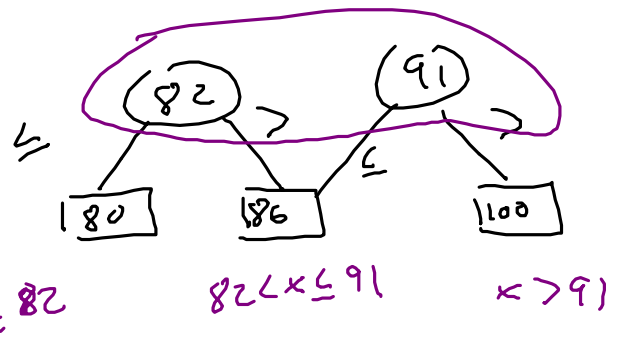
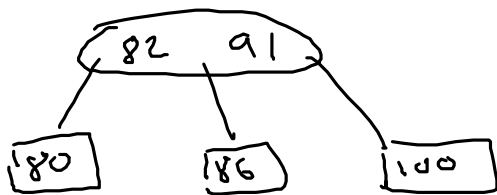


B-Trees



order : b (odd number)
 bounds on # of children of a node

underflow $\frac{b+1}{2} \longleftrightarrow b$

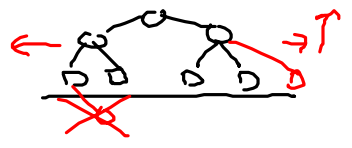
b	$\frac{b+1}{2}$	b
3	2	3
5	3	5
11	6	11
101	51	101

overflow

"node is
 at least
 half full"

Rules for B-Tree of order b

1) All leaves at same depth



2) All non-root internal nodes (internal node = non-leaf) have between $\frac{b+1}{2}$ and b children

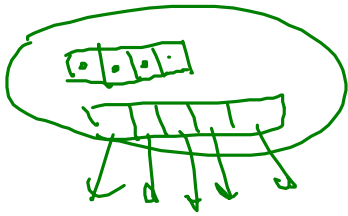
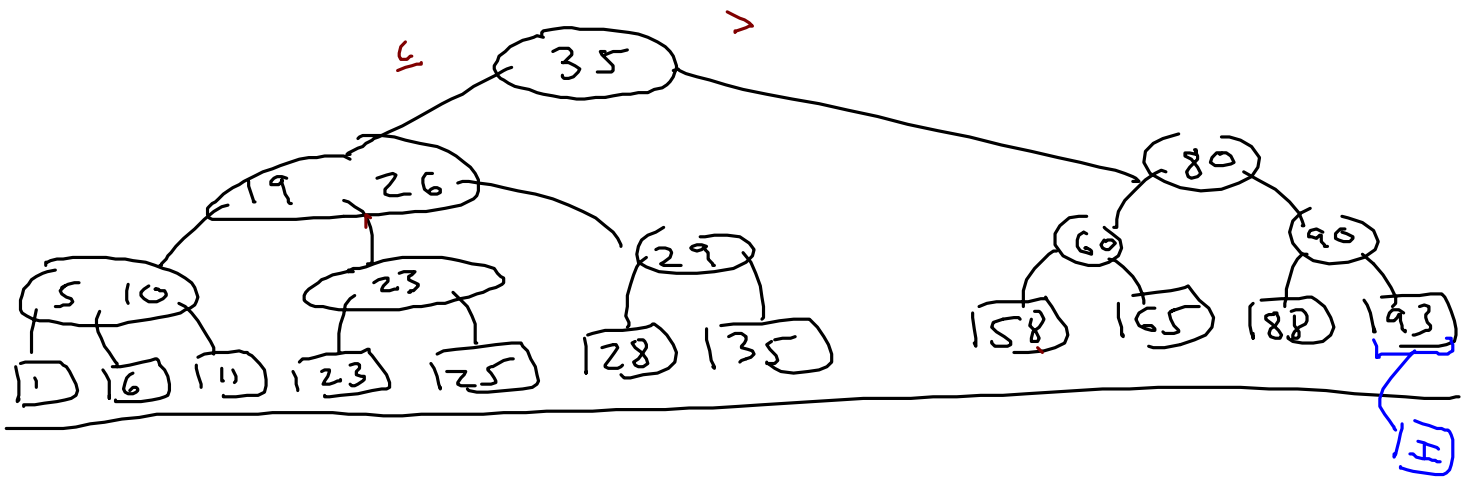
3) root can have between 2 and b children

