

# A6

March 27, 2023

```
[ ]: # Enable interactive rotation of graph
%matplotlib widget

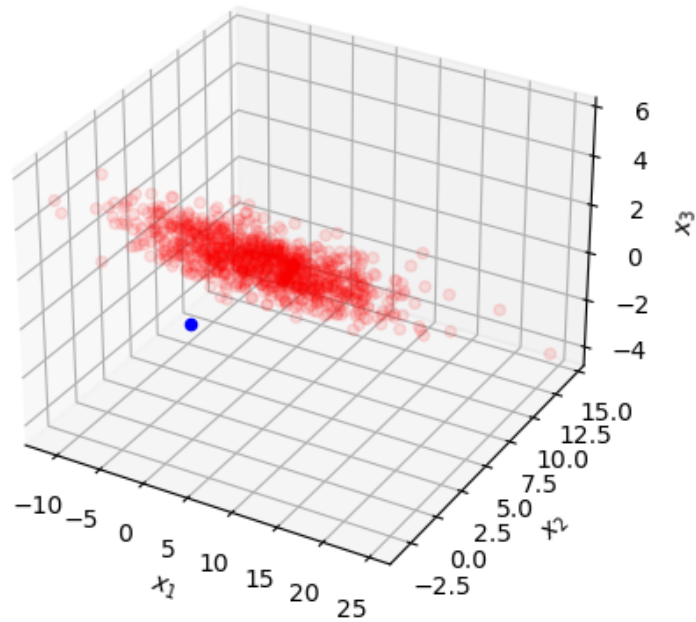
import numpy as np
from scipy.io import loadmat
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D

# Load data for activity
X = np.loadtxt('sdata.csv', delimiter=',')

[ ]: fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')

ax.scatter(X[:,0], X[:,1], X[:,2], c='r', marker='o', alpha=0.1)
ax.scatter(0,0,0,c='b', marker='o')
ax.set_xlabel('$x_1$')
ax.set_ylabel('$x_2$')
ax.set_zlabel('$x_3$')

plt.show()
# Use the rotate tool to view the data cloud from different perspectives.
```



