Discussion Session 6: Trees

CS 225: Data Structures

& Software Principles

Agenda

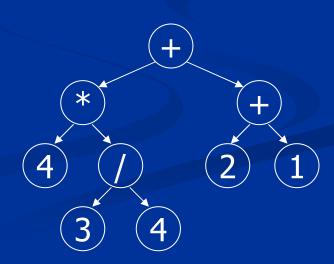
- Trees
- Binary Search Trees
- Basic BST operations
- Implementations of Trees

By the end of this class, you

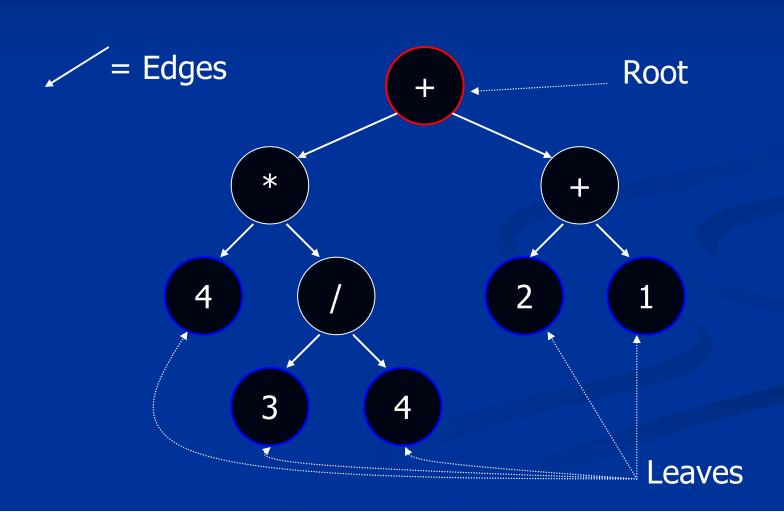
- Need to
 - Understand tree terminology
 - Follow different tree traversals
 - Understand all the BST operations
- Ought to be able to implement a BST
- Might want to think about iterative versions of recursive functions.

Trees

- What is a Tree structure ?
- Some Tree terminology
 - Nodes and Edges
 - Root and Leaf
 - Parent, Child, Descendant and Ancestor
 - Height, Depth
 - Sub-trees and Forests

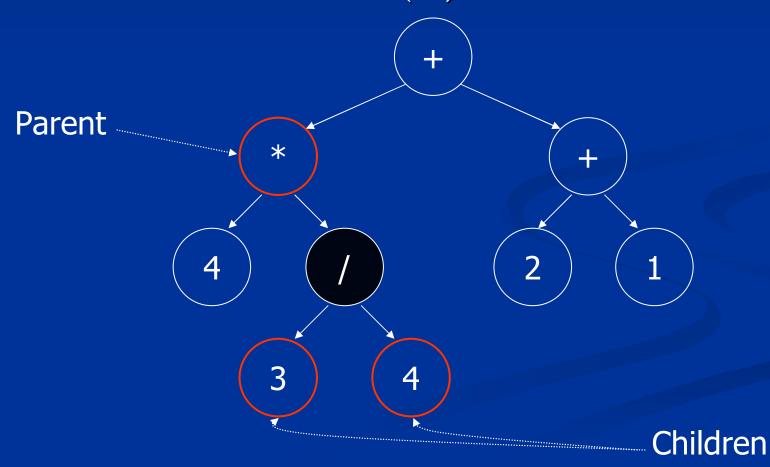


Nodes, Root & Leaves



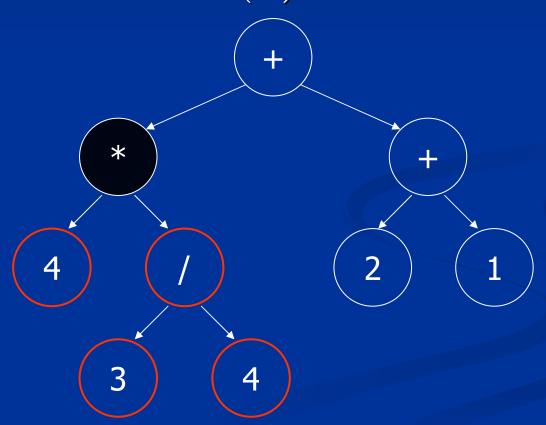
Parent & Children

Consider the node (/)