4) all real data is in leaves (one per leaf); internal nodes merely guide search

5) in every internal node, # of index values is one less than # of children



B-Tree of order 3



Insert (x)

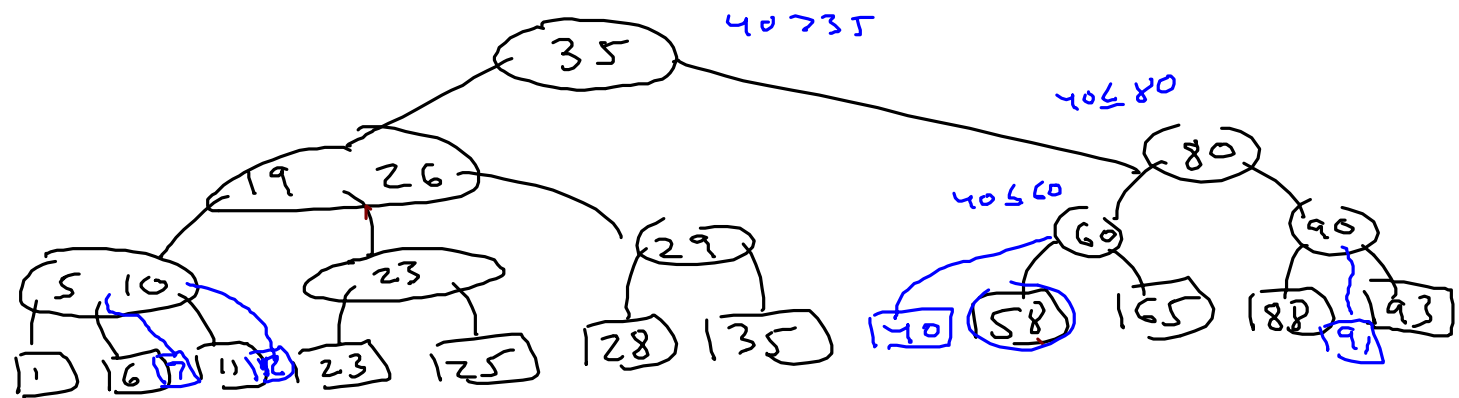
- traverse down to where x "should be"
i.e. search for x
- if found, return (won't insert duplicate)
- else (not found) insert leaf with this
new value in "same place" as
leaf that "should have" contained x
- add new index value to parent
(whatever is in leaf to left
of new index value's position)
- label parent of leaf " p "

cases:

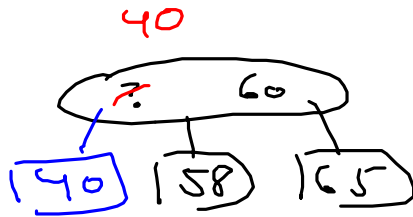
→ case 1: if p doesn't overflow, STOP

case 2: p overflows \Rightarrow
SPLIT, index moves
up into parent of p
relabel p 's parent as p
CONTINUE

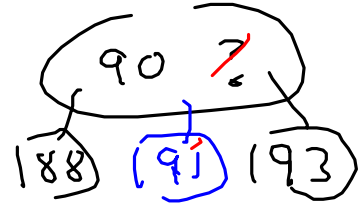
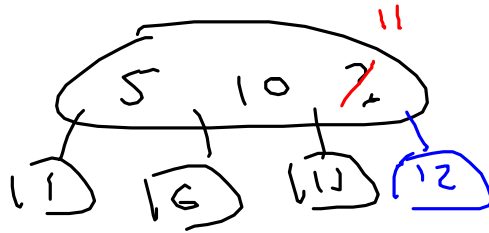
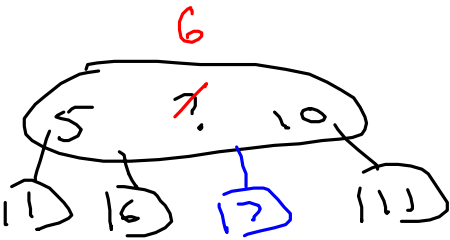
B-Tree of order 3



