# GP2Y0A21YK/ GP2Y0D21YK

#### **■** Features

1. Less influence on the color of reflective objects, reflectivity

2. Line-up of distance output/distance judgement type

Distance output type (analog voltage): GP2Y0A21YK

Detecting distance: 10 to 80cm

Distance judgement type: GP2Y0D21YK

Judgement distance: 24cm

(Adjustable within the range of 10 to 80cm [Optionally available])

3. External control circuit is unnecessary

4. Low cost

#### Applications

2. Personal computers

3. Cars

4. Copiers

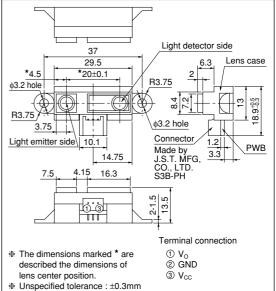
## ■ Absolute Maximum Ratings $(T_a=25^{\circ}C, V_{CC}=5V)$

Parameter	Symbol	Rating	Unit
Supply voltage	$V_{CC}$	-0.3 to +7	V
Output terminal voltage	$V_{O}$	$-0.3$ to $V_{CC} + 0.3$	V
Operating temperature	Topr	-10 to +60	°C
Storage temperature	$T_{stg}$	-40 to +70	°C

## **General Purpose Type Distance Measuring Sensors**

#### **■** Outline Dimensions

(Unit: mm)



#### **■** Recommended Operating Conditions

Parameter	Symbol	Rating	Unit
Operating supply voltage	$V_{CC}$	4.5 to +5.5	V

#### **■ Electro-optical Characteristics**

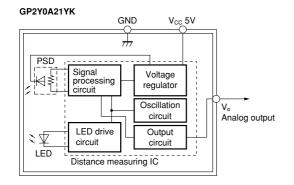
(TD	2500	<b>T</b> 7	EX.7
( L <sub>o</sub> =	=23 C	. Vc	c=5V

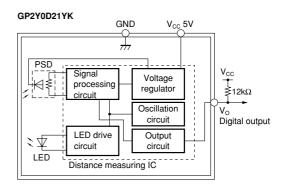
Parameter		Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Distance measuring ra	inge	$\Delta$ L	*1 *3	10	-	80	cm
Output terminal valtage	GP2Y0A21YK	$V_{O}$	L=80cm *1	0.25	0.4	0.55	V
	GP2Y0D21YK	$V_{OH}$	Output voltage at High *1	V <sub>CC</sub> -0.3	-	_	V
	GPZTODZTTK	$V_{OL}$	Output voltage at Low*1	_	I	0.6	V
Difference of output voltage	GP2Y0A21YK	$\Delta V_{\rm O}$	Output change at L=80cm to 10cm*1	1.65	1.9	2.15	V
Distance characteristics of output	GP2Y0D21YK	$V_{O}$	*1 *4 *2	21	24	27	cm
Average Dissipation c	urrent	$I_{CC}$	L=80cm *1	_	30	40	mA

Note) L: Distance to reflective object

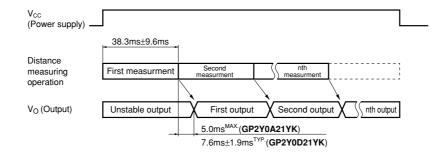
#### Fig.1 Internal Block Diagram

### Fig.2 Internal Block Diagram





## **Fig.3 Timing Chart**



 $<sup>*1\</sup> Using\ reflective\ object: White\ paper\ \ (Made\ by\ Kodak\ Co.\ Ltd.\ gray\ cards\ R-27\cdot white\ face,\ reflective\ ratio\ ;\ 90\%)$ 

<sup>\*2</sup> We ship the device after the following adjustment: Output switching distance L=24cm±3cm must be measured by the sensor

<sup>\*3</sup> Distance measuring range of the optical sensor system

<sup>\*4</sup> Output switching has a hysteresis width. The distance specified by Vo should be the one with which the output L switches to the output H

**Fig.4 Distance Characteristics** 

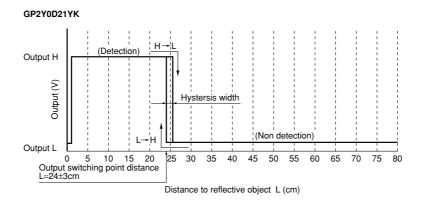
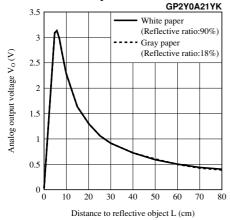


Fig.5 Analog Output Voltage vs. Distance to Reflective Object



#### NOTICE

- The circuit application examples in this publication are provided to explain representative applications of SHARP
  devices and are not intended to guarantee any circuit design or license any intellectual property rights. SHARP takes
  no responsibility for any problems related to any intellectual property right of a third party resulting from the use of
  SHARP's devices.
- Contact SHARP in order to obtain the latest device specification sheets before using any SHARP device. SHARP
  reserves the right to make changes in the specifications, characteristics, data, materials, structure, and other contents
  described herein at any time without notice in order to improve design or reliability. Manufacturing locations are
  also subject to change without notice.
- Observe the following points when using any devices in this publication. SHARP takes no responsibility for damage
  caused by improper use of the devices which does not meet the conditions and absolute maximum ratings to be used
  specified in the relevant specification sheet nor meet the following conditions:
  - (i) The devices in this publication are designed for use in general electronic equipment designs such as:
    - --- Personal computers
    - --- Office automation equipment
    - --- Telecommunication equipment [terminal]
    - --- Test and measurement equipment
    - --- Industrial control
    - --- Audio visual equipment
    - --- Consumer electronics
  - (ii) Measures such as fail-safe function and redundant design should be taken to ensure reliability and safety when SHARP devices are used for or in connection with equipment that requires higher reliability such as:
    - --- Transportation control and safety equipment (i.e., aircraft, trains, automobiles, etc.)
    - --- Traffic signals
    - --- Gas leakage sensor breakers
    - --- Alarm equipment
    - --- Various safety devices, etc.
  - (iii)SHARP devices shall not be used for or in connection with equipment that requires an extremely high level of reliability and safety such as:
    - --- Space applications
    - --- Telecommunication equipment [trunk lines]
    - --- Nuclear power control equipment
    - --- Medical and other life support equipment (e.g., scuba).
- Contact a SHARP representative in advance when intending to use SHARP devices for any "specific" applications
  other than those recommended by SHARP or when it is unclear which category mentioned above controls the
  intended use.
- If the SHARP devices listed in this publication fall within the scope of strategic products described in the Foreign Exchange and Foreign Trade Control Law of Japan, it is necessary to obtain approval to export such SHARP devices.
- This publication is the proprietary product of SHARP and is copyrighted, with all rights reserved. Under the copyright laws, no part of this publication may be reproduced or transmitted in any form or by any means, electronic or mechanical, for any purpose, in whole or in part, without the express written permission of SHARP. Express written permission is also required before any use of this publication may be made by a third party.
- Contact and consult with a SHARP representative if there are any questions about the contents of this publication.