

EDUCATION	<b>M.S. Electrical Engineering and Computer Science</b>	Aug. 2021 - May 2022
	<b>University of California, Berkeley</b> <ul style="list-style-type: none"> <li>• Research Area: Robotics and Artificial Intelligence</li> <li>• Coursework: Deep Reinforcement Learning, NLP, Multimodal ML, Product Development</li> </ul>	Berkeley, CA
	<b>B.A. Computer Science, Minor in Creative Writing</b>	Aug. 2017 - Dec. 2020
	<b>University of California, Berkeley</b> <ul style="list-style-type: none"> <li>• Honors: Magna Cum Laude; GPA: 3.9/4.0</li> <li>• Coursework: Machine Learning, AI, Probability Theory, Efficient Algorithms, Convex Optimization, Robotics, Computer Architecture, Data Structures, Linear Algebra</li> </ul>	Berkeley, CA
PROFESSIONAL EXPERIENCE	<b>J.P. Morgan</b>	New York, NY
	<b>Senior Artificial Intelligence Research Associate</b>	June 2022 - Present
	<ul style="list-style-type: none"> <li>• Computer vision and reinforcement learning in industry.</li> </ul>	
	<b>Berkeley Artificial Intelligence Research</b>	Berkeley, CA
	<b>Graduate Researcher</b>	Apr. 2020 - June 2022
	<ul style="list-style-type: none"> <li>• Graduate student in the Video and Image Processing Lab, advised by Professor Avideh Zakhor. Worked on: <ol style="list-style-type: none"> <li>1. Autonomous robotic navigation. <ul style="list-style-type: none"> <li>• Designed six-legged robots to perform building inspection tasks in inaccessible spaces. Built methods in reinforcement learning for multi-objective rewards and novel approaches to sim-to-real transfer.</li> <li>• Deployed policies learned entirely in simulation to real robots in rough terrain, surmounting 3 obstacles in under 15 seconds. All using a single GPU and \$600 in robotic hardware.</li> </ul> </li> <li>2. Automatic detection of skin cancer. <ul style="list-style-type: none"> <li>• Building deep-learning based approaches for segmentation of invasive melanoma. Collaborating with UCSF pathology for expert data annotation.</li> </ul> </li> <li>3. Image compression for vision tasks. <ul style="list-style-type: none"> <li>• Leader of research team designing neural-network based compression systems to jointly optimize for recognition, distortion, and compression losses. Project owner, contributing 98% of lines of code in repository.</li> <li>• First author on paper accepted for oral presentation at conference. Author on grant proposal for up to \$150,000 in funding (Sony Focused Research Award).</li> </ul> </li> </ol> </li> </ul>	
	<b>J.P. Morgan</b>	New York, NY
	<b>Summer Analyst – Fixed Income Research</b>	Jun. 2021 - Aug. 2021
	<ul style="list-style-type: none"> <li>• Designed AI models to predict relevant market movements from sparse datasets for the U.S. Rates Strategy team (Corporate and Investment Bank).</li> <li>• Contributed to, copy-edited and laid out mid-week, end-of-week, and daily publications for institutional clients and internal partners.</li> <li>• Automated data collection and aggregation methods, producing higher resolution insights for researchers and improving data accessibility.</li> </ul>	
	<b>Salesforce, Inc.</b>	San Francisco, CA
	<b>Software Developer Intern</b>	Jun. 2019 - Aug. 2019
	<ul style="list-style-type: none"> <li>• Developed a novel anomaly detection algorithm with Salesforce's AI group, Einstein. Proposed method helped team launch the Messaging Insights feature, used by thousands of marketers worldwide.</li> </ul>	

PUBLICATIONS  
AND TALKS

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**Learning to Walk: Legged Hexapod Locomotion from Simulation to the Real World**

*Maxime Kawawa-Beaudan, Avidesh Zakhor*

- We employ hierarchical reinforcement learning to train robotic systems to navigate challenging environments. We train on-policy algorithms entirely in simulation before transferring to a real robot. We successfully surmount obstacles in the real world and propose novel approaches to the sim-to-real problem. [Paper](#). [Project page](#).

**Recognition-Aware Learned Image Compression**

Comp. Img. 2022

*Maxime Kawawa-Beaudan, Ryan Roggenkemper, Avidesh Zakhor*

- We jointly learn compression and recognition networks to optimize a rate-distortion loss alongside a task-specific loss. We achieve as much as 26% higher recognition accuracy at equivalent bitrates compared to state-of-the-art traditional compression methods. [Paper](#).

SKILLS

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**Languages:** Python, Java, C; **Platforms:** AWS, Google Cloud; **Frameworks:** Apache Spark, PyTorch, ROS, OpenAI Gym; **Tools:** NumPy, Pandas, OpenCV, matplotlib, Jupyter notebooks, Unix; **Natural Languages:** English (native), French (fluent)