

# Global Regularity Estimates for the Optimal Transport via Entropic Regularization

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# **Some known regularity results**

Let  $\mu$  and  $\nu$  be two probability measures on  $\mathbb{R}^n$  with finite second moments. The quadratic transport cost between  $\mu$  and  $\nu$  is defined as

$$W_2^2(\mu, \nu) = \inf_{\pi \in \Pi(\mu, \nu)} \int \|y - x\|^2 \pi(dx dy). \quad (1)$$

### Theorem [Brenier, 1991]

If  $\mu$  is absolutely continuous with respect to the Lebesgue measure, then there exists a unique optimal transport map  $T$  from  $\mu$  to  $\nu$  such that  $\nu = T_{\#}\mu$  and  $\int \|T(x) - x\|^2 \mu(dx) = W_2^2(\mu, \nu)$ . Moreover,  $T$  is the gradient of a convex function  $\phi$ .

### Theorem [Caffarelli, 1992]

Let  $\mu(dx) = e^{-V(x)}dx$ ,  $\nu(dy) = e^{-W(y)}dy$  be two probability measures on  $\mathbb{R}^n$  such that  $\text{dom } V = \mathbb{R}^n$  and  $\text{dom } W$  is convex with non empty interior. Further assume that  $V, W$  are twice continuously differentiable on the interior of their domains and satisfy

$$\nabla^2 V \leq \alpha_V Id, \quad \nabla^2 W \geq \beta_W Id,$$

with  $\alpha_V, \beta_W > 0$ . Then the optimal transport map for the quadratic transport problem from  $\mu$  to  $\nu$  is  $\sqrt{\alpha_V/\beta_W}$ -Lipschitz.

# Entropic framework

The entropic optimal transport problem is the following

$$\mathcal{C}_\epsilon(\mu, \nu) = \inf_{\pi \in \Pi(\mu, \nu)} \int \frac{1}{2} \|x - y\|^2 d\pi + \epsilon H(\pi | \mu \otimes \nu)$$

where  $H(\pi | \mu \otimes \nu) = \int \log \frac{d\pi}{d(\mu \otimes \nu)} d\pi$ . It is now well known [Carlier et al., 2017], that  $\mathcal{C}_\epsilon(\mu, \nu) \rightarrow \frac{1}{2} W_2^2(\mu, \nu)$  as  $\epsilon \rightarrow 0$ . The minimizer of the entropic regularized transport problem is of the form

$$\pi_\epsilon(dx dy) = e^{\frac{\langle x, y \rangle - \phi_\epsilon(x) - \psi_\epsilon(y)}{\epsilon}} \mu(dx) \nu(dy),$$

# Entropic framework

with  $(\phi_\epsilon, \psi_\epsilon)$  a couple of convex functions solution of the following system

$$\begin{aligned}\phi_\epsilon(x) &= \mathcal{L}_{\epsilon, \nu}(\psi_\epsilon)(x) = \epsilon \log \left( \int e^{\frac{\langle x, y \rangle - \psi_\epsilon(y)}{\epsilon}} \nu(dy) \right), & \forall x \in \mathbb{R}^n \\ \psi_\epsilon(y) &= \mathcal{L}_{\epsilon, \mu}(\phi_\epsilon)(y) = \epsilon \log \left( \int e^{\frac{\langle x, y \rangle - \phi_\epsilon(x)}{\epsilon}} \mu(dx) \right), & \forall y \in \mathbb{R}^n.\end{aligned}$$

Moreover, the entropic Kantorovich potential  $\phi_\epsilon$  converges  $\mu$ -almost everywhere (along to some sequence  $\epsilon_k$ ) to the Kantorovich potential  $\phi$  such that  $T = \nabla \phi$  [Nutz and Wiesel, 2021].

## A regularity result for the entropic potentials

### Theorem [Fathi et al., 2020, Chewi and Pooladian, 2023]

Let  $\mu(dx) = e^{-V(x)}dx$ ,  $\nu(dy) = e^{-W(y)}dy$  be two probability measures on  $\mathbb{R}^n$  such that  $\text{dom } V = \mathbb{R}^n$  and  $\text{dom } W$  is convex with non empty interior. Further assume that  $V, W$  are twice continuously differentiable on the interior of their domains and satisfy

$$\nabla^2 V \leq \alpha_V Id, \quad \nabla^2 W \geq \beta_W Id,$$

with  $\alpha_V, \beta_W > 0$ . Then  $\nabla \phi_\epsilon$  is  $\sqrt{\alpha_V/\beta_W}$ -Lipschitz, for all  $\epsilon \geq 0$ .

## Three steps

The main objective is to relax the  $\mathcal{C}^2$  hypothesis on  $V, W$ .

