

# Neural Uncertainty

Max Cohen

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# Chapter 1

## Model definition

### 1.1 Notations

We consider the prediction task of a set of observations  $(y^1, \dots, y^T)$  given a set of input  $(u^1, \dots, u^T)$ .

### 1.2 Model

We define a  $L$  layer RNN followed by a fully connected layer. At time step  $t$ ,

$$\begin{cases} y_{t+1} = \tanh(W_y x_{t+1}^L + b_y) \\ x_{t+1}^l = \tanh(W_{xx}^l x_t^l + W_{xu}^l x_{t+1}^{l-1} + b_x^l) \quad \forall 1 \leq l \leq L \end{cases}$$

with  $x_t^0 \equiv u_t \forall t$  and  $x_0^l \equiv 0 \forall 1 \leq l \leq L$ .

Let's consider the weights of the last RNN and fully connected layers as  $\Theta \equiv (W_{xx}^L, W_{xu}^L, b_x^L, W_y, b_y)$ . We can define a new matrix  $y_t$  at each time step corresponding to the concatenation of all RNN layers:  $x_t \equiv (x_t^1 \dots x_t^L)$ . We also introduce two sequences of random noises as i.i.d real valued random variables  $\epsilon$  and  $\eta$ . We can now write our model in terms of two functions  $f$  and  $g$  as:

$$\begin{cases} y_{t+1} = f_{\Theta}(x_{t+1}) + \epsilon_{t+1} & \text{observation model} \\ x_{t+1} = g_{\Theta}(x_t, u_{t+1}) + \eta_{t+1} & \text{state model} \end{cases} \quad (1.1)$$

$$Q(\hat{\Theta}_p, \Theta) = \mathbb{E}_{\hat{\Theta}_p} [\log p_{\Theta}(X_{1:T}, y_{1:T}, u_{1:T}) | y_{1:T}] \quad (1.2)$$

Let's develop the interior of the expectation:

$$\begin{aligned}
p_{\Theta}(X_{1:T}, y_{1:T}, u_{1:T}) &= \frac{1}{T} \log \left( \prod_{k=1}^T p_{\Theta}(x_k | x_{k-1}, u_k) p_{\Theta}(y_k | x_k) \right) \\
&= \frac{1}{T} \sum_{k=1}^T \log p_{\Theta}(x_k | x_{k-1}, u_k) + \log p_{\Theta}(y_k | x_k) \\
&= \frac{1}{T} \sum_{k=1}^T \log \left( \det(2\pi\Sigma_x)^{-1/2} \exp\left(-\frac{1}{2}(x_k - g_{\Theta}(x_{k-1}, u_k))^T \Sigma_x^{-1} (x_k - g_{\Theta}(x_{k-1}, u_k))\right) \right) \\
&\quad + \log \left( \det(2\pi\Sigma_y)^{-1/2} \exp\left(-\frac{1}{2}(y_k - f_{\Theta}(x_k))^T \Sigma_y^{-1} (y_k - f_{\Theta}(x_k))\right) \right) \\
&= -\frac{1}{2} \log |\Sigma_x| - \frac{1}{2} \log |\Sigma_y| \\
&\quad - \frac{1}{2T} \sum_{k=1}^T (x_k - g_{\Theta}(x_{k-1}, u_k))^T \Sigma_x^{-1} (x_k - g_{\Theta}(x_{k-1}, u_k)) \\
&\quad - \frac{1}{2T} \sum_{k=1}^T (y_k - f_{\Theta}(x_k))^T \Sigma_y^{-1} (y_k - f_{\Theta}(x_k))
\end{aligned}$$