

Neural Uncertainty

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Chapter 1

Model definition

1.1 Notations

We consider the prediction task of a set of observations (x^1, \dots, x^T) given a set of input (u^1, \dots, u^T) .

1.2 Model

We define a L layer RNN followed by a fully connected layer. At time step t ,

$$\begin{cases} x_{t+1} = \tanh(W_x y_{t+1}^L + b_x) \\ y_{t+1}^l = \tanh(W_{yu}^l y_{t+1}^{l-1} + W_{yy}^l y_t^l + b_y^l) \quad \forall 1 \leq l \leq L \end{cases}$$

with $y_t^0 \equiv u_t \forall t$ and $y_0^l \equiv 0 \forall 1 \leq l \leq L$.

Let's consider the weights of the last RNN and fully connected layers as $\Theta \equiv (W_{yu}^L, W_{yy}^L, b_y^L, W_x, b_x)$. We can define a new matrix y_t at each time step corresponding to the concatenation of all RNN layers: $y_t \equiv (y_t^1 \dots y_t^L)$. We also introduce two sequences of random noises as i.i.d real valued random variables ϵ and η . We can now write our model in terms of two functions f and g as:

$$\begin{cases} x_{t+1} = f_{\Theta}(y_{t+1}) + \epsilon_{t+1} & \text{observation model} \\ y_{t+1} = g_{\Theta}(y_t, u_{t+1}) + \eta_{t+1} & \text{state model} \end{cases} \quad (1.1)$$

$$Q(\hat{\Theta}_p, \Theta) = \mathbb{E}_{\hat{\Theta}_p} [\log p_{\Theta}(X_{1:T}, y_{1:T}, u_{1:T}) | y_{1:T}] \quad (1.2)$$

Let's develop the interior of expectation:

$$\begin{aligned}
p_{\Theta}(X_{1:T}, y_{1:T}, u_{1:T}) &= \frac{1}{T} \log \left(\prod_{k=1}^T p_{\Theta}(y_k | y_{k-1}, u_k) p_{\Theta}(x_k | y_k) \right) \\
&= \frac{1}{T} \sum_{k=1}^T \log p_{\Theta}(y_k | y_{k-1}, u_k) + \log p_{\Theta}(x_k | y_k) \\
&= \frac{1}{T} \sum_{k=1}^T \log \left(\det(2\pi\Sigma_y)^{-1/2} \exp\left(-\frac{1}{2}(y_k - g_{\Theta}(y_{k-1}, u_k))^T \Sigma_y^{-1} (y_k - g_{\Theta}(y_{k-1}, u_k))\right) \right) \\
&\quad + \log \left(\det(2\pi\Sigma_x)^{-1/2} \exp\left(-\frac{1}{2}(x_k - f_{\Theta}(y_k))^T \Sigma_x^{-1} (x_k - f_{\Theta}(y_k))\right) \right) \\
&= -\frac{1}{2} \log |\Sigma_y| - \frac{1}{2} \log |\Sigma_x| \\
&\quad - \frac{1}{2T} \sum_{k=1}^T (y_k - g_{\Theta}(y_{k-1}, u_k))^T \Sigma_y^{-1} (y_k - g_{\Theta}(y_{k-1}, u_k)) \\
&\quad - \frac{1}{2T} \sum_{k=1}^T (x_k - f_{\Theta}(y_k))^T \Sigma_x^{-1} (x_k - f_{\Theta}(y_k))
\end{aligned}$$