



Projecte EDD-Llums

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Eines de Disseny
2024/2025

Diagrama de blocs



De què tracta el projecte?

Disseny del sistema de control d'il·luminació d'un cotxe mitjançant un microcontrolador.

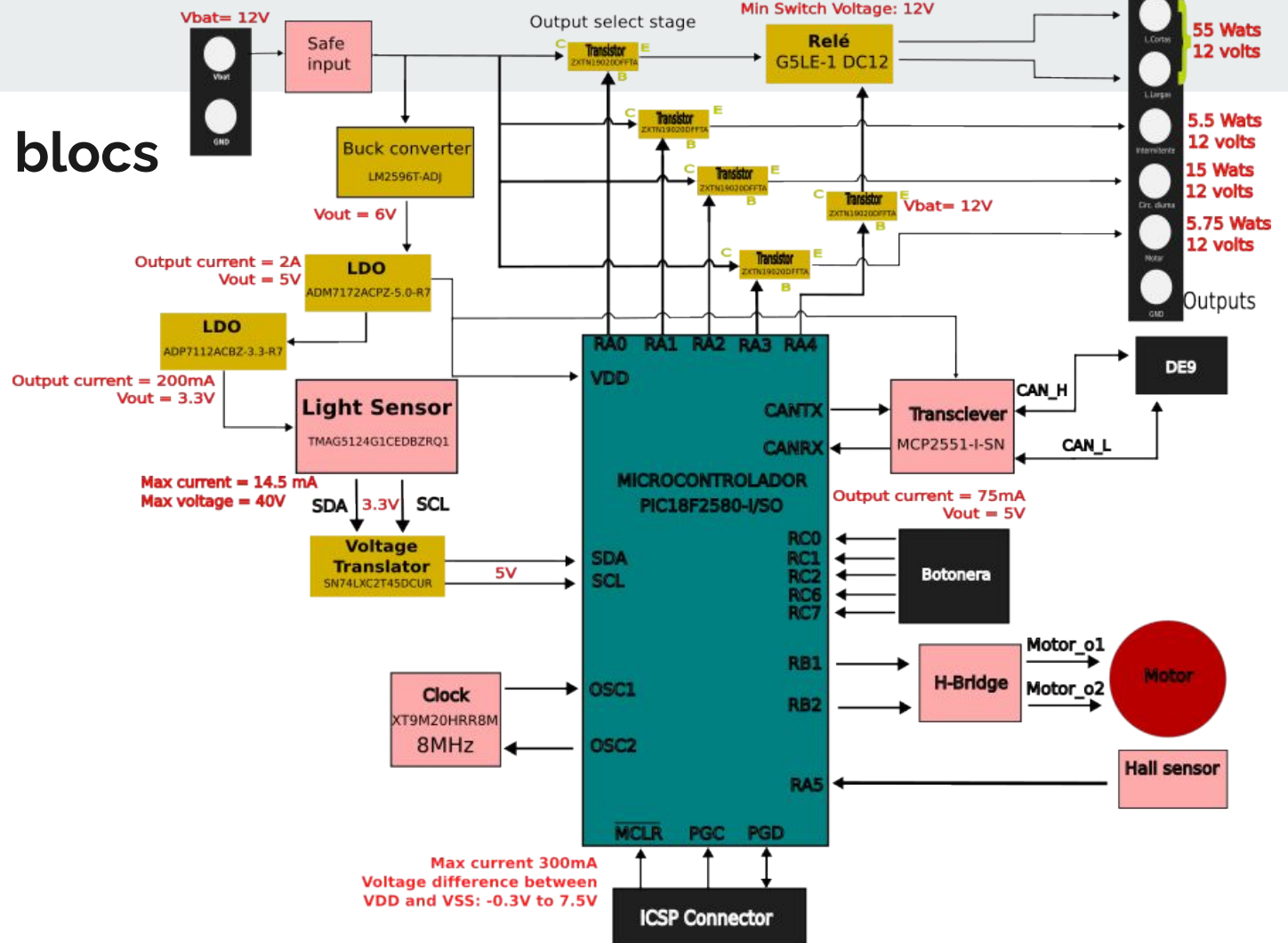


Requisits del projecte

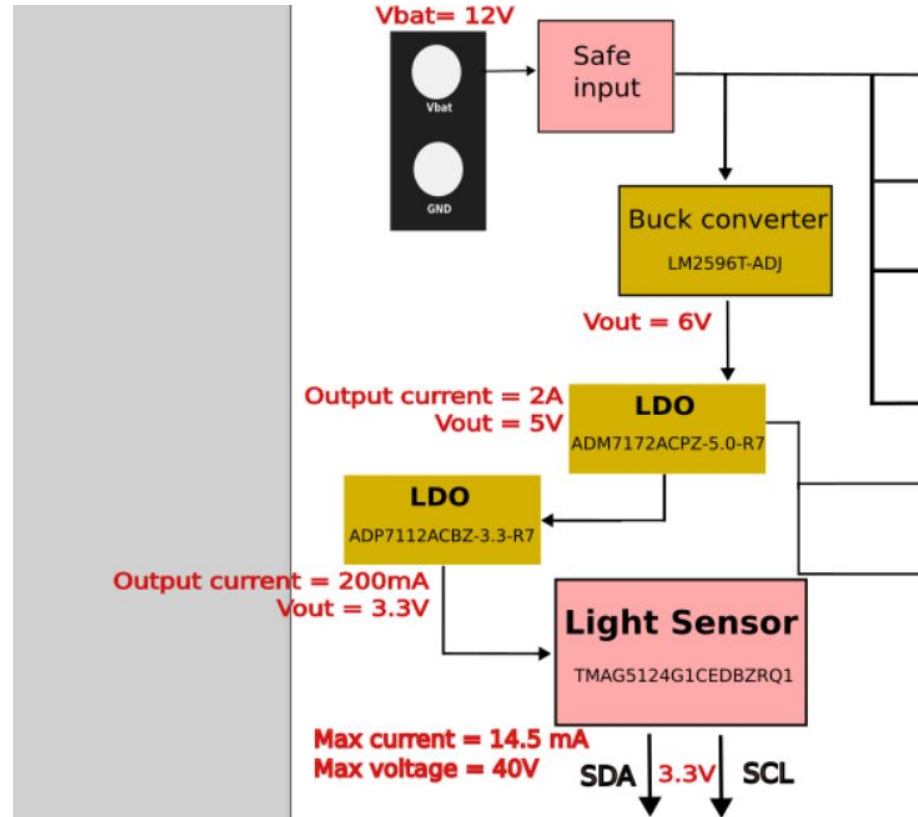
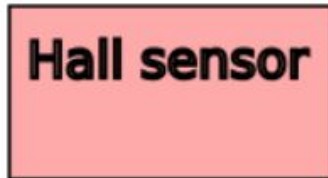
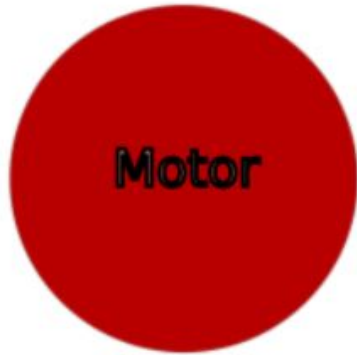
Parts clau del diagrama:

- Llums de carretera.
- Llums d'encreuament.
- Llums de circulació diürna.
- Intermitents
- Motor escombreta neteja-fars.
- Sensor digital de llum, per activar les llums.

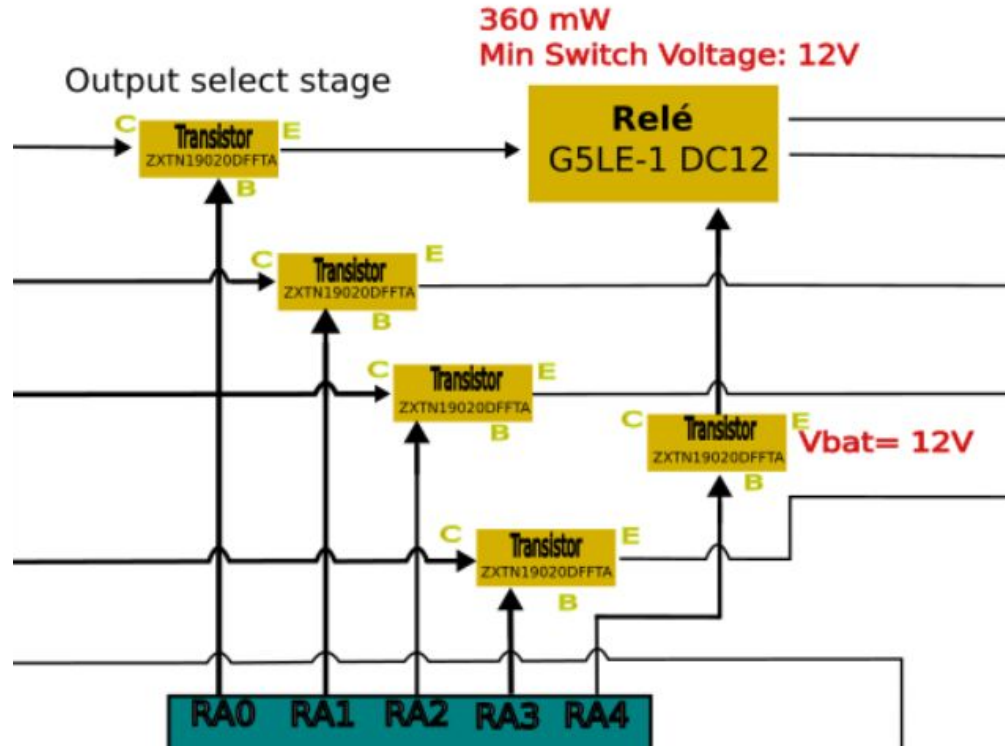
Diagrama de blocs



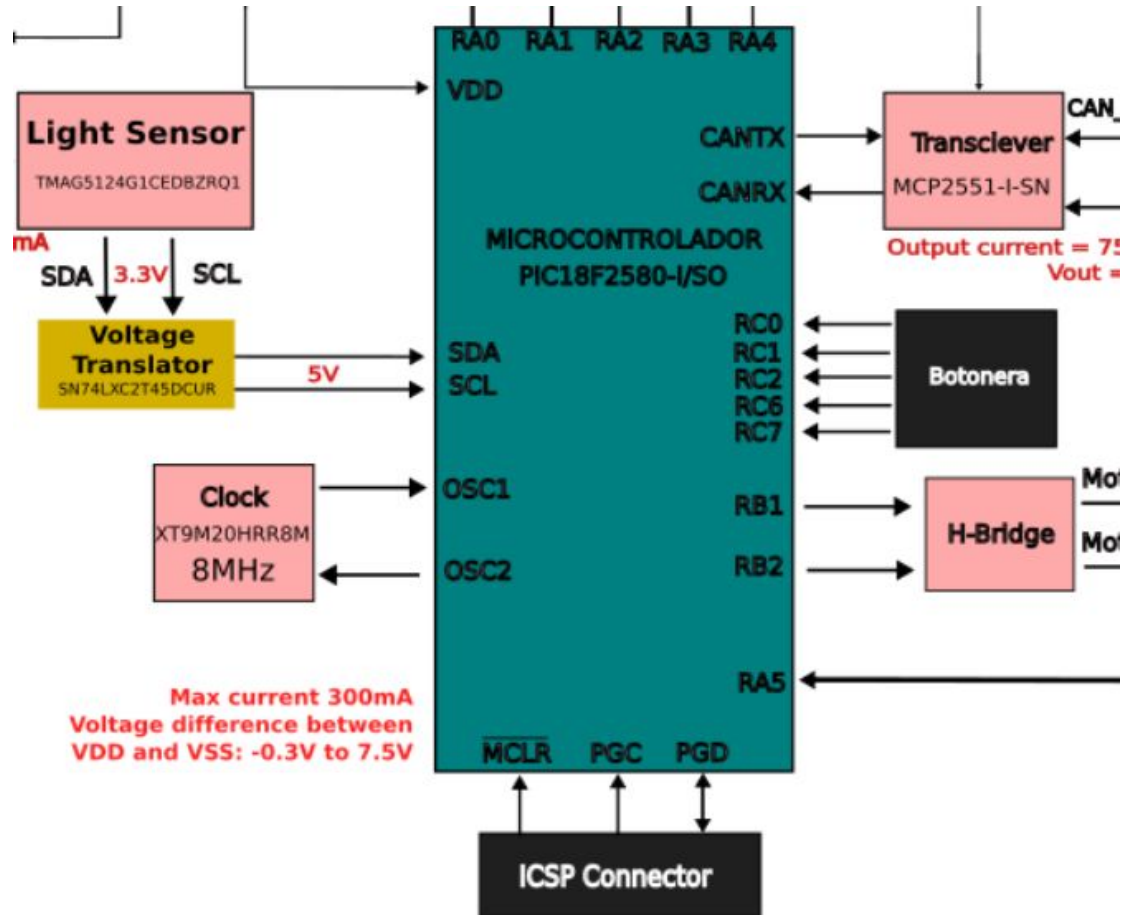
Inputs



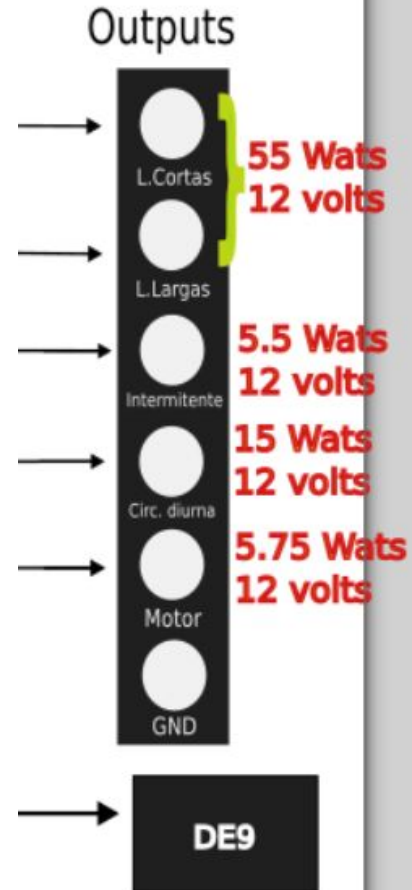
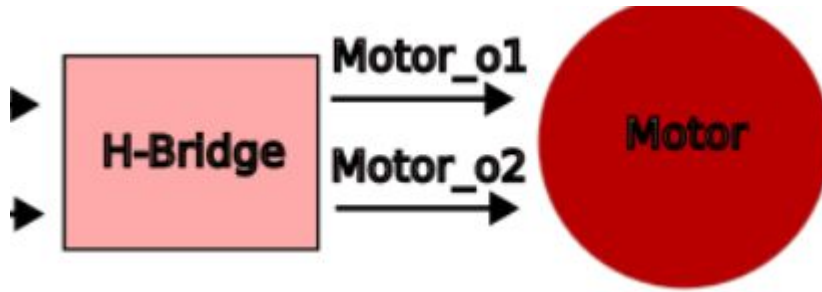
Output selection stage



Microcontrolador

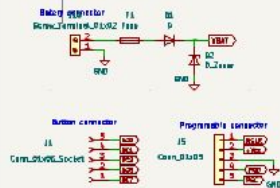


Outputs

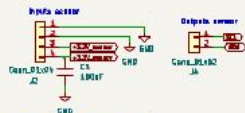


Esquemàtic

INPUTS



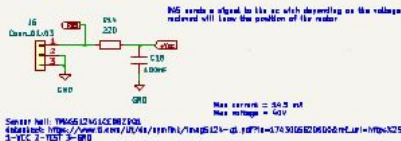
Light Sensor (out of the pcb)



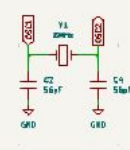
Simplest way to use the sensor is to connect it to a 5V supply and ground. The sensor output is connected to a 1N4148 diode to ground.



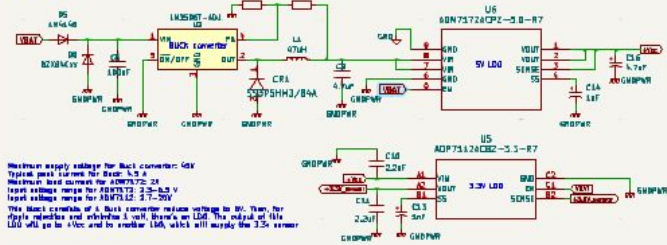
SENSOR HALL



CLOCK



POWER

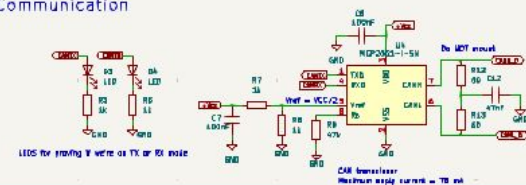


DIGITAL

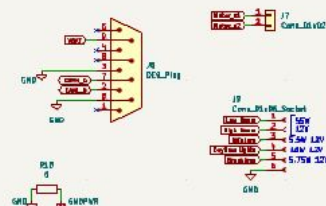


Maximum current by the LED is 20 mA.
Maximum current by the LED is 20 mA.
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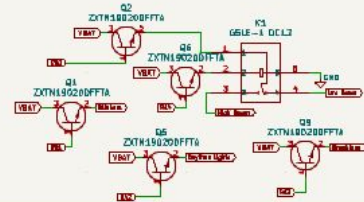
Communication



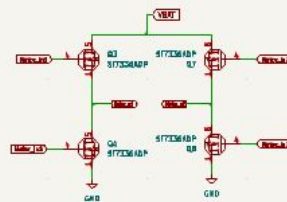
OUTPUT



OUTPUT SELECT STAGE



H-BRIDGE



For "1" turn motor from Motor1 to Motor2.
For "0" turn motor from Motor1 to Motor2.
For "1" turn motor from Motor1 to Motor2.

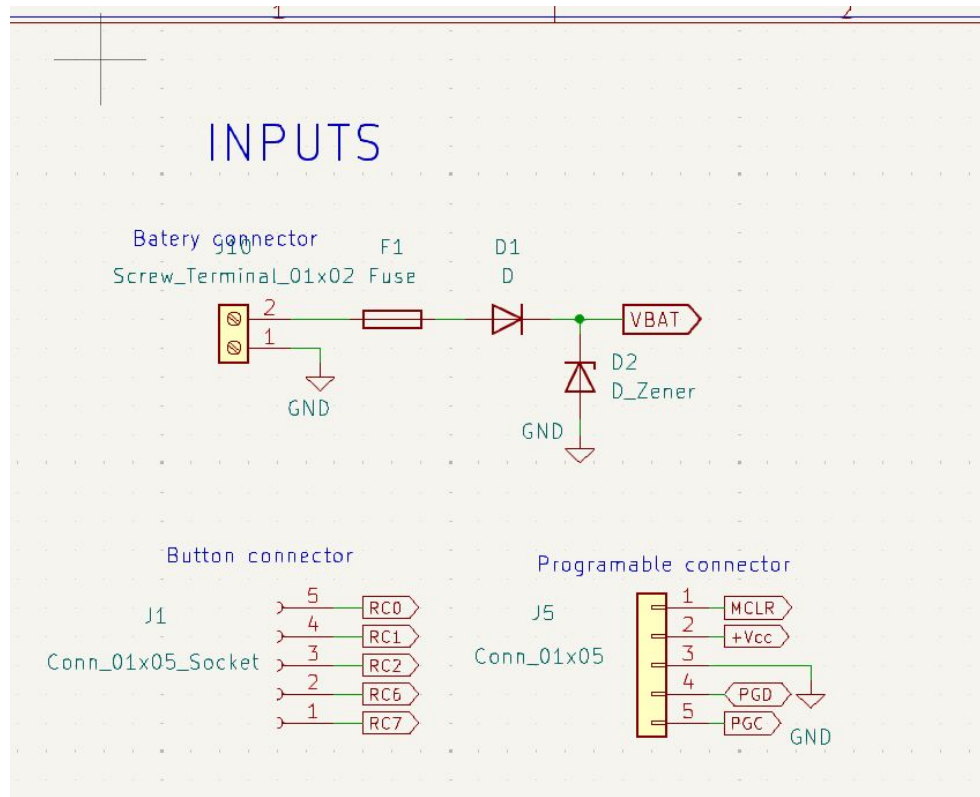
Simplest way to use the sensor is to connect it to a 5V supply and ground.

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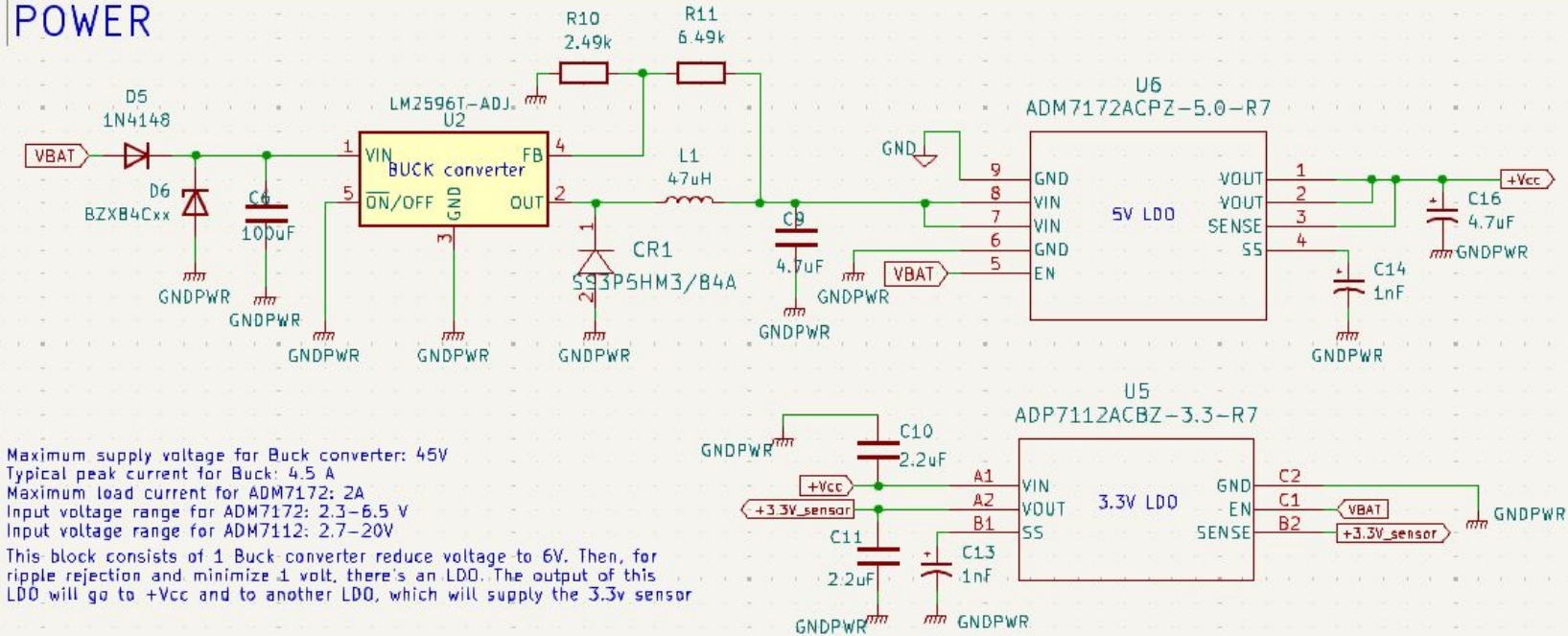
Simplest way to use the sensor is to connect it to a 5V supply and ground.

Inputs



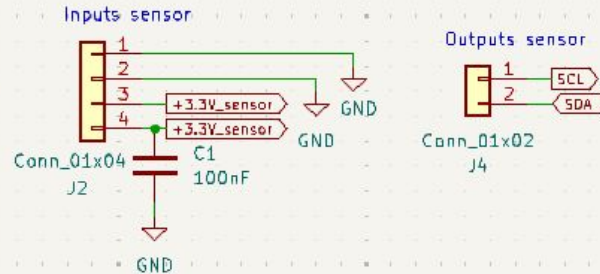
Power

POWER

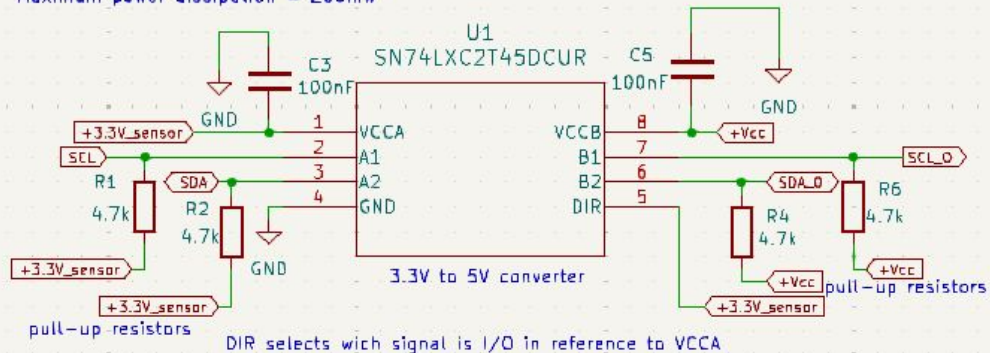


Light Sensor

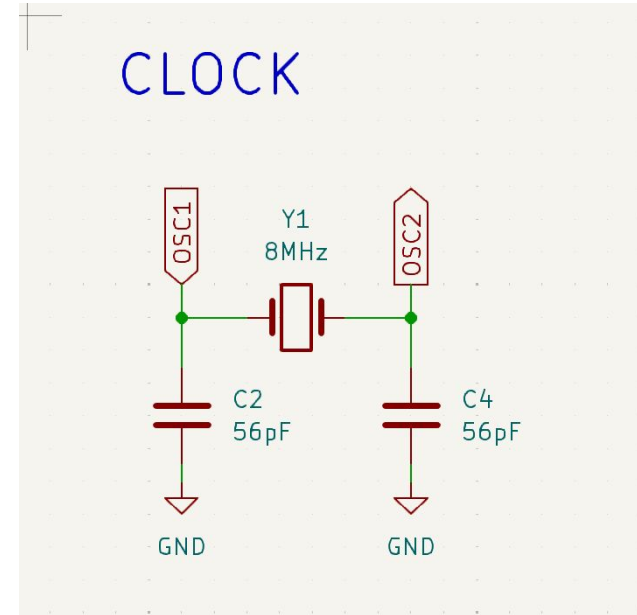
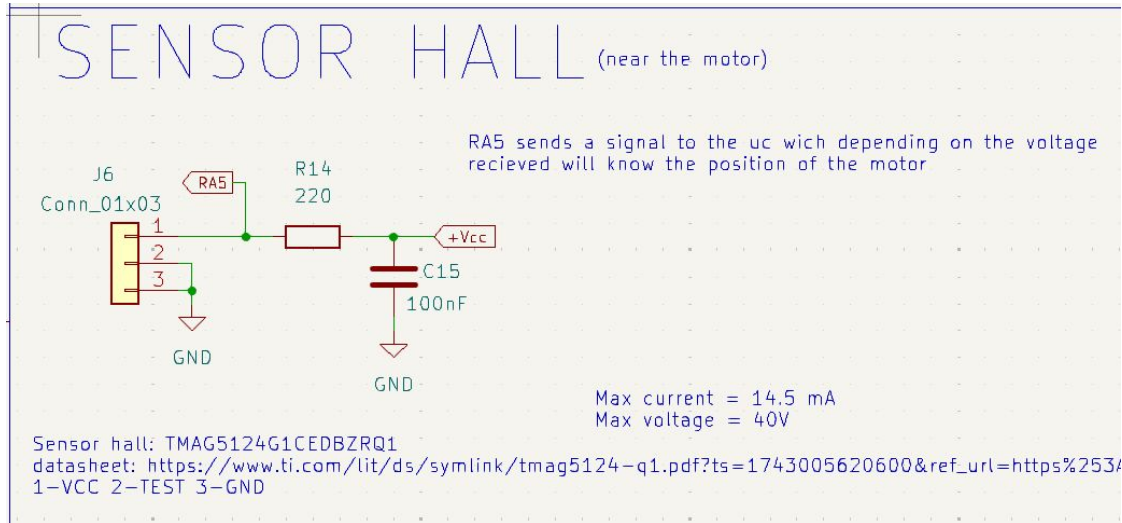
Light Sensor (out of the pcb)



Sensor utilizat: BH1750FVI-TR
https://www.mouser.com/catalog/specsheets/Rohm_11162017_ROHM534826-1.pdf
Inputs: 1-GND 2-ADDR 3-DVI 4-VIN
Outputs: 1-SCL 2-SDA
Vmax = 4.5V
Maximum power dissipation = 260mW

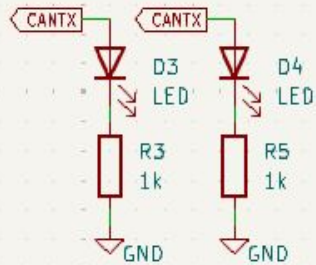


Sensor Hall i Clock

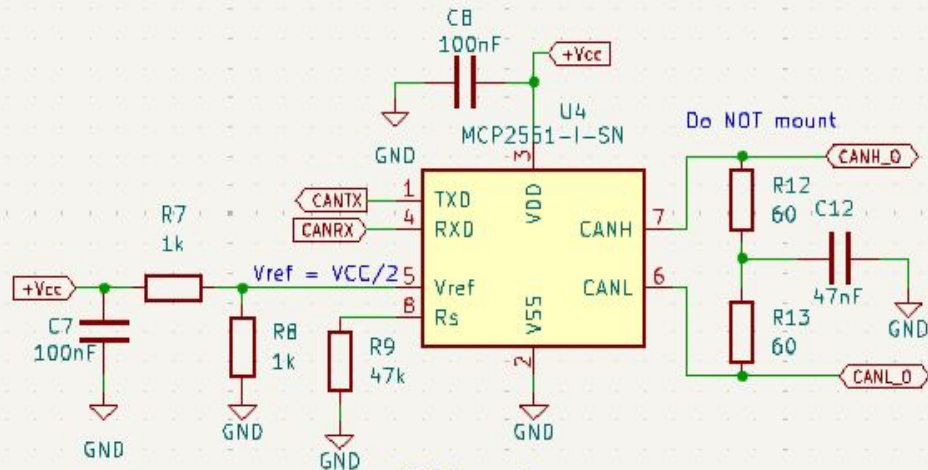


Transceiver i leds

Communication



LEDS for proving if we're on TX or RX mode

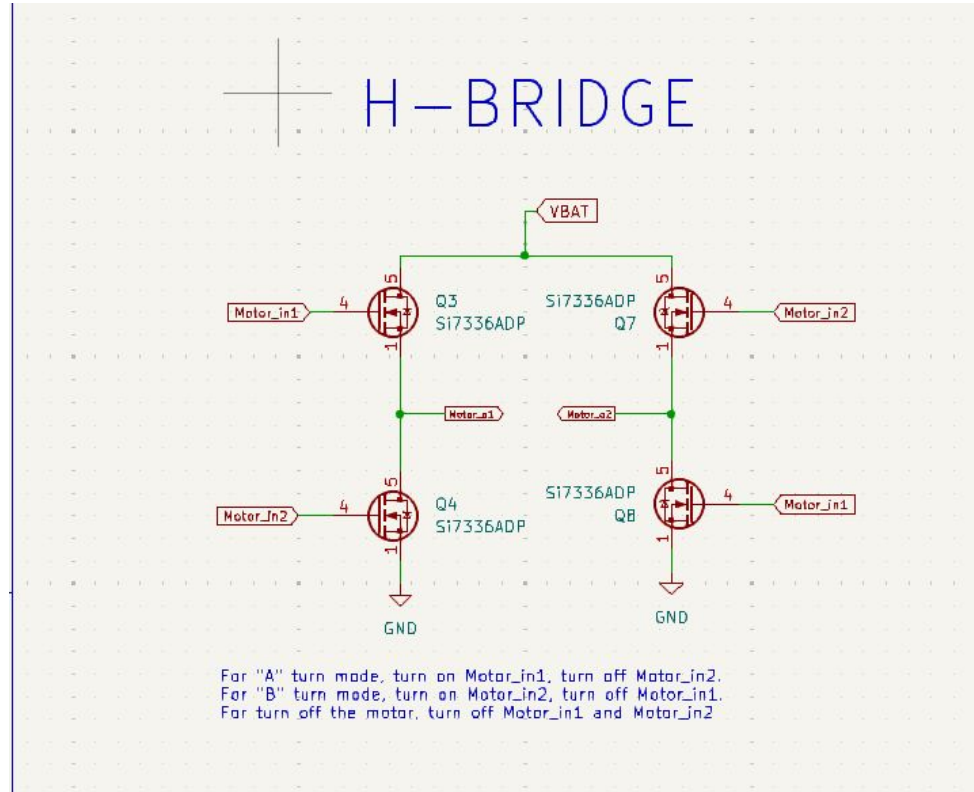


CAN transceiver

Maximum supply current = 75 mA

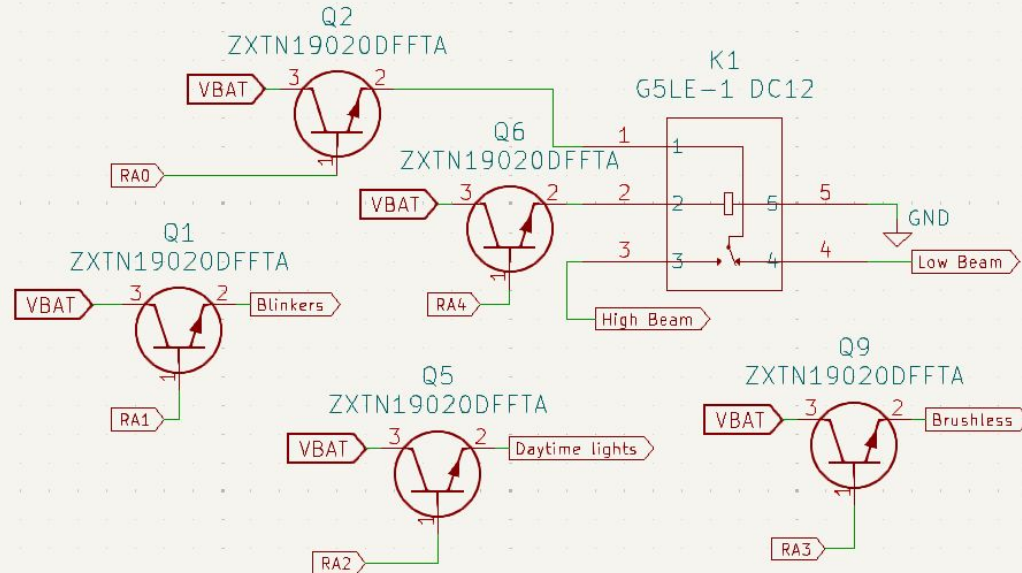
Maximum supply voltage = 7 V

H-bridge



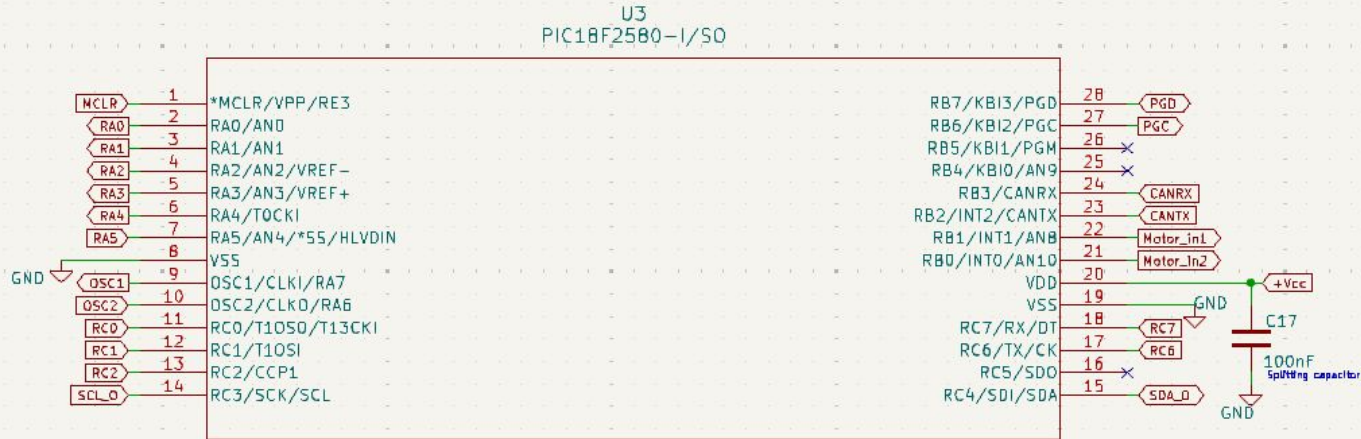
Output select stage

OUTPUT SELECT STAGE



Microcontrolador

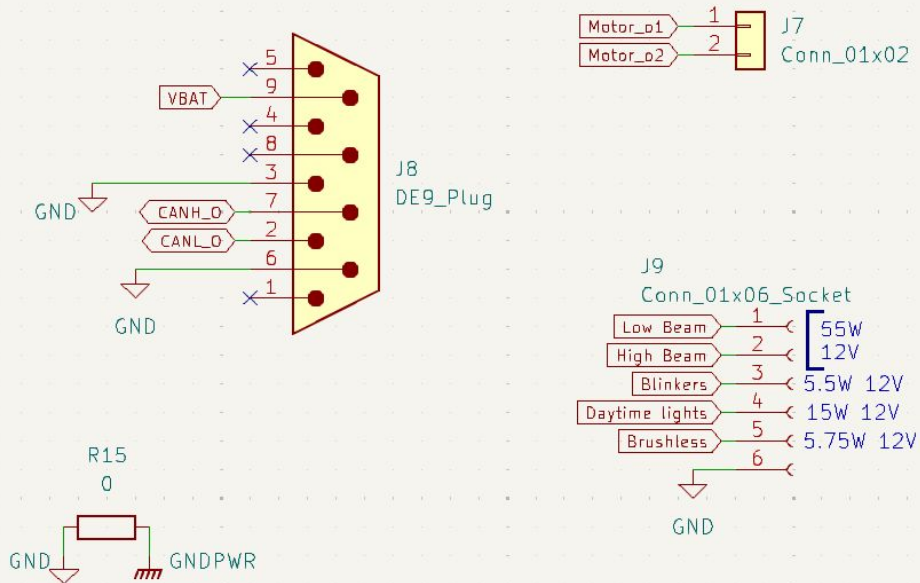
DIGITAL



Maximum current by any I/O = 25 mA
 Maximum current by all ports 200 mA
 Maximum current out of VSS = 300 mA
 Maximum current into VDD = 250 mA
 Voltage difference between VDD and VSS: -0.3V to 7.5V

Outputs

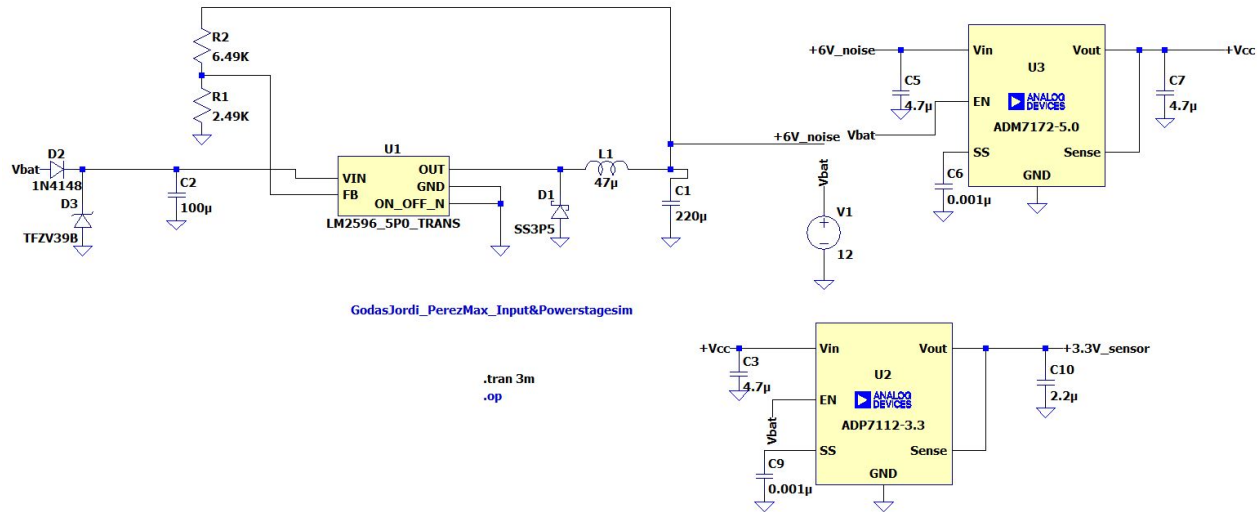
OUTPUT



Simulacions

Power stage

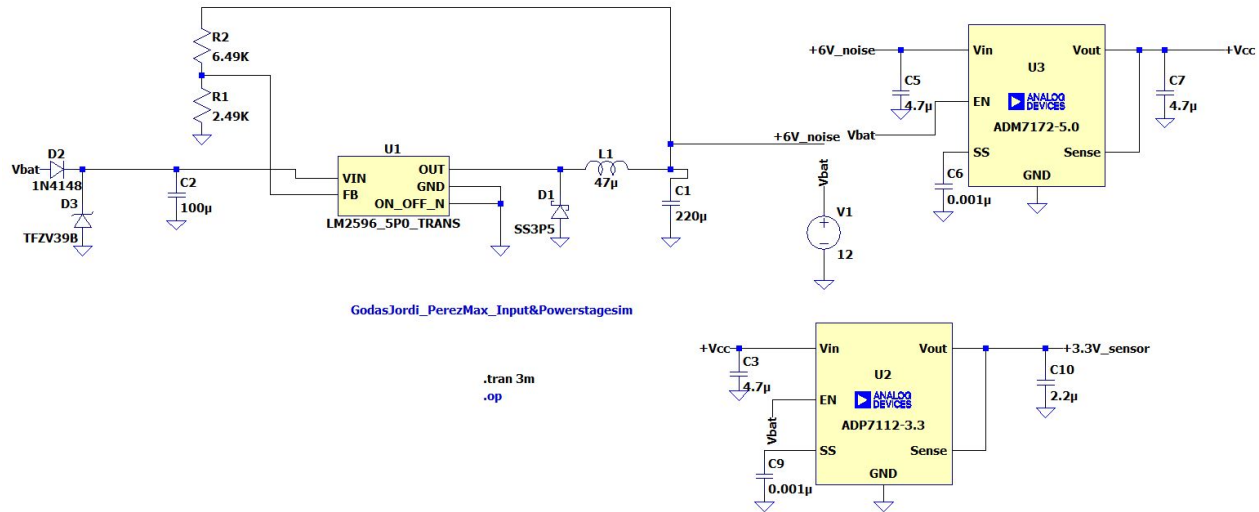
Ripple LM2596:



Etapa de potència

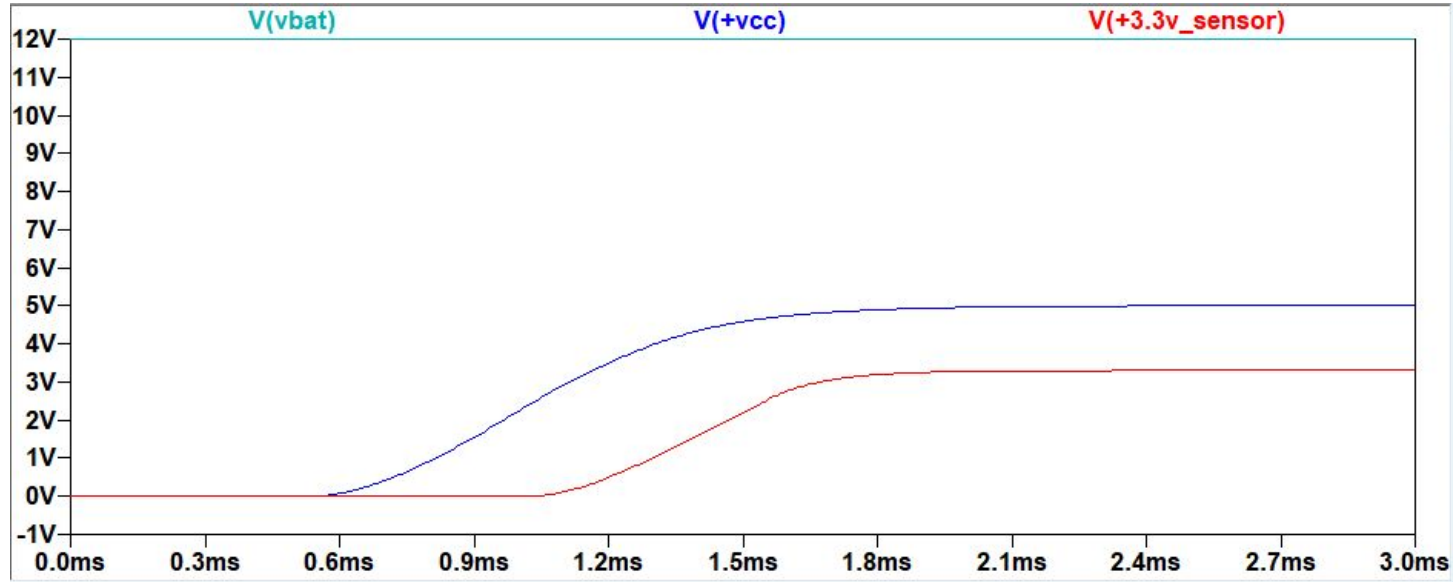
Power stage

Ripple LM2596:



Etapa de potència

Power stage



Representació gràfica dels diferents voltatges de l'etapa de potència en funció del temps

H-Bridge

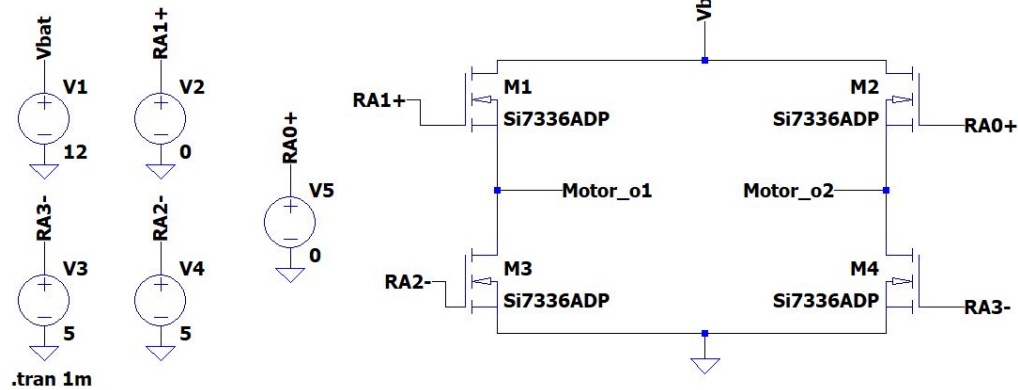
GodasJordi_PerezMax_hbridge

Todo esto se controlará con el micro, inclusive el fin de carrera

Para que el motor gire en el sentido A, hay que dar corriente de base RA1+ y RA3-

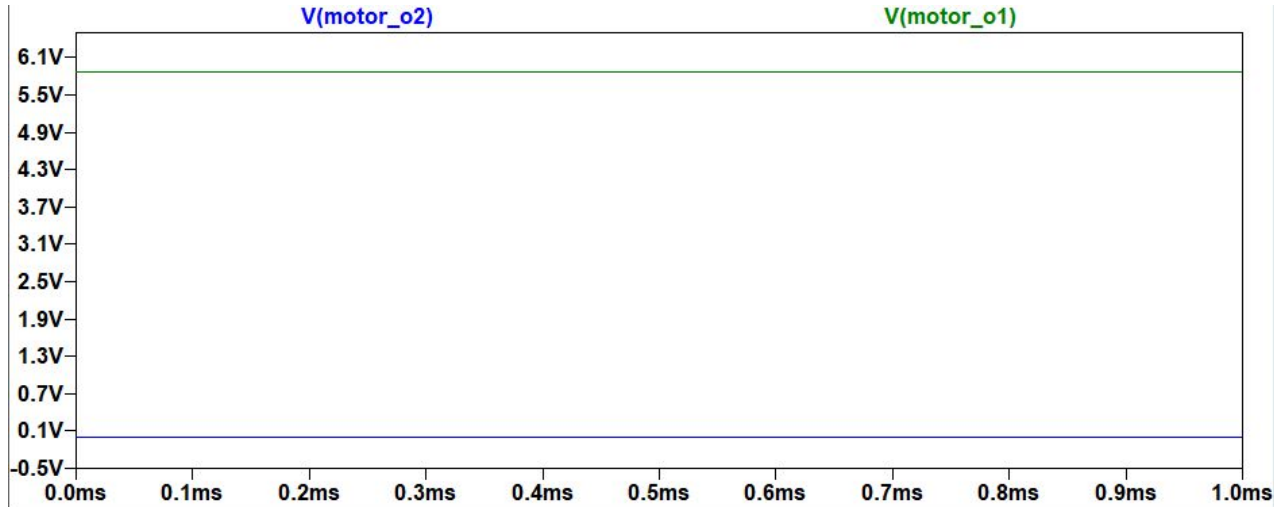
Para que el motor gire en el sentido B, hay que dar corriente de base RA0+ y RA2-

Para que el motor no gire, aplicamos voltage en RA2- y RA3-



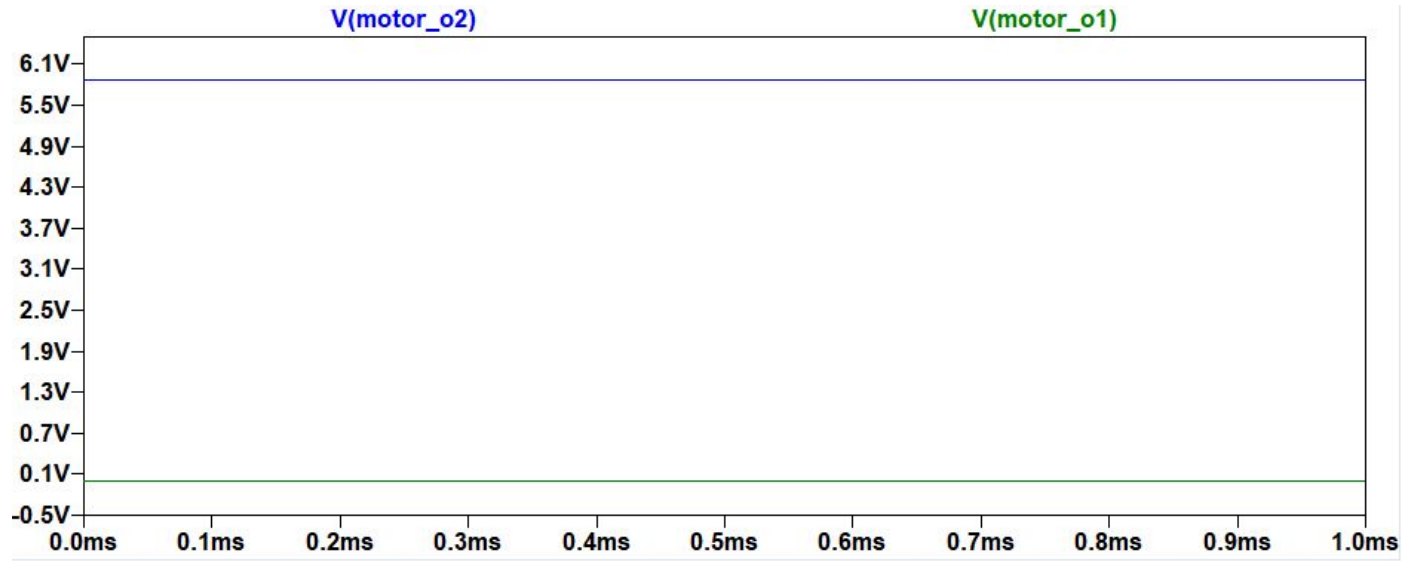
Pont H per controlar el sentit de gir del motor i final de carrera

H-Bridge (sentit de gir A)



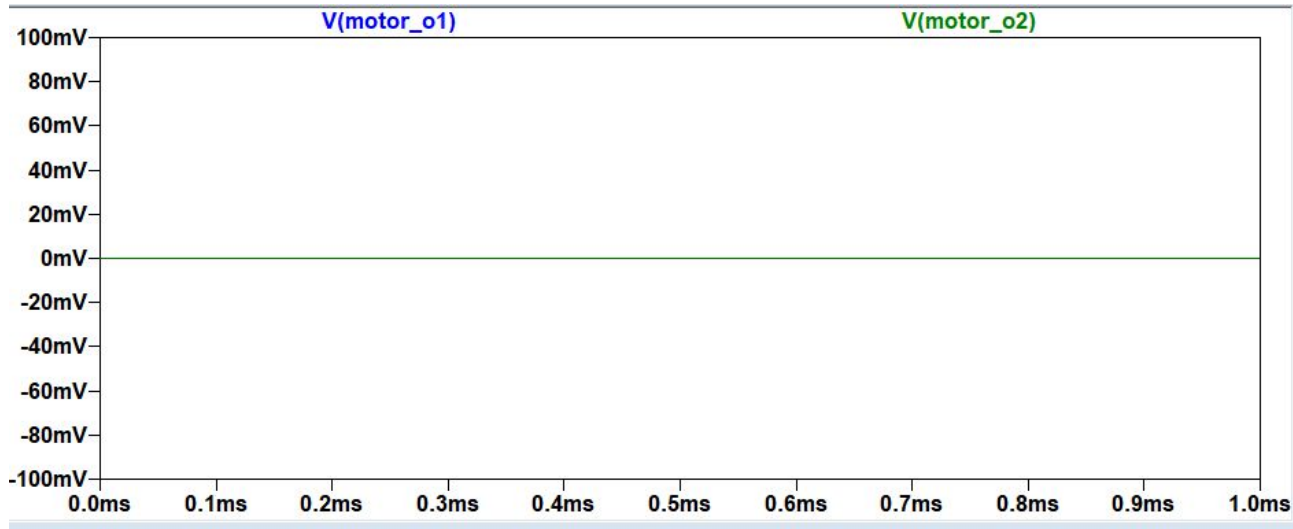
Representació gràfica dels voltatges en el Pont H per a un sentit de gir "A"

H-Bridge (sentit de gir B)



Representació gràfica dels voltatges en el Pont H per a un sentit de gir "B"

H-Bridge (motor apagat)



Representació gràfica dels voltatges en el Pont H per al motor apagat

Components



Nom del component	Funció	Datasheet
ADM7172ACPZ-5.0-R7	LDO 5V	ADM7172ACPZ-5.0-R7
ADP7112ACBZ-3.3-R7	LDO 3.3V	ADP7112ACBZ-3.3-R7
BH1750FVI-TR	Sensor de llum	BH1750FVI-TR
G5LE-1 DC12	Relé	G5LE-1 DC12
LM2596T-ADJ	BUCK converter	LM2596T-ADJ
MCP2551-I-SN	Transciever	MCP2551-I-SN
PIC18F2580-I/SO	Microprocesador	PIC18F2580-I/SO
Si7336ADP	Transistor BJT	Si7336ADP
SN74LXC2T45DCUR	Traductor de 5V a 3.3V	SN74LXC2T45DCUR
TMAG5124G1CEDBZRQ1	Sensor hall	TMAG5124G1CEDBZRQ1
ZXTN19020DFFTA	Transistor mosfet	ZXTN19020DFFTA