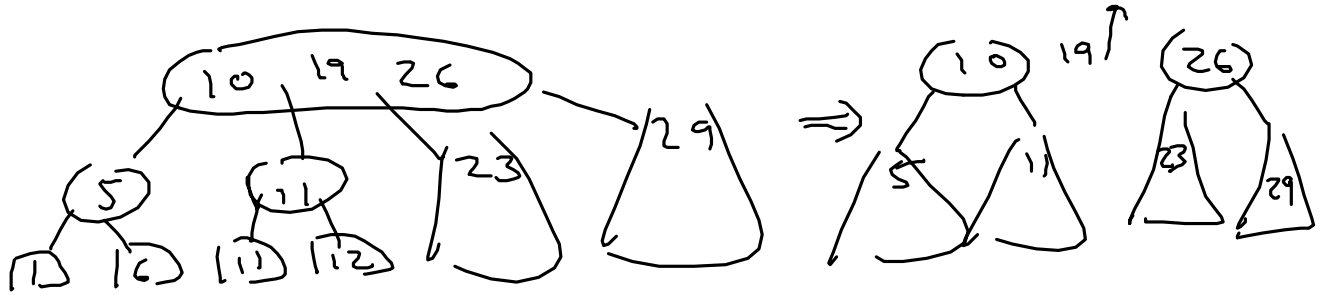
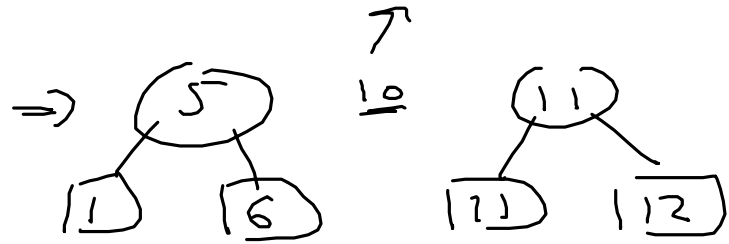
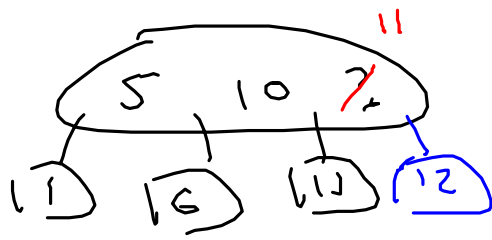
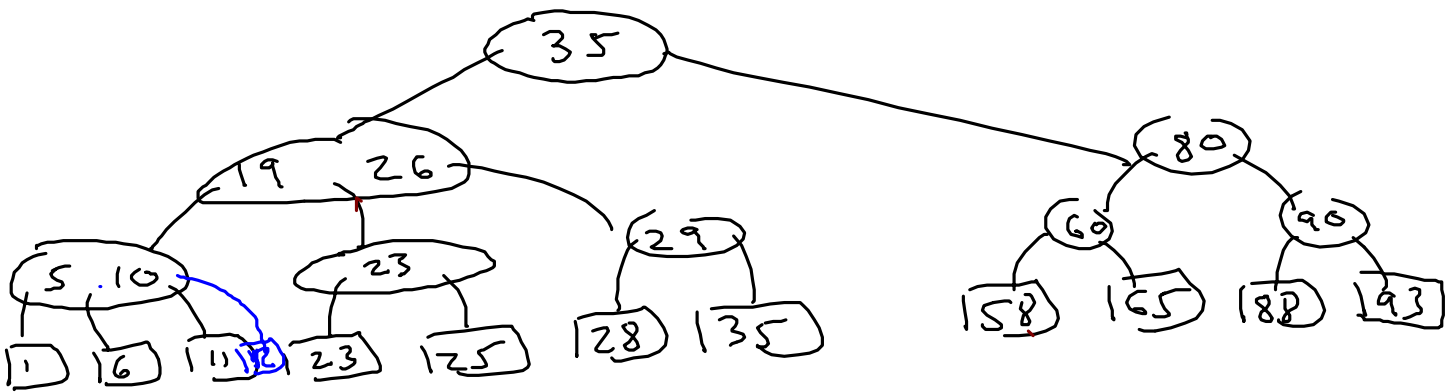
\Rightarrow



