

Hash tables

$$h_0(x) = (h(x) + f_0) \bmod m, \quad f_i = i \quad \# \text{ Linear probing}$$

$$f_i = ih^+(x), \quad h^+(x) = R - (x \bmod R), \quad \text{prime } R < m$$

$$f_i = i^2 \quad \# \text{ Quadratic probing}$$

For quadratic probing hash table of size $m > 3$, first $\lfloor \frac{m}{2} \rfloor$ probes would be distinct.

$$\lambda = \frac{m}{n} \quad \# \text{ Load factor}$$

Ideal: prime m , $\lambda = 1$ for open hashing, $\lambda = \frac{1}{2}$ for closed hashing.

Use separate chaining (linked list) when don't know # of insertion/deletion

Else, use closed hashing

Growth rates:

if $\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = c$, then:

$$0 \leq c < \infty \Rightarrow f(n) = O(g(n))$$

$$0 < c \leq \infty \Rightarrow f(n) = \Omega(g(n))$$

$$0 < c < \infty \Rightarrow f(n) = \Theta(g(n))$$

$$c = 0 \Rightarrow f(n) = o(g(n))$$

$$c = \infty \Rightarrow f(n) = \omega(g(n))$$

Use L'Hopital's rule in the proof

$$\sum_{1 \leq i \leq n} i = \frac{n(n+1)}{2}$$

$$\sum_{1 \leq i \leq n} i^2 = \frac{n(n+1)(2n+1)}{6}$$

$$\sum_{1 \leq i \leq n} i^3 = \left(\frac{n(n+1)}{2} \right)^2$$

$$T(n) = \sum_{i=1}^n \left(\sum_{j=1}^i \sum_{k=1}^n \right) C = C \sum_{i=1}^n (i + n) = C \left(\frac{n(n+1)}{2} + n^2 \right)$$

Trees

Complete binary tree is left-justified

For el i in array binary tree: parent $\frac{i-1}{2}$, left $2i + 1$, right $2i + 2$

Binary Search Trees

left nodes < root ≤ right nodes

Inorder traversal = sorted order

Can deserialize preorder traversal

Can balance by rebuilding from inorder serialization

$$c_{i,j} = \min_{i \leq k \leq j} \{c_{i,k-1} + c_{k+1,j} + \sum_{l=i}^j p_l\} \text{ # min avg search cost}$$

$$c_{i,i} = p_i$$

$$c_{i+1,i} = 0$$

Approach to compute $c_{1,n}$:

1. Compute $c_{i,i}$ for all i
2. Compute $c_{i,j}$ in increasing difference of $(j - i)$

$t_{i,j} = k \Leftrightarrow x_k$ is the root of optimal BST

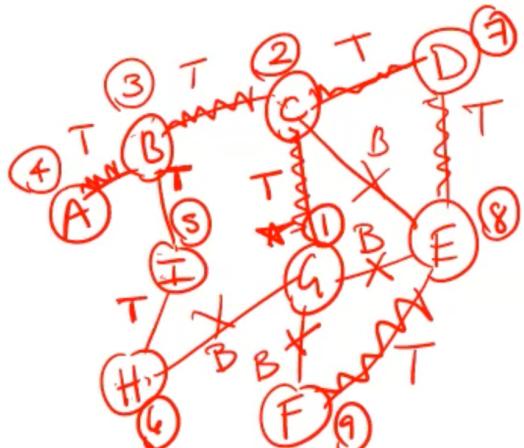
$$\{x_i, x_{i+1}, \dots, x_k, x_{k+1}, \dots, x_j\}$$

for $i = 1$ to n do:

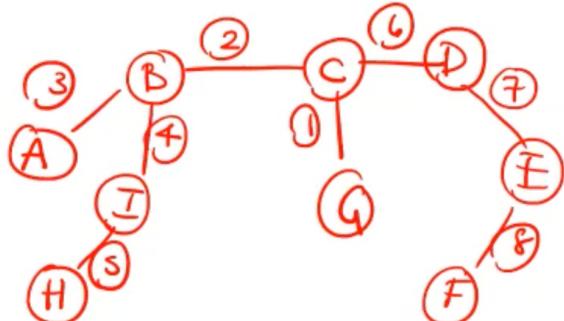
$$c_{i,i} = p_i$$

$$t_{i,i} = i$$

$$Cost = \sum_{i=1}^n p_i (d_{epth\ i} + 1)$$



DFS(Q)

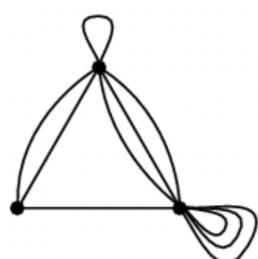


Kruskals MST: add all edges from cheapest skipping loops

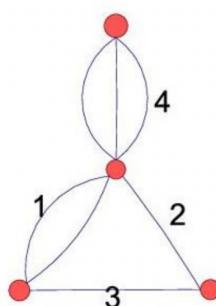
Prims MST: store and update costs of neighbours

Additional Graph Definitions

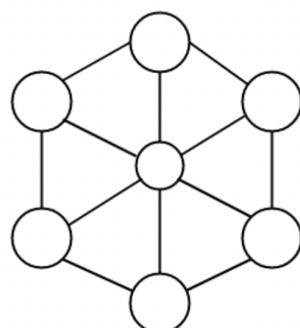
- **Pseudograph:** A graph with possible loops and parallel edges.
- **Multigraph:** A graph with no loops but possible parallel edges.
- **Simple graph:** A graph with no loops or parallel edges.



pseudograph



multigraph



simple graph

More on Connectivity in Undirected Graphs

A vertex v is an **isolated vertex** if it is not connected to any other vertex in V .

G is a **connected graph** iff $\forall x, y \in V$, x and y are connected. Otherwise, it is a **disconnected graph**.

A path is **simple** if all the vertices on the path, except possibly the initial and terminal vertices, are distinct.

Given an undirected graph $G = (V, E)$.

G is a **tree** iff G is a connected graph without a cycle.

G is a **complete graph** iff $\forall x, y \in V$, $(x, y) \in E$.

A tree has $n-1$ edges, where n is the number of vertices.

A complete graph has $n(n-1)/2$ edges, where n is the number of vertices.

Connectivity in Directed Graphs

Given a directed graph $G = (V, E)$.

For any vertices $x, y \in V$, a **weakly connected path** from x to y of length k is a sequence of $k+1$ vertices (v_0, v_1, \dots, v_k) such that $v_0 = x$, $v_k = y$, and $(v_i, v_{i+1}) \in E$, or $(v_{i+1}, v_i) \in E$, $\forall i, 0 \leq i \leq k-1$.

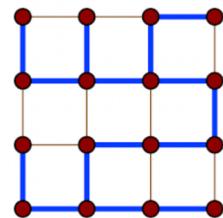
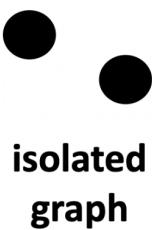
Vertices x and y are **weakly connected** iff there exists a weakly connected path of length k , $k \geq 0$, from x to y .

If $\forall i, 0 \leq i \leq k-1$, $(v_i, v_{i+1}) \in E$, the path is a **strongly connected path** from x to y of length k .

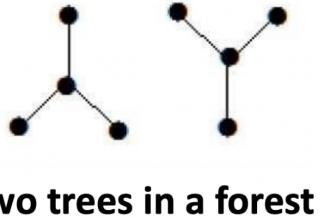
Vertices x and y are **strongly connected** iff there exists a strongly connected path of length k , $k \geq 0$, from x to y .

Some Special Undirected Graphs

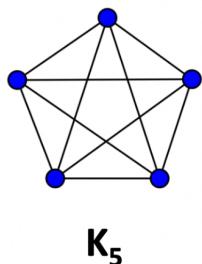
1. A graph with no edge is an **isolated graph**.
2. A connected graph with n vertices and $n-1$ edges is a **tree**. Equivalently, a tree is a simple connected graph with no cycle.
3. A collection of trees is a **forest**.
4. Given a connected graph $G = (V, E)$. A **spanning tree** of G is any spanning subgraph $T = (V, E_T)$ such that T forms a tree.



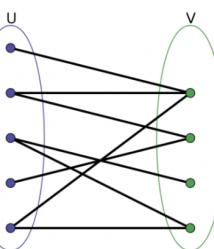
spanning
tree



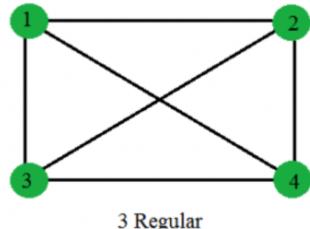
Examples of Special Types of Graphs



complete
graph

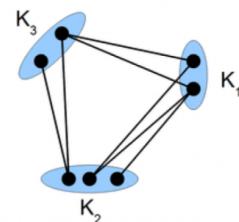


bipartite
graph

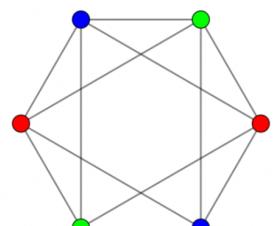


3 Regular

regular
graph



k-partite graph



complete k-partite
graph: $K_{2,2,2}$

B-tree Definition

Definition: A B-tree of order M is an M-ary tree with the following properties:

1. All leaf nodes are on the **same level**.
2. All **non-leaf nodes** (except the root) have **at most M** and **at least $\lfloor M/2 \rfloor$ children**.
3. The **number of keys is one less than the number of children** for **non-leaf nodes** and **at most M-1** and **at least $\lfloor M/2 \rfloor$** for leaf nodes.
4. The **root** may have **as few as 2 children** unless the tree is the root alone. It can have **at most M children**.
5. Typically, the number of keys in a node ranges from **d to 2d**, where **$2d+1 = M$ (for $M = \text{odd}$)**.

Note: The **keys are sorted**, just like in a BST.

Note: This definition is not consistent across references. Everyone must use this definition.