- (i) Define a notion of smoothness which grants regularity of the gradient of a function without referring to its second derivative.
- (ii) Study the interaction between smoothness and the entropic Legendre transform  $\mathcal{L}_{\epsilon, m}$ .
- (iii) Apply the results to the entropic regularized transport problem.



# Reminders on convex analysis

### Smoothness and Strong convexity

Let  $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$  be a proper, l.s.c. function. We say that  $f$  is  $R$ -convex, or that  $R$  is a convexity modulus for  $f$ , if for any  $x_0, x_1 \in \mathbb{R}^n$  and  $t \in [0, 1]$ , we have

$$f((1-t)x_0 + tx_1) + t(1-t)R(x_1 - x_0) \leq (1-t)f(x_0) + tf(x_1).$$

We say that  $f$  is  $S$ -smooth, or that  $S$  is a smoothness modulus for  $f$ , if for any  $x_0, x_1 \in \mathbb{R}^n$  and  $t \in [0, 1]$ , we have

$$f((1-t)x_0 + tx_1) + t(1-t)S(x_1 - x_0) \geq (1-t)f(x_0) + tf(x_1).$$

## Remarks

Note that when  $R(d) = \frac{\alpha}{2}\|d\|^2$  we recover the definition of  $\alpha$  strong convexity, and when  $S(d) = \frac{\beta}{2}\|d\|^2$  we recover  $\beta$  smoothness of the function.

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### Definition

The smallest function  $S$  such that  $f$  is  $S$ -smooth is called the smoothness modulus of  $f$  and is denoted  $S_f$ . It is convex when  $f$  is convex.

The smallest function  $R$  such that  $f$  is  $R$ -convex is called the convexity modulus of  $f$  and is denoted  $R_f$ .

## Examples

**Quadratic functions** Let  $A$  be a  $n \times n$  matrix, then the function  $f(x) = \langle x, Ax \rangle$  admits the following moduli

$$R_f(d) = S_f(d) = \langle d, Ad \rangle, \quad d \in \mathbb{R}^n,$$

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**Bounded Hessians** Let  $f$  be a twice continuously differentiable function on  $\mathbb{R}^n$ , then it admits the following moduli

$$R_f(d) \geq \frac{1}{2} \inf_x \langle d, \nabla^2 f(x) d \rangle, \quad S_f(d) \leq \frac{1}{2} \sup_x \langle d, \nabla^2 f(x) d \rangle, \quad d \in \mathbb{R}^n.$$

## Examples

**Radial functions** Let  $\alpha : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  be a non-decreasing function such that  $\alpha(ct) \geq c\alpha(t)$  for all  $t \geq 0$  and  $c \geq 1$ . Define  $A(r) = \int_0^r \alpha(u) du$ ,  $r \geq 0$ , and  $f_\alpha(x) = A(\|x\|)$ ,  $x \in \mathbb{R}^n$ . Then, the function  $f_\alpha$  is  $R$ -convex, with  $R(d) = 2A(\|d\|/2)$ ,  $d \in \mathbb{R}^n$ .

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**Continuous gradients** Let  $f$  be a continuously differentiable function such that  $\nabla f$  admits a non-decreasing modulus of continuity  $\omega$  then

$$S(d) \leq 2\|d\|\omega(\|d\|), \quad d \in \mathbb{R}^n,$$

is a smoothness modulus for  $f$ .



### Proposition

Let  $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$  be a function with a non-empty convex domain and  $S : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$  be even. If  $f$  is  $S$ -smooth, then for all  $x_0, x_1 \in \text{dom} f$  and  $y_0 \in \partial f(x_0), y_1 \in \partial f(x_1)$ , it holds

$$S^*(y_1 - y_0) \leq S(x_1 - x_0).$$

If  $f$  is  $\beta$ -smooth, we have  $S(d) \leq \frac{\beta}{2} \|d\|^2$  and  $S^*(u) \geq \frac{1}{2\beta} \|u\|^2$ , thus we get  $\|y_1 - y_0\| \leq \beta \|x_1 - x_0\|$ , which is the classical Lipschitz property of the gradient.

# **Moduli and Legendre transform**

### Proposition [Azé and Penot, 1995]

Let  $f, g : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$  be two functions with non-empty convex domains and  $S, R : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\pm\infty\}$  be even functions.

- (i) If  $f$  is  $S$ -smooth, then  $f^*$  is  $S^*$ -convex.
- (ii) If  $g$  is  $R$ -convex, then  $g^*$  is  $R^*$ -smooth.

Note that when  $f$  is  $\alpha$ -strongly convex we recover that  $f^*$  is  $\alpha^{-1}$ -smooth.