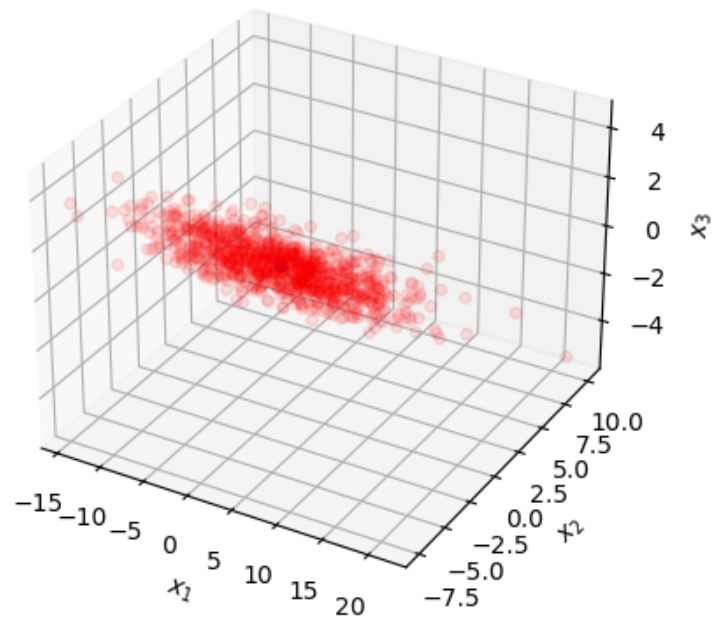
```
[ ]: # Subtract mean
X_m = X - np.mean(X, 0)

[ ]: # display zero mean scatter plot
fig = plt.figure()

ax = fig.add_subplot(111, projection='3d')
ax.scatter(X_m[:,0], X_m[:,1], X_m[:,2], c='r', marker='o', alpha=0.1)

ax.scatter(0,0,0,c='b', marker='o')
ax.set_xlabel('$x_1$')
ax.set_ylabel('$x_2$')
ax.set_zlabel('$x_3$')

plt.show()
```



```
[ ]: # Use SVD to find first principal component

U,s,VT = np.linalg.svd(X_m,full_matrices=False)

# complete the next line of code to assign the first principal component to a
a = VT[0]

[ ]: # display zero mean scatter plot and first principal component

fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')

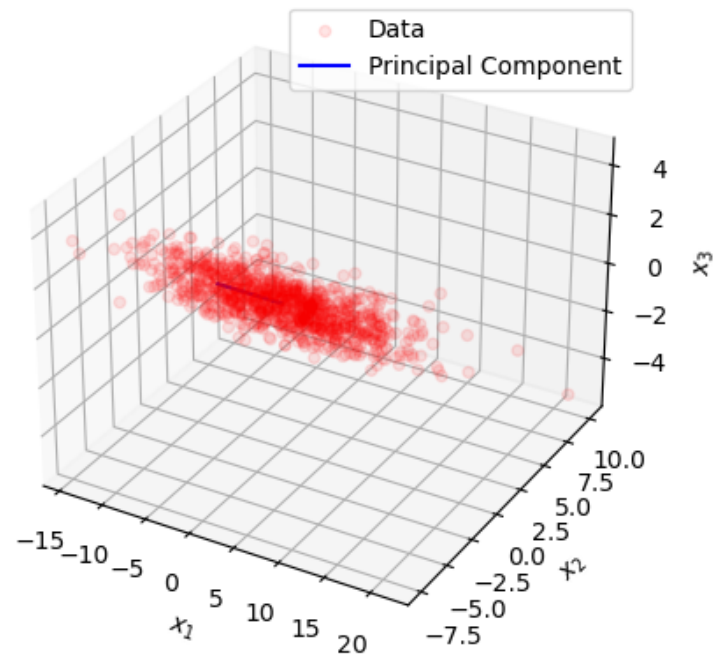
#scale length of line by root mean square of data for display
ss = s[0]/np.sqrt(np.shape(X_m)[0])

ax.scatter(X_m[:,0], X_m[:,1], X_m[:,2], c='r', marker='o', label='Data',
           alpha=0.1)

ax.plot([0,ss*a[0]],[0,ss*a[1]],[0,ss*a[2]], c='b',label='Principal Component')
```

```
ax.set_xlabel('$x_1$')
ax.set_ylabel('$x_2$')
ax.set_zlabel('$x_3$')
```

```
ax.legend()
plt.show()
```



```
[ ]: # f)
      # get mean value of each coordinate
      mean = np.mean(X,0)
      print(mean)
```

```
[3.17585563  4.24319511  1.25610797]
```

```
[ ]: # h)
      a2 = VT[1]
      # display zero mean scatter plot and second principal component

      fig = plt.figure()
      ax = fig.add_subplot(111, projection='3d')
```

```

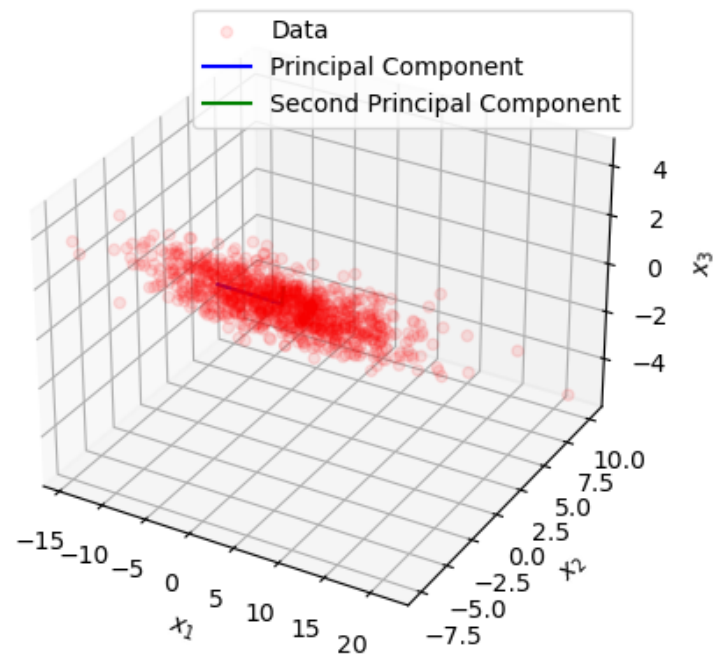
#scale length of line by root mean square of data for display
ss2 = s[1]/np.sqrt(np.shape(X_m)[0])

ax.scatter(X_m[:,0], X_m[:,1], X_m[:,2], c='r', marker='o', label='Data',
           alpha=0.1)

ax.plot([0,ss*a[0]],[0,ss*a[1]],[0,ss*a[2]], c='b',label='Principal Component')
ax.plot([0,ss2*a2[0]],[0,ss2*a2[1]],[0,ss2*a2[2]], c='g',label='Second
Principal Component')
ax.set_xlabel('$x_1$')
ax.set_ylabel('$x_2$')
ax.set_zlabel('$x_3$')

ax.legend()
plt.show()

