} \Rightarrow T_2 = \frac{2\pi}{\omega_2} = \frac{4\pi}{5}$ (1)

So $\frac{T_1}{T_2} = \frac{\pi}{\frac{4\pi}{5}} = \frac{5}{4}$ (1)

This is not a rational number, (1) hence x is not periodic. (1)

(c) $y[n] = v^5[n+1]$
 is not linear.

Let $v[n] = \delta[n]$, $y[n] = \delta[n+1]$
 and let $\alpha = 2$. Then let

$v_1[n] = \alpha v[n] = 2\delta[n]$

The output $y_1[n] = v_1^5[n+1]$
 $= (2\delta[n+1])^5$
 $= 2^5 \delta^5[n+1]$
 $\neq 2 y[n]$

Hence the homogeneity property is not satisfied, and the system is nonlinear. (5)

(1) (d) Yes the system is time-invariant
 Let (v, y) be any trajectory of the system, then

$$y(t) = v(t-1)$$

Let $T \in \mathbb{R}$ and let

$$v_1(t) = v(t-T)$$

Let y_1 be the output from v_1 ,

$$\text{so } y_1(t) = v_1(t-1)$$

$$= v(t-T-1)$$

$$= y(t-T)$$

So $(v(t-T), y(t-T))$ is also a trajectory and the system is time-invariant. [5]

(e) Yes the system has memory because the output at time t depends on the input at earlier time $t-1$. [2]

(f) Yes the system is causal because the output at time t does not depend on the input at future time $t_0 > t$. [2]

(2) Let $x_1(t) = x(t) \cos(\omega_0 t)$.

Then by Euler's Identities

$$X_1(\omega) = \int_{-\infty}^{\infty} x_1(t) e^{-j\omega t} dt$$

$$= \int_{-\infty}^{\infty} x(t) \left(\frac{1}{2}\right) [e^{j\omega_0 t} + e^{-j\omega_0 t}] e^{-j\omega t} dt$$

$$= \frac{1}{2} \int_{-\infty}^{\infty} x(t) e^{-j(\omega-\omega_0)t} + x(t) e^{-j(\omega+\omega_0)t} dt$$

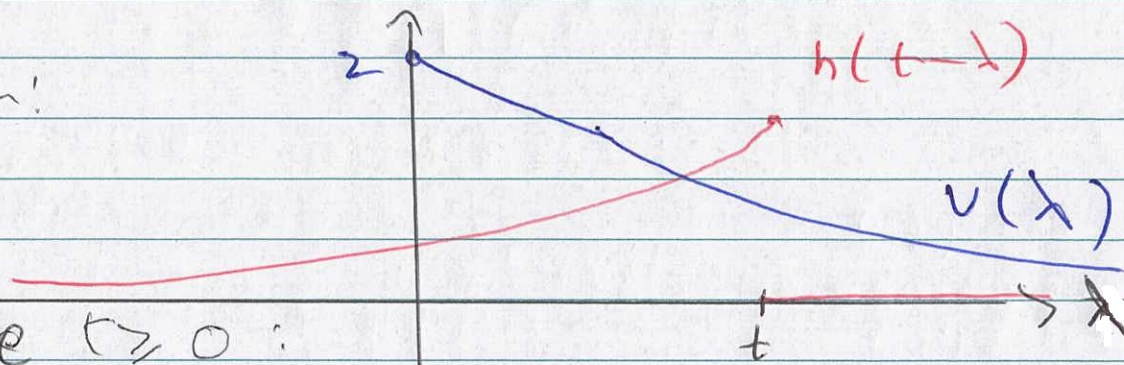
$$= \frac{1}{2} [X(\omega_0 - \omega) + X(\omega + \omega_0)]$$

as required. [6]

(3) The output is given by

$$y(t) = (v * h)(t) \\ = \int_{-\infty}^{\infty} v(\lambda) h(t-\lambda) d\lambda \quad (2)$$

Sketch:



Assume $t \geq 0$:

$$y(t) = \int_0^t 2e^{-2\lambda} e^{-(t-\lambda)} d\lambda \quad (2)$$

$$= 2 \int_0^t e^{-(\lambda+t)} d\lambda \quad (2)$$

$$= -2 \left[e^{-(\lambda+t)} \right]_0^t \quad (2)$$

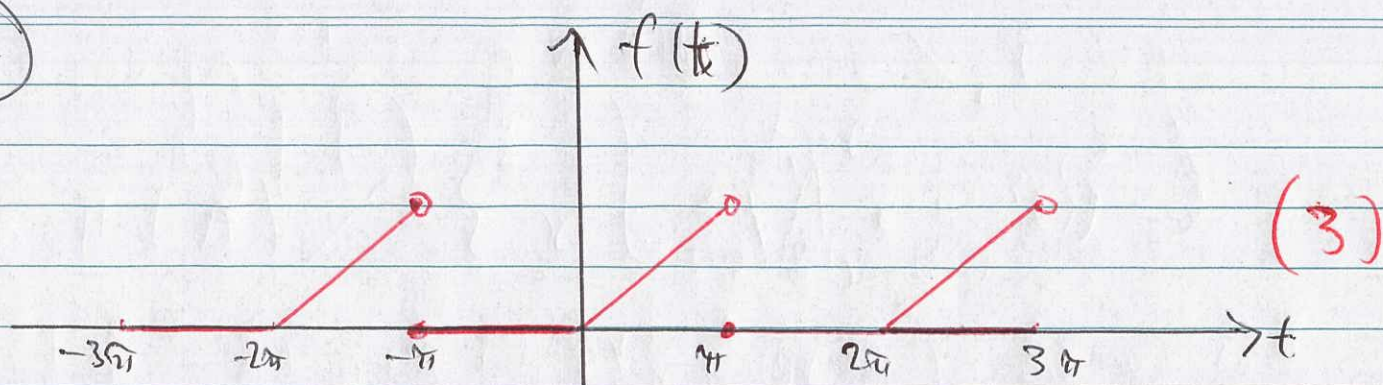
$$= -2(e^{-2t} - e^{-t}) \quad (2)$$

$$= 2(e^{-t} - e^{-2t})$$

$$= \begin{cases} 2e^{-t}(1 - e^{-t}), & t \geq 0 \\ 0, & t < 0 \end{cases}$$

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(4)



(1) Dirichlet condition:

As f is bounded on the interval $[-\pi, \pi]$ hence it is absolutely integrable. (1)

(2) f has a local maximum at π , and one minima at $[-\pi, 0]$, so it has finitely many maxima and minima on $[-\pi, \pi]$ (1)

(3) f is discontinuous at $t = \pi$, hence it has finitely many discontinuities on $[-\pi, \pi]$ (1)

[6]

(b) $T = 2\pi \Rightarrow \omega_0 = 1$.

$$\text{So } c_1 = \frac{1}{T} \int_0^T x(t) e^{-j\omega_0 t} dt$$

$$= \frac{1}{2\pi} \int_0^\pi t e^{-j\omega_0 t} dt \quad (1)$$

Let $u = t$, $u' = 1$, $v' = e^{-j\omega_0 t}$, $v = \frac{1}{-j\omega_0} e^{-j\omega_0 t}$

$$\text{So } c_1 = \frac{1}{2\pi} \left[t \frac{1}{-j\omega_0} e^{-j\omega_0 t} - \int_0^\pi \frac{1}{-j\omega_0} e^{-j\omega_0 t} dt \right] \quad (1)$$

$$= \frac{1}{2\pi} \left[t \frac{1}{-j\omega_0} e^{-j\omega_0 t} + \frac{1}{j\omega_0} e^{-j\omega_0 t} \right]_0^\pi \quad (1)$$

$$= \frac{1}{2\pi} \left[\left(\frac{j\pi}{\omega_0} e^{-j\omega_0 \pi} + \frac{1}{j\omega_0} e^{-j\omega_0 \pi} \right) - \left(0 + \frac{1}{j\omega_0} \right) \right] \quad (1)$$

$$= \frac{1}{2\pi} \left[-\pi j - 2 \right] \quad (1)$$

$$= \frac{1}{2\pi} \left[-2 - j\pi \right] \quad (1)$$

and

$$c_{-1} = \overline{c_1} = \frac{1}{2\pi} \left[-2 + j\pi \right] \quad (1) \quad [6]$$