Formalization of DFA using lattices

Recall worklist algorithm

```
let m: map from edge to computed value at edge
let worklist: work list of nodes
for each edge e in CFG do
   m(e) := \emptyset
for each node n do
   worklist.add(n)
while (worklist.empty.not) do
   let n := worklist.remove any;
   let info in := m(n.incoming edges);
   let info out := F(n, info in);
   for i := 0 .. info out.length do
      let new_info := m(n.outgoing_edges[i]) U
                      info out[i];
      if (m(n.outgoing edges[i]) ≠ new info])
         m(n.outgoing edges[i]) := new_info;
         worklist.add(n.outgoing edges[i].dst);
```

Using lattices

- We formalize our domain with a powerset lattice
- What should be top and what should be bottom?

Using lattices

- We formalize our domain with a powerset lattice
- What should be top and what should be bottom?
- Does it matter?
 - It matters because, as we've seen, there is a notion of approximation, and this notion shows up in the lattice

Using lattices

- Unfortunately:
 - dataflow analysis community has picked one direction
 - abstract interpretation community has picked the other
- We will work with the abstract interpretation direction
- Bottom is the most precise (optimistic) answer,
 Top the most imprecise (conservative)

Direction of lattice

- Always safe to go up in the lattice
- Can always set the result to ⊤
- Hard to go down in the lattice
- Bottom will be the empty set in reaching defs

Worklist algorithm using lattices

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Termination of this algorithm?

- For reaching definitions, it terminates...
- Why?
 - lattice is finite
- Can we loosen this requirement?
 - Yes, we only require the lattice to have a finite height
- Height of a lattice: length of the longest ascending or descending chain
- Height of lattice (2^S, ⊆) = ∫

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Termination

 Still, it's annoying to have to perform a join in the worklist algorithm

 It would be nice to get rid of it, if there is a property of the flow functions that would allow us to do so

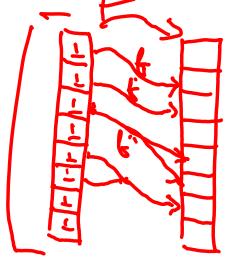
Even more formal

 To reason more formally about termination and precision, we re-express our worklist algorithm mathematically

We will use fixed points to formalize our algorithm



- Recall, we are computing m, a map from edges to dataflow information
- Define a global flow function F as follows: F takes a map m as a parameter and returns a new map m', in which individual local flow functions have been applied



$$m = F(m)$$

- We want to find a fixed point of F, that is to say a map m such that m = F(m)
- Approach to doing this?
- Define \perp , which is \perp lifted to be a map: $\perp = \lambda$ e. \perp
- Compute $F(\widetilde{\bot})$, then $F(F(\widetilde{\bot}))$, then $F(F(F(\widetilde{\bot})))$, ... until the result doesn't change anymore

Formally:

Soln =
$$\lim_{i=0}^{\infty} F^{i}(\widehat{\perp})$$

- Outer join has same role here as in worklist algorithm: guarantee that results keep increasing
- BUT: if the sequence $F^{i}(\perp)$ for i = 0, 1, 2 ... is increasing, we can get rid of the outer join!
- How? Require that F be monotonic:
 - $\forall a, b . a \sqsubseteq b \Rightarrow F(a) \sqsubseteq F(b)$

$$\widetilde{I} = F(\widetilde{I})$$

$$F(\widetilde{I}) \subseteq FF(\widehat{I})$$

$$F(\widetilde{I}) \subseteq FF(\widehat{I})$$

$$F(\widetilde{L}) \subseteq F(F(\widetilde{L}))$$

$$F(\widetilde{L}) \subseteq F^{k+1}(\widehat{L})$$

$$F^{k+1}(\widetilde{L}) \subseteq F^{k+2}(\widehat{L})$$

Back to termination

- So if F is monotonic, we have what we want: finite height ⇒ termination, without the outer join
- Also, if the local flow functions are monotonic, then global flow function F is monotonic

Another benefit of monotonicity

- Suppose Marsians came to earth, and miraculously give you a fixed point of F, call it fp.
- Then:

Another benefit of monotonicity

- Suppose Marsians came to earth, and miraculously give you a fixed point of F, call it fp.
- Then:

$$\frac{\widehat{L}}{F(I)} \sqsubseteq fP$$

$$F(\widehat{I}) \sqsubseteq fP$$

$$F(\widehat{I}) \sqsubseteq fP$$

$$F^{2}(\widehat{I}) \sqsubseteq fP$$

$$\vdots$$

$$OBP \sqsubseteq IP$$

Another benefit of monotonicity

We are computing the least fixed point...

Recap

Let's do a recap of what we've seen so far

Started with worklist algorithm for reaching definitions

Worklist algorithm for reaching defns

```
let m: map from edge to computed value at edge
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for each edge e in CFG do
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for each node n do
   worklist.add(n)
while (worklist.empty.not) do
   let n := worklist.remove any;
   let info in := m(n.incoming edges);
   let info out := F(n, info in);
   for i := 0 .. info out.length do
      let new info := m(n.outgoing edges[i]) ∪
                      info out[i];
      if (m(n.outgoing edges[i]) ≠ new info])
         m(n.outgoing edges[i]) := new info;
         worklist.add(n.outgoing edges[i].dst);
```