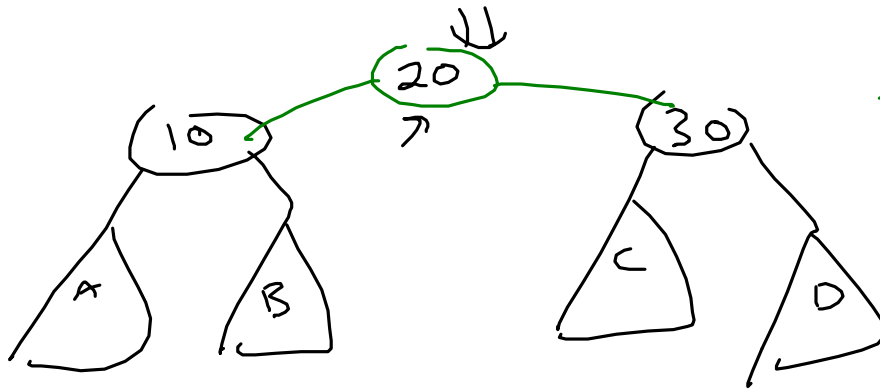
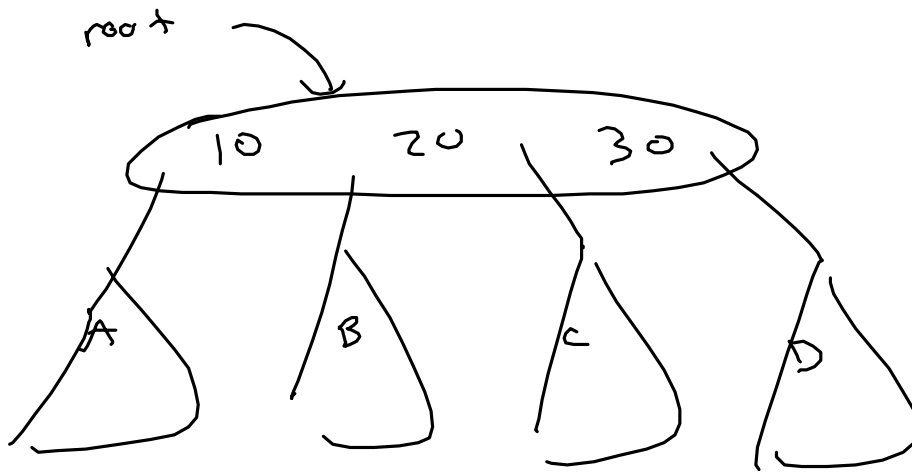
91



B-Tree of order 3



If root splits \rightarrow new root



height ++;

Remove(x)

