RNA FOLDING PATHWAYS

Maximilian Faissner

Introduction

Previous work / algorithms

Outlook

Direct RNA folding pathways

	Structures GGGGAAAACCCCUUUU	Energy (kcal/mol)	Actions
$\overline{S_1}$	((((())))	-6.60	$\mathtt{del}_{1,12}$
	.((()))	-2.90	$\mathtt{del}_{2,11}$
	(())	0.40	$\mathtt{del}_{3,10}$
	()	3.70	$\mathtt{del}_{4,9}$
		0.00	$\mathtt{add}_{8,13}$
	()	5.50	$add_{7,14}$
	(())	4.60	$\mathtt{add}_{6,15}$
	((())).	3.70	$\mathtt{add}_{5,16}$
S_2	((((())))	2.80	50 0000 \$ 000 \$400 \$300.

Goal: Finding a direct pathway with the lowest energy barrier

<u>direct</u> pathways: number of refolding moves = basepair distance

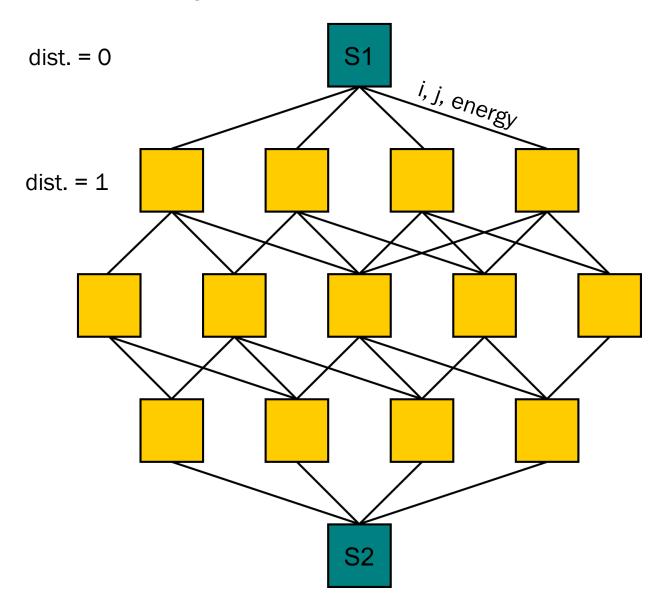
Combinatorial search of the best permutation of moves

NP-hard problem

Findpath:

Bounded BFS heuristic, implemented in the ViennaRNA package (Turner energy model)

Findpath: Bounded Breadth-first search heuristic



Graph structure:

nodes: unique structures

edges: valid moves (i, j) with

associated move energy

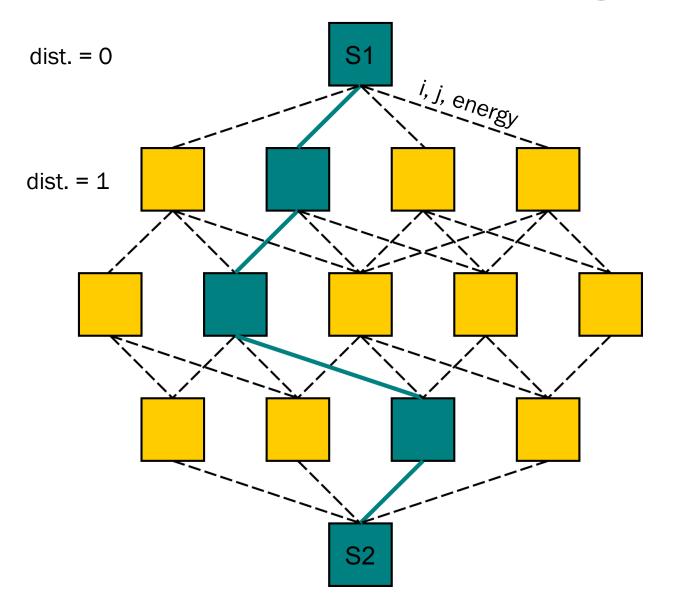
Bounded look-ahead heuristic:

keep the best k candidates after each distance step

Criterion for best candidates:

- lowest saddle energy (so far)
- lowest current node energy remove duplicates (one unique structure per distance)

Findpath: Increasing the search width *k*



First iteration: k = 1

Similar to the greedy approach as proposed by Morgan and Higgs:

