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#Hotplate Sensing
#Feb 29, 2019
#50% Max Huggins
import RPi.GPIO as GPIO
import time
import uControllersDataAcquisition as DtA
#This segment of code deals with setting up GPIO pins for the MCP
GPIO.setmode(GPIO.BOARD)
CS = [29, 32, 18, 8]
CLK = [31, 36, 22, 10]
DOUT = [33, 38, 24, 12]
DIN = [37, 40, 26, 16]
for i in range(0,4):
   GPIO.setup(CS[i], GPIO.OUT)
   GPIO.setup(CLK[i], GPIO.OUT)
   GPIO.setup(DOUT[i], GPIO.IN)
   GPIO.setup(DIN[i], GPIO.OUT)
#-----#
#This creates two matrices that can hold 25 different lists of data (One for
#each MCP channel and corresponding times.)
TEMP = [[] for i in range(0,25)]
TIME = [[] for i in range(0,25)]
#Here is where the magic happens
try:
   my test = True
   start_time = time.time()
   while my_test == True:
      #This is in charge of ending the program in case a sensor reads 100C
      #and also helps us see that we are getting good data
      test = DtA.calc tempMCPBudgetLM34(DtA.readMCP(0, CS[0], CLK[0], DOUT[0], DIN[0]))
      print(test)
      test = float(test)
      if test > 100:
          break
      #These two Loops go through each MCP (i) and each MCP channel(n)
      for i in range(0,4):
          for n in range(0,8):
             if i == 3 and n == 1:#Last channel of the last MCP taking data.
             #It reads from a function defined in the data acquisition file
             d = DtA.readMCP(n, CS[i], CLK[i], DOUT[i], DIN[i])
             TIME[8 * i + n].append(time.time() - start time)
             t = DtA.calc_tempMCPBudgetLM34(d)
             TEMP[8 * i + n].append(t)
#-----#
#This just writes data to a file.
   file = open('./Data/HOTPLATETESTING.txt', 'w')
   for i in range(0,25):
      for n in range(0,len(TIME[i])):
      #Write the data as comma delimites
          file.write(str(TIME[i][n]) + ',' + TEMP[i][n] + '\n')
```