→ search for x

→ if not found, return

→ else (found) remove leaf, and index
from parent

→ label parent P

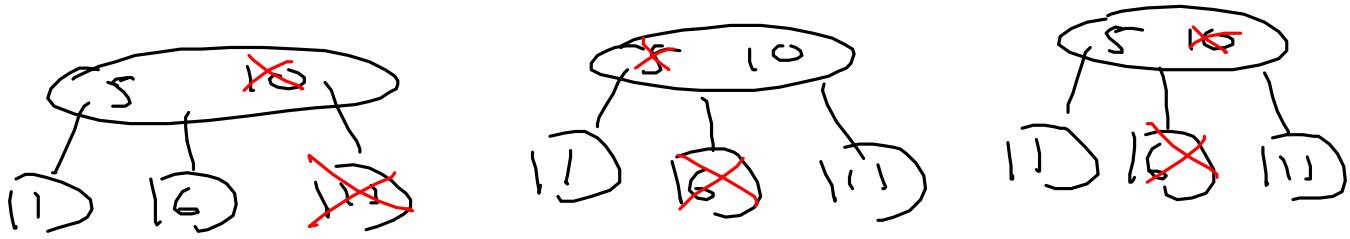
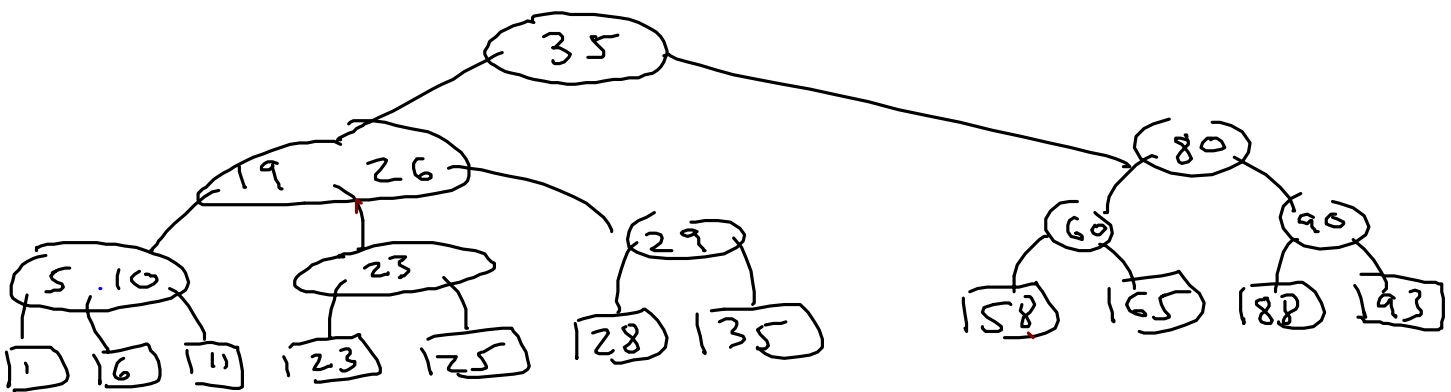
cases

1) if p does NOT underflow, STOP

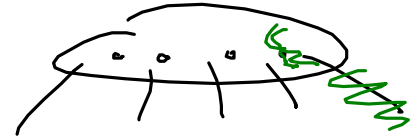
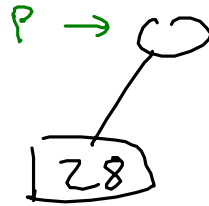
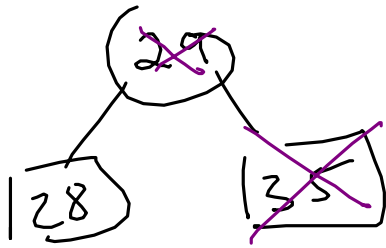
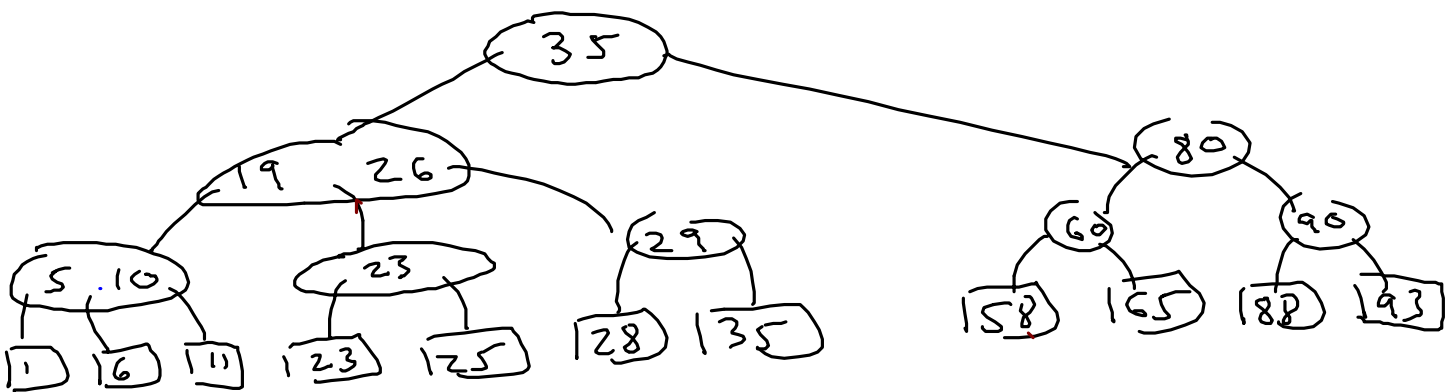
2) if p does underflow, but we
can steal from immediate
sibling, steal, STOP

