

4/4/25

Defⁿ: The matrix for the linear transformation

$T(\vec{v}) = [\vec{v}]_{\mathcal{B}}$ is called the change of basis matrix from the standard basis to the basis \mathcal{B} .

Ex: $\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \end{bmatrix} \right\}$

bad cursive "s" $\rightarrow \mathcal{S} = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$

$$M_{\mathcal{B} \rightarrow \mathcal{S}} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad M_{\mathcal{B} \rightarrow \mathcal{S}} = \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}$$

$$M_{\mathcal{B} \rightarrow \mathcal{S}} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix} \quad \hookrightarrow M_{\mathcal{S} \rightarrow \mathcal{B}} = \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}^{-1} = \begin{bmatrix} -3 & 2 \\ 2 & -1 \end{bmatrix}$$

Prop: The change of basis matrix is invertible.

Pf $\mathcal{B} = \{ \vec{b}_1, \dots, \vec{b}_n \} \Rightarrow M_{\mathcal{B} \rightarrow \mathcal{S}} = [\vec{b}_1 \dots \vec{b}_n]$

linearly independent
& span \mathbb{R}^n (by def)

\vec{b}_i are independent $\Rightarrow M_{\mathcal{B} \rightarrow \mathcal{S}}$ is invertible

□

Q: Let $B = \{\vec{b}_1, \vec{b}_2\}$. What is the inverse of T w/

$$T(\vec{v}) = [\vec{v}]_B$$

A: $T(\vec{b}_1) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $T(\vec{b}_2) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

$$T^{-1}(\vec{e}_1) = \vec{b}_1 , \quad T^{-1}(\vec{e}_2) = \vec{b}_2$$

Summary $B = \{\vec{b}_1, \dots, \vec{b}_n\}$, $\mathcal{A} = \{\vec{e}_1, \dots, \vec{e}_n\}$

$M_{B \rightarrow \mathcal{A}}$ taking B coordinates to standard coordinates:

$$M_{B \rightarrow \mathcal{A}} = [\vec{b}_1, \dots, \vec{b}_n] \quad \text{since} \quad M_{B \rightarrow \mathcal{A}} \vec{e}_i = \vec{b}_i$$

$M_{\mathcal{A} \rightarrow B}$ taking standard coordinates to B coordinates:

$$M_{\mathcal{A} \rightarrow B} = M_{B \rightarrow \mathcal{A}}^{-1}$$

Q: why is this useful?

A: Matrices can be simpler w/ different basis!

Ex: A matrix w/ e-vals -1 (e-vec $v_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$) ,
2 (e-vec $v_2 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$)

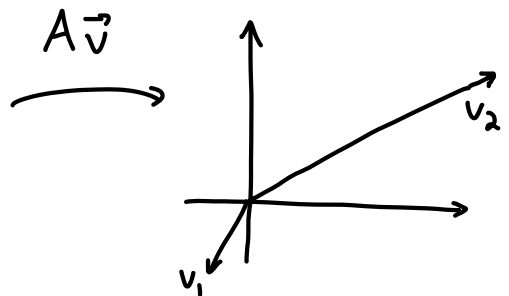
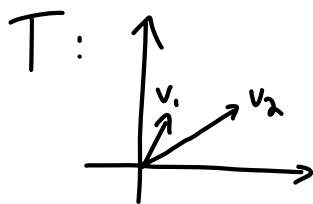
Let's write $T(\vec{v}) = A\vec{v}$ w.r.t. $\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \end{bmatrix} \right\}$

We want D w.r.t this basis.

$$De_1 = [A\vec{b}_1]_{\mathcal{B}} = [-\vec{b}_1]_{\mathcal{B}} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$De_2 = [A\vec{b}_2]_{\mathcal{B}} = [2\vec{b}_1]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$$

$$D = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}$$



To find A : use $A = M_{\mathcal{B} \rightarrow \mathcal{B}} D M_{\mathcal{A} \rightarrow \mathcal{B}}$

$$\begin{aligned} A &= \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}^{-1} \\ &= \begin{bmatrix} -1 & 4 \\ -2 & 6 \end{bmatrix} \begin{bmatrix} -3 & 2 \\ 2 & -1 \end{bmatrix} = \begin{bmatrix} 11 & -6 \\ 18 & -10 \end{bmatrix} \end{aligned}$$

$$A\vec{v}_1 = \begin{bmatrix} 11 & -6 \\ 18 & -10 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ -2 \end{bmatrix} = -\vec{v}_1$$

$$A\vec{v}_2 = \begin{bmatrix} 11 & -6 \\ 18 & -10 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 4 \\ 6 \end{bmatrix} = 2\vec{v}_2$$

Let's
check:

∴
✓

Defⁿ: Two $n \times n$ matrices are similar if there is an invertible B w/ $A = BCB^{-1}$

Ex: $\begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}$ is similar to $\begin{bmatrix} 11 & -6 \\ 18 & -10 \end{bmatrix}$ because

$$\begin{bmatrix} 11 & -6 \\ 18 & -10 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}^{-1}$$

$\begin{matrix} \text{"} \\ A \end{matrix}$ $\begin{matrix} \text{"} \\ B \end{matrix}$ $\begin{matrix} \text{"} \\ C \end{matrix}$ $\begin{matrix} \text{"} \\ B^{-1} \end{matrix}$

Rmk: Similar matrices represent the same linear transformations w.r.t. a different basis

Basic Properties

1. (reflexive) A is similar to A

Pf: $A = IAI^{-1}$

2. (symmetric) If A is similar to C , then C is similar to A

Pf: $A = BCB^{-1}$

$$B^{-1}AB = C$$

$$C = B^{-1}A(B^{-1})^{-1}$$

(contd. next time!)