```



```

[ ]: x_hat1 = U[:, :1]@np.diag(s)[ :1, :1]@VT[:1, :]
      print(np.linalg.norm(x_hat1-X_m))

```

```
x_hat2 = U[:, :2]@np.diag(s)[:2, :2]@VT[:2, :]
print(np.linalg.norm(x_hat2-X_m))
```

25.033775591913372

12.367116712429965

### 0.1 3

```
[ ]: # a)

face_data = loadmat('face_emotion_data.mat')
x = face_data['X']
y = face_data['y']

X = [x[i::8] for i in range(8)]
Y = [y[i::8] for i in range(8)]

totalError = 0
n = 1
for i in range(8):
    for j in range(8):
        if i == j:
            continue
        xTrain = np.vstack([X[k] for k in range(8) if k != i])
        yTrain = np.vstack([Y[k] for k in range(8) if k != i])
        xTest = X[i]
        yTest = Y[i]
        xVal = X[j]
        yVal = Y[j]
        U,s,VT = np.linalg.svd(xTrain,full_matrices=False)
        sigma_inverse = np.diag(1/s)

        min = 1000000
        rank = 0
        bestW = 0
        for r in range(1, 10):
            wCross = VT.T[:, :r]@sigma_inverse[:r, :r]@U.T[:, :r]@yTrain
            yPred = np.sign(xTest@wCross)
            diff = np.count_nonzero(yTest - yPred)
            if (diff < min):
                min = diff
                rank = r
                bestW = wCross
        yPred = np.sign(xVal@bestW)
        diff = np.count_nonzero(yVal - yPred)
        print("n: ", n, "Error: ", str(diff/16))
        totalError += diff/16
```

```
        n += 1
print("Average error: ", str(totalError/64))
```

```
n:  1 Error:  0.0625
n:  2 Error:  0.0
n:  3 Error:  0.125
n:  4 Error:  0.0625
n:  5 Error:  0.0625
n:  6 Error:  0.0625
n:  7 Error:  0.125
n:  8 Error:  0.0
n:  9 Error:  0.0625
n: 10 Error:  0.0
n: 11 Error:  0.0
n: 12 Error:  0.0625
n: 13 Error:  0.0625
n: 14 Error:  0.0
n: 15 Error:  0.0
n: 16 Error:  0.0625
n: 17 Error:  0.0
n: 18 Error:  0.0
n: 19 Error:  0.0625
n: 20 Error:  0.0
n: 21 Error:  0.0
n: 22 Error:  0.0
n: 23 Error:  0.0625
n: 24 Error:  0.0625
n: 25 Error:  0.0
n: 26 Error:  0.0
n: 27 Error:  0.0625
n: 28 Error:  0.0
n: 29 Error:  0.0
n: 30 Error:  0.0625
n: 31 Error:  0.0625
n: 32 Error:  0.0
n: 33 Error:  0.0
n: 34 Error:  0.0625
n: 35 Error:  0.0
n: 36 Error:  0.0
n: 37 Error:  0.0625
n: 38 Error:  0.0625
n: 39 Error:  0.0
n: 40 Error:  0.0
n: 41 Error:  0.0625
n: 42 Error:  0.0
n: 43 Error:  0.0
n: 44 Error:  0.0625
```

```

n: 45 Error: 0.0625
n: 46 Error: 0.125
n: 47 Error: 0.0625
n: 48 Error: 0.0625
n: 49 Error: 0.0625
n: 50 Error: 0.1875
n: 51 Error: 0.25
n: 52 Error: 0.25
n: 53 Error: 0.25
n: 54 Error: 0.0625
n: 55 Error: 0.375
n: 56 Error: 0.1875
Average error: 0.052734375

