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Recap: $I_n = \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix}$ $AI_n = A = I_mA$

$$A\vec{x} = b, \quad A = \begin{bmatrix} | & | & | \\ v_1 & \dots & v_n \\ | & | & | \end{bmatrix}$$
$$x_1\vec{v}_1 + \dots + x_n\vec{v}_n$$
$$\vdots$$

Other Matrix Operations:

- Addition: $A = [a_{ij}], B = [b_{ij}]$ are $m \times n$ matrices

$A + B$ is matrix with entries $[a_{ij} + b_{ij}]$

- Scalar Multiplication: $rA = [ra_{ij}]$

Ex: $A = \begin{bmatrix} 1 & 2 & -4 \\ 0 & 3 & -1 \end{bmatrix}$ $B = \begin{bmatrix} -1 & 0 & 2 \\ 1 & -5 & 3 \end{bmatrix}$

$$2A - 3B = \begin{bmatrix} 2 & 4 & -8 \\ 0 & 6 & -2 \end{bmatrix} + \begin{bmatrix} 3 & 0 & -6 \\ -3 & 15 & -9 \end{bmatrix} = \begin{bmatrix} 5 & 4 & -14 \\ -3 & 21 & -11 \end{bmatrix}$$

Zero Matrix:

0 is the matrix of all zeros
(size is often clear from context)

$$0 + A = 0 + A = 0$$

Defⁿ: The transpose of an $n \times m$ matrix $A = [a_{ij}]$ is the matrix $A^T = [a_{ji}]$

Defⁿ: A square matrix is called symmetric if $A^T = A$

Ex: Find A^T when $A = \begin{bmatrix} 1 & 4 & 5 \\ -3 & 2 & 7 \end{bmatrix}$

Soln: $A^T = \begin{bmatrix} 1 & -3 \\ 4 & 2 \\ 5 & 7 \end{bmatrix}$

Ex: Fill in the missing entries of

think about "flipping" matrix across the diagonal

$$\begin{bmatrix} 5 & -6 & \boxed{-2} & 8 \\ \boxed{-6} & 3 & \boxed{1} & \boxed{11} \\ -2 & 1 & 0 & 4 \\ \boxed{8} & 11 & 4 & -1 \end{bmatrix} \quad \text{to make it symmetric.}$$

Transpose (A^T)

- $(A^T)^T = A$
- $(A + B)^T = A^T + B^T$
- $(AB)^T = B^T A^T$

$m \times n$ $n \times p$ $p \times n$ $n \times m$ $\rightarrow p \times m$

PF.

If $A = [a_{ij}]$ $B = [b_{ij}]$

$$AB = \left[\sum_{k=1}^n a_{ik} b_{kj} \right]$$

$$(AB)^T = \left[\sum_{k=1}^n a_{jk} b_{ki} \right]$$

$$= \left[\sum_{k=1}^n b_{ki} a_{jk} \right] = B^T A^T$$

□

Non-property: $AB \neq BA$ in general

also, $AB = AC \not\Rightarrow B = C$

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 2 & 7 \\ 3 & 9 \end{bmatrix} = \begin{bmatrix} 2 & 7 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 2 & 7 \\ 18 & 24 \end{bmatrix}$$

(loses information
~ a is not invertable)

Elementary Matrices

Defn: A matrix that can be obtained from an identity matrix by doing a single elementary row operation (① swap, ② add a mult. of one row to another, ③ scaling) is called an elementary matrix.

Ex: $I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$$3R_2 \quad L_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_1 \leftrightarrow R_2 \quad L_2 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_3 - 7R_1 \quad L_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -7 & 0 & 1 \end{bmatrix}$$

$$\begin{array}{ccc} \text{Ex: } A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} & \rightarrow & L_1 A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 12 & 15 & 18 \\ 7 & 8 & 9 \end{bmatrix} \\ & \curvearrowright & L_2 A = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} = \begin{bmatrix} 4 & 5 & 6 \\ 1 & 2 & 3 \\ 7 & 8 & 9 \end{bmatrix} \end{array}$$

$$\rightarrow L_3 A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -7 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ -21 & -27 & -33 \end{bmatrix}$$

(oops, this shows $R_3 - 7R^2$)

Observation/Theorem:

Multiplying a matrix A on the left by an elementary matrix L is equivalent to performing the corresponding elementary operation on A .

Pf. Recall that if $A = \begin{bmatrix} | & | & | \\ v_1 & \dots & v_n \\ | & \dots & | \end{bmatrix}$, then

$$LA = \begin{bmatrix} | & | & | \\ Lv_1 & \dots & Lv_n \\ | & \dots & | \end{bmatrix}, \text{ so it is enough to show}$$

this for products Lv , w/ \vec{v} a vector.

We show this for L corresponding to $R_k - rR_l$

$$\begin{bmatrix} 1 & & & \\ \ddots & \ddots & \ddots & \\ -r & \cdots & \cdots & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} v_1 \\ \vdots \\ v_k - rv_l \\ \vdots \\ v_n \end{bmatrix}$$

\uparrow
 k, l