3) else COMBINE two nodes
parent loses child & index,
label parent of p as p
CONTINUE

B-Tree of order 3

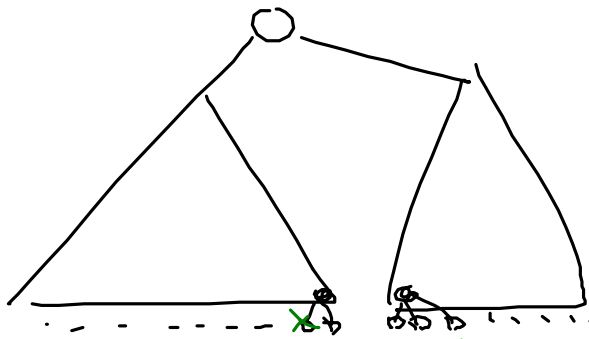


B-Tree of order 3



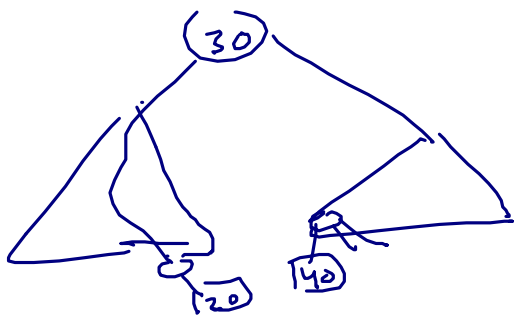
Immediate

Sibling

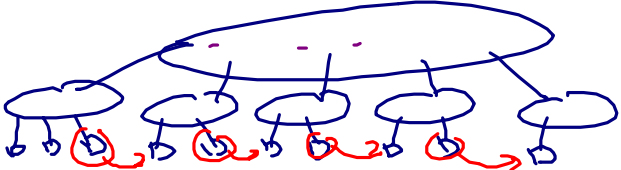
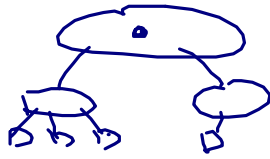


remove from here

not a sibling!



NO!

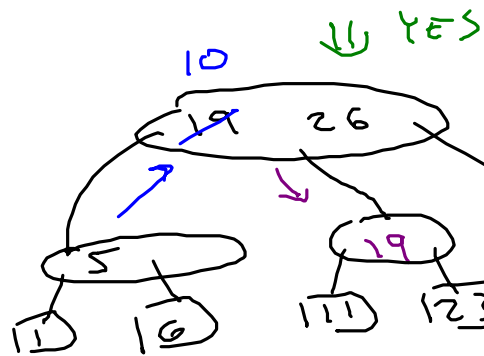
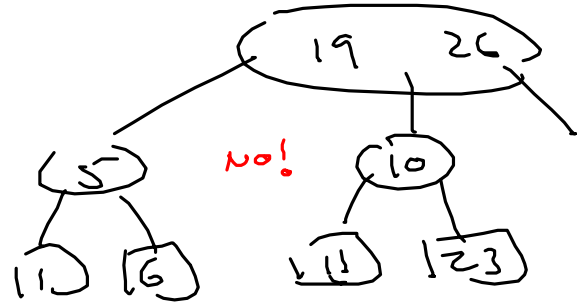
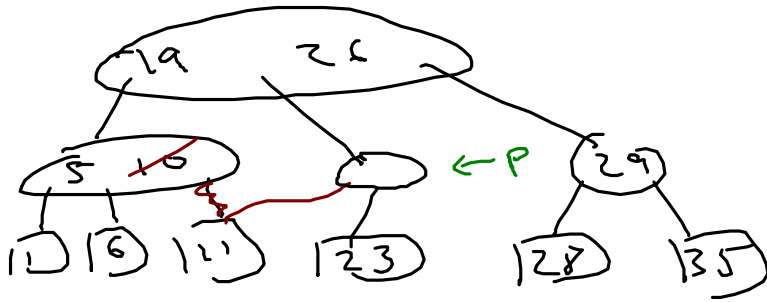
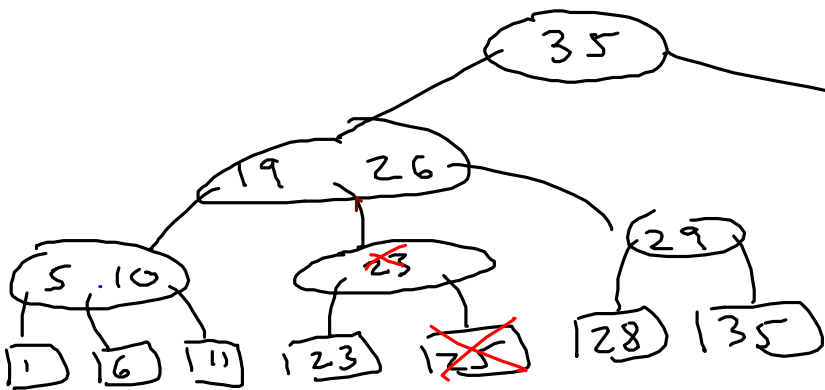


