

MAX J. EMERICK

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SUMMARY

Ph.D. Candidate at UC Santa Barbara and NDSEG Graduate Fellow specializing in dynamical systems, control theory, and applied mathematics. Current research focuses on the analysis and control of continuum models for large-scale systems, with applications in fluid systems, ensemble systems, and swarm robotics. Experience in research, teaching, industry, and leadership, with recognized achievements across all areas.

EDUCATION

Ph.D. in Mechanical Engineering , University of California, Santa Barbara Focus in Dynamical Systems and Control Theory	Sep 2022 – Present 4.0 GPA
M.S. in Mechanical Engineering , University of California, Santa Barbara Focus in Dynamical Systems and Control Theory Thesis: <i>Control of Continuum Swarm Systems via Optimal Control and Optimal Transport Theory</i>	Sep 2020 – Sep 2022 4.0 GPA
B.S. in Mechanical Engineering , California Polytechnic State University Concentration in Mechatronics , Minor in Mathematics Capstone Project: <i>Surface Autonomous Vehicle for Emergency Rescue</i>	Sep 2015 – Jun 2020 3.9 GPA

HONORS & AWARDS

National Defense Science and Engineering Graduate (NDSEG) Fellowship	Sep 2024 – Present
Outstanding Teaching Assistant Award , UCSB Mechanical Engineering Department	May 2025
Outstanding Student Paper Award , 62 nd IEEE Conference on Decision and Control	Dec 2023
Best Teaching Assistant Award , UCSB Mechanical Engineering Department	Oct 2023
IFAC Young Author Award , 9 th IFAC Conference on Networked Systems	Jul 2022
Graduated Summa Cum Laude , California Polytechnic State University	Jun 2020
Cal Poly Outreach Academic Scholarship	Sep 2015 – Jun 2019

WORK & RESEARCH EXPERIENCE

Graduate Student Researcher , Bamieh Lab, UC Santa Barbara	Apr 2021 – Present
• Conducting fundamental research on control of continuum models for large-scale systems	
• Developed new techniques for control design for various swarm-based, ensemble, and fluid systems	
• Published and presented results in various peer-reviewed journals and international conferences	
Graduate Teaching Assistant/Instructor , UC Santa Barbara	Jan 2021 – Dec 2024
• Provided teaching, tutoring, grading support, and hands-on training to students in a variety of courses, including Dynamic Systems Modeling, Vibrations, Controls, Robotics, Mechatronics, Nonlinear Phenomena, and Design for Test Automation	
• Developed and taught (as instructor of record) a new TA training course for the UCSB Mechanical Engineering Department	
Engineering Intern , Tesla, Fremont, CA	Jun 2021 – Sep 2021
• Worked in manufacturing for the castings team on the pilot line for the “Giga Press”, the largest aluminum die-casting machine in the world	
• Took on a wide variety of responsibilities including controls engineering, new station development and testing, line-down recovery, project management, and project coordination	
• Improved process and workflow throughout the casting and finishing lines by adding new stations, improving interfaces, and automating and optimizing processes	

- Student Researcher**, Flight Test Data System Lab, Cal Poly Jun 2019 – Sep 2020
- Designed, programmed, and tested embedded systems for taking real-time measurements of boundary layers on aircraft
 - Assisted in writing and maintaining C/C++ libraries for numerous devices and applications
 - Designed experiments and performed data analysis for device testing and calibration
 - Completed three projects, authored four internal reports, and devised new firmware architecture to accelerate the research group's progress
- Engineering Intern**, Panasonic Avionics Corporation, Bothell, WA Jul 2017 – Aug 2017
- Designed and implemented mounting systems for avionics onboard Boeing 747s and Airbus A330s
 - Provided on-site engineering support for system installations and retrofits

- Teaching Assistant**, California Polytechnic State University Jan 2017 – Mar 2017
- Provided teaching and tutoring support to three sections of Electricity & Magnetism

- Private Tutor**, Self-Employed Sep 2013 – Jun 2018
- Provided high school and college-level tutoring in mathematics, physics, and engineering

PUBLICATIONS

“Classification of Limit Solutions of a Mean-Field Oscillator Ising Model,”

A. R. Venkatakrishnan, **M. Emerick**, B. Bamieh, and F. Bullo. In preparation.

“Incompressible Optimal Transport and Applications in Fluid Mixing,”

M. Emerick and B. Bamieh, 64th IEEE Conference on Decision and Control. To appear.

“Optimal Assignment and Motion Control in Two-Class Continuum Swarms,”

M. Emerick, S. Patterson, and B. Bamieh, IEEE Transaction on Control of Network Systems. To appear.

“Causal Tracking of Distributions in Wasserstein Space: A Model Predictive Control Scheme,”

M. Emerick, J. Jonas, and B. Bamieh, 63rd IEEE Conference on Decision and Control, pp. 7606-7611, 2024.

“Continuum Swarm Tracking Control: A Geometric Perspective in Wasserstein Space,”

M. Emerick and B. Bamieh, 62nd IEEE Conference on Decision and Control, pp. 1367-1374, 2023.

“Optimal Combined Motion and Assignments with Continuum Models,”

M. Emerick, S. Patterson, and B. Bamieh, IFAC-PapersOnLine, vol. 55, no. 13, pp. 121-126, 2022.

CONFERENCE PRESENTATIONS

- “Incompressible Optimal Transport and Application in Fluid Mixing” Dec 2025
Invited Talk, 64th IEEE Conference on Decision and Control Rio do Janeiro, Brazil

- “Tracking Control in The Wasserstein Space” Jul 2025
Contributed Talk, 2025 SIAM Conference on Control and Its Applications Montreal, Canada

- “Causal Tracking of Distributions in Wasserstein Space: A Model Predictive Control Scheme” Dec 2024, Milan, Italy
Contributed Talk, 63rd IEEE Conference on Decision and Control

- “Tracking Control in The Wasserstein Space” Nov 2024
Contributed Talk, 44th Southern California Control Workshop Los Angeles, United States

- “Optimal Control of Distributions in Wasserstein Space” Aug 2024, Cambridge, United Kingdom
Invited Talk, 26th International Symposium on Mathematical Theory of Networks and Systems

“Continuum Swarm Tracking Control: A Geometric Perspective in Wasserstein Space” Contributed Talk, 62 nd IEEE Conference on Decision and Control	Dec 2023 Singapore
“Optimal Combined Motion and Assignments with Continuum Models” Contributed Talk, 9 th IFAC Conference on Networked Systems	Jul 2022 Zurich, Switzerland

CERTIFICATIONS & ASSOCIATIONS

Engineer-in-Training , State of California (#172585)	Dec 2020 – Present
Affiliate Member , International Federation of Automatic Control (IFAC)	Aug 2022 – Present
Graduate Student Member , IEEE & IEEE Control Systems Society (CSS) <ul style="list-style-type: none"> • Member, CSS Technical Committee on Distributed-Parameter Systems 	Jul 2022 – Present
Graduate Student Member , Society for Industrial and Applied Mathematics <ul style="list-style-type: none"> • Member, Activity Group on Controls and Systems Theory 	Jul 2022 – Present

LEADERSHIP & INVOLVEMENT

Member, UCSB SIAM Student Chapter	Sep 2024 – Present
<ul style="list-style-type: none"> • Attending and participating in weekly seminars on various topics in applied mathematics • Led seminars on the topics of control theory, optimal control, and stochastic optimal control 	
Lead Teaching Assistant (TA) , Mech. Eng. Dept., UC Santa Barbara	Apr 2023 – Jun 2025
<ul style="list-style-type: none"> • Selected to serve as Lead TA for over 70 graduate students in Mechanical Engineering • Developed new TA trainings, mentorship programs, and courses within the department 	
Founding Board Member & Secretary , UCSB Mech. Eng. Grad. Student Assn.	Nov 2023 – Jun 2025
<ul style="list-style-type: none"> • Helped to organize and set up a new departmental graduate student association • Took meeting notes, kept records, met with department administration, and helped organize events 	
STEM Outreach Speaker , Various	Nov 2016 – Aug 2022
<ul style="list-style-type: none"> • Helped organize and deliver STEM workshops at various middle schools in California and Arizona 	
Member, Cal Poly “Simple Group” (Undergraduate Math Seminar)	Sep 2016 – Mar 2020
<ul style="list-style-type: none"> • Attended and participated in weekly seminars on various topics in pure and applied mathematics 	
Member, Cal Poly Bike Builders Club	Sep 2017 – Jun 2019
<ul style="list-style-type: none"> • Helped to design and build custom steel-frame bicycles from the ground up 	
NCAA Division I Athlete , Cal Poly Men’s Swim Team	Sep 2015 – Mar 2017
<ul style="list-style-type: none"> • Competed as a varsity athlete for two seasons for the Cal Poly Men’s Swim Team 	
Volunteer Swim Instructor , Various	Sep 2013 – Mar 2017
<ul style="list-style-type: none"> • Taught swimming at all levels from fundamentals to competition to children aged 4 to 18 	