

Student Research Paper Critical clearing time of synchronous generators

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Todo list

Insert state-of-the-art.	 2

Author's declaration

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Erlangen, January 4, 2024

B. Eng. Maximilian Köhler

Note:

For reasons of readability, the generic masculine is primarily used in this Student Research Paper. Female and other gender identities are explicitly included where this is necessary for the statement.

Abstract

Objektivität soll sich jeder persönlichen Wertung enthalten

Kürze soll so kurz wie möglich sein

Genauigkeit soll genau die Inhalte und die Meinung der Originalarbeit wiedergeben

Diese etwa einseitige Zusammenfassung soll es dem Leser ermöglichen, Inhalt der Arbeit und Vorgehensweise des Autors rasch zu überblicken. Gegenstand des Abstract sind insbesondere

- Problemstellung der Arbeit,
- im Rahmen der Arbeit geprüfte Hypothesen bzw. beantwortete Fragen,
- der Analyse zugrunde liegende Methode,
- wesentliche, im Rahmen der Arbeit gewonnene Erkenntnisse,
- Einschränkungen des Gültigkeitsbereichs (der Erkenntnisse) sowie nicht beantwortete Fragen.

Assignment of the paper

Topic: Critical clearing time of synchronous generators

The critical clearing time (CCT) is an essential parameter in power system stability analysis. For example, in the case of synchronous generator (SG), the CCT determines the maximum fault-clearing time a generator can withstand without losing synchronism. This seminar will introduce the concept of CCT computing. We will discuss the factors influencing CCT, such as generator characteristics, system parameters, and fault type, and explore the methods used to calculate CCT in practical power system analysis.

The seminar research paper should contain:

- A literature research of governing equations describing the short-term dynamic behavior of SG, relevant fault types and their influence;
- an investigation of the influences from machine characteristics and system parameters on the CCT;
- a computed simulation model for numerical determination of the CCT with the equal area criterion (EAC);
- simulations of system faults and comparisons to analytical solutions.

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1 Introduction

Some fancy introduction.

- 1 Introduction (1 page)
- 2 State-of-the-art (\sim 4 pages)
 - 2.1 Basics synchronous generators
 - -> swing-equations
 - 2.2 System stability esp. transient context
 - -> rotor angle stability, **derivation of EAC**, basic assessment models (single machine infinite bus, see [1])
 - 2.3 Numerical methods for TDSs and system modelling
 - -> solving second order ODEs (explicit)
 - 2.4 Events harming the system stability
 - -> **faults,** load-changes, effects of electrical networks (esp. generator networks) vs. single machine systems
- 3 Numerical modeling (\sim 5 pages)
 - 3.1 (Object relations and classes)
 - 3.2 Algorithm and functional structure
 - 3.3 Implementation of functions and dependencies
 - 3.4 Implementation of numerical solvers
- 4 Results (\sim 3 pages)
 - 4.1 Analytical results
 - 4.2 Numerical results
- 5 Discussion (\sim 2 pages)
 - 5.1 Numerical vs. analytical
 - 5.2 (Single machine vs. network models)
 - 5.3 ... (dependent on time and outcomes)
- 6 Summary and outlook (1 page)

Total amount \sim 16 pages (without appendix and supplementary pages)

Bullet points for the thesis from Ilya:

- Swing equation of synchronous generators
- Solving the Swing equation with the help of Python -> Solving of second order ODEs
- Equal-area criterion -> Derivation of the equations
- Simulation of a fault -> applying the equal-area criteria with the help of Python.
- Comparison between analytical and (numerical) simulation results

Das ist ein Testkommentar.

Insert state-of-the-art.

2 Basics

General sources in terms of standard literature: [1]-[4]

Relevant basics:

- dynamic behavior synchronous generators
- determination of CCT (equal area criteria)
- relevant faults, their modeling and effects
- analytic ways to calculate the CCT
- numerical methods for solving differential equations
- 2.1 Basics synchronous generators
- 2.2 System stability esp. transient context
- 2.3 Numerical methods for TDSs and system modeling
- 2.4 Events harming the system stability

3 Numerical modelling

- 3.1 Object relations and classes
- 3.2 Algorithm and functional structure
- 3.3 Implementation of functions and dependencies
- 3.4 Implementation of numerical solvers

Euler's method

Heun's method

Heun's method is implemented in Python. An example is provided in Listing A.2

4 Results

- 4.1 Analytical results
- 4.2 Numerical results

5 Discussion

- 5.1 Analytical vs. numerical
- 5.2 Single machine vs. network models

6 Summary and outlook

In der Zusammenfassung werden die Ergebnisse der Arbeit kurz zusammengefasst. Der Umfang beträgt ca. eine Seite.

