

Neural Uncertainty

Max Cohen

September 14, 2020

Chapter 1

Model definition

We define a L layer RNN followed by a fully connected layer. At time step t ,

$$\begin{cases} x_{t+1} = \tanh(W_x h_{t+1}^L + b_x) + \epsilon_t \\ h_{t+1}^l = \tanh(W_{hy}^l h_{t+1}^{l-1} + W_{hh}^l h_t^l + b_h^l) + \eta_t \quad \forall 1 \leq l \leq L \end{cases}$$

and $h_t^0 \equiv y_t$.

Let's consider the weights of the last RNN layer as $\Theta^L \equiv (W_{hy}^L, W_{hh}^L, b_h^L)$, we have $h_{t+1}^L = f_{\Theta^L}(h_{t+1}^{L-1}, h_t^L) + \eta_t$.

$$Q(\hat{\Theta}_p^L, \Theta^L) = \mathbb{E}_{\hat{\Theta}_p^L} [\log p_{\Theta^L}(X_{1:T}, h_{1:T}, y_{1:T} | X_{1:T})] \quad (1.1)$$

$$\simeq \frac{1}{M} \sum_{i=1}^M \log p_{\Theta^L}(X_{1:T}, h_{1:T}, y_{1:T}) \quad (1.2)$$