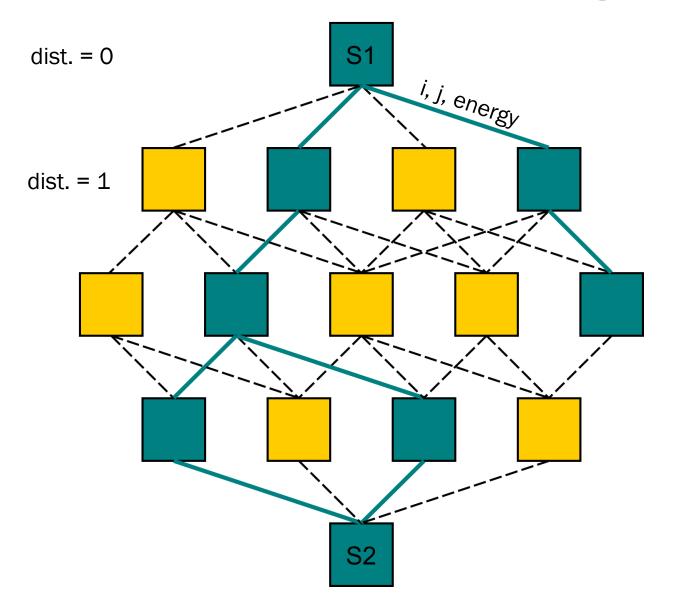
Single next structure with lowest energy

S. R. Morgan and P. G. Higgs. Barrier heights between ground states in a model of RNA secondary structure, J. Phys. A.: Math. Gen., 31, 1998, 3153-3170.

Result:

Path with associated saddle energy (highest energy along the path)

Findpath: Increasing the search width *k*



Second iteration: k = 2

Keep 2 candidate paths per iteration

Saddle energy from previous iteration (k = 1) serves as upper energy limit, limiting the search space

Increase search with *k* as desired

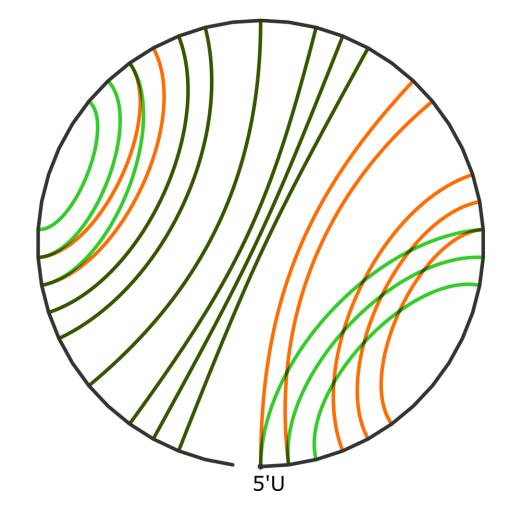
Preferable approach: Final k should depend on the basepair distance

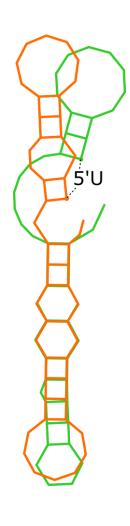
Project Motivation

- Findpath is a computationally heavy heuristic for large sequences
 - time dependent step for DrTransformer (cotranscriptional folding)
- Optimization & Improvements for the Findpath heuristic:
 - Reduce the search space by separating folding pathways into <u>independent sections</u>
 - Generate multiple independent folding pathways
 - Merge independent pathways recursively
- Additional point of interest: <u>indirect folding pathways</u>

Divide & Conquer approach for Findpath

UCGGACAGAAACGGUUGAGGGGCGGCGGGAAGCGAUUGUUCUAGGCGCGG





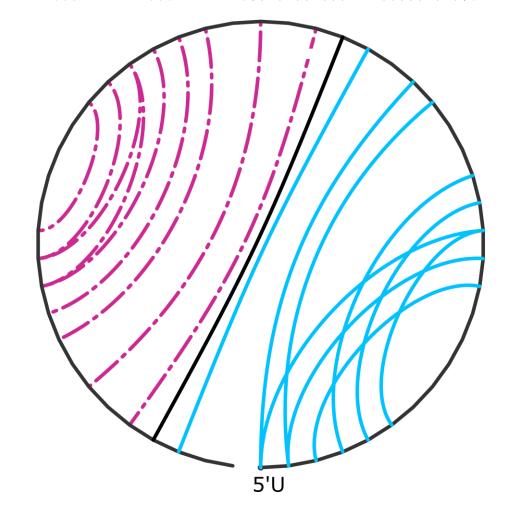
Splitting interior loops:

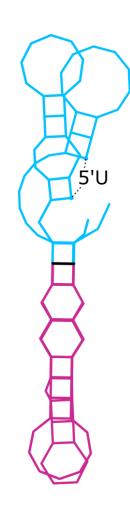
- Find constant basepairs present in both S_1 and S_2
- Recursively start a new section at a constant basepair
- Reconstruct final path by recursively merging individual paths

