

# proximal\_gradient\_descent\_example

March 30, 2023

## 1 Activity 17

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[ ]: import numpy as np
import matplotlib.pyplot as plt
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[ ]: def prxgraddescent_l2(X,y,tau,lam,w_init,it):

    ## compute it iterations of L2 proximal gradient descent starting at w1
    ##  $w_{k+1} = (w_k - \tau X'(Xw_k - y)) / (1 + \lambda \tau)$ 
    ## step size tau
    W = np.zeros((w_init.shape[0], it+1))
    Z = np.zeros((w_init.shape[0], it+1))
    W[:,0] = w_init
    for k in range(it):
        Z[:,k+1] = W[:,k] - tau * X.T @ (X @ W[:,k] - y)
        W[:,k+1] = Z[:,k+1] / (1 + lam * tau)

    return W,Z
```

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[ ]: ## Proximal gradient descent trajectories
## Least Squares Problem
U = np.array([[1, 0], [0, 1], [0, 0], [0, 0]])
S = np.array([[1, 0], [0, 0.5]])
Sinv = np.linalg.inv(S)
V = 1/np.sqrt(2)*np.array([[1, 1], [1, -1]])
y = np.array([np.sqrt(2)], [0], [1], [0])

X = U @ S @ V.T

### Find Least Squares Solution
w_ls = V @ Sinv @ U.T @ y
c = y.T @ y - y.T @ X @ w_ls

### Find values of  $f(w)$ , the contour plot surface for
w1 = np.arange(-1,3,.1)
w2 = np.arange(-1,3,.1)
fw = np.zeros((len(w1), len(w2)))
```

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for i in range(len(w2)):
    for j in range(len(w1)):
        w = np.array([ w1[j], w2[i] ])
        fw[i,j] = (w-w_ls).T @ X.T @ X @ (w-w_ls) + c

```

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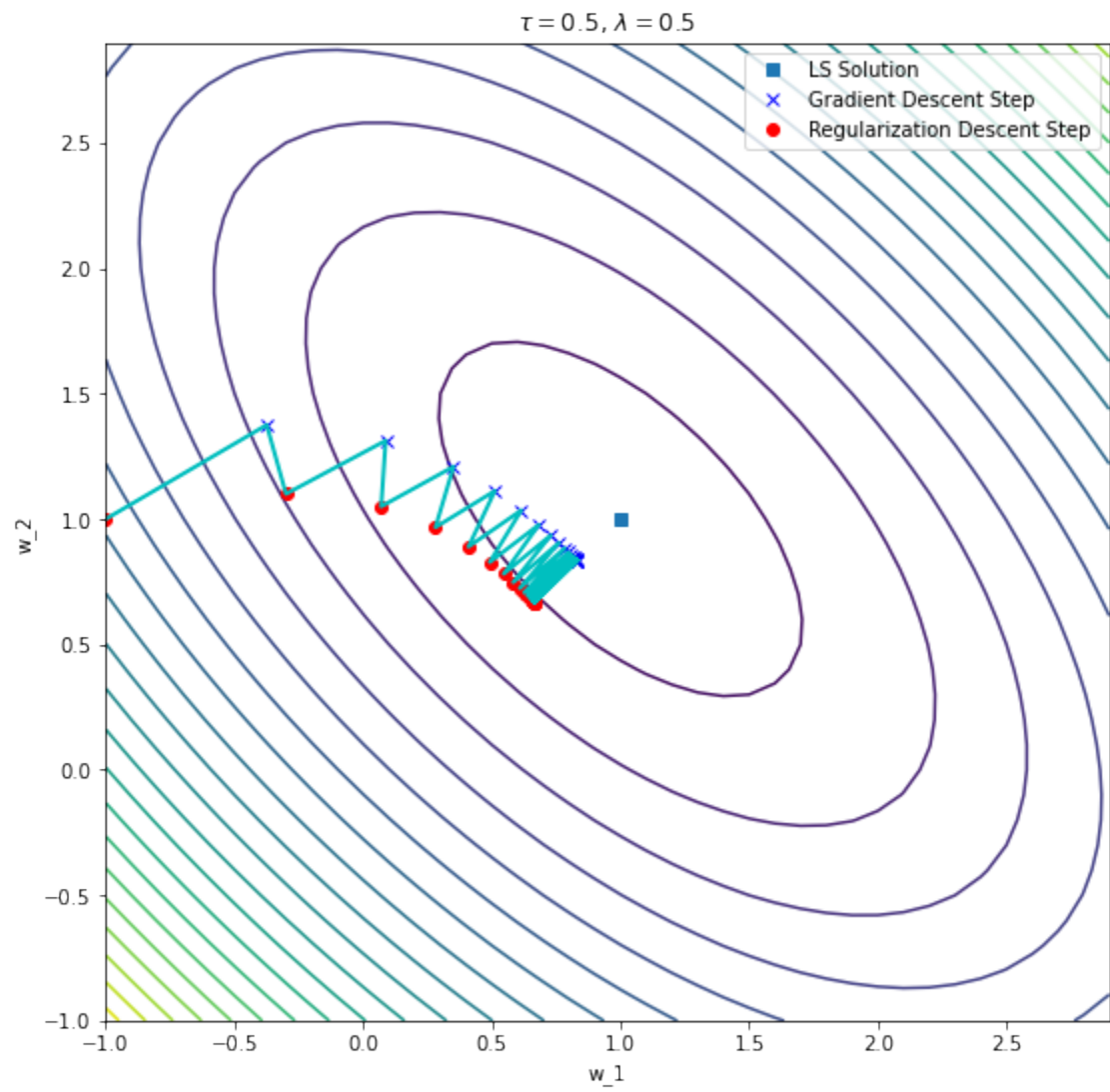
[ ]: ## Find and display weights generated by gradient descent

w_init = np.array([[ -1 ], [ 1 ]])
lam = 0.5
it = 20
tau = 0.5
W,Z = prxgraddescent_l2(X,y,tau,lam,w_init,it)

# Concatenate gradient and regularization steps to display trajectory
G = np.zeros((2,0))
for i in range(it):
    G = np.hstack((G,np.hstack((W[:, [i]], Z[:, [i+1]]))))

plt.figure(figsize=(9,9))
plt.contour(w1,w2,fw,20)
plt.plot(w_ls[0],w_ls[1], "s", label="LS Solution")
plt.plot(Z[0,1:],Z[1,1:], 'bx',linewidth=2, label="Gradient Descent Step")
plt.plot(W[0,:],W[1,:], 'ro',linewidth=2, label="Regularization Descent Step")
plt.plot(G[0,:],G[1,:], '-c',linewidth=2)
plt.legend()
plt.xlabel('w_1')
plt.ylabel('w_2')
plt.title('$\\tau = $'+str(.5)+' , $\\lambda = $'+str(lam))

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