Acronyms

CCT	critical clearing time
EAC	equal area criterion
SG	synchronous generator
TDS	time domain solution

Bibliography

- [1] P. S. Kundur and O. P. Malik, *Power System Stability and Control*, Second edition. New York Chicago San Francisco Athens London Madrid Mexico City Milan New Delhi Singapore Sydney Toronto: McGraw Hill, 2022, 948 pp., ISBN: 978-1-260-47354-4.
- [2] D. Oeding and B. R. Oswald, *Elektrische Kraftwerke und Netze*, 8. Auflage. Berlin [Heidelberg]: Springer Vieweg, 2016, 1107 pp., ISBN: 978-3-662-52702-3. DOI: 10.1007/978-3-662-52703-0.
- [3] J. D. Glover, T. J. Overbye, and M. S. Sarma, "Power system analysis & design," Boston, MA, 2017.
- [4] J. Machowski, Z. Lubosny, J. W. Bialek, and J. R. Bumby, *Power System Dynamics: Stability and Control*, Third edition. Hoboken, NJ, USA: John Wiley, 2020, 1 p., ISBN: 978-1-119-52636-0 978-1-119-52638-4.

Appendix

A	Cod	e	В
	A.1	Model functions	В
	A.2	Model of GK	C

A Code

A.1 Model functions

```
{\color{red} \textbf{import}} \ \ \textbf{matplotlib.pyplot} \ \ \textbf{as} \ \ \textbf{plt}
   import numpy as np
4 def mag_and_angle_to_cmplx(mag, angle):
       return mag * np.exp(1j * angle)
   # Define the parameters of the system
   fn = 60
   H_gen = 3.5
   X_gen = 0.2
10
   X_{ibb} = 0.1
12 | X_line = 0.65
   # Values are initialized from loadflow
15 E_fd_gen = 1.075
   E_fd_ibb = 1.033
16
17
   P_m_{gen} = 1998/2200
   # init states of variables
19
   omega_gen_init = 0 # init state
   delta_gen_init = np.deg2rad(45.9) # init state
   delta_ibb_init = np.deg2rad(-5.0) # init state
   v_bb_gen_init = mag_and_angle_to_cmplx(1.0, np.deg2rad(36.172))
   result_ode = []
   def smib_model(result_ode, t):
        # defines a ode 2nd order ode for decribing the dynamic behavior of a
30
             synchronous generator vs. an infinite bus
        # Those lines cause a short circuit at t = 1 s until t = 1.05 s
31
        if 1 <= t < 1.1001:</pre>
            sc_on = True
        else:
            sc_on = False
        \mbox{\tt\#} If the SC is on, the admittance matrix is different.
37
        # The SC on busbar 0 is expressed in the admittance matrix as a very large
             admittance (1000000) i.e. a very small impedance.
39
            y_{adm} = np.array([[(-1j / X_gen - 1j / X_line) + 1000000, 1j / X_line],
40
41
                                [1j / X_line, -1j / X_line - 1j / X_ibb]])
        else:
            y_adm = np.array([[-1j / X_gen - 1j / X_line, 1j / X_line],
                                [1j / X_line, -1j / X_line - 1j / X_ibb]])
        # Calculate the inverse of the admittance matrix (Y^-1)
46
        y_inv = np.linalg.inv(y_adm)
```

```
# Calculate current injections of the generator and the infinite busbar
49
       i_inj_gen = mag_and_angle_to_cmplx(E_fd_gen, delta_gen) / (1j * X_gen)
50
51
       i_inj_ibb = mag_and_angle_to_cmplx(E_fd_ibb, delta_ibb_init) / (1j * X_ibb)
       # Calculate voltages at the bus by multiplying the inverse of the admittance
53
            matrix with the current injections
       v_bb_gen = y_inv[0, 0] * i_inj_gen + y_inv[0, 1] * i_inj_ibb
       v_bb_ibb = y_inv[1, 0] * i_inj_gen + y_inv[1, 1] * i_inj_ibb
55
       # Calculate the electrical power extracted from the generator at its busbar.
57
58
       E_gen_cmplx = mag_and_angle_to_cmplx(E_fd_gen, delta)
       P_{egen} = (v_bb_gen * np.conj((E_gen_cmplx - v_bb_gen) / (1j * X_gen))).real
       # transform the constant mechanical energy into torque
61
       T_m_gen = P_m_gen / (1 + omega)
62
64
       # Differential equations of a generator according to Machowski
       domega_dt = 1 / (2 * H_gen) * (T_m_gen - P_e_gen)
       ddelta_dt = omega * 2 * np.pi * fn
66
       return [result_ode[0], result_ode[1]] # domega_dt, ddelta_dt
68
   if __name__ == "__main__":
70
71
       def showplot():
           from matplotlib import pyplot as plt
72
73
           x = [1,5,10,15]
           y = [12,59,100,155]
76
           plt.plot(x, y)
           plt.show()
```

Listing A.1: Module containing all relevant functions of the SMIB model in Python

A.2 Model of GK

```
import matplotlib.pyplot as plt
   import numpy as np
   def mag_and_angle_to_cmplx(mag, angle):
5
       return mag * np.exp(1j * angle)
   fn = 60
   H_gen = 3.5
11
   X_gen = 0.2
12
   X_{ibb} = 0.1
13
   X_{line} = 0.65
   # Values are initialized from loadflow
16
17 E_fd_gen = 1.075
18 \mid E_fd_ibb = 1.033
19 P_m_gen = 1998/2200
```

```
omega_gen_init = 0
   delta_gen_init = np.deg2rad(45.9)
   delta_ibb_init = np.deg2rad(-5.0)
   v_bb_gen_init = mag_and_angle_to_cmplx(1.0, np.deg2rad(36.172))
   def differential(omega, v_bb_gen, delta):
28
       # Calculate the electrical power extracted from the generator at its busbar.
29
       E_gen_cmplx = mag_and_angle_to_cmplx(E_fd_gen, delta)
30
       P_{e-gen} = (v_bb_gen * np.conj((E_gen_cmplx - v_bb_gen) / (1j * X_gen))).real
       # transform the constant mechanical energy into torque
       T_m_gen = P_m_gen / (1 + omega)
34
       # Differential equations of a generator according to Machowski
36
       domega_dt = 1 / (2 * H_gen) * (T_m_gen - P_e_gen)
       ddelta_dt = omega * 2 * np.pi * fn
       return domega_dt, ddelta_dt
40
   def algebraic(delta_gen, sc_on):
       # If the SC is on, the admittance matrix is different.
       # The SC on busbar 0 is expressed in the admittance matrix as a very large
45
            admittance (1000000) i.e. a very small impedance.
           y_{adm} = np.array([[(-1j / X_gen - 1j / X_line) + 1000000, 1j / X_line],
                              [1j / X_line, -1j / X_line - 1j / X_ibb]])
48
       else:
49
           y_{adm} = np.array([[-1j / X_gen - 1j / X_line, 1j / X_line],
50
51
                              [1j / X_line, -1j / X_line - 1j / X_ibb]])
       # Calculate the inverse of the admittance matrix (Y^-1)
       y_inv = np.linalg.inv(y_adm)
54
       # Calculate current injections of the generator and the infinite busbar
56
       i_inj_gen = mag_and_angle_to_cmplx(E_fd_gen, delta_gen) / (1j * X_gen)
       i_inj_ibb = mag_and_angle_to_cmplx(E_fd_ibb, delta_ibb_init) / (1j * X_ibb)
       # Calculate voltages at the bus by multiplying the inverse of the admittance
60
            matrix with the current injections
       v_bb_gen = y_inv[0, 0] * i_inj_gen + y_inv[0, 1] * i_inj_ibb
61
       v_bb_ibb = y_inv[1, 0] * i_inj_gen + y_inv[1, 1] * i_inj_ibb
       return v_bb_gen
   def do_sim():
       # Initialize the variables
69
       omega_gen = omega_gen_init
70
71
       delta_gen = delta_gen_init
       v_bb_gen = v_bb_gen_init
74
       \# Define time. Here, the time step is 0.005 s and the simulation is 5 s long
       t = np.arange(0, 5, 0.005)
75
       x_result = []
76
```

```
78
        for timestep in t:
            # Those lines cause a short circuit at t = 1 s until t = 1.05 s
80
            if 1 <= timestep < 1.05:</pre>
81
                sc_on = True
82
            else:
                sc_on = False
            # Calculate the initial guess for the next step by executing the
86
                 differential equations at the current step
            domega_dt_guess, ddelta_dt_guess = differential(omega_gen, v_bb_gen,
87
                 delta_gen)
            omega_guess = omega_gen + domega_dt_guess * (t[1] - t[0])
88
            delta_guess = delta_gen + ddelta_dt_guess * (t[1] - t[0])
89
            v_bb_gen = algebraic(delta_guess, sc_on)
91
93
            # Calculate the differential equations with the initial guess
            domega_dt_guess2, ddelta_dt_guess2 = differential(omega_guess, v_bb_gen,
94
                 delta_guess)
            domega_dt = (domega_dt_guess + domega_dt_guess2) / 2
96
            ddelta_dt = (ddelta_dt_guess + ddelta_dt_guess2) / 2
            omega_gen = omega_gen + domega_dt * (t[1] - t[0])
99
            delta_gen = delta_gen + ddelta_dt * (t[1] - t[0])
100
            v_bb_gen = algebraic(delta_gen, sc_on)
102
            # Save the results, so they can be plotted later
105
106
            x_result.append(omega_gen)
        # Convert the results to a numpy array
        res = np.vstack(x_result)
109
        return t, res
110
    if __name__ == '__main__':
        # Here the simulation is executed and the timesteps and corresponding results
115
             are returned.
        # In this example, the results are omega, delta, e_q_t, e_d_t, e_q_st, e_d_st
116
             of the generator and the IBB
        t_sim, res = do_sim()
117
        # load the results from powerfactory for comparison
119
        delta_omega_pf = np.loadtxt('pictures/powerfactory_data.csv', skiprows=1,
120
             delimiter=',')
        # Plot the results
122
        plt.plot(t_sim, res[:, 0].real, label='delta_omega_gen_python')
123
124
        plt.plot(delta_omega_pf[:, 0], delta_omega_pf[:, 1] - 1, label='
             delta_omega_gen_powerfactory')
125
        plt.legend()
126
        plt.title('Reaction of a generator to a short circuit')
        plt.savefig('pictures/short_circuit_improved.png')
128
```

130 plt.show()

Listing A.2: GK's SMIB model with Heun's integration method