Divide & Conquer approach for Findpath

UCGGACAGAAACGGUUGAGGGGCGGCGGGAAGCGAUUGUUCUAGGCGCGG

```
S1 ((.(((....)))..)).(((.(.(((....))))..)))...
S2 (((....))).....((..(.((.(.(...)))))..)))...
```

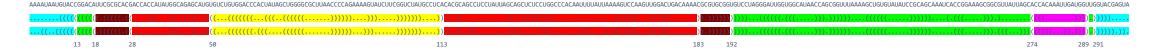




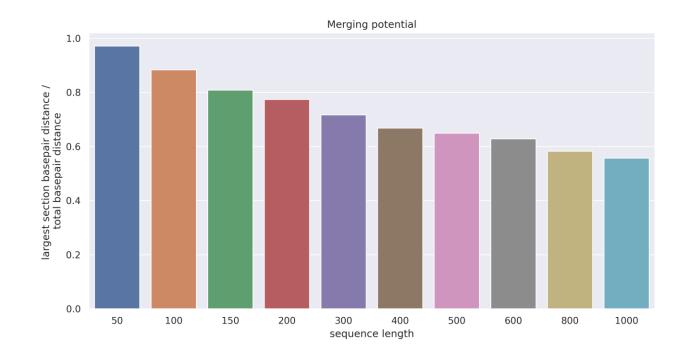
```
UCGGACAGAAACGGUUGAGGGGCGGCGGGAAGCGAUUGUUCUAGGCGCGG
S1 ((.(((....)))..)).(((.(.(((....))))..)))...
S2 (((....))).....(((.(.((.((.((...)))))..)))...
 Outer Section
 ((.(((.....)))..)).((......))..
 .(.(((.....)))..)..((......))..
 ...(((.....))).....((.......))..
 ....((.....)).....((......))..
 ....(.....)....((......))...
 ..(.....).....((......))...
 .((.....)).....((......))...
 (((.....)))......((.......))...
 Inner Section
 .....((((....))))....)...
 .....((((.(...)))))....)...
 .....(...((.((.(...)))))....)...
```

How often can we apply this method?

Finding the largest section



Random 300 nt example with sections: [1, [13, [18, [28, [50, 113], 183], 192], [274, 289], 291], 300] Total basepair distance: 40 / largest section basepair distance: 23 (red section)



Dataset generation:

- Random RNA sequence strings
- structure pairs: RNAsubopt (Boltzmann weighted samples)
- gradient descent to local minimum
- Structure pairs with a basepair distance < 10 are filtered out

Merging independent paths

```
UCGGACAGAAACGGUUGAGGGGCGGCGGGAAGCGAUUGUUCUAGGCGCGG
S1 ((.(((....)))..)).(((.(.(((....))))..)))...
S2 (((....))).....(((.((.((.((...))))).).))...
 Outer Section
 ((.(((.....)))..)).((..........))...
 .(.(((.....)))..)..((......))..
 ...(((.....)))....((......))...
 ....((.....)).....((.......))...
 ....(.....).....((......))...
 ..(.....).....((......))...
 .((.....)).....((......))...
 (((.....)))......((.......))...
 Inner Section
 .....((((....))))....)...
 .....((((.(...)))))....)...
 .....((...((...(...).)))....)...
 .....(...((.((.((...)))))....)...
```

```
UCGGACAGAAACGGUUGAGGGGCGGCGGGAAGCGAUUGUUCUAGGCGCGG
S2 (((....))).....(((.(((((...))))).).))...
  Merged Result
  ((.(((.....)))..)).(((.(.(((.....)))).).))..
  .(.(((.....)))..)..(((.(.(((.....))))..).))..
  ...(((.....)))....(((.((((.....)))).).))...
  ....((.....)).....(((.((((.....)))).).))).
  ....(.....).....(((.((((.....)))).).)))..
  .....(((.(((((.....)))))).).))).
  ..(.....).....(((.((((.....))))).).)).
  .((.....)).....(((.((((.....)))).).)).
  (((.....))).....(((.((((.....)))).).))...
  (((....))).....(((.((((.(...)))))).).))...
  (((.....)))......(((.(((..(...).))).).))...
  (((.....))).....(((.((.((.((...)))))...)))..
  (((....))).....(((.((.((.((...)))))).).))...
```

First approach: Dynamic Programming

$$E_{i,j} = max (\Delta G(a_{i,j}), min (E_{i-1,j}, E_{i,j-1}))$$

moves outer section

Dynamic Programming matrix to merge 2 folding pathways

Issues with the initial DP-approach

Findings:

Assuming there is no additional local minimum along the path, the optimal merged path can be constructed with 2 optimal input paths.

