

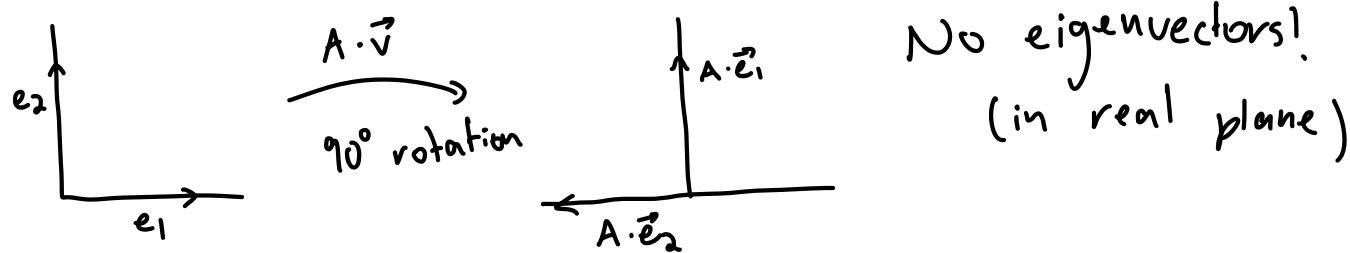
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Ex: $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ Find e-vals & e-vecs HW asks for real eigenvalues

$$\det(A - \lambda I) = \begin{vmatrix} -\lambda & -1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 + 1 = 0$$

$$\lambda^2 = -1 \quad \lambda = \pm i$$
(none)

what is A doing?



(challenge from last class)

Ex: A 2×2 , $A\vec{v}_1 = -\vec{v}_1$, $A\vec{v}_2 = 2\vec{v}_2$

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad \vec{v}_2 = \begin{bmatrix} 2 \\ 3 \end{bmatrix} \quad A^5 = ?$$

Soln To find a 2×2 matrix B , we need $B\vec{e}_1$, $B\vec{e}_2$

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} = ? \vec{v}_1 + ? \vec{v}_2 \quad \begin{bmatrix} 0 \\ 1 \end{bmatrix} = ? \vec{v}_1 + ? \vec{v}_2$$

$$\left[\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 2 & 3 & 0 & 1 \end{array} \right] \xrightarrow{\text{RREF}} \left[\begin{array}{cc|cc} 1 & 0 & -3 & 2 \\ 0 & 1 & 2 & -1 \end{array} \right]$$

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} = -3\vec{v}_1 + 2\vec{v}_2 \quad \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 2\vec{v}_1 - \vec{v}_2$$



$$A^5 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = A^5(-3v_1 + 2v_2) = -3A^5v_1 + 2A^5v_2$$

$$= -3(-1)^5 v_1 + 2(2)^5 v_2$$

$$= 3 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 64 \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 3 \\ 6 \end{bmatrix} + \begin{bmatrix} 128 \\ 192 \end{bmatrix} \\ = \begin{bmatrix} 131 \\ 198 \end{bmatrix}$$

$$A^5 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = A^5(2v_1 - v_2) = 2A^5v_1 - A^5v_2$$

$$= 2(-1)^5 v_1 - (2)^5 v_2$$

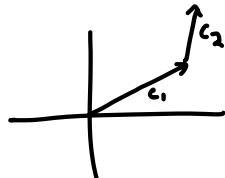
$$= -2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} - 32 \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} -2 & -64 \\ -4 & -96 \end{bmatrix} = \begin{bmatrix} -66 \\ -100 \end{bmatrix}$$

$$A^5 = \begin{bmatrix} 131 & -66 \\ 198 & -100 \end{bmatrix} \quad \therefore$$

Change of Basis

Ex: $\beta = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \end{bmatrix} \right\}$ is a basis for \mathbb{R}^2

$$\text{Given } \vec{v} = c_1 \vec{v}_1 + c_2 \vec{v}_2 \quad [\vec{v}]_{\beta} = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$



Prop: Given a basis $\beta = \{v_1, \dots, v_n\}$ for \mathbb{R}^n ,
 the fn $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ w/ $T(\vec{v}) = [\vec{v}]_{\beta}$
 is a linear transformation

Pf $\boxed{+} \vec{u} = c_1 \vec{v}_1 + \dots + c_n \vec{v}_n, \vec{v} = b_1 \vec{v}_1 + \dots + b_n \vec{v}_n$

$$\vec{u} + \vec{v} = (c_1 + b_1) \vec{v}_1 + \dots + (c_n + b_n) \vec{v}_n$$

$$T(\vec{u} + \vec{v}) = \begin{bmatrix} c_1 + b_1 \\ \vdots \\ c_n + b_n \end{bmatrix} = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} + \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix} = T(\vec{u}) + T(\vec{v})$$

$\boxed{\cdot} T(c\vec{u}) = \begin{bmatrix} c c_1 \\ \vdots \\ c c_n \end{bmatrix} = c \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} = c T(\vec{u})$

□

Q: what is the matrix for this T ?

A is matrix $\begin{bmatrix} T([1]) & T([0]) \end{bmatrix}$

$$T([1]) = \begin{bmatrix} -3 \\ 2 \end{bmatrix} \quad T([0]) = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

$$A = \begin{bmatrix} -3 & 2 \\ 2 & -1 \end{bmatrix} \quad \text{which is inverse of} \quad \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} !$$