## Proposition

- (a) Let  $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$  be an  $R$ -convex function with convex domain with positive  $\mathcal{H}^n$  measure, then the function  $\mathcal{L}_{\epsilon, \mathcal{H}^n}(\psi)$  is  $R^*$ -smooth.
- (b) Let  $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$  be an  $S$ -smooth function with full domain, then the function  $\mathcal{L}_{\epsilon, \mathcal{H}^n}(\psi)$  is  $S^*$ -convex.

Recall that

$$\mathcal{L}_{\epsilon, \mathcal{H}^n}(\psi) = \epsilon \log \left( \int e^{\frac{\langle x, y \rangle - \psi(y)}{\epsilon}} dy \right)$$

## Prekopa-Leindler inequality

Let  $f_0, f_1, h : L \rightarrow \mathbb{R}_+$  be measurable functions defined on  $\mathbb{R}^n$  such that, for some  $t \in ]0, 1[$ , it holds

$$h((1-t)y_0 + ty_1) \geq f_0^{1-t}(y_0)f_1^t(y_1), \quad \forall y_0, y_1 \in \mathbb{R}^n$$

then

$$\int h \geq \left( \int f_0 \right)^{1-t} \left( \int f_1 \right)^t.$$

## Proof sketch of (a)

Set

$$h(y) = \exp\left(\frac{\langle x_t, y \rangle - \psi(y)}{\epsilon}\right), f_0(y) = \exp\left(\frac{\langle x_0, y \rangle - \psi(y)}{\epsilon}\right), f_1(y) = \exp\left(\frac{\langle x_1, y \rangle - \psi(y)}{\epsilon}\right),$$

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which satisfy

$$\begin{aligned} h(y_t) &\geq \exp\left(\frac{t(1-t)(R(y_1 - y_0) - \langle x_1 - x_0, y_1 - y_0 \rangle)}{\epsilon}\right) f_0^{1-t}(y_0) f_1^t(y_1) \\ &\geq \exp\left(\frac{-t(1-t)R^*(x_1 - x_0)}{\epsilon}\right) f_0^{1-t}(y_0) f_1^t(y_1) \end{aligned}$$

because  $\psi$  is  $R$ -convex.

## Proof sketch of (a)

Applying Prekopa-Leindler inequality to  $h, f_0, f_1$  to grants

$$\int h \geq \exp\left(\frac{-t(1-t)R^*(x_1 - x_0)}{\epsilon}\right) \left(\int f_0\right)^{1-t} \left(\int f_1\right)^t.$$

Finally taking the logarithm and multiplying by  $\epsilon$  gives

$$\mathcal{L}_{\epsilon, \mathcal{H}^n}(\psi)(x_t) \geq -t(1-t)R^*(x_1 - x_0) + (1-t)\mathcal{L}_{\epsilon, \mathcal{H}^n}(\psi)(x_0) + t\mathcal{L}_{\epsilon, \mathcal{H}^n}(\psi)(x_1),$$

which ensures that  $\mathcal{L}_{\epsilon, \mathcal{H}^n}(\psi)$  is  $R^*$ -smooth.



# **Regularity estimates for the optimal transport map**

# Entropic regularity theorem

## Theorem

Let  $\mu(dx) = e^{-V(x)}dx$  and  $\nu(dy) = e^{-W(y)}dy$  be two measures on  $\mathbb{R}^n$  with finite second moment such that  $V$  is  $S_V$ -smooth,  $\text{dom } V = \mathbb{R}^n$  and  $W$  is  $R_W$ -convex. Then for all  $\epsilon > 0$  the entropic potentials  $\phi_\epsilon$  is  $S$ -smooth with  $S$  such that

$$S(d) \leq \int_0^1 \sup_{R_W^{**}(p) \leq S_V(td)} \langle p, d \rangle dt, \quad \forall d \in \mathbb{R}^n.$$

Note that the result holds for  $\epsilon = 0$  by pointwise convergence of  $\phi_\epsilon$  towards  $\phi$ .

## Remark on radial moduli

In the case  $S_V(.) = \sigma_V(\|.\|)$  and  $R(.)_W = \rho_W(\|.\|)$ , the estimate on the smoothness modulus  $S$  can be rewritten as

$$S(\|d\|) \leq \int_0^{\|d\|} (\rho_W^{**})^{-1}(\sigma_V(s)) \, ds.$$

Which gives the following regularity estimate on the gradient of  $\phi_\epsilon$

$$\|\nabla \phi_\epsilon(x) - \nabla \phi_\epsilon(y)\| \leq \frac{2}{\|x - y\|} \int_0^{\|x-y\|} (\rho_W^{**})^{-1}(\sigma_V(s)) \, ds.$$