Findpath <u>does not</u> necessarily output all required paths with respect for merging

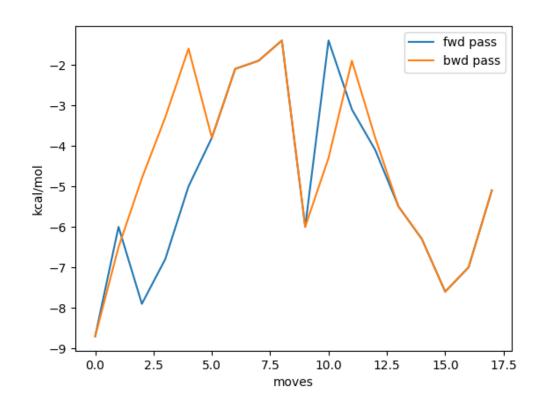
Lowest energy barrier as criterion is not good enough for subsequent merging.

Conclusions:

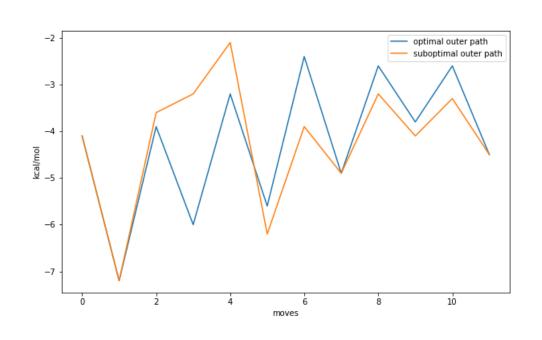
Multiple <u>candidate paths</u> need to be tested for merging

No guarantee that Findpath outputs the ideal input path (with respect to merging)

No guarantee that the merged output has a lower barrier than regular Findpath



Optimal input paths are not always sufficient



Findings:

Paths with <u>local minima</u> along the path:

suboptimal input paths are sometimes required to reconstruct optimal paths

→ Find the lowest minimum along the path

conflicts with the general findpath idea to minimize the energy barrier

Conclusions:

Adjustments to Findpath to potentially produce such paths (trade-off!)

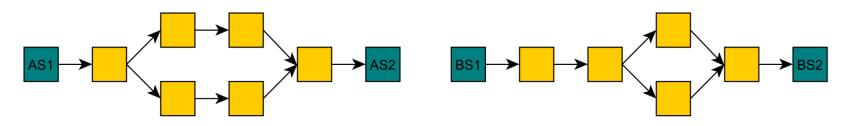
No guarantee to find "correct" suboptimal paths

Alternative approach to merge inner/outer sections

Toy example: 2 candidate paths

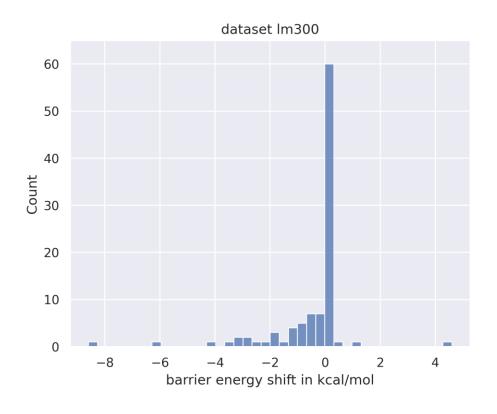
Reduce redundancy of input paths \rightarrow input graph (edges are move tuples):

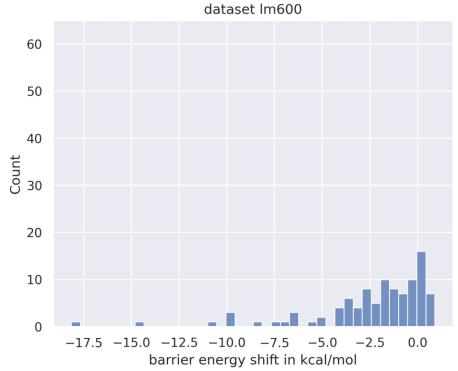
→ Apply Findpath algorithm to merge 2 input graphs



Barrier energy comparison

(energy shift vs. regular findpath)