NO!

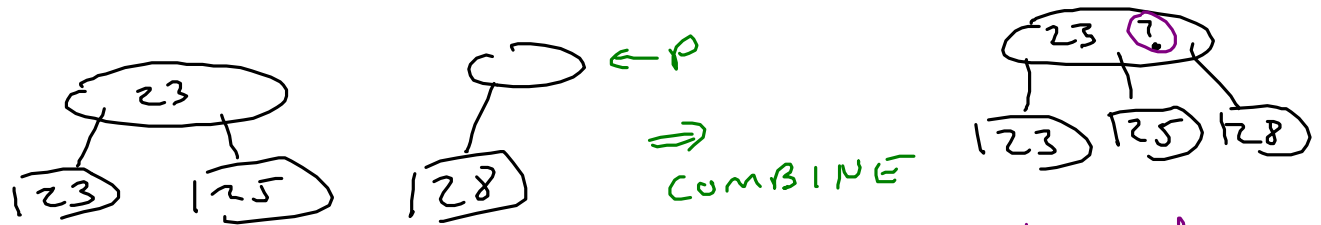
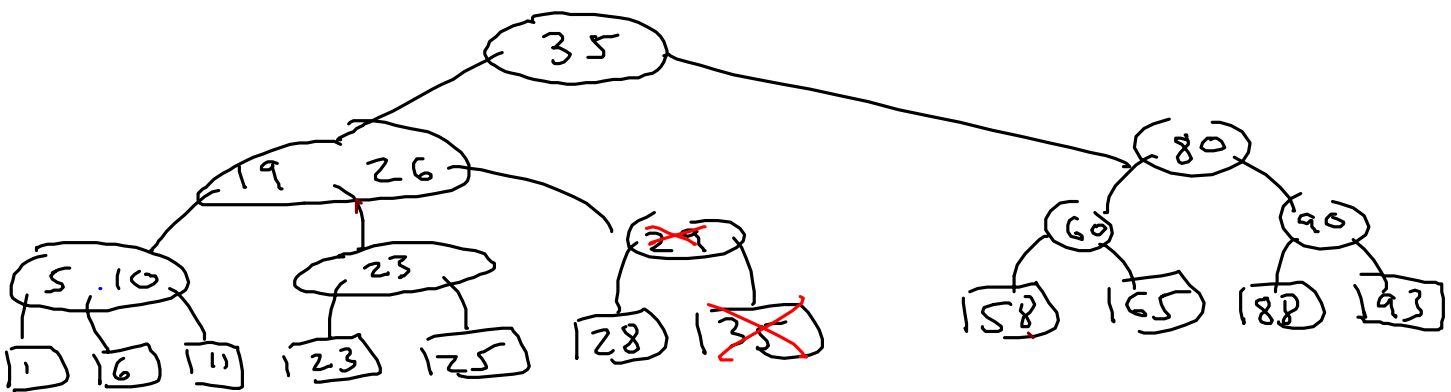
=>



