

2/26/25

Quiz recap: Rank is $\text{Dim}(\text{Col}(A))$

$\begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ r \end{bmatrix}$ basis \mathbb{R}^2 whenever $r \neq -2$

Solns to $A\vec{x} = \vec{b}$ look like translate of $\text{Nul}(A)$
by single soln.

Review:

$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a linear transformation

if preserves sums, i.e. $T(\vec{u}) + T(\vec{v})$ for all $\vec{u}, \vec{v} \in \mathbb{R}^n$

and preserves scalar mult., i.e. $T(c\vec{u}) = cT(\vec{u})$ for all $c \in \mathbb{R}$
 $\vec{u} \in \mathbb{R}^n$

Key Example

Let A be an $m \times n$ matrix

Then $T(x) = A\vec{x}$ is a linear transformation

$$1) T(\vec{u} + \vec{v}) = A(\vec{u} + \vec{v}) = A\vec{u} + A\vec{v} = T(\vec{u}) + T(\vec{v})$$

$$2) T(c\vec{u}) = A(c\vec{u}) = cA\vec{u} = cT(\vec{u})$$

Ex: $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$

$T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 3x-y \\ x \\ y \end{bmatrix}$ is a linear transformation.

check: ① $T\left(\begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} w \\ z \end{bmatrix}\right) = T\left(\begin{bmatrix} x+w \\ y+z \end{bmatrix}\right) = \begin{bmatrix} 3(x+w)-(y+z) \\ x+w \\ y+z \end{bmatrix}$

$$= \begin{bmatrix} 3x-y \\ x \\ y \end{bmatrix} + \begin{bmatrix} 3w-z \\ w \\ z \end{bmatrix} = T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) + T\left(\begin{bmatrix} w \\ z \end{bmatrix}\right)$$

② $T(c\begin{bmatrix} x \\ y \end{bmatrix}) = T\left(\begin{bmatrix} cx \\ cy \end{bmatrix}\right) = \begin{bmatrix} 3cx-cy \\ cx \\ cy \end{bmatrix} = c \begin{bmatrix} 3x-y \\ x \\ y \end{bmatrix} = cT\left(\begin{bmatrix} x \\ y \end{bmatrix}\right)$

Ex: $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$

$T(\vec{x}) = \vec{x} + \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ is a translation.

Not linear! $T(\vec{0}) = \vec{0} + \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \neq \vec{0}$

Ex: $T_1\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 1x1 \\ y \end{bmatrix}$ $T_2\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} xy \\ y \end{bmatrix}$ $T_3\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 2x+1 \\ x-2y \end{bmatrix}$

↪ not linear!

↪ not linear!

$$T_1(-2[1]) = T_1\left(\begin{bmatrix} -2 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 2 \\ -2 \end{bmatrix}$$

$$T_2(2[1]) = T_2\left(\begin{bmatrix} 2 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$$

$$-2T_1([1]) = \begin{bmatrix} -2 \\ -2 \end{bmatrix}$$

$$2T_2([1]) = 2\begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$$

or... $T_2\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 2 \\ 1 \end{bmatrix}\right) = T_2\left(\begin{bmatrix} 3 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 9 \\ 3 \end{bmatrix}$

$$T_2([1]) + T_2\left(\begin{bmatrix} 2 \\ 1 \end{bmatrix}\right) = [1] + \begin{bmatrix} 4 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 3 \end{bmatrix}$$

$$T_3 \rightarrow \text{not linear!} \quad T_3 \left(\begin{bmatrix} 0 \\ 0 \end{bmatrix} \right) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \neq \vec{0}$$

Ex: $T: \mathbb{R} \rightarrow \mathbb{R}$

$$T(x) = x^2 \quad \text{Not linear! (phew!)}$$

$$T(2 \cdot 1) = 4 \neq 2T(1) = 2$$

Ex: What are the linear maps $T: \mathbb{R} \rightarrow \mathbb{R}$?

$$T(x) = cx \quad \text{are the only ones:}$$

$T(x) = T(x \cdot 1) = xT(1)$ so $T(x)$ is totally determined by $T(1)$, and $T(x) = cx$ where $c = T(1)$.