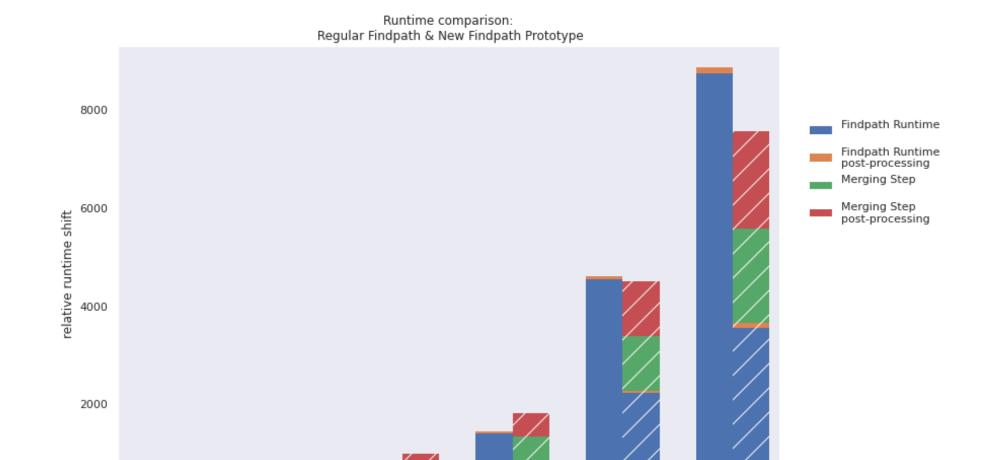
Dataset generation:

- Random RNA sequence strings
- (see slide 10)

Findpath settings:

- search width = bp_dist*2
- merge search width = bp_dist*0.4

Runtimes



Im600

lm800

lm1000

0

lm 300

Im 400

lm 500

datasets

Regular Findpath
New Findpath Prototype

Ongoing / future work

- Adapt Findpath for <u>indirect folding pathways</u> prior work:
 - RNATabuPath

Ivan Dotu, William A. Lorenz, Pascal Van Hentenryck, Peter Clote, Computing folding pathways between RNA secondary structures, Nucleic Acids Research, Volume 38, Issue 5, 1 March 2010, Pages 1711–1722, https://doi.org/10.1093/nar/gkp1054

RNAEAPath

Li, Y., Zhang, S. Predicting folding pathways between RNA conformational structures guided by RNA stacks. BMC Bioinformatics 13, S5 (2012). https://doi.org/10.1186/1471-2105-13-S3-S5

Indirect folding pathways

```
GGGCGCGGUUCGCCCUCCGCUAAAUGCGGAAGAUAAAUUGUGUCU
((((((....))))))(((((....)))))(((((....))))) [
                                 0 ] -18.10
((((((....)))))(((((....))))).((((....)))). [
                                -45 ] -17.20
((((((....)))))(((((....))))).(((.....))). [
                                -41 1 -15.90
(((((((....))))))(((((....))))).((....)).[-34,
((((((....)))))(((((....))))).(....).
-44 1 -16.80
.....[
                                     -8.40
-5.20
....((.....((((((.....))))))......)).....[
                                     -6.90
...(((.....))))....[
                                     -9.10
..(((((.....)))))......))))...[
                                 43 ] -10.70
.(((((.....))))).....))))...[
                                 44 1 -13.00
.(((((((....)))))).....)))))). [
                                 39 ] -13.80
.((((((((....)))))).....)))))). [
                                 38 ] -14.40
.(((((((((....)))))).....))))))). [
                                 37 1 -16.00
.((((((((((....))))))).....))))))).....)
                                 36 ] -17.10
45 ] -17.70
S: -5.00 kcal/mol | B: 13.10 kcal/mol | E[start]:-18.10 E[end]:-17.70
```

```
GGGCGCGGUUCGCCCUCCGCUAAAUGCGGAAGAUAAAUUGUGUCU
((((((....)))))(((((....)))))(((((....))))) [
                         0 ] -18.10
(((((((....)))))(((((....))))),((((....)))), [-31, -45] -17.20
-41 ] -15.90
-42 1 -13.90
(((...((...)))))(((((...))))).....
                           -10.40
-13 ]
((..(((...)))))(((((....)))))......
                        13 ] -10.50
-5.90
..((((((...)))..(((((....))))).......))...[
                           -7.50
((((((((...)))...(((((....)))))).....)))
((((((....))...(((((....)))))......))))
                           -9.20
(((((....)...(((((....)))))).....)))) [
((((.....))))) [
((((((....))))))......)))))
                         41 1 -10.20
(((((((....))))))......)))))
                         40 1 -13.60
((((((((....)))))))......)))))))))
                         39 ] -14.40
38 ] -15.00
37 ] -16.60
36 ] -17.70
S: -5.80 kcal/mol | B: 12.30 kcal/mol | E[start]:-18.10 E[end]:-17.70
```

Basepair distance distribution

