

3/31/25

(Review)

Ex: Find the e-vals and e-vects of  $\begin{bmatrix} 2 & 1 & 0 \\ -1 & 0 & 1 \\ 1 & 3 & 1 \end{bmatrix}$

① to find e-vals: find roots of characteristic polynomial

$\det(A - \lambda I) = 0$ , solns  $\lambda$  are e-vals

② to find e-vects: find null space of  $A - \lambda I$

Pf review

$$A\vec{v} = \lambda\vec{v}$$

$$\Leftrightarrow A\vec{v} - \lambda\vec{v} = 0$$

$$\text{Nul}(A - \lambda I)$$

$$\Leftrightarrow (A - \lambda I)\vec{v} = 0$$

$$A - \lambda I = \begin{bmatrix} 2-\lambda & 1 & 0 \\ -1 & -\lambda & 1 \\ 1 & 3 & 1-\lambda \end{bmatrix}$$

①

$$\det(A - \lambda I) = (2-\lambda) \begin{vmatrix} -\lambda & 1 \\ 3 & 1-\lambda \end{vmatrix} - \begin{vmatrix} -1 & 1 \\ 1 & 1-\lambda \end{vmatrix}$$

$$= (2-\lambda)(\lambda^2 - \lambda - 3) - (\lambda - 1 - 1)$$

$$= -(\lambda - 2)(\lambda^2 - \lambda - ) - (\lambda - 2)$$

$$= (\lambda - 2)(\lambda^2 - \lambda - 2)$$

$$= (\lambda - 2)(\lambda - 2)(\lambda + 1)$$

$$\lambda = -1, 2$$

$$\textcircled{2} \quad \text{Nul}(A - \lambda I) = \text{Nul} \left( \begin{bmatrix} 2-2 & 1 & 0 \\ -1 & -2 & 1 \\ 1 & 3 & 1-2 \end{bmatrix} \right)$$

$$\begin{bmatrix} 0 & 1 & 0 \\ -1 & 2 & 1 \\ 1 & 3 & -1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_3} \begin{bmatrix} 1 & 3 & -1 \\ -1 & 2 & 1 \\ 0 & 1 & 0 \end{bmatrix} \xrightarrow{R_2 + R_1} \begin{bmatrix} 1 & 3 & -1 \\ 0 & 5 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$\xrightarrow{\frac{1}{5}R_2} \begin{bmatrix} 1 & 3 & -1 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix} \xrightarrow{R_1 - 3R_2, R_3 - R_2} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_3 \\ 0 \\ x_3 \end{bmatrix} \xrightarrow{\text{let } x_3 = 1} \vec{v} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$\text{Nul}(A - \lambda I) \stackrel{\lambda = -1}{=} \begin{bmatrix} 3 & 1 & 0 \\ -1 & 1 & 1 \\ 1 & 3 & 2 \end{bmatrix} \xrightarrow{\text{REF}} \begin{bmatrix} 1 & 3 & 2 \\ 0 & 4 & 3 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\Rightarrow x_3 = x_3 \quad x_1 = -2x_3 - 3x_2 \\ x_2 = -\frac{3}{4}x_3 \quad = -2x_3 + \frac{9}{4}x_3 = \frac{1}{4}x_3$$

$$\vec{v} = x_3 \begin{bmatrix} \frac{1}{4} \\ -\frac{3}{4} \\ 1 \end{bmatrix} \text{ "eigen space"} \quad \text{let } x_3 = 4 \\ \vec{v} = \begin{bmatrix} 1 \\ -3 \\ 4 \end{bmatrix}$$

$$\underline{\text{Ex:}} \quad A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad e\text{-vals} = 1 \\ e\text{-vecs} = \text{anything (except } \vec{0} \text{ by def)}$$

$$0 = \det(A - \lambda I) = \begin{vmatrix} 1-\lambda & 0 \\ 0 & 1-\lambda \end{vmatrix} = (1-\lambda)^2 = 0 \Rightarrow \lambda = 1$$

$$\text{Nul}(A - \lambda I) \stackrel{\lambda = 1}{=} \text{Nul} \left( \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \right) = \mathbb{R}^2$$

