

2/19/25

Recap: Thm (Dimension) Let $V \subseteq \mathbb{R}^m$ be a subspace.

let $\vec{a}_1, \dots, \vec{a}_k \in V$ be linearly independent

and $\vec{b}_1, \dots, \vec{b}_l \in V$ span V . Then $k \leq l$

Corollary: If $V \subseteq \mathbb{R}^m$ is a subspace, then any two bases have the same size.

$$(k \leq l \text{ and } l \leq k \Rightarrow k = l)$$

Defn: The dimension of a subspace V , written as $\dim V$, is the number of vectors in any basis

Thm Let $V \subseteq \mathbb{R}^m$ be a subspace of $\dim d$.

For $\vec{v}_1, \dots, \vec{v}_d \in V$, the following are equivalent:

① $\vec{v}_1, \dots, \vec{v}_d$ form a basis for V

② $\vec{v}_1, \dots, \vec{v}_d$ spans V

③ $\vec{v}_1, \dots, \vec{v}_d$ are linearly independent

Thm (Rank-Nullity) For any $m \times n$ matrix A , we have:

$$\dim(\text{Col}(A)) + \dim(\text{Nul}(A)) = n$$

Pf. $\dim(\text{Col}(A)) = \# \text{ of pivots in } A$

$\dim(\text{Nul}(A)) = \# \text{ of free variables}$

Defn: For a matrix A , the rank of A is $\dim(\text{Col}(A))$

Thm Let $V \subseteq \mathbb{R}^m$ be a subspace. Then every linearly independent set of vectors in V can be extended to a basis.

Ex: Extend $\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ to a basis of \mathbb{R}^3

Soln. ① Find a spanning set of vectors:

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad (\text{"over-doing it" here})$$

② Find an independent subset with the same span.

$$\left[\begin{array}{ccccc} 1 & 1 & 1 & 0 & 0 \\ 1 & 2 & 0 & 1 & 0 \\ 1 & 2 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\text{RREF}} \left[\begin{array}{ccccc} 1 & 0 & 2 & 0 & -1 \\ 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \end{array} \right]$$

↑↑
pivots ↑↑
free variables (dependent vectors)

$$\Rightarrow \text{Basis: } \left[\begin{array}{c} 1 \\ 1 \\ 1 \end{array} \right], \left[\begin{array}{c} 1 \\ 2 \\ 2 \end{array} \right], \left[\begin{array}{c} 0 \\ 1 \\ 0 \end{array} \right]$$

Ex: Suppose $\vec{v}_1, \vec{v}_2 \in V$ is a basis.

Show that $\vec{u}_1 = \vec{v}_1 + \vec{v}_2$ and $\vec{u}_2 = \vec{v}_1 - \vec{v}_2$ is also a basis.

Soln. $\{\vec{v}_1, \vec{v}_2\}$ basis $\Rightarrow \dim(V) = 2$. So, enough

to show that \vec{u}_1, \vec{u}_2 span V , i.e.

$$v_1, v_2 \in \text{span}\{\vec{u}_1, \vec{u}_2\}$$

$$\vec{u}_1 = \vec{v}_1 + \vec{v}_2 \quad \vec{u}_2 = \vec{v}_1 - \vec{v}_2$$

$$\vec{v}_1 = \vec{u}_1 - \vec{v}_2 \quad \vec{v}_2 = \vec{v}_1 - \vec{u}_2$$

$$\vec{v}_1 = \vec{u}_1 - \vec{v}_1 + \vec{u}_2$$

$$2\vec{v}_1 = \vec{u}_1 + \vec{u}_2$$

$$\vec{v}_1 = \frac{1}{2}(u_1 + u_2)$$

$$\vec{v}_2 = \vec{u}_1 - \vec{v}_2 - \vec{u}_2$$

$$2\vec{v}_2 = \vec{u}_1 - \vec{u}_2$$

$$\vec{v}_2 = \frac{1}{2}(\vec{u}_1 - \vec{u}_2)$$

..

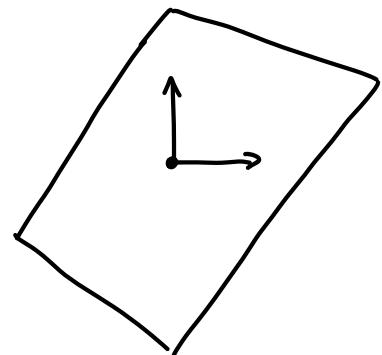
General solution to a linear equation:

Thm Let $A\vec{x} = \vec{b}$ be a consistent system with \vec{p} one solution. Then all solutions have the form $\vec{p} + \vec{n}$ with $\vec{n} \in \text{Nul}(A)$.

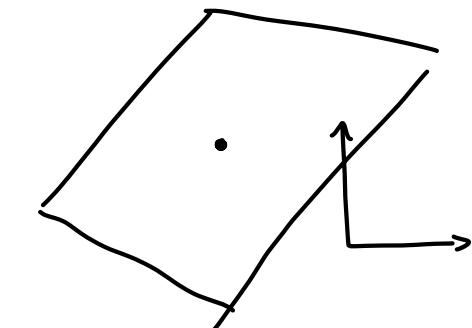
Picture:

solutions to $A\vec{x} = \vec{0}$

$\text{Nul}(A)$ is a subspace



Solutions to $A\vec{x} = \vec{b}$ are
a translate of the subspace by \vec{p}



Think:
Solutions to
linear systems
look linear!