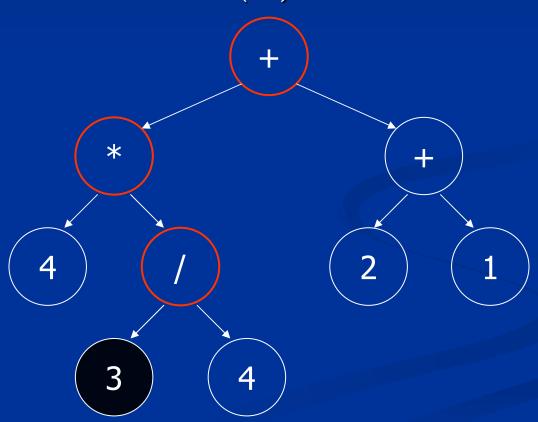
Descendants

Consider the node (*)

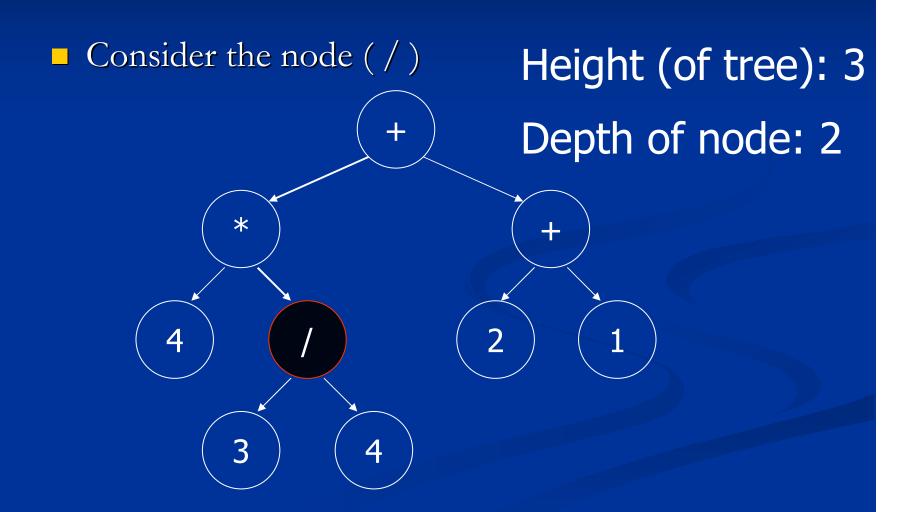


Ancestors

Consider the node (3)

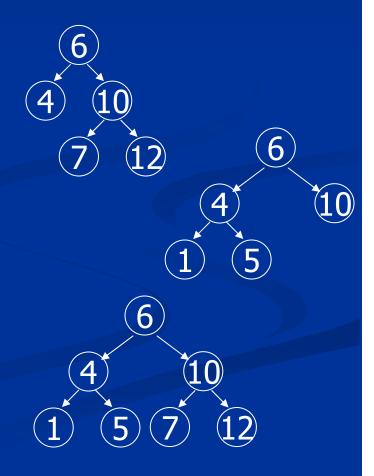


Height & Depth



Some Types of Trees

- Ordered trees
- Binary trees
 - Empty binary tree
 - Full binary tree
 - Every node has 0 or 2 children
 - Complete binary tree
 - Every level filled except possibly...
 - ...bottom level. Has all nodes as far left as possible
 - Perfect binary tree
 - Leaves have same depth
 - Internal nodes are degree 2



Tree Traversals

- Pre-Order Traversal
- In-Order Traversal
- Post-Order Traversal
- Level-Order Traversal
 - Use a queue
- Future Topic:Graph Traversals

```
Where does DoStuff(node) go?
void Traverse(node)
 if (node == null) return;
  // pre
 Traverse(node \rightarrow left);
  // in
     Traverse(node > right);
  // post
```