B-Tree of order 3

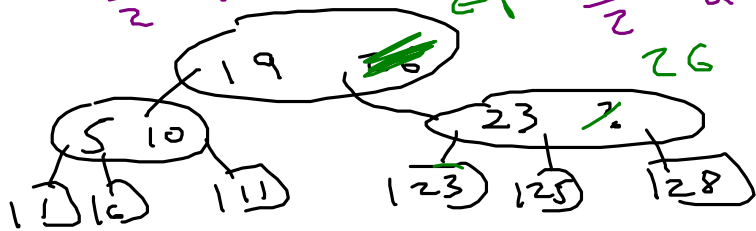


B-Tree of order 3

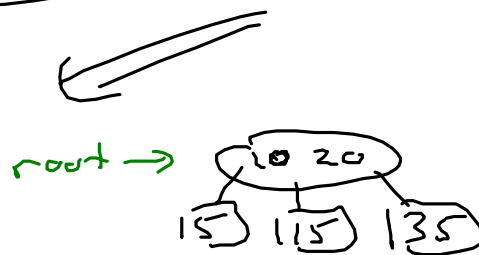
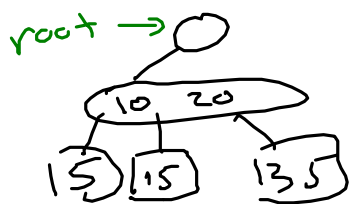
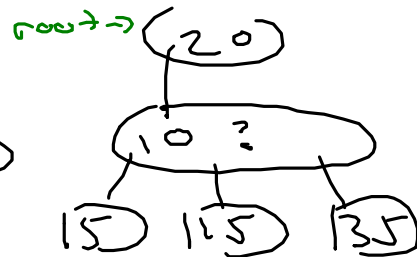
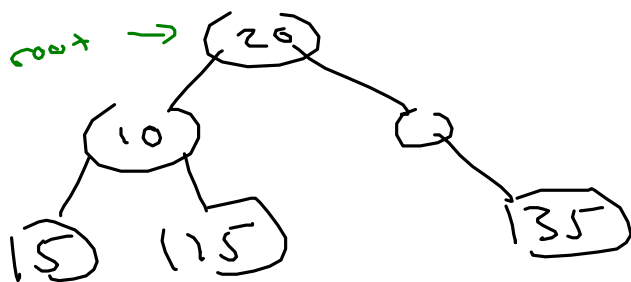
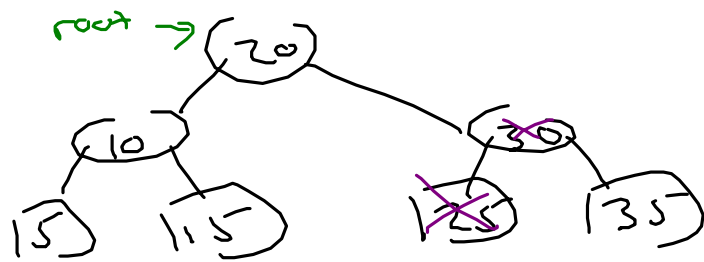


$\frac{b+1}{2}$ children $\frac{b+1}{2} - 1$ children \rightarrow b children

$\frac{b+1}{2} - 1$ indices $\frac{b+1}{2} - 2$ indices \rightarrow $b - 2$ indices




Root under-flow



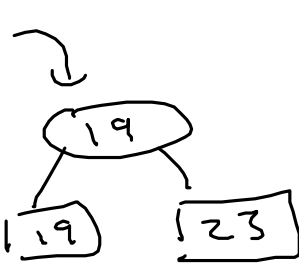
under-flowing root is
deleted, its 1 child
is new root

height ---;

Degenerate cases

root 

root 

root 

← now rules apply

1 million values

List : 1 million nodes in unsuccessful search

AVL tree : height ≈ 20

B-Tree order 199 : height ≈ 4



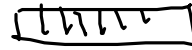
↳ but node :



AVL



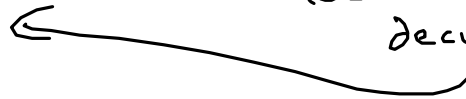
Binary search



199 children

198 index values

loooooong time to
decide subtree



main memory is an order of magnitude faster to access than disk

let's reduce # of disk reads when lots of info on disk

AVL: height 20 \rightarrow 20 levels, 20 reads
(1 million values)

B-Tree of order 199 \rightarrow if each node only as large as a disk block, then 4 levels, 4 disk reads (1 million values)

\hookrightarrow searching nodes is much faster than getting it into memory in first place