```

```

[ ]: # b)

totalError = 0
n = 1

for i in range(8):
    for j in range(8):
        if i == j:
            continue
        xTrain = np.vstack([X[k] for k in range(8) if k != i])
        yTrain = np.vstack([Y[k] for k in range(8) if k != i])
        xTest = X[i]
        yTest = Y[i]
        xVal = X[j]
        yVal = Y[j]
        U,s,VT = np.linalg.svd(xTrain,full_matrices=False)
        sigma = np.diag(s)

        min = 1000000
        bestLambda = 0
        bestW = 0
        for l in [0, 2**-1, 2**0, 2**1, 2**2, 2**3, 2**4]:
            wCross = VT.T@np.linalg.inv(sigma**2+l*np.identity(9))@sigma@U.
            ↪T@yTrain
            yPred = np.sign(xTest@wCross)
            diff = np.count_nonzero(yTest - yPred)

            if (diff < min):
                min = diff
                bestLambda = l
                bestW = wCross
        yPred = np.sign(xVal@bestW)
        diff = np.count_nonzero(yVal - yPred)

```



```
print("n: ", n, "Error: ", str(diff/16))
totalError += diff/16
n += 1
print("Average error: ", str(totalError/64))
```

```
n:  1 Error:  0.0625
n:  2 Error:  0.0625
n:  3 Error:  0.0
n:  4 Error:  0.0
n:  5 Error:  0.0
n:  6 Error:  0.0625
n:  7 Error:  0.0
n:  8 Error:  0.0
n:  9 Error:  0.0625
n: 10 Error:  0.0
n: 11 Error:  0.0
n: 12 Error:  0.0
n: 13 Error:  0.0625
n: 14 Error:  0.0
n: 15 Error:  0.0
n: 16 Error:  0.0625
n: 17 Error:  0.0
n: 18 Error:  0.0
n: 19 Error:  0.0
n: 20 Error:  0.0625
n: 21 Error:  0.0
n: 22 Error:  0.0
n: 23 Error:  0.0625
n: 24 Error:  0.0625
n: 25 Error:  0.0
n: 26 Error:  0.0
n: 27 Error:  0.0625
n: 28 Error:  0.0
n: 29 Error:  0.0
n: 30 Error:  0.0625
n: 31 Error:  0.125
n: 32 Error:  0.0
n: 33 Error:  0.0
n: 34 Error:  0.0625
n: 35 Error:  0.0
n: 36 Error:  0.0
n: 37 Error:  0.0625
n: 38 Error:  0.125
n: 39 Error:  0.0
n: 40 Error:  0.0
n: 41 Error:  0.0625
n: 42 Error:  0.0
```

```
n: 43 Error: 0.0
n: 44 Error: 0.0625
n: 45 Error: 0.125
n: 46 Error: 0.0
n: 47 Error: 0.0
n: 48 Error: 0.0
n: 49 Error: 0.0
n: 50 Error: 0.0
n: 51 Error: 0.0625
n: 52 Error: 0.0625
n: 53 Error: 0.0
n: 54 Error: 0.0
n: 55 Error: 0.0
n: 56 Error: 0.0625
Average error: 0.0234375
```