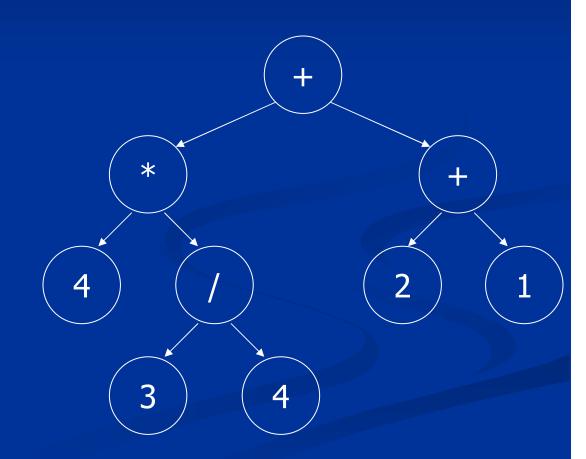
Traversal Example

Preorder:

Postorder:

■ Inorder:

Level-order:



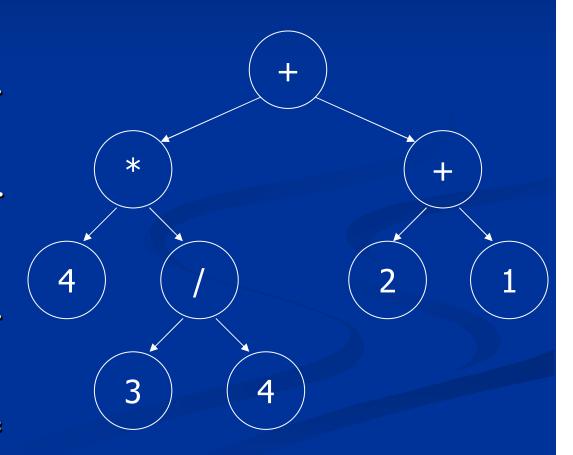
Traversal Example

Preorder:

Postorder:

■ Inorder:

Level-order:



Binary Trees

- Height of a complete binary tree with n nodes is exactly lg n
- The maximum height binary tree with n nodes has a height n-1
- The minimum height binary tree with n nodes has height lg n

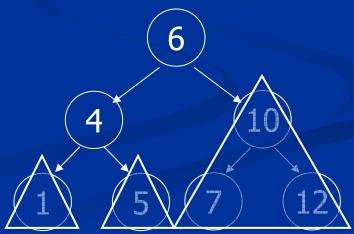
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- Trees
- Binary Search Trees
- Basic BST operations
- Implementations of Trees

Binary Search Trees

Definition :

- Have a value associated with each node
- the values have a linear order
- Every node has a value greater than any value in the left sub-tree and less than any value in the right sub-tree.
- Abbreviated as BST



Binary Search Trees

- The worst-case search time
 - for all possible search trees with n nodes is $\Theta(n)$
 - for the best search tree with n nodes is $\Theta(\lg n)$



Agenda

- Trees
- Binary Search Trees
- Basic BST operations
- **■** Implementations of Trees

One Implementation: use Tree Nodes

```
// private, nested in BSTree class
class TreeNode {
 public:
  TreeNode(): element(), left(NULL), right(NULL) {}
  TreeNode(Etype elmt,
       TreeNode* leftPtr = NULL,
       TreeNode* rightPtr = NULL):
              element(elmt), left(leftPtr), right(rightPtr) { }
   Etype element; // element of node
   TreeNode* left;
                       // pointer to left subtree
   TreeNode* right; // pointer to right subtree
```

Basic BST Operations

- Find
 - Recursive implementation
 - Iterative implementation
- Insert
- Remove

Basic BST Operations: Find

```
Recursive Find Algorithm
treePtr Find(treePtr P, key K)
  if (P == NULL)
      return NULL
  else if (K == P \rightarrow key)
      return P
  else if (K < P \rightarrow key)
      return Find(P→LeftChild, K)
  else
      return Find(P→RightChild, K)
```