Defn: For an eigenvalue  $\lambda$  of  $A$ , the  $\lambda$ -eigenspace of  $A$  is  $\text{Nul}(A - \lambda I)$

Ex: Find e-vals, e-vects of

a)  $A_1 = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$   $\det(A_1 - \lambda I) = \begin{vmatrix} 2-\lambda & 0 & 0 \\ 0 & 2-\lambda & 0 \\ 0 & 0 & 2-\lambda \end{vmatrix} = (2-\lambda)^3 = 0 \Rightarrow \lambda = 2$

$$\text{Nul}(A_1 - 2I) = \text{Nul}\left(\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}\right) \Rightarrow \text{eigenspace} = \mathbb{R}^3$$

b)  $A_2 = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$   $\det(A_2 - \lambda I) = \begin{vmatrix} 2-\lambda & 1 & 0 \\ 0 & 2-\lambda & 0 \\ 0 & 0 & 2-\lambda \end{vmatrix} = (2-\lambda)^3 = 0 \Rightarrow \lambda = 2$

$$\text{Nul}(A_2 - 2I) = \text{Nul}\left(\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}\right) \quad \begin{aligned} x_2 &= 0 \\ \text{e-space} &= \text{span}\left\{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right\} \\ \dim &= 2 \end{aligned}$$

c)  $A_3 = \begin{bmatrix} 2 & 0 & 0 \\ 1 & 2 & 0 \\ 0 & 1 & 2 \end{bmatrix}$   $\det(A_3 - \lambda I) = (2-\lambda)^3 = 0 \Rightarrow \lambda = 2$

$$\text{Nul}(A_3 - 2I) = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \quad \begin{aligned} x_1 &= 0 \\ x_2 &= 0 \\ x_3 &= x_3 \end{aligned} \quad \text{e-space} = \text{span}\left\{\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}\right\}$$

Ex:  $A = \begin{bmatrix} 3 & 0 \\ 0 & -2 \end{bmatrix}$

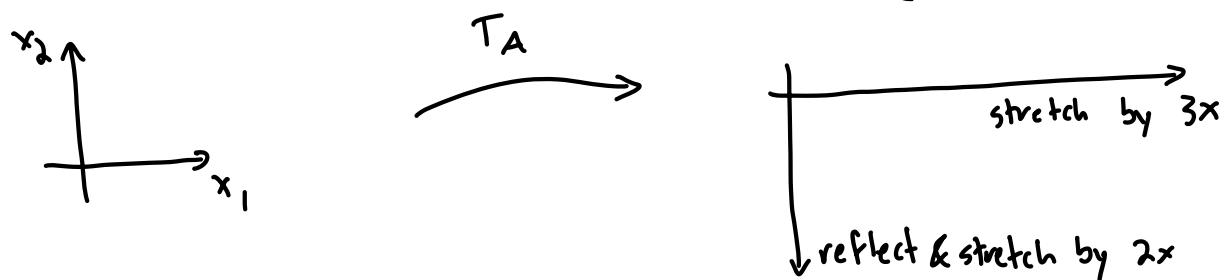
- 1) what does  $T_A(\vec{v}) : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  look like?
- 2) what is  $A^{10}$ ?

$$\begin{bmatrix} 3 & 0 \\ 0 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3x_1 \\ -2x_2 \end{bmatrix}$$

$$A^{10} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = 3^{10} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 3^{10} \\ 0 \end{bmatrix}$$

$$A^{10} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = (-2)^{10} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ (-2)^{10} \end{bmatrix}$$

$$A^{10} = \begin{bmatrix} 3^{10} & 0 \\ 0 & (-2)^{10} \end{bmatrix}$$



upshot: diagonal matrices make it easy to find powers of A