

Gaussian Mixture Models

It is a model with a PDF of the form :

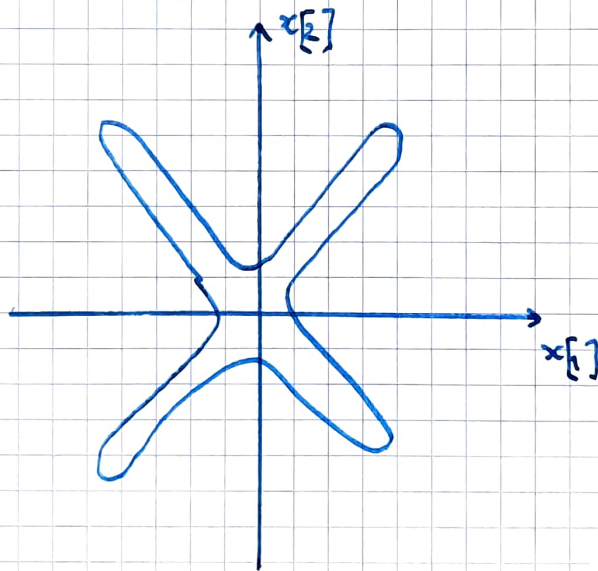
$$\sum_{j=1}^J w_j \mathcal{N}(\mu_j, \Sigma_j)$$

where $\mathcal{N}(x | \mu_j, \Sigma_j) = \frac{1}{\sqrt{(2\pi)^m \det \Sigma_j}} \exp\left(-\frac{1}{2} (x - \mu_j)^T \Sigma_j^{-1} (x - \mu_j)\right)$

$\in \mathbb{R}^m$ \rightarrow m is often 2 because we often work in \mathbb{R}^2 (2 Dimensions)

First case : we want to build a model of this type

Example : we want to create a density in \mathbb{R}^2 such that the iso-densities look like this :



According to Gaussian - Multivariate - Covariance - Matrix / Gaussian.pdf we can define :

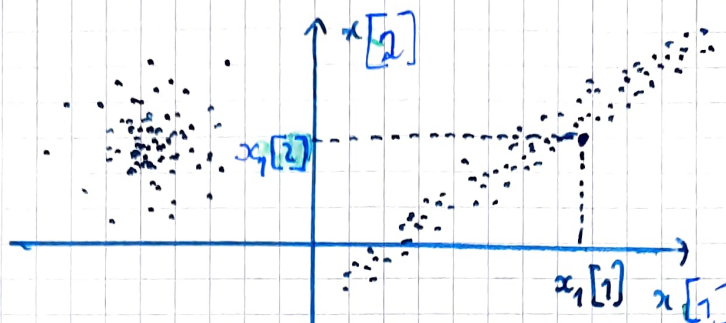
$$\text{PDF}(x) = \frac{1}{2} \mathcal{N}(0, \Sigma_1) + \frac{1}{2} \mathcal{N}(0, \Sigma_2)$$

with $\Sigma_1 = Q D_1 Q^T$ $\Sigma_2 = Q D_2 Q^T$ $Q = \begin{pmatrix} -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}$

$$D_1 = \begin{pmatrix} 10 & 0 \\ 0 & 1 \end{pmatrix}$$

$$D_2 = \begin{pmatrix} 1 & 0 \\ 0 & 10 \end{pmatrix}$$

Case two: We have a cloud of points and want to find the best GMM to model these points (real life)



These "observed" points are denoted by x_1, x_2, \dots, x_n . For each point x_i ($1 \leq i \leq n$), $x_i[1]$ is his first coordinate and $x_i[2]$ the second.

Step 1: choose J

Algorithms won't do it for us

Now we have a model:

$$PDF(x) = \sum_{j=1}^J w_j \mathcal{N}(\mu_j, \Sigma_j)$$

We have $\underbrace{J}_{w_j} + \underbrace{mJ}_{\mu_j} + \underbrace{J \frac{m(m-1)}{2}}_{\Sigma_j} = \frac{J}{2} (m^2 + m + 2)$ parameters to optimize

\uparrow
 $m=2$
in the graphics above
(because 2 Dimensional)

Step 2: Use EM algorithm:

At step t :

① Compute $\gamma_{ij}^{(t)} = \frac{w_j^{(t)} \mathcal{N}(x_i | \mu_j^{(t)}, \Sigma_j^{(t)})}{\sum_{k=1}^J w_k^{(t)} \mathcal{N}(x_i | \mu_k^{(t)}, \Sigma_k^{(t)})}$

and $w_j^{(t+1)} = \frac{1}{n} \sum_{i=1}^n \gamma_{ij}^{(t)}$

② Compute $\mu_j^{(t+1)} = \frac{\sum_{i=1}^n \gamma_{ij}^{(t)} x_i}{\sum_{i=1}^n \gamma_{ij}^{(t)}}$ for all $j \in [1, J]$

and $\Sigma_j^{(t+1)} = \frac{\sum_{i=1}^n \gamma_{ij}^{(t)} (x_i - \mu_j^{(t+1)})(x_i - \mu_j^{(t+1)})^T}{\sum_{i=1}^n \gamma_{ij}^{(t)}}$ for all $j \in [1, J]$

This algorithm converges to a local maximum likelihood.

See the folder GMM - EM - Proof because the proof is particularly interesting in itself, with the use of:

- Jensen inequality
- Deriving the Lagrangian
- Kullback-Leibler divergence
- Some nice differential calculations
- Conditional probabilities

Without proving anything, note that the EM algorithm is intuitive because:

$$\gamma_{ij}^{(t)} = \frac{P(Z_i=j) \mathcal{N}(X_i|Z_i=j)}{\mathcal{N}(X_i|)} = \underbrace{P}_{f}(Z_i=j|X_i=x_i)$$

is the probability of belonging to the j -th Gaussian given x_i :

- This probability is used to weight each new average parameter

$$\mu_j^{(t+1)} = \frac{\sum_i \gamma_{ij}^{(t)} x_i}{\sum_i \gamma_{ij}^{(t)}}$$

- Similarly for the expression of the covariance.