Basic BST Operations: Find

Iterative Find Algorithm

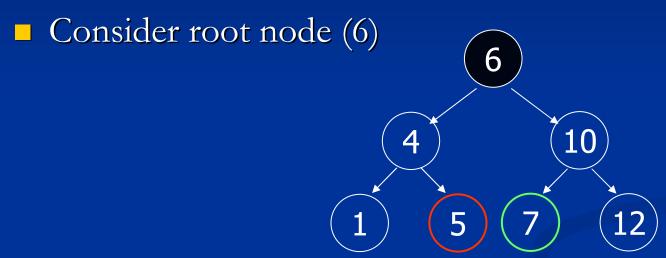
```
treePtr Find(treePtr P, key K)
   while (P!= NULL) {
         if (K == P \rightarrow key)
                  return P
         else if (K < P \rightarrow key)
                  P = P \rightarrow LeftChild
         else
                  P = P \rightarrow RightChild
   return NULL
```

Basic BST Operations: Insert

- Insertion
 - Must ensure that tree remains a binary search tree after insertion
 - Determine where the element would have been if it were actually in the BST. Insert there.
 - Compare Insert() vs. Find()

- Remove
 - More tricky than Insertion
 - First find node with element to remove
 - Split into three cases
 - Node to be deleted is a leaf
 - Node to be deleted has one child
 - Node to be deleted has two children

Terminology for Remove



- In-order predecessor: greatest (right-most) element in left subtree
- In-order successor: smallest (left-most) element in right subtree

- Leaf case
 - Simply delete the node
- One-child case
 - Just connect the node's child to it's parent
- Two-child case
 - Replace the node by it's in-order successor and delete the in-order successor
 - Alternatively, we could use also the in-order predecessor

- Two-child case
 - Replace node with in-order successor (predecessor) and delete the in-order successor (predecessor)

```
typename BSTree<Etype>::TreeNode* tempPtr;
if ((ptr->left != NULL) && (ptr->right != NULL)) {
    // Replace with smallest in right subtree.
    tempPtr = ptr->right;
    while (tempPtr->left != NULL)
        tempPtr = tempPtr->left;
    ptr->element = tempPtr->element;
    Remove(ptr->right, ptr->element);
}
```

- One-child case
 - Just connect the node's child to it's parent

```
else
  tempPtr = ptr;
  if (ptr->left == NULL)
                          // only a right child
      ptr = ptr->right;
  else // ptr->right == NULL // only a left child
      ptr = ptr->left;
  delete tempPtr;
```

BST Operation: Clear

- Used in public interface, destructor, operator=
- How is Jason traversing the tree?

```
// recursively clears the tree
template <class Etype>
void BSTree<Etype>::Clear(
       typename BSTree<Etype>::TreeNode*& ptr) {
  if (ptr!= NULL) {
       Clear(ptr->left);
       Clear(ptr->right);
       delete ptr;
       ptr = NULL;
```

BST Operation: Copy

- Used in copy constructor & operator=
- How is Jason traversing the tree?

```
// makes a new TreeNode which is a copy of the parameter node, and returns it
template <class Etype>
typename BSTree<Etype>::TreeNode*
BSTree<Etype>::Copy(typename BSTree<Etype>::TreeNode const * ptr) {
   if (ptr!= NULL) {
        typename BSTree<Etype>::TreeNode * temp =
                 new typename BSTree<Etype>::TreeNode(ptr->element);
        temp->left = Copy(ptr->left);
        temp->right = Copy(ptr->right);
        return temp;
   else return NULL;
```

Implementation Detail

- Recursive operations have 2 versions:
 - Public interface version
 - Private interface version with extra TreeNode parameter
- Examples:

```
void PreOrder() const { PreOrder(root); }
void PreOrder(typename BSTree<Etype>::TreeNode const * ptr)
    const;
```

Sample Code for BST

The entire code is available in

~cs225/src/library/06-bst/_latestBST

The BST Applet is available at

www.cs.jhu.edu/~goodrich/dsa/trees/btree.html