## Proof of the entropic regularity theorem

Using the notations above the entropic potentials  $\phi_\epsilon$  and  $\psi_\epsilon$  satisfy

$$\phi_\epsilon = \mathcal{L}_{\epsilon,\nu}(\psi) = \mathcal{L}_{\epsilon,\nu}(\psi + \epsilon W) \quad \psi_\epsilon = \mathcal{L}_{\epsilon,\mu}(\phi) = \mathcal{L}_{\epsilon,\nu}(\phi + \epsilon V).$$

Then by the entropic Legendre transform property, we have that the modulus of smoothness  $S_\epsilon$  of  $\phi_\epsilon$  and the modulus of convexity  $R_\epsilon$  of  $\psi_\epsilon$  satisfy

$$S_\epsilon \leq (R_\epsilon + \epsilon R_W)^*, \quad R_\epsilon \geq (S_\epsilon + \epsilon S_V)^*.$$

Combining the two inequalities and using the inverse monotonicity of the Legendre transform we get

$$S_\epsilon \leq ((S_\epsilon + \epsilon S_V)^* + \epsilon R_W)^* \leq (S_\epsilon + \epsilon S_V) \square \epsilon R_W.$$

## Proof of the entropic regularity theorem

Applying the inequality above at  $u + \epsilon v$  and using the convexity of  $S_\epsilon$  grants

$$\langle \partial S_\epsilon(u), v \rangle \leq \frac{S_\epsilon(u + \epsilon v) - S_\epsilon(u)}{\epsilon} \leq S_V(u) + R_W^*(v).$$

Finally optimizing over  $v$  we have  $R_W^{**}(\partial S_\epsilon(u)) \leq S_V(u)$ . The conclusion follows by integration.

# Examples

$V$	$W$	$S_V(\cdot)$	$R_W(\cdot)$	$\ \nabla\phi(x) - \phi(y)\  \leq$
$\nabla^2 V \leq \alpha_V Id$	$\nabla^2 W \geq \beta_V Id$	$\frac{\alpha_V}{2} \ \cdot\ ^2$	$\frac{\beta_W}{2} \ \cdot\ ^2$	$\sqrt{\frac{\alpha_V}{\beta_W}} \ x - y\ $
$V \in \mathcal{C}^1, 1 \leq p \leq 2$	$W \in \mathcal{C}^1, 2 \leq q$	$\alpha_V \ \cdot\ ^p$	$\beta_W \ \cdot\ ^q$	$\frac{2q}{p+q} \left( \frac{\alpha_V}{\beta_W} \right)^{\frac{1}{q}} \ x - y\ ^{\frac{p}{q}}$
$V$ $L$ -Lipschitz	$\nabla^2 W = Id$	$4L \ \cdot\ $	$\frac{1}{2} \ \cdot\ ^2$	$\frac{8\sqrt{2}}{3} L \ x - y\ ^{\frac{1}{2}}$
$V(\cdot) = n \ln(1 + \ x\ ^2) + C$	$\nabla^2 W = Id$	$6n \ \cdot\ ^2 \wedge 4n \ \cdot\ $	$\frac{1}{2} \ \cdot\ ^2$	$2\sqrt{3n} \ x - y\  \wedge \frac{8\sqrt{2}}{3} \ x - y\ ^{\frac{1}{2}}$
$\nabla^2 V \leq A^{-1}$	$\nabla^2 W \geq B^{-1}$	$A^{-1}$	$B^{-1}$	$B^{1/2} (B^{-1/2} A^{-1} B^{-1/2})^{1/2} B^{1/2}$

### Corollary

Assume that  $V$  is  $S$ -smooth with  $S(\cdot) = \sigma(\|\cdot\|)$  where  $\sigma : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  non-decreasing and that  $W$  is  $R$ -convex with  $R(\cdot) = \rho(\|\cdot\|)$  where  $\rho : \mathbb{R}_+ \rightarrow \mathbb{R} \cup \{+\infty\}$ . Then the optimal transport  $T$  from  $\mu$  to  $\nu$  satisfies

$$\|T(x)\| \leq \|T(0)\| + 2(\rho^{**})^{-1}(\sigma(\|x\|)).$$

Note that it is not required to have  $\rho \geq 0$ .

### Corollary

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$$\|T(x)\| \leq \|T(0)\| + 2(\rho^{**})^{-1}(\sigma(\|x\|)).$$

Note that it is not required to have  $\rho \geq 0$ .




This estimate is of the same order as the one obtained in [Fathi, 2024]. It is strictly better in the case of a rotationnaly invariant target measure.










## Conclusion

- (i) This approach also allows us to recover the recent result on a log-subharmonic "contraction" theorem when the target is log-concave [Philippis and Shenfeld, 2024].
- (ii) It is possible to deduce results for the entropic Legendre transform with a general cost. However the application to optimal transport is unclear.
- (iii) The entropic Legendre transform result is to be compared with the result on weak semiconvexity of Schrödinger potentials [Conforti, 2024].

**Thank you for your attention !**

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