Generalized algorithm using lattices

```
let m: map from edge to computed value at edge
let worklist: work list of nodes
for each edge e in CFG do
   m(e) := \bot
for each node n do
   worklist.add(n)
while (worklist.empty.not) do
   let n := worklist.remove any;
   let info in := m(n.incoming edges);
   let info out := F(n, info in);
   for i := 0 .. info out.length do
      let new info := m(n.outgoing_edges[i])
                      info out[i];
      if (m(n.outgoing edges[i]) ≠ new info])
         m(n.outgoing edges[i]) := new info;
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```

Next step: removed outer join

Wanted to remove the outer join, while still providing termination guarantee

To do this, we re-expressed our algorithm more formally

 We first defined a "global" flow function F, and then expressed our algorithm as a fixed point computation

Guarantees

- If F is monotonic, don't need outer join
- If F is monotonic and height of lattice is finite: iterative algorithm terminates
- If F is monotonic, the fixed point we find is the least fixed point.

What about if we start at top?

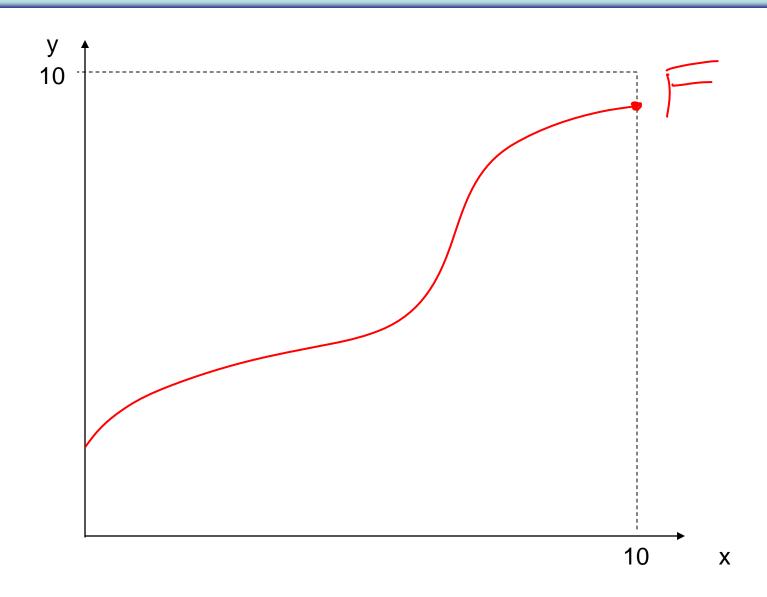
• What if we start with $\widetilde{\top}$: $F(\widetilde{\top})$, $F(F(\widetilde{\top}))$, $F(F(F(\widetilde{\top})))$

What about if we start at top?

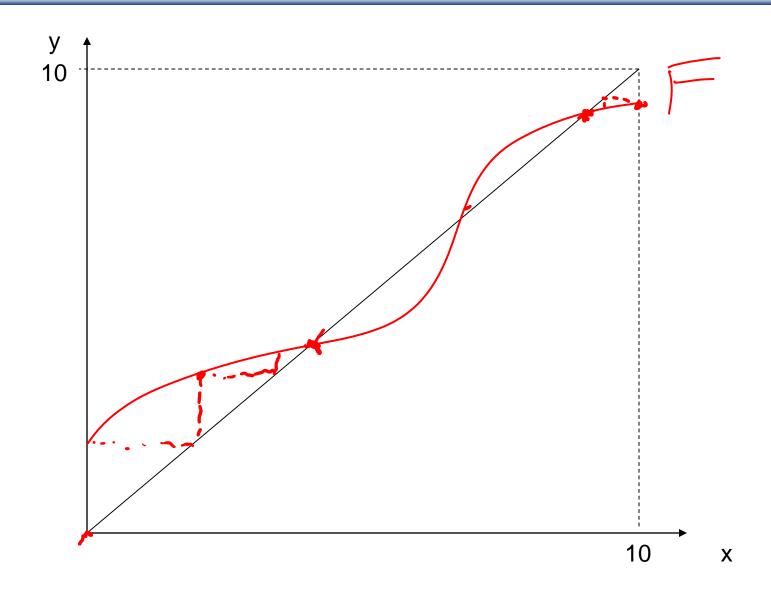
- What if we start with Υ : $F(\Upsilon)$, $F(F(\Upsilon))$, $F(F(\Upsilon))$
- We get the greatest fixed point
- Why do we prefer the least fixed point?
 - More precise

a56 => F(a) [F(b)

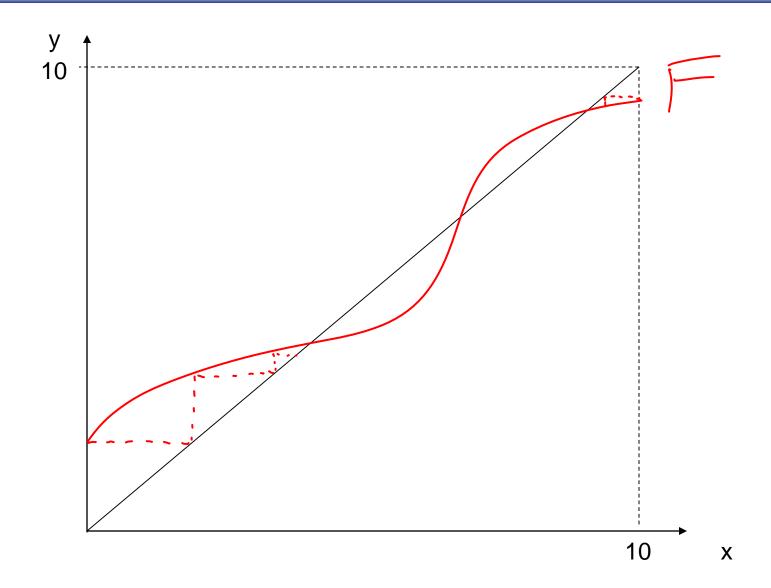
Graphically



Graphically



Graphically



Graphically, another way