

runVertexProcessor

```
for $i: 0 to $drawCalls.size - 1
    for $j: 0 to $drawCalls[$i].trianglesNum - 1

        Triangle $triangle

        for $k: 0 to 2
            $triangle.vertices[$k] = runVertexShader(
                $drawCalls[$i].transform,
                $drawCalls[$i].trianglesBuffer.triangles[$j].vertices[$k])

        if ((all vertices of $triangle are not visible))
            continue

        if ((all vertices of $triangle are visible))
            processProspectiveTriangleToRasterize(
                $triangle,
                $drawCalls[$i].texture)
            continue

        list<Vertex> $vertices
        $vertices.add($triangle.vertices[0])
        $vertices.add($triangle.vertices[1])
        $vertices.add($triangle.vertices[2])

        $vertices = clipPolygonToPlaneIn4D($vertices, vec4(0, 0, -1, -1))

        // triangulate the polygon formed of $vertices array
        if ($vertices.size >= 3)
            for $k: 0 to $vertices.size - 2
                processProspectiveTriangleToRasterize(
                    $vertices[0],
                    $vertices[1 + $k],
                    $vertices[2 + $k],
                    $drawCalls[$i].texture)
```

```
Vertex runVertexShader(mtx $transform, Vertex $input)
{
    Vertex $output

    $output.position = $input.position * $transform
    $output.color = $input.color
    $output.texCoord = $input.texCoord

    return $output
}
```

```
list<Vertex> clipPolygonToPlaneIn4D(list<Vertex> $vertices, vec4 $planeNormal)
{
    list<Vertex> $clippedVertices;

    for $i: 0 to $vertices.size - 1

        $a = $i
        $b = ($i + 1) % $vertices.size

        if (($vertices[$a] and $vertices[$b] are on opposite sides of $planeNormal))
        {
            [find intersection point $vertex and linearly interpolate attributes]

            if (($vertices[$a] is on the negative side of $planeNormal))
                $clippedVertices.add($vertices[$a])
                $clippedVertices.add($vertex)
            elseif (($vertices[$b] is on the negative side of $planeNormal))
                $clippedVertices.add($vertex)
                $clippedVertices.add($vertices[$b])
            elseif (($vertices[$a] and $vertices[$b] are both on the negative side of $planeNormal))
            {
                $clippedVertices.add($vertices[$a])
            }
        }

    return $clippedVertices
}
```

runPixelProcessor

```
for $i: 0 to $Renderer.trianglesToRasterize.size

    TriangleToRasterize& $t = $Renderer.trianglesToRasterize[$i]

    for $y: $t.minY to $t.maxY
        for $x: $t.minX to $t.maxX

            [compute barycentric weights of point ($x, $y): $alpha, $beta, $gamma]

            // is pixel (x, y) inside the triangle
            if ($alpha >= 0 and $beta >= 0 and $gamma >= 0)

                $pixelIndex = $y*$Renderer.width + $x

                $z_affine = $alpha*$t.v0.position.z + $beta*$t.v1.position.z + $gamma*$t.v2.position.z

                if ($z_affine < $depthBuffer[$pixelIndex] and $z_affine <= 1)

                    // make barycentric weights to be perspective-correct
                    $l1 = $alpha*$t.one_over_z0 + $beta*$t.one_over_z1 + $gamma*$t.one_over_z2
                    $l1 = 1 / $l1
                    $alpha *= $l1 * $t.one_over_z0
                    $beta *= $l1 * $t.one_over_z1
                    $gamma *= $l1 * $t.one_over_z2

                    $color_persp = $alpha*$t.v0.color + $beta*$t.v1.color + $gamma*$t.v2.color
                    $texCoord_persp = $alpha*$t.v0.texCoord + $beta*$t.v1.texCoord + $gamma*$t.v2.texCoord

                    [compute partial derivatives of texture coordinates]

                    $pixelColor = runPixelShader($t.texture, $color_persp, $texCoord_persp)

                    $colorBuffer[4*$pixelIndex + 0] = $pixelColor.red
                    $colorBuffer[4*$pixelIndex + 1] = $pixelColor.green
                    $colorBuffer[4*$pixelIndex + 2] = $pixelColor.blue
                    $depthBuffer[$pixelIndex] = $z_affine
```

```
void processProspectiveTriangleToRasterize(
    Vertex $v0, Vertex $v1, Vertex $v2, CTexture $texture)
{
    TriangleToRasterize $t

    $t.v0 = $v0
    $t.v1 = $v1
    $t.v2 = $v2
    $t.texture = $texture

    $t.one_over_z0 = 1.0f / $t.v0.position.w
    $t.one_over_z1 = 1.0f / $t.v1.position.w
    $t.one_over_z2 = 1.0f / $t.v2.position.w

    // project from homogenous coordinates to window coordinates
    $t.v0.position.divideByW()
    $t.v0.position *= $Renderer.windowTransform
    $t.v1.position.divideByW()
    $t.v1.position *= $Renderer.windowTransform
    $t.v2.position.divideByW()
    $t.v2.position *= $Renderer.windowTransform

    if ((are vertices $t.v0, $t.v1 and $t.v2 in clockwise order in screen space))
        return

    [find bounding box of the triangle and store it in
    [$t.minX, $t.minY] x [$t.maxX, $t.maxY] square]

    if ($t.maxX <= $t.minX or $t.maxY <= $t.minY)
        return

    [compute the remaining attributes of $t]

    $Renderer.trianglesToRasterize.add($t);
}
```

```
vec3 runPixelShader(CTexture $texture, vec3 $color, vec2 $texCoord)
{
    return $color * tex2D